

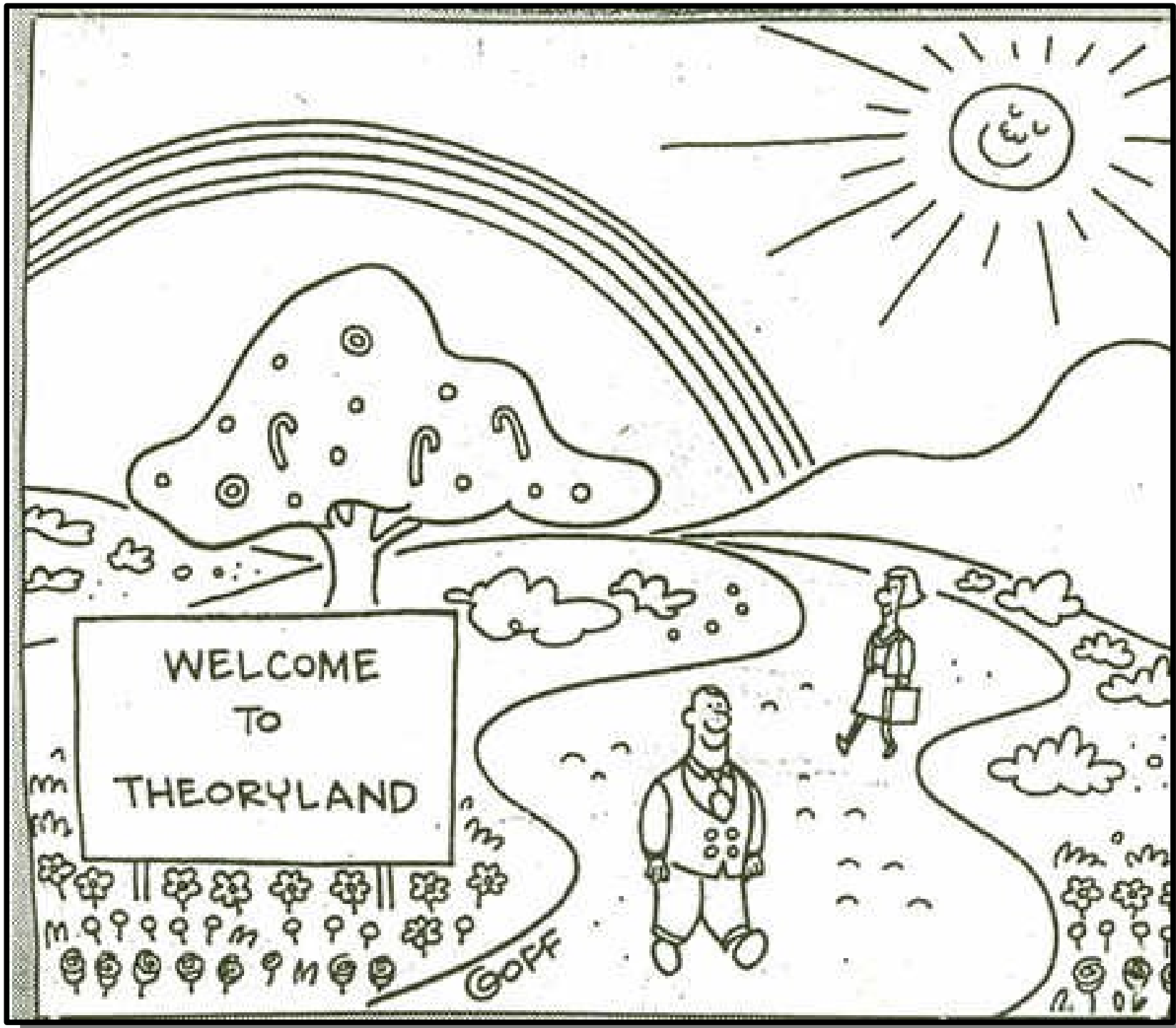
Complexity Theory

Part One

Complexity Theory

It may be that since one is customarily concerned with existence, [...] finiteness, and so forth, one is not inclined to take seriously the question of the existence of a *better-than-finite* algorithm.

- Jack Edmonds, "Paths, Trees, and Flowers"



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It may be that since one is customarily concerned with existence, [...] *decidability*, and so forth, one is not inclined to take seriously the question of the existence of a *better-than-decidable* algorithm.

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A Decidable Problem

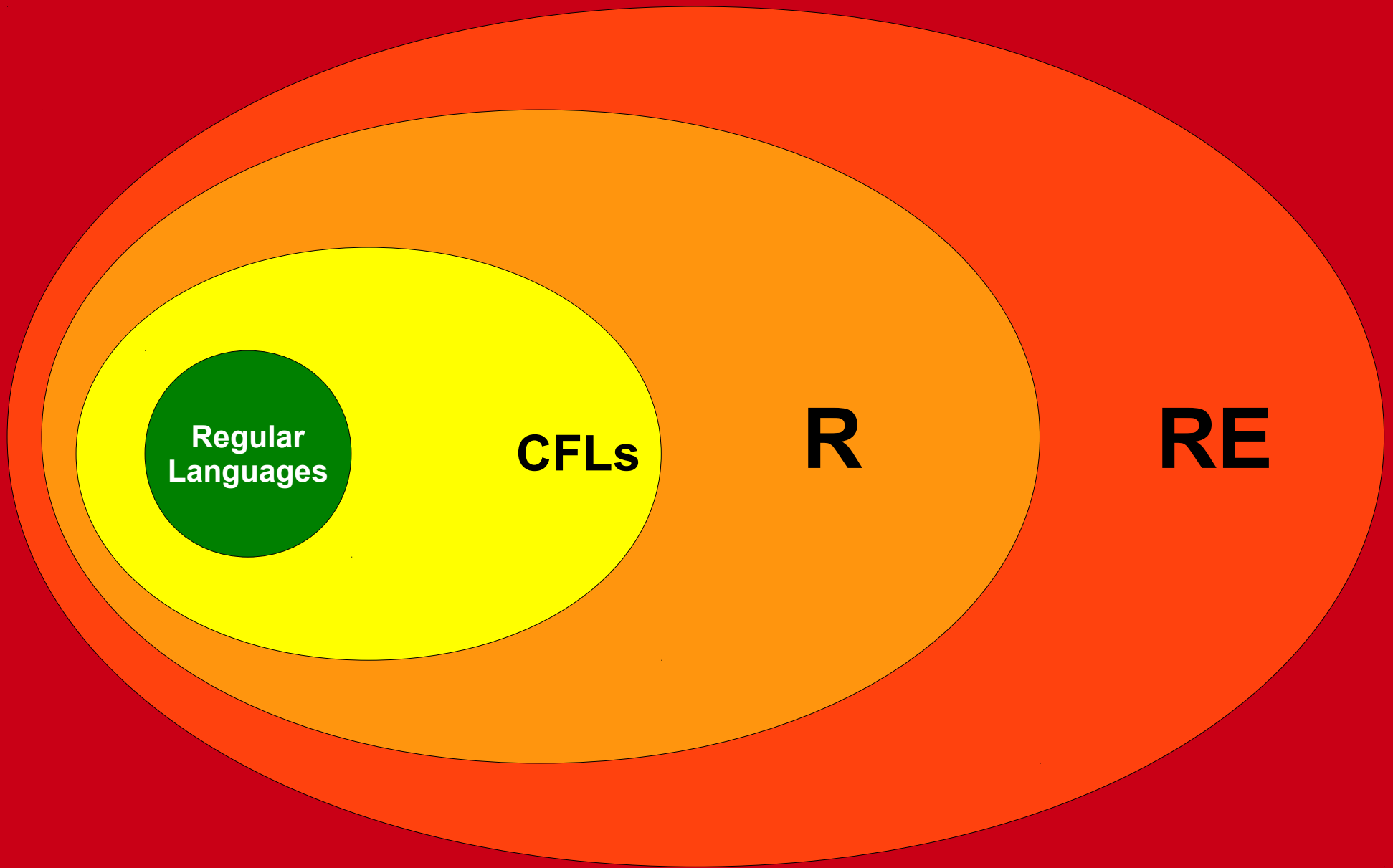
- **Presburger arithmetic** is a logical system for reasoning about arithmetic.
 - $\forall x. x + 1 \neq 0$
 - $\forall x. \forall y. (x + 1 = y + 1 \rightarrow x = y)$
 - $\forall x. x + 0 = x$
 - $\forall x. \forall y. (x + y) + 1 = x + (y + 1)$
 - $(P(0) \wedge \forall y. (P(y) \rightarrow P(y + 1))) \rightarrow \forall x. P(x)$
- Given a statement, it is decidable whether that statement can be proven from the laws of Presburger arithmetic.
- Any Turing machine that decides whether a statement in Presburger arithmetic is true or false has to move its tape head at least $2^{2^{cn}}$ times on some inputs of length n (for some fixed constant c).

For Reference

- Assume $c = 1$.

The Limits of Decidability

- The fact that a problem is decidable does not mean that it is *feasibly* decidable.
- In ***computability theory***, we ask the question
What problems can be solved by a computer?
- In ***complexity theory***, we ask the question
What problems can be solved ***efficiently*** by a computer?
- In the remainder of this course, we will explore this question in more detail.



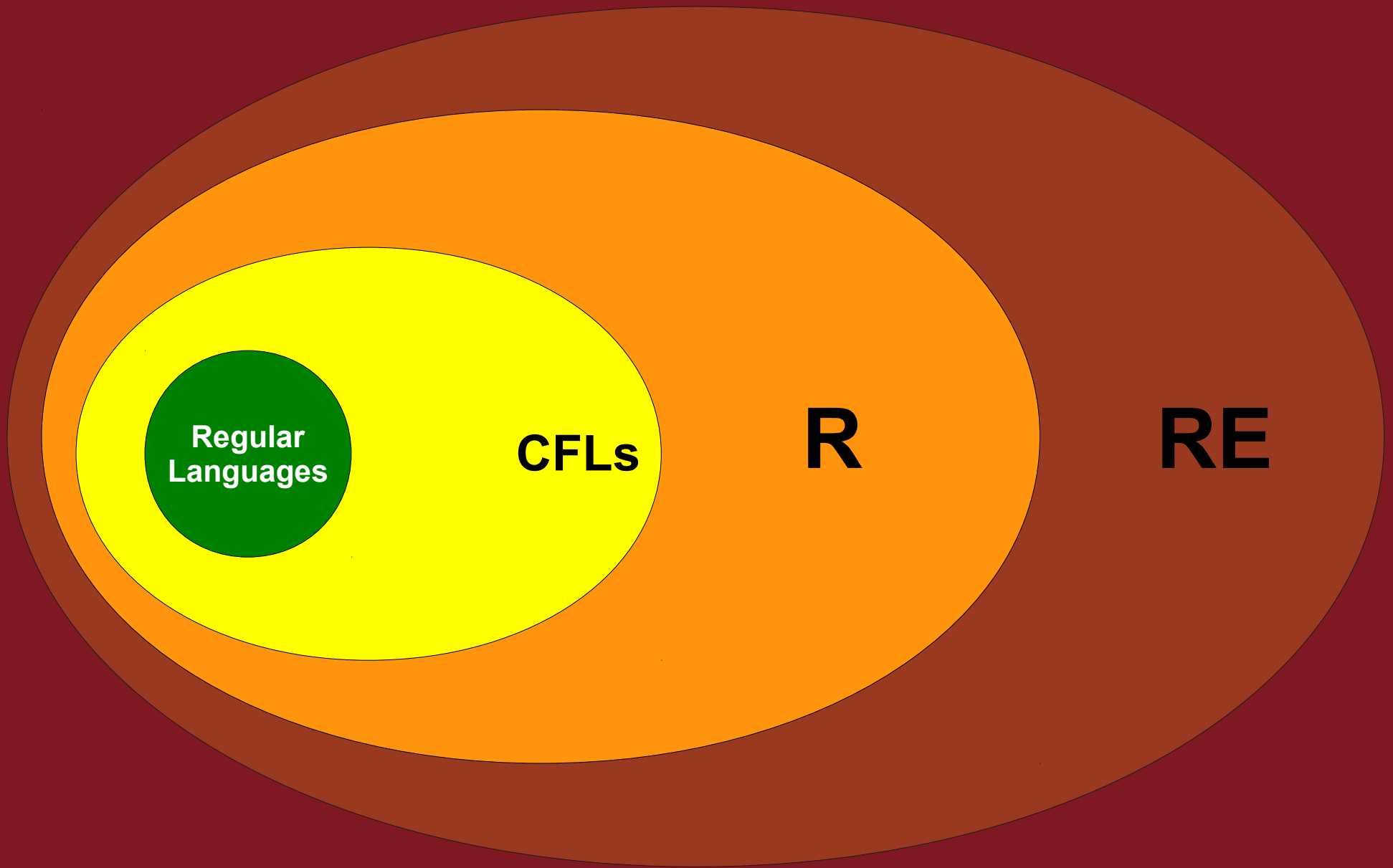
Regular
Languages

CFLs

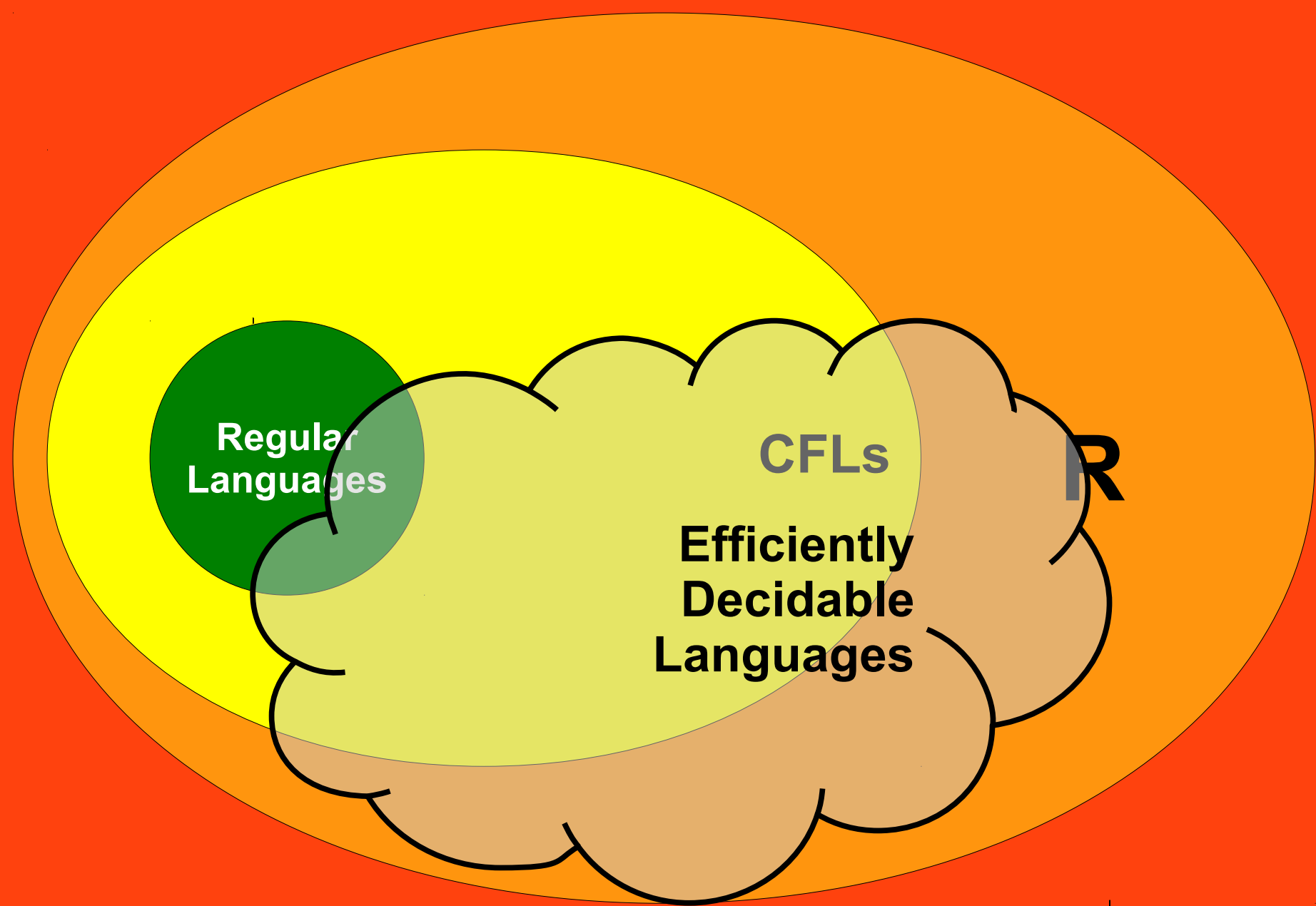
R

RE

All Languages



All Languages



Regular Languages

CFLs

Efficiently Decidable Languages

Undecidable Languages

R

The Setup

- In order to study computability, we needed to answer these questions:
 - What is “computation?”
 - What is a “problem?”
 - What does it mean to “solve” a problem?
- To study complexity, we need to answer these questions:
 - What does “complexity” even mean?
 - What is an “efficient” solution to a problem?

Measuring Complexity

- Suppose that we have a decider D for some language L .
- How might we measure the complexity of D ?

Measuring Complexity

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 - Number of states.
 - Size of tape alphabet.
 - Size of input alphabet.
 - Amount of tape required.
 - Amount of time required.
 - Number of times a given state is entered.
 - Number of times a given symbol is printed.
 - Number of times a given transition is taken.
 - (Plus a whole lot more...)

Measuring Complexity

- Suppose that we have a decider D for some language L .
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Amount of tape required.

- **Amount of time required.**

Number of times a given state is entered.

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(Plus a whole lot more...)

What is an efficient algorithm?

Searching Finite Spaces

- Many decidable problems can be solved by searching over a large but finite space of possible options.
- Searching this space might take a staggeringly long time, but only finite time.
- From a decidability perspective, this is totally fine.
- From a complexity perspective, this is totally unacceptable.

A Sample Problem

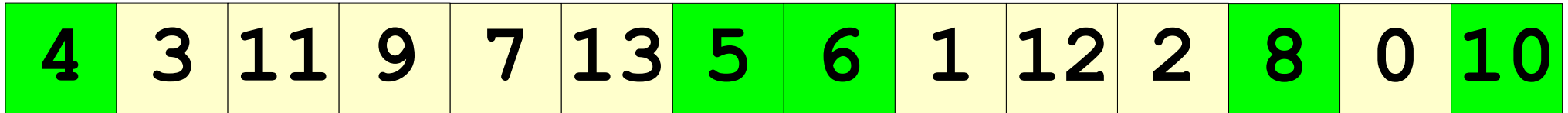
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A Sample Problem

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Goal: Find the length of the longest increasing subsequence of this sequence.

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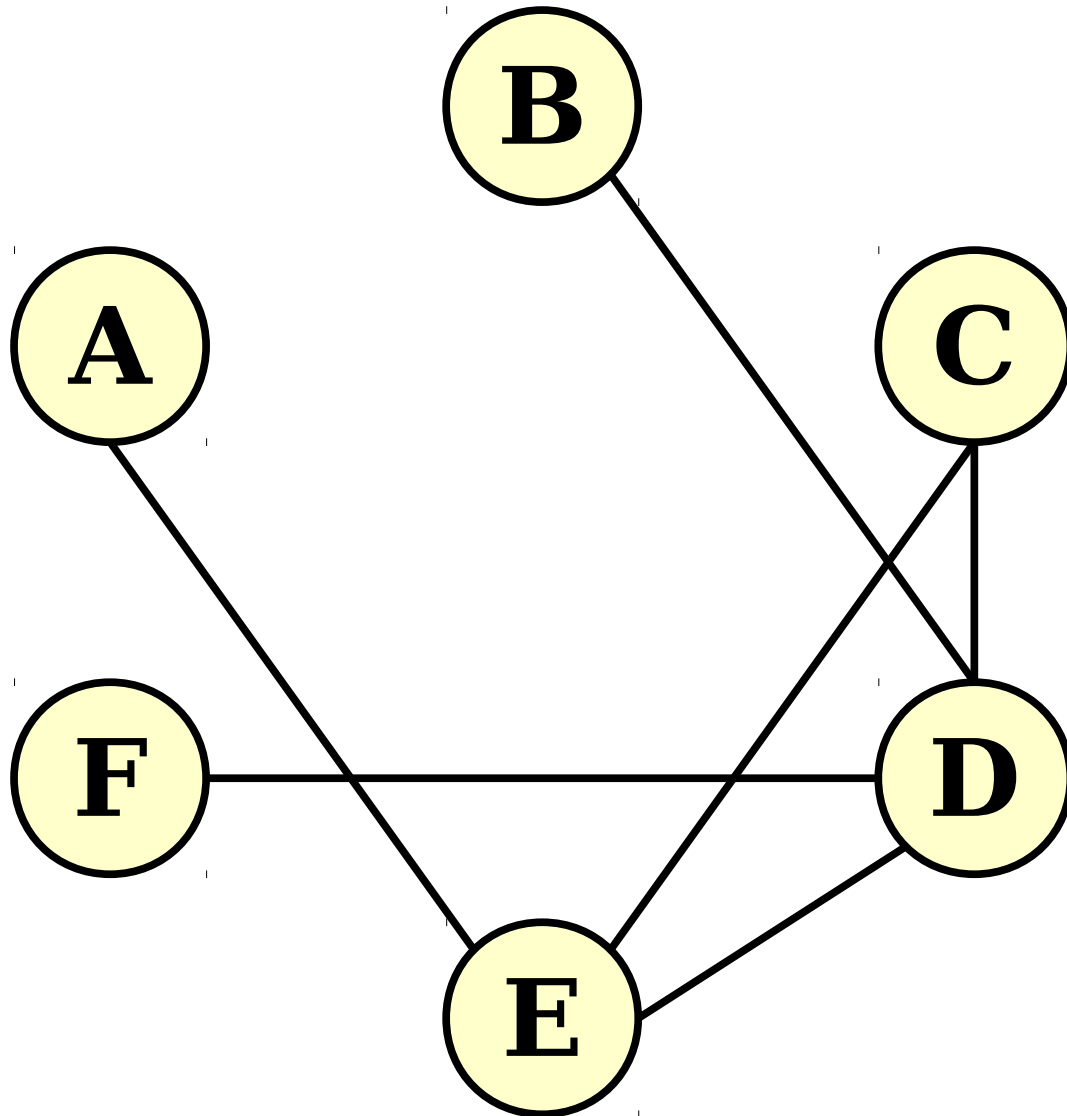
Longest Increasing Subsequences

- ***One possible algorithm:*** try all subsequences, find the longest one that's increasing, and return that.
- There are 2^n subsequences of an array of length n .
 - (Each subset of the elements gives back a subsequence.)
- Checking all of them to find the longest increasing subsequence will take time $O(n \cdot 2^n)$.
- Nifty fact: the age of the universe is about 4.3×10^{26} nanoseconds old. That's about 2^{85} nanoseconds.
- Practically speaking, this algorithm doesn't terminate if you give it an input of size 100 or more.

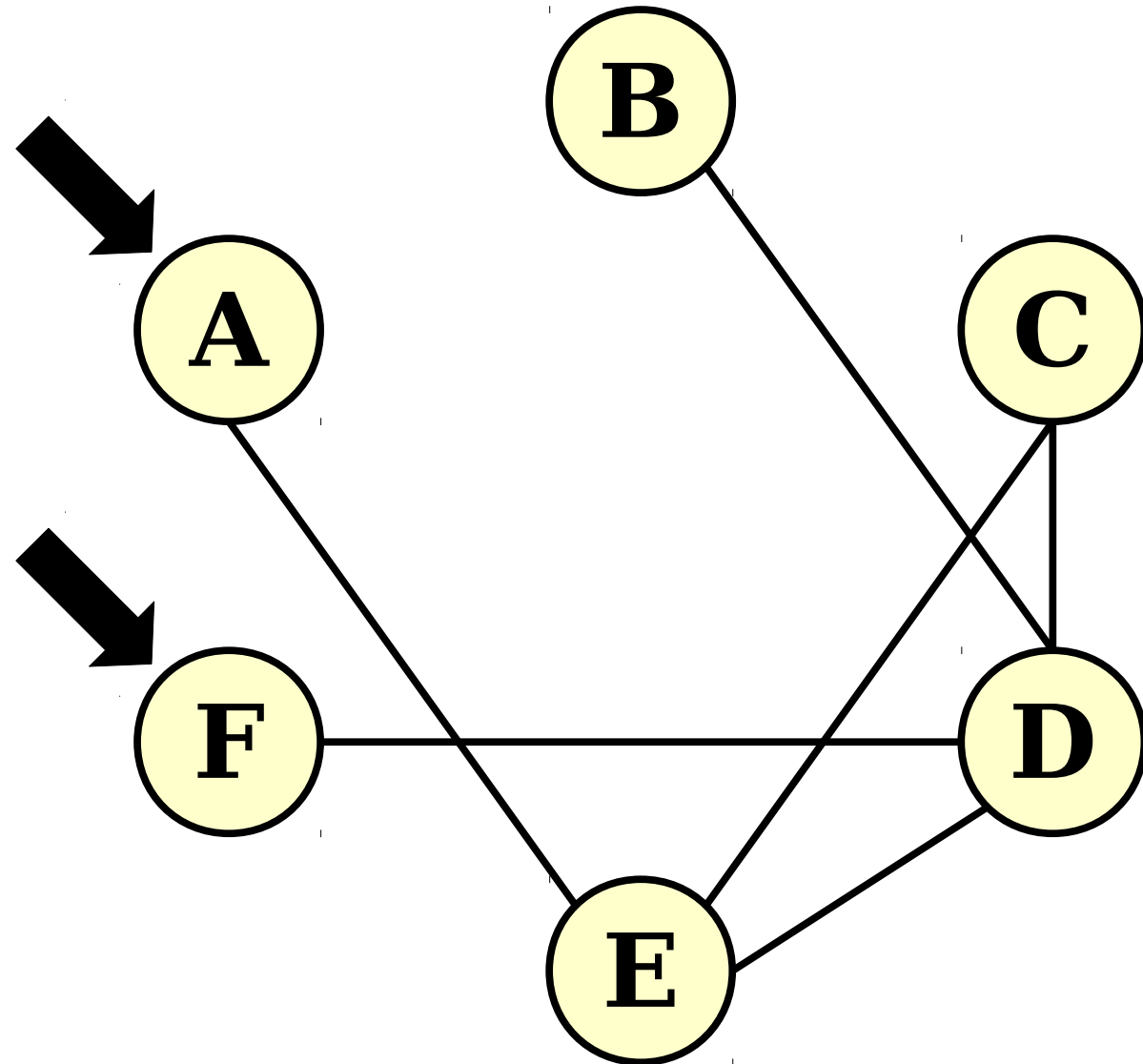
Longest Increasing Subsequences

- ***Theorem:*** There is an algorithm that can find the longest increasing subsequence of an array in time $O(n \log n)$.
- The algorithm is *beautiful* and surprisingly elegant. Look up ***patience sorting*** if you're curious.
- This algorithm works by exploiting particular aspects of how longest increasing subsequences are constructed. It's not immediately obvious that it works correctly.

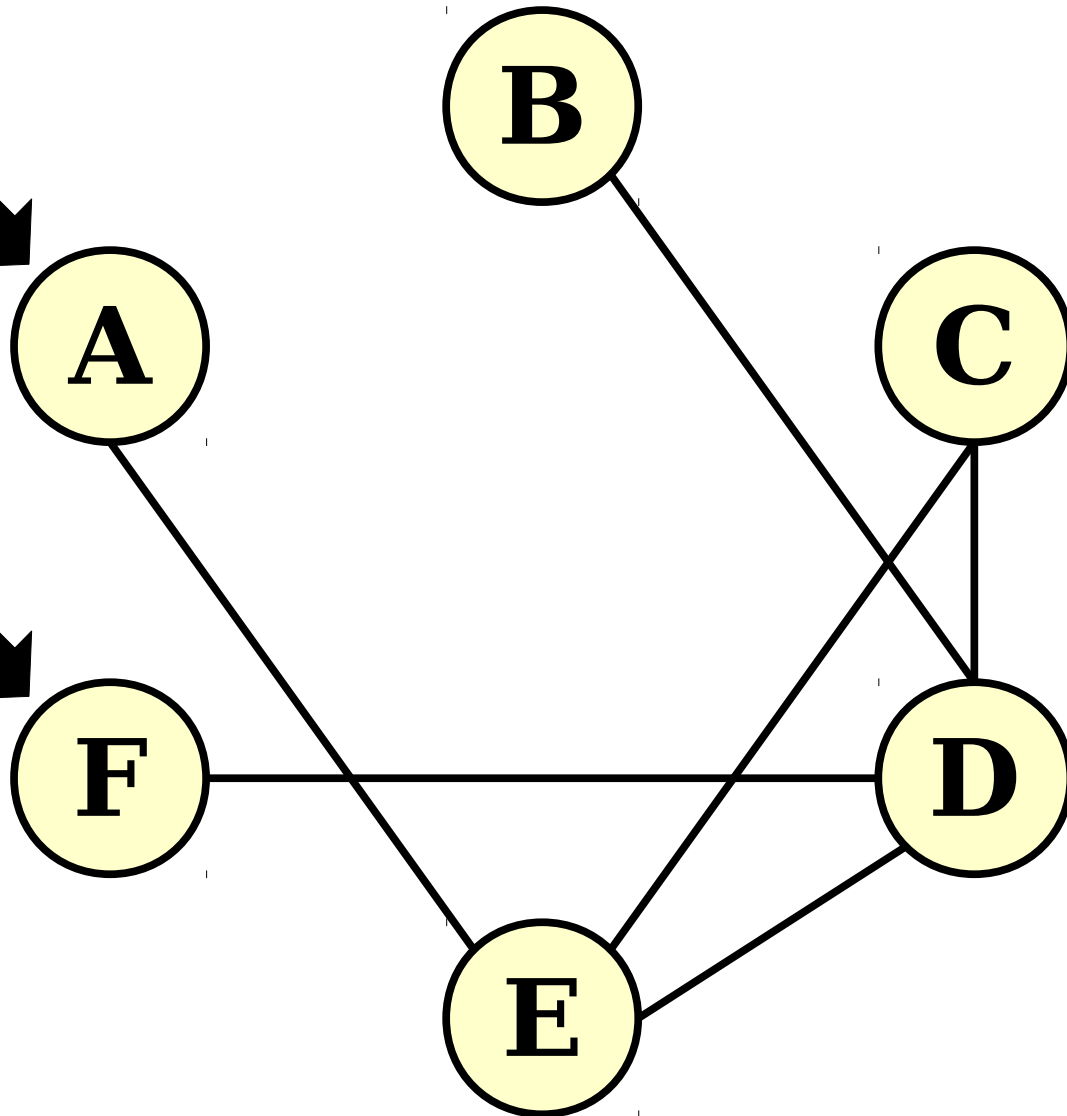
Another Problem



Another Problem



Another Problem



Goal: Determine the length of the shortest path from **A** to **F** in this graph.

Shortest Paths

- It is possible to find the shortest path in a graph by listing off all sequences of nodes in the graph in ascending order of length and finding the first that's a path.
- This takes time $O(n \cdot n!)$ in an n -node graph.
- For reference: $29!$ nanoseconds is longer than the lifetime of the universe.

Shortest Paths

- ***Theorem:*** It's possible to find the shortest path between two nodes in an n -node, m -edge graph in time $O(m + n)$.
- This is the breadth-first search algorithm. Take CS106B/X or CS161 for more details!
- The algorithm is a bit nuanced. It uses some specific properties of shortest paths and the proof of correctness is nontrivial.

For Comparison

- ***Longest increasing subsequence:***
 - Naive: $O(n \cdot 2^n)$
 - Fast: $O(n^2)$
- ***Shortest path problem:***
 - Naive: $O(n \cdot n!)$
 - Fast: $O(n + m)$.

Defining Efficiency

- When dealing with problems that search for the “best” object of some sort, there are often at least exponentially many possible options.
- Brute-force solutions tend to take at least exponential time to complete.
- Clever algorithms often run in time $O(n)$, or $O(n^2)$, or $O(n^3)$, etc.

Polynomials and Exponentials

- An algorithm runs in ***polynomial time*** if its runtime is some polynomial in n .
 - That is, time $O(n^k)$ for some constant k .
- Polynomial functions “scale well.”
 - Small changes to the size of the input do not typically induce enormous changes to the overall runtime.
- Exponential functions scale terribly.
 - Small changes to the size of the input induce huge changes in the overall runtime.

The Cobham-Edmonds Thesis

A language L can be ***decided efficiently*** if there is a TM that decides it in polynomial time.

Equivalently, L can be decided efficiently if it can be decided in time $O(n^k)$ for some $k \in \mathbb{N}$.

Like the Church-Turing thesis, this is ***not*** a theorem!

It's an assumption about the nature of efficient computation, and it is somewhat controversial.

The Cobham-Edmonds Thesis

- Efficient runtimes:
 - $4n + 13$
 - $n^3 - 2n^2 + 4n$
 - $n \log \log n$
- “Efficient” runtimes:
 - $n^{1,000,000,000,000}$
 - 10^{500}
- Inefficient runtimes:
 - 2^n
 - $n!$
 - n^n
- “Inefficient” runtimes:
 - $n^{0.0001 \log n}$
 - 1.0000000001^n

Why Polynomials?

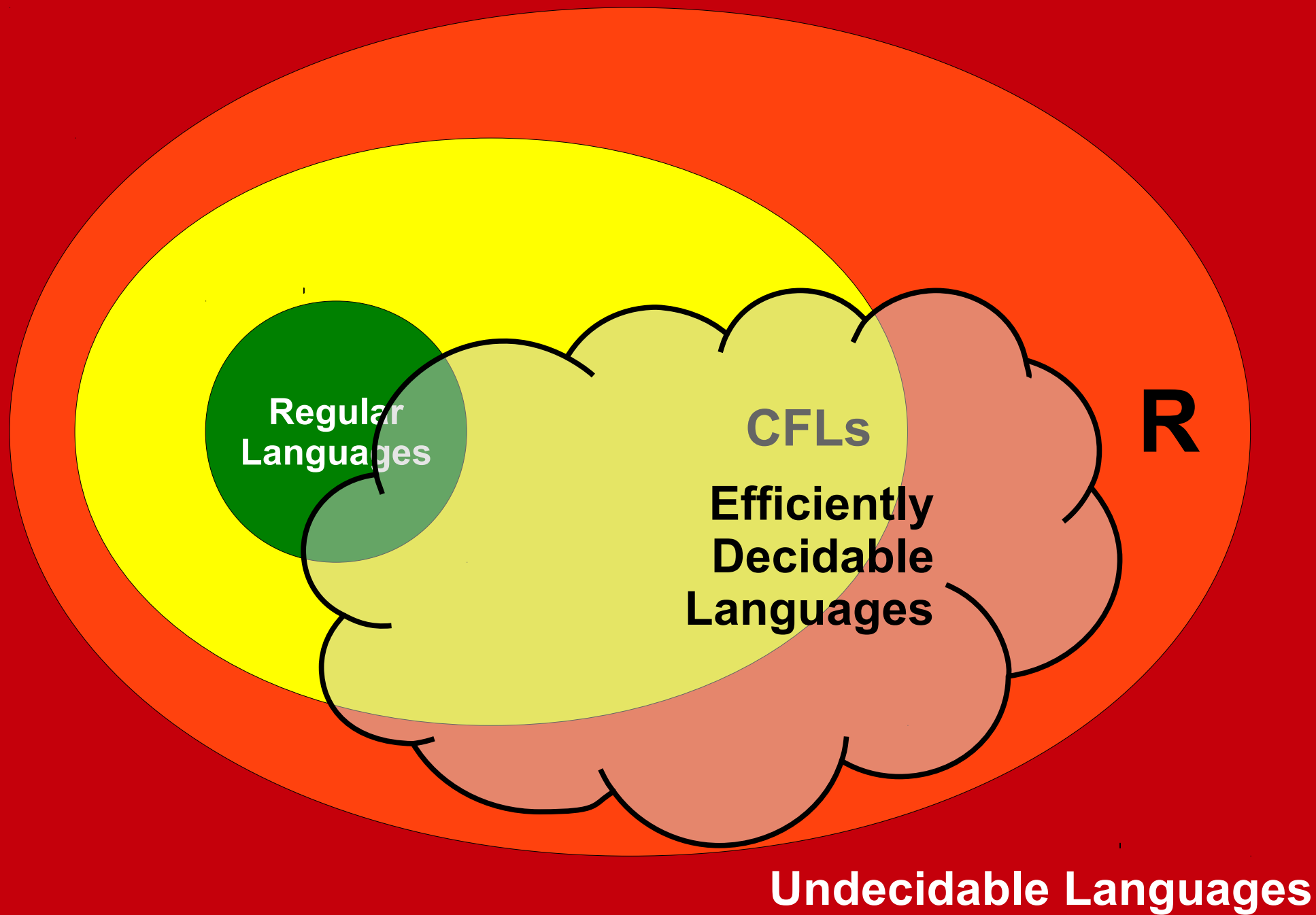
- Polynomial time *somewhat* captures efficient computation, but has a few edge cases.
- However, polynomials have very nice mathematical properties:
 - The sum of two polynomials is a polynomial. (Running one efficient algorithm after the other gives an efficient algorithm.)
 - The product of two polynomials is a polynomial. (Running one efficient algorithm a “reasonable” number of times gives an efficient algorithm.)
 - The *composition* of two polynomials is a polynomial. (Using the output of one efficient algorithm as the input to another efficient algorithm gives an efficient algorithm.)

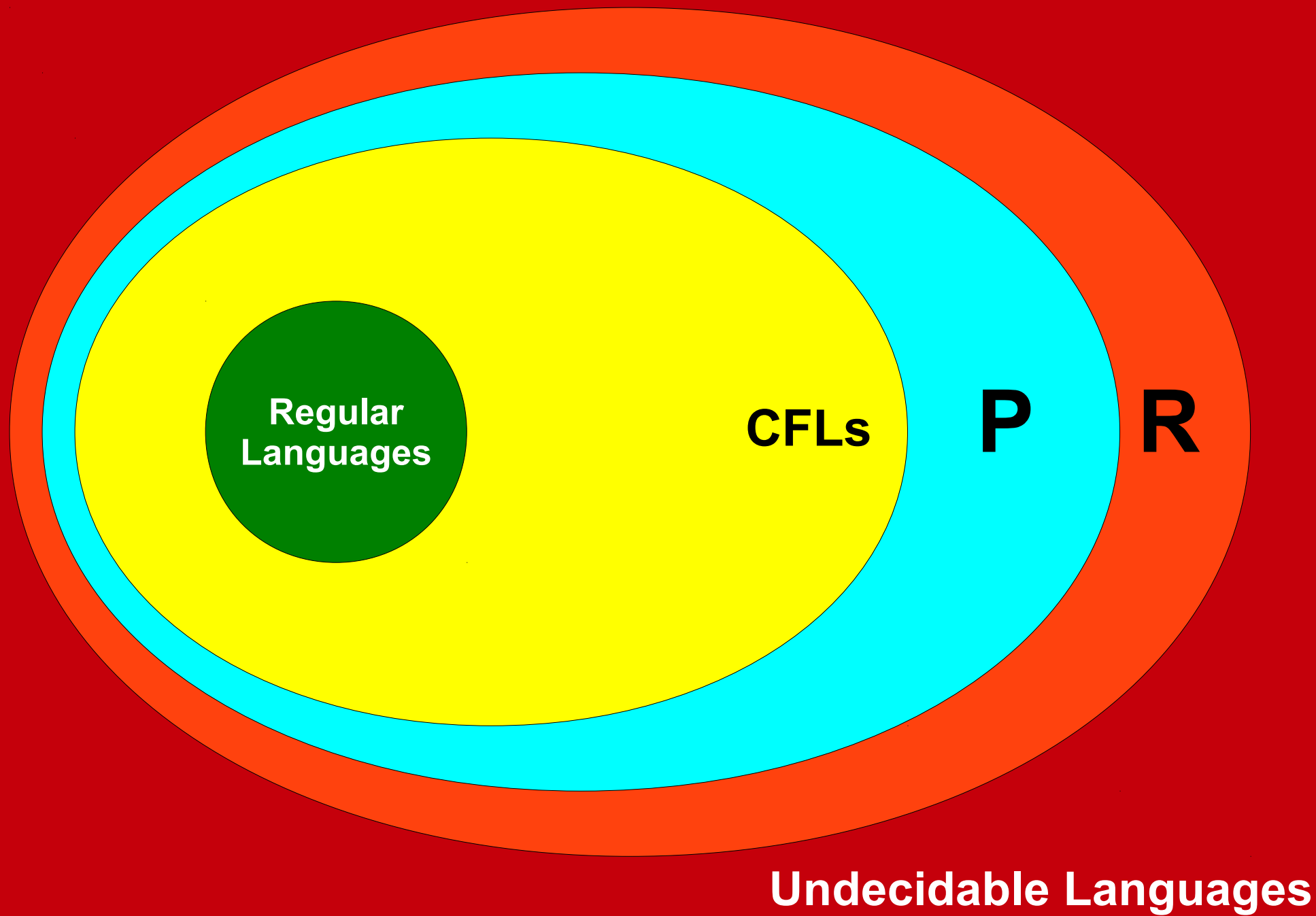
The Complexity Class **P**

- The **complexity class \mathbf{P}** (for ***p***olynomial time) contains all problems that can be solved in polynomial time.
- Formally:
$$\mathbf{P} = \{ L \mid \text{There is a polynomial-time decider for } L \}$$
- Assuming the Cobham-Edmonds thesis, a language is in **P** if it can be decided efficiently.

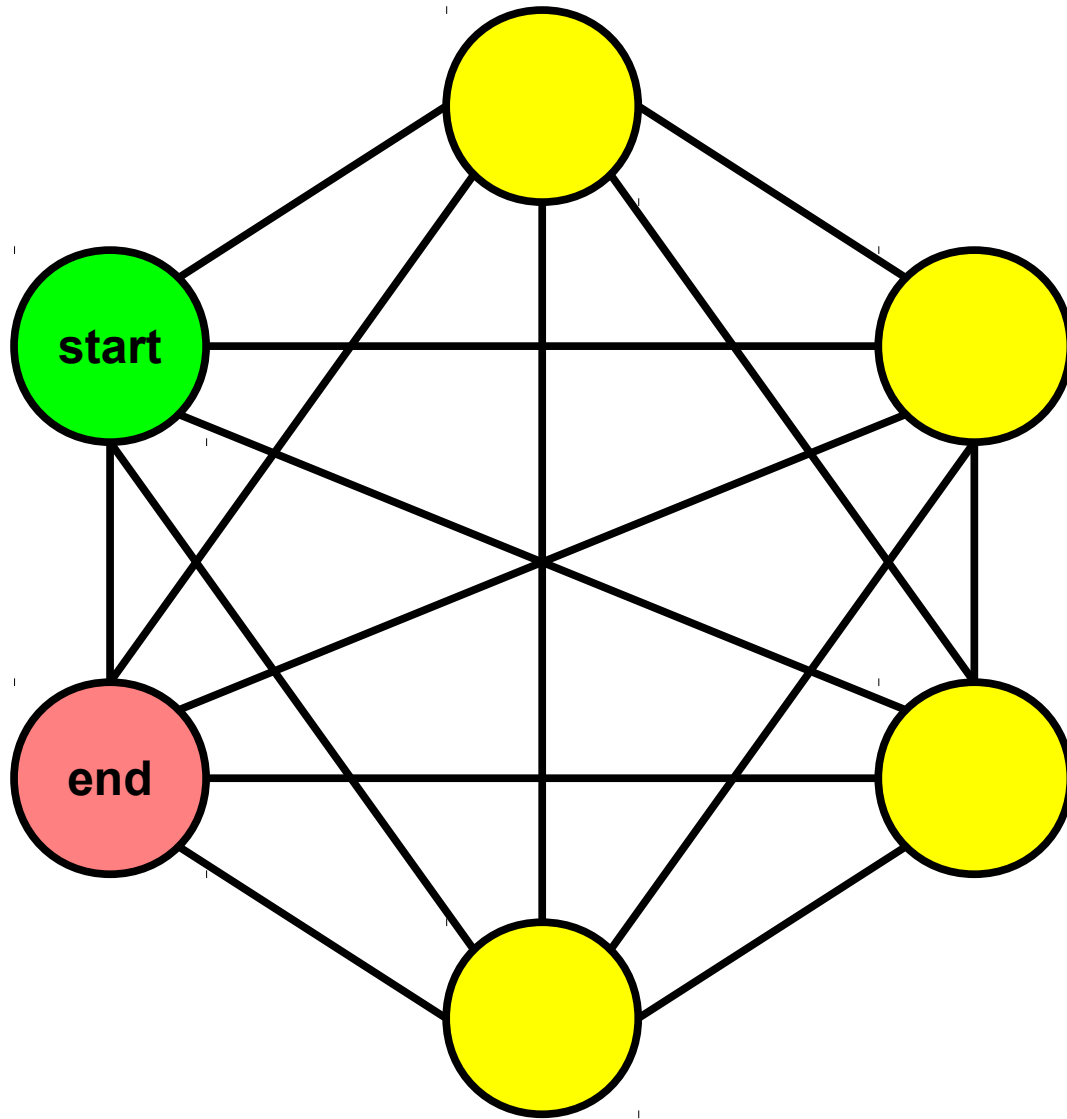
Examples of Problems in **P**

- All regular languages are in **P**.
 - All have linear-time TMs.
- All CFLs are in **P**.
 - Requires a more nuanced argument (the *CYK algorithm* or *Earley's algorithm*.)
- And a *ton* of other problems are in **P** as well.
 - Curious? Take CS161!





What *can't* you do in polynomial time?



How many simple paths are there from the start node to the end node?



How many
subsets of this
set are there?

An Interesting Observation

- There are (at least) exponentially many objects of each of the preceding types.
- However, each of those objects is not very large.
 - Each simple path has length no longer than the number of nodes in the graph.
 - Each subset of a set has no more elements than the original set.
- This brings us to our next topic...

What if you need to search a large space for a single object?

Verifiers - Again

		7		6		1		
					3		5	2
3			1		5	9		7
6		5		3		8		9
	1						2	
8		2		1		5		4
1		3	2		7			8
5	7		4					
		4		8		7		

Does this Sudoku problem
have a solution?

Verifiers - Again

2	5	7	9	6	4	1	8	3
4	9	1	8	7	3	6	5	2
3	8	6	1	2	5	9	4	7
6	4	5	7	3	2	8	1	9
7	1	9	5	4	8	3	2	6
8	3	2	6	1	9	5	7	4
1	6	3	2	5	7	4	9	8
5	7	8	4	9	6	2	3	1
9	2	4	3	8	1	7	6	5

Does this Sudoku problem
have a solution?

Verifiers - Again

9	3	11	4	2	13	5	6	1	12	7	8	0	10
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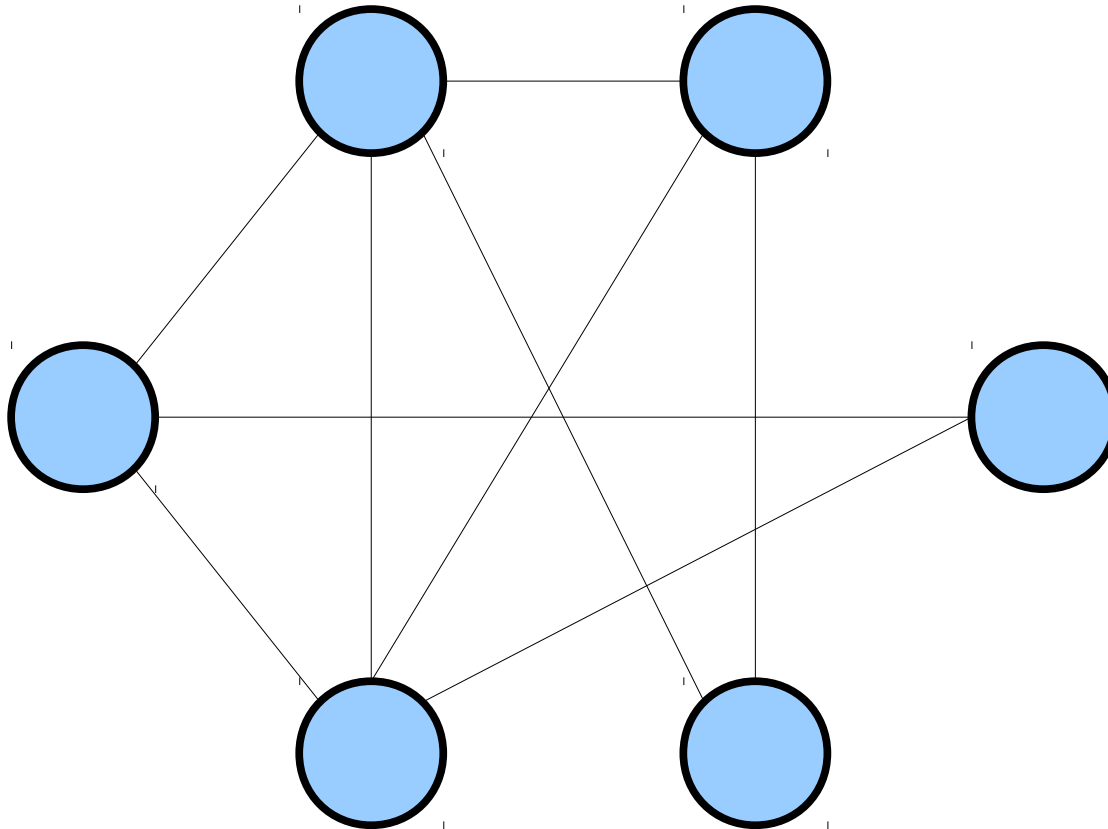
Is there an ascending subsequence of length at least 7?

Verifiers - Again

9	3	11	4	2	13	5	6	1	12	7	8	0	10
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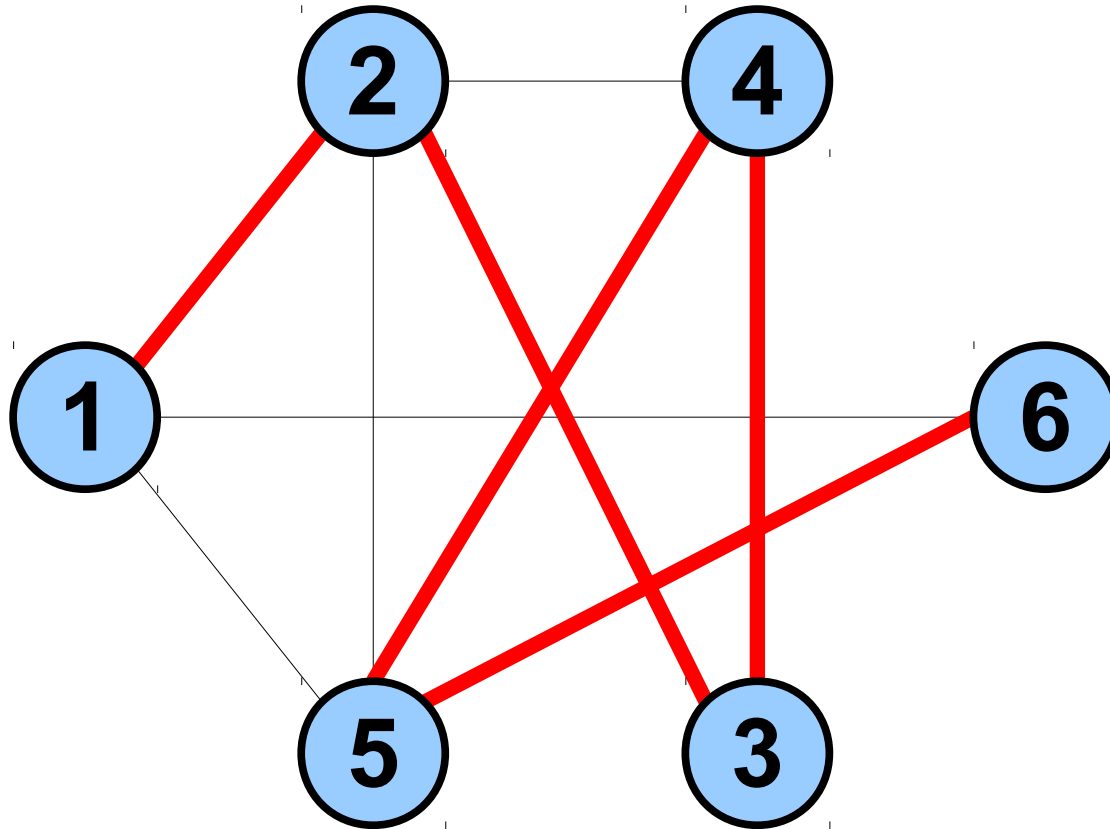
Is there an ascending subsequence of length at least 7?

Verifiers - Again



Is there a simple path that goes through every node exactly once?

Verifiers - Again



Is there a simple path that goes through every node exactly once?

Verifiers

- Recall that a ***verifier*** for L is a TM V such that
 - V halts on all inputs.
 - $w \in L$ iff $\exists c \in \Sigma^*. V$ accepts $\langle w, c \rangle$.

Polynomial-Time Verifiers

- A ***polynomial-time verifier*** for L is a TM V such that
 - V halts on all inputs.
 - $w \in L$ iff $\exists c \in \Sigma^*. V$ accepts $\langle w, c \rangle$.
 - V 's runtime is a polynomial in $|w|$ (that is, V 's runtime is $O(|w|^k)$ for some integer k)

The Complexity Class **NP**

- The complexity class **NP** (*nondeterministic polynomial time*) contains all problems that can be verified in polynomial time.
- Formally:

$$\mathbf{NP} = \{ L \mid \text{There is a polynomial-time verifier for } L \}$$

- The name **NP** comes from another way of characterizing **NP**. If you introduce *nondeterministic Turing machines* and appropriately define “polynomial time,” then **NP** is the set of problems that an NTM can solve in polynomial time.

And now...

The

Most Important Question

in

Theoretical Computer Science

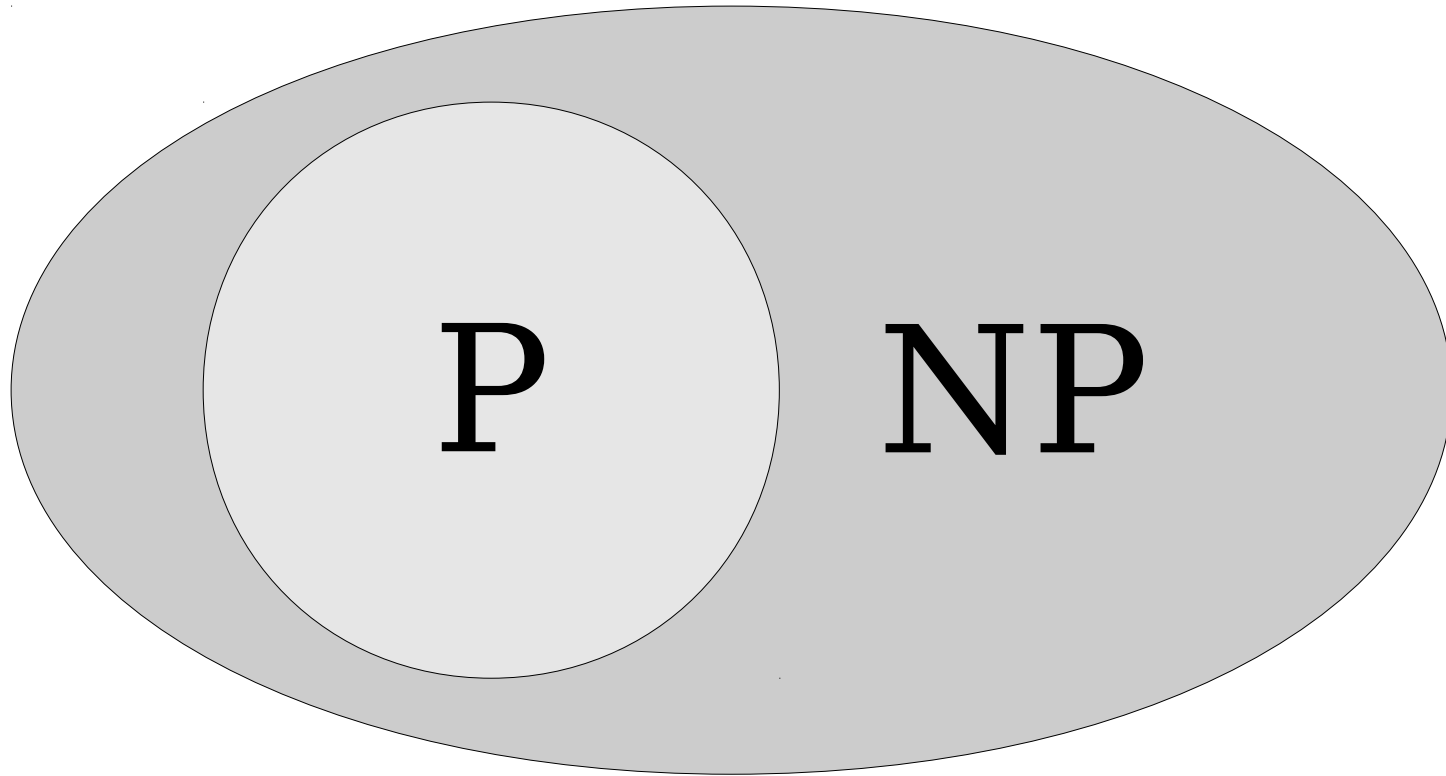
What is the connection between **P** and **NP**?

P = { L | There is a polynomial-time decider for L }

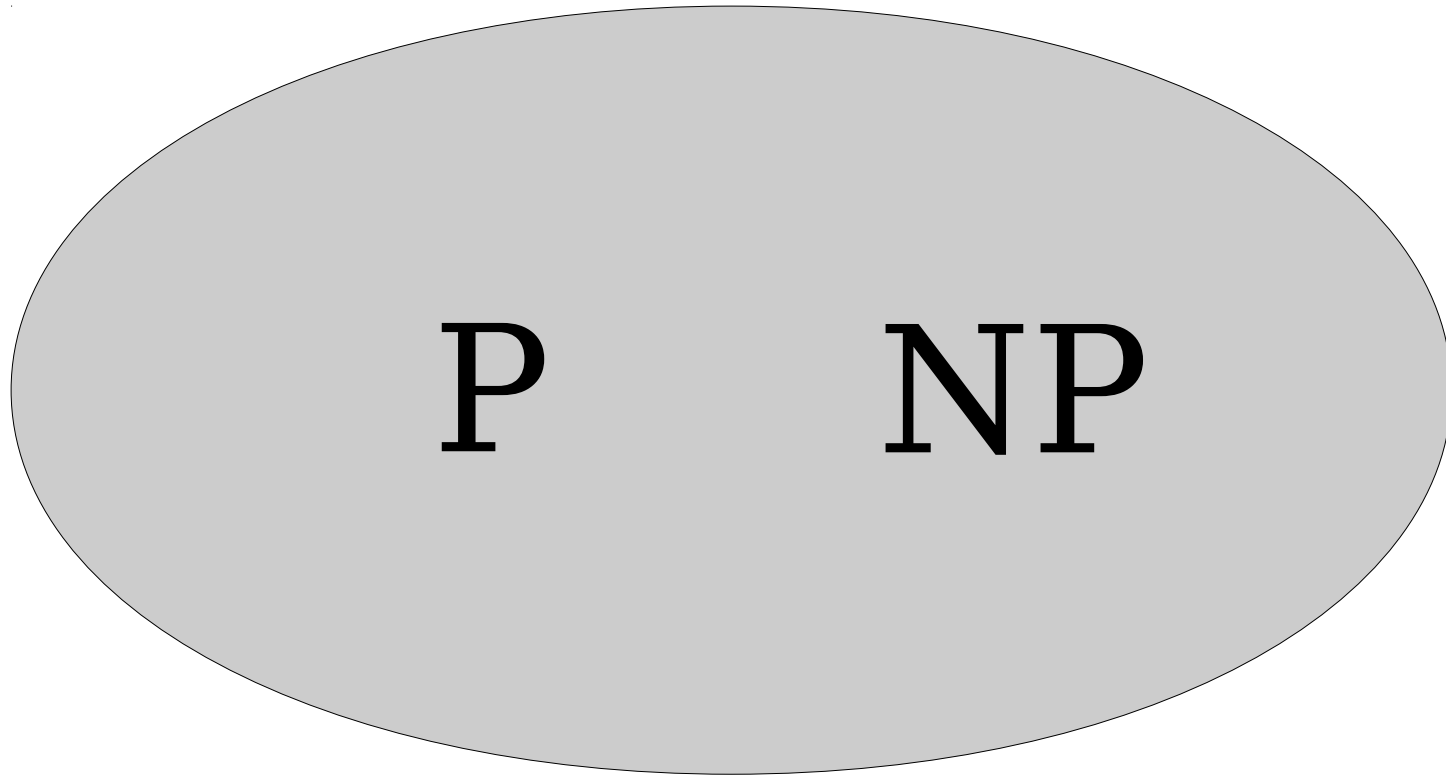
NP = { L | There is a polynomial-time verifier for L }

P \subseteq **NP**

Which Picture is Correct?



Which Picture is Correct?



Does **P** = **NP**?

$\mathbf{P} \stackrel{?}{=} \mathbf{NP}$

- The $\mathbf{P} \stackrel{?}{=} \mathbf{NP}$ question is the most important question in theoretical computer science.
- With the verifier definition of \mathbf{NP} , one way of phrasing this question is
*If a solution to a problem can be **checked** efficiently, can that problem be **solved** efficiently?*
- An answer either way will give fundamental insights into the nature of computation.

Why This Matters

- The following problems are known to be efficiently verifiable, but have no known efficient solutions:
 - Determining whether an electrical grid can be built to link up some number of houses for some price (Steiner tree problem).
 - Determining whether a simple DNA strand exists that multiple gene sequences could be a part of (shortest common supersequence).
 - Determining the best way to assign hardware resources in a compiler (optimal register allocation).
 - Determining the best way to distribute tasks to multiple workers to minimize completion time (job scheduling).
 - *And many more.*
- If $P = NP$, *all* of these problems have efficient solutions.
- If $P \neq NP$, *none* of these problems have efficient solutions.

Why This Matters

- If **P = NP**:
 - A huge number of seemingly difficult problems could be solved efficiently.
 - Our capacity to solve many problems will scale well with the size of the problems we want to solve.
- If **P ≠ NP**:
 - Enormous computational power would be required to solve many seemingly easy tasks.
 - Our capacity to solve problems will fail to keep up with our curiosity.

What We Know

- Resolving $\mathbf{P} \stackrel{?}{=} \mathbf{NP}$ has proven *extremely difficult*.
- In the past 45 years:
 - Not a single correct proof either way has been found.
 - Many types of proofs have been shown to be insufficiently powerful to determine whether $\mathbf{P} \stackrel{?}{=} \mathbf{NP}$.
 - A majority of computer scientists believe $\mathbf{P} \neq \mathbf{NP}$, but this isn't a large majority.
- Interesting read: Interviews with leading thinkers about $\mathbf{P} \stackrel{?}{=} \mathbf{NP}$:
 - <http://web.eng.puc.cl/~jabaier/iic2212/poll-1.pdf>

The Million-Dollar Question

CHALLENGE ACCEPTED



The Clay Mathematics Institute has offered a ***\$1,000,000 prize*** to anyone who proves or disproves **$P = NP$** .

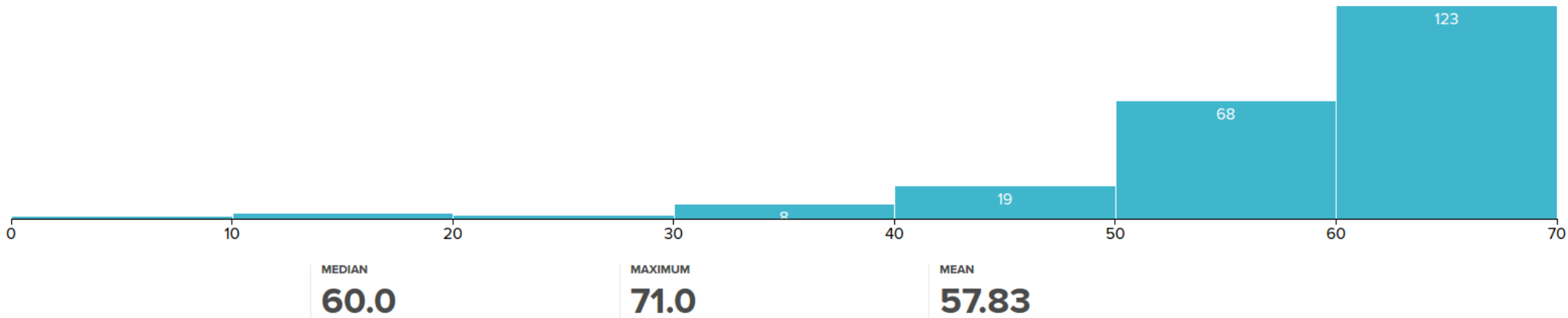
Time-Out for Announcements!

Problem Sets

- Problem Set Eight was due at the start of class today.
 - You can use late days to extend the deadline to Monday, but it's not recommended.
- Problem Set Nine goes out today. It's due next **Wednesday** at the start of class.
 - ***No late submissions can be accepted.*** This is university policy.
 - This problem set is much shorter than the other ones we've given out so far this quarter.

Problem Set Seven

- PS7 has been graded and returned. Here's the overall distribution:



- The trickiest problems were the tautonyms problem and the regex design questions.

Final Exam Logistics

- Our final exam is one week from Friday. It'll be from 3:30PM – 6:30PM. Rooms are divvied up by last (family) name:
 - Abb – Kan: Go to Bishop Auditorium.
 - Kar – Zuc: Go to Cemex Auditorium.
- Exam is cumulative and all topics from the lectures and problem sets are fair game.
- The exam focus is roughly 50/50 between discrete math topics (PS1 – PS5) and computability/complexity topics (PS6 – PS9).
- As with the midterms, the exam is closed-book, closed-computer, and limited-note. You can bring a single, double-sided, 8.5" × 11" sheet of notes with you to the exam.
- Students with OAE accommodations: please contact us ASAP if you haven't already done so.

Preparing for the Exam

- Up on the course website, you'll find
 - three sets of extra practice problems (EPP9 – EPP11), with solutions, and
 - four practice final exams, with solutions.
- Feel free to ask questions about them on Piazza or in office hours.
- Need more practice on a particular topic? Let us know!

Your Questions

“Earlier you said "it's great that [almost] everyone did really well on the midterm". How does that bode for the midterm's curve? Doesn't that just make it hard?”

We don't curve individual exam grades - it makes no sense to enforce a fixed distribution that doesn't match the actual distribution. If you did well on the exam, that's fantastic! Don't worry if other folks did better. That doesn't put you at a disadvantage.

You're not competing against your classmates. If everyone in this class rocks the final, we'll give out more As than usual.

“I'm concerned/stressed with the quick turnaround between PSET 9 and our FINAL so what do suggest, realistically, to be the best way to prep for this exam?”

We've deliberately scaled back the size and difficulty of this problem set to try to give you some more time to study for the final. Working through this problem set is a great way to study the “apex predator” topics from the course from the last week, and hopefully you'll have time to study up on the topics that you need some practice with.

Realistically: aim to complete this problem set as soon as you can (you know everything you need for it with the exception of one part of one problem), and spend your remaining time prepping for the final however you best see fit.

Back to CS103!

What do we know about $\mathbf{P} \stackrel{?}{=} \mathbf{NP}$?

Adapting our Techniques

A Problem

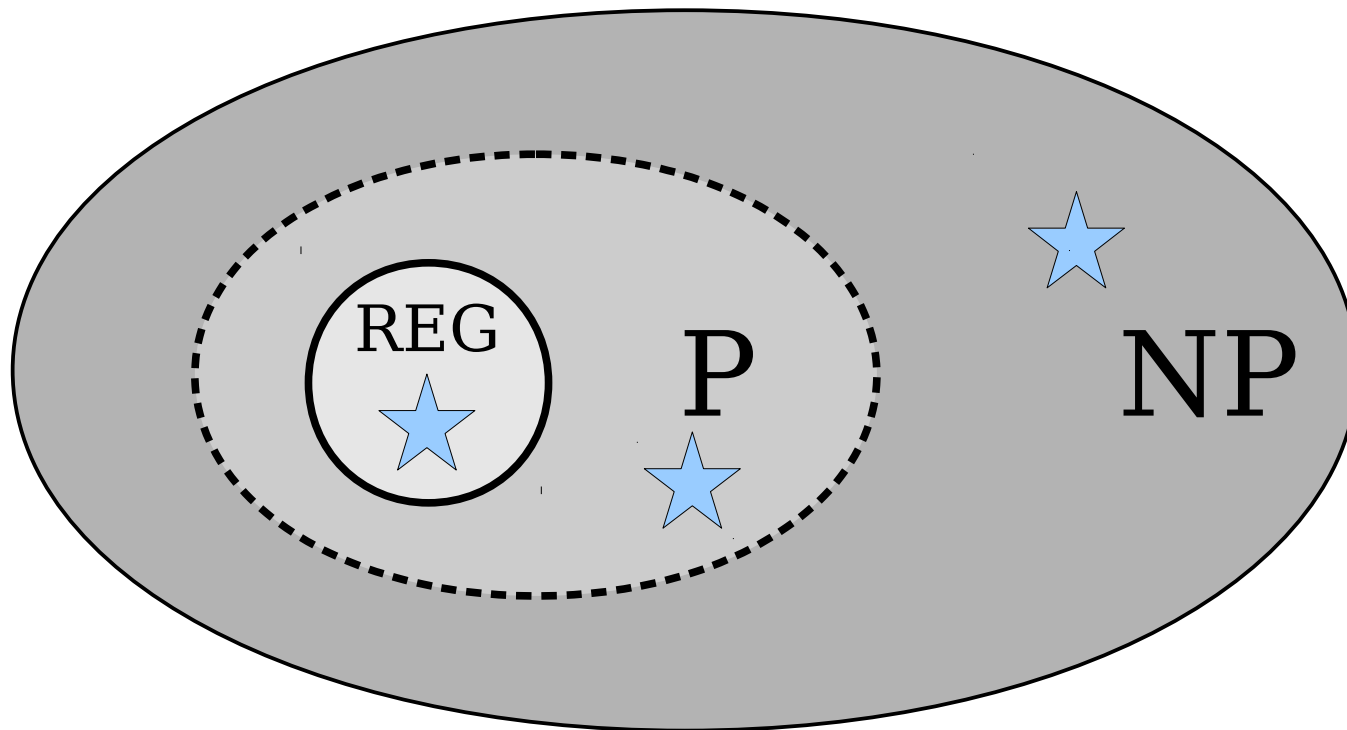
- The **R** and **RE** languages correspond to problems that can be decided and verified, *period*, without any time bounds.
- To reason about what's in **R** and what's in **RE**, we used two key techniques:
 - **Universality**: TMs can run other TMs as subroutines.
 - **Self-Reference**: TMs can get their own source code.
- Why can't we just do that for **P** and **NP**?

Theorem (Baker-Gill-Solovay): Any proof that purely relies on universality and self-reference cannot resolve $\mathbf{P} \stackrel{?}{=} \mathbf{NP}$.

Proof: Take CS154!

So how *are* we going to
reason about **P** and **NP**?

A Challenge



Problems in **NP** vary widely in their difficulty, even if **P = NP**.

How can we rank the relative difficulties of problems?

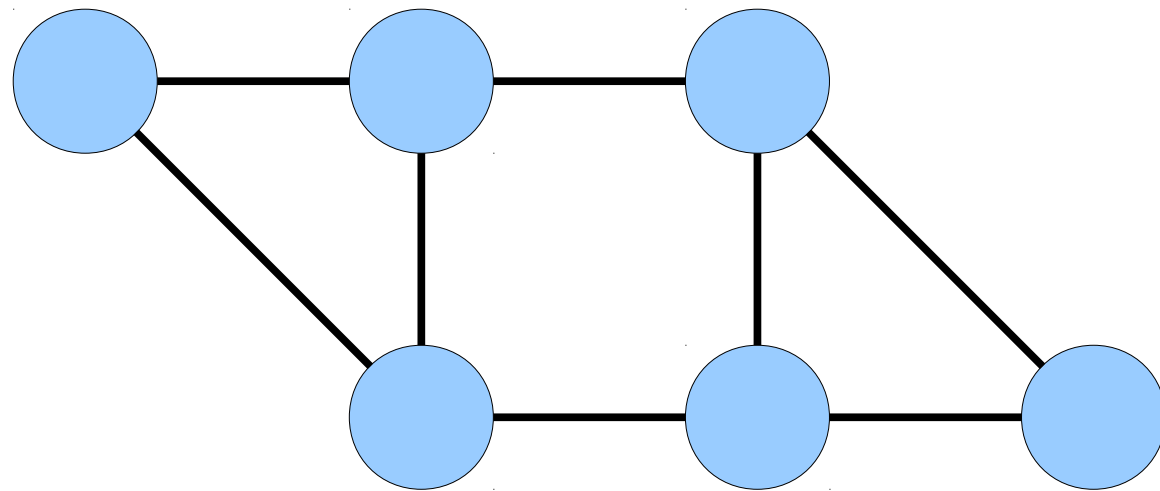
Reducibility

Maximum Matching

- Given an undirected graph G , a ***matching*** in G is a set of edges such that no two edges share an endpoint.
- A ***maximum matching*** is a matching with the largest number of edges.

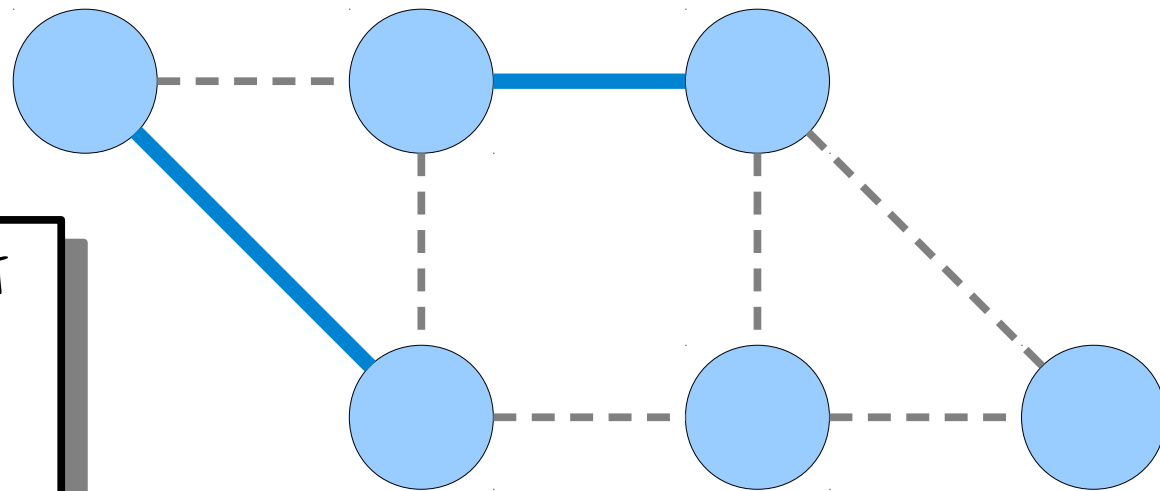
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Maximum Matching

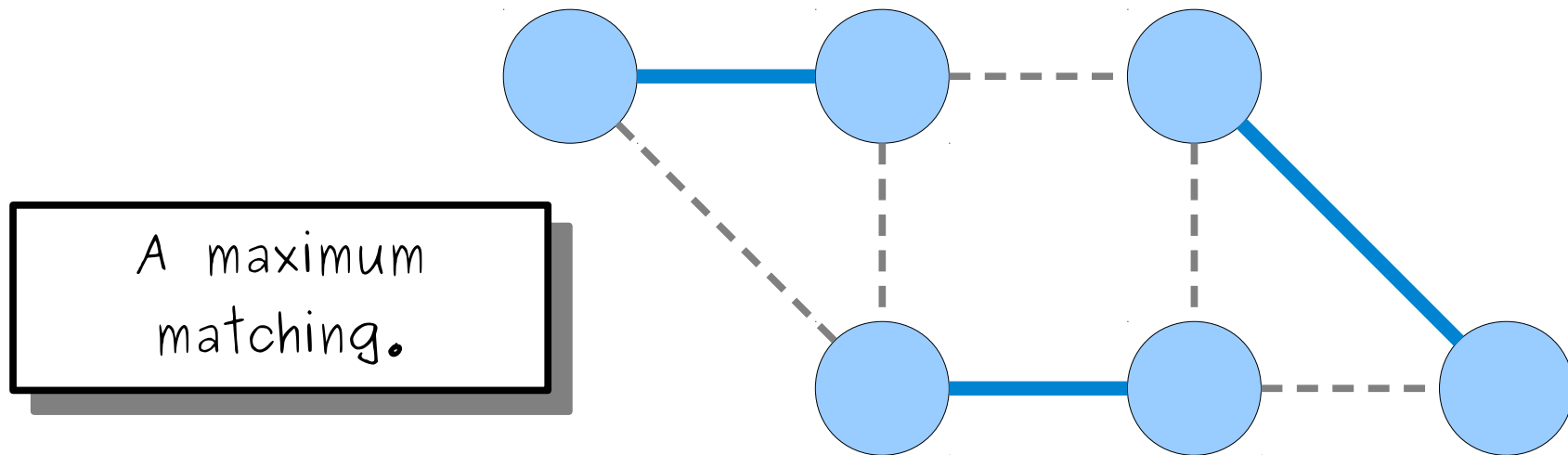
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A matching, but
not a maximum
matching.

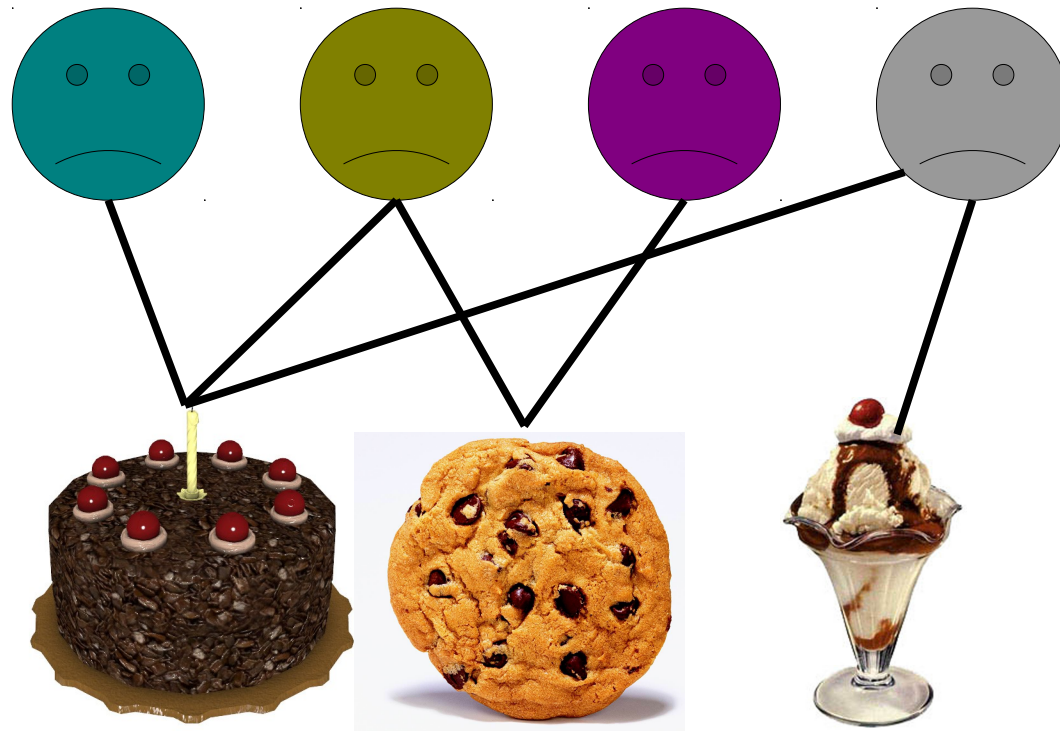
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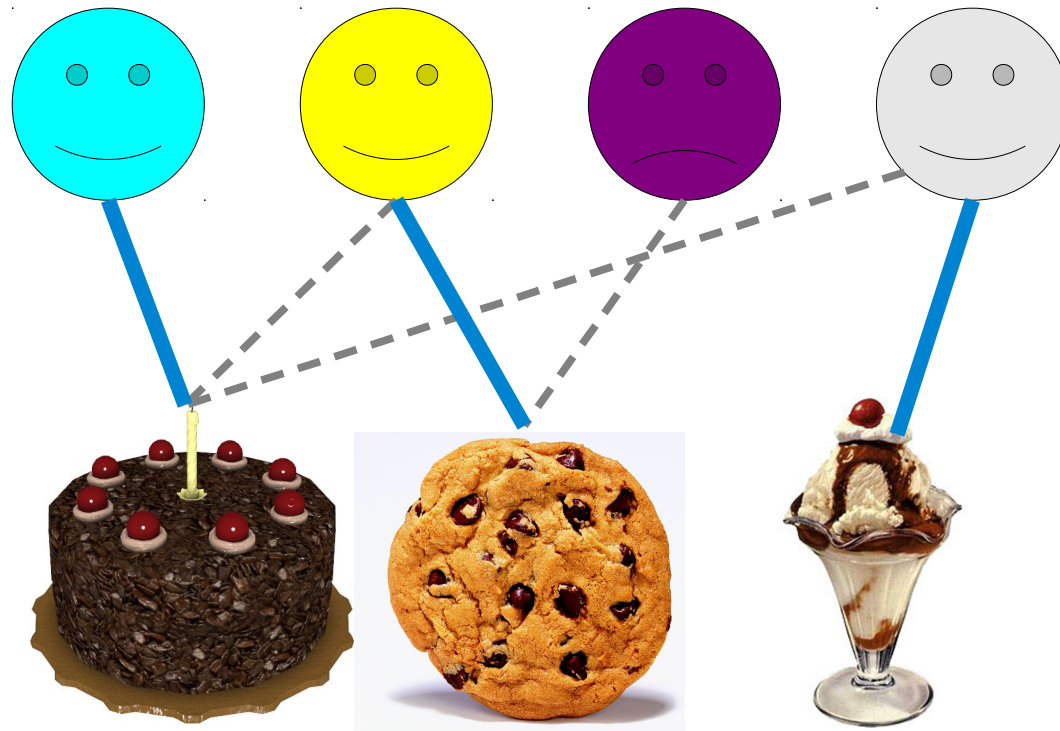
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Maximum Matching

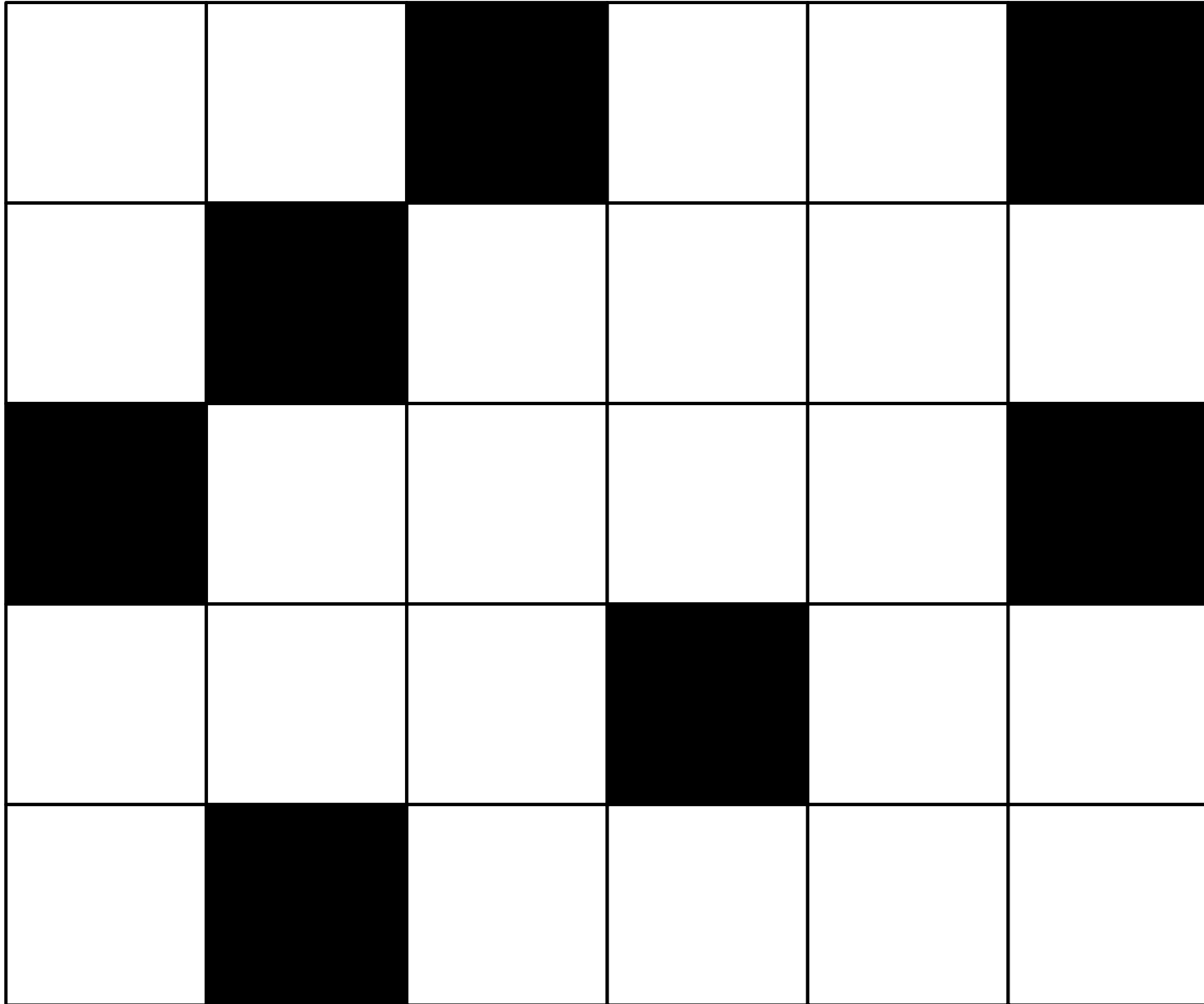
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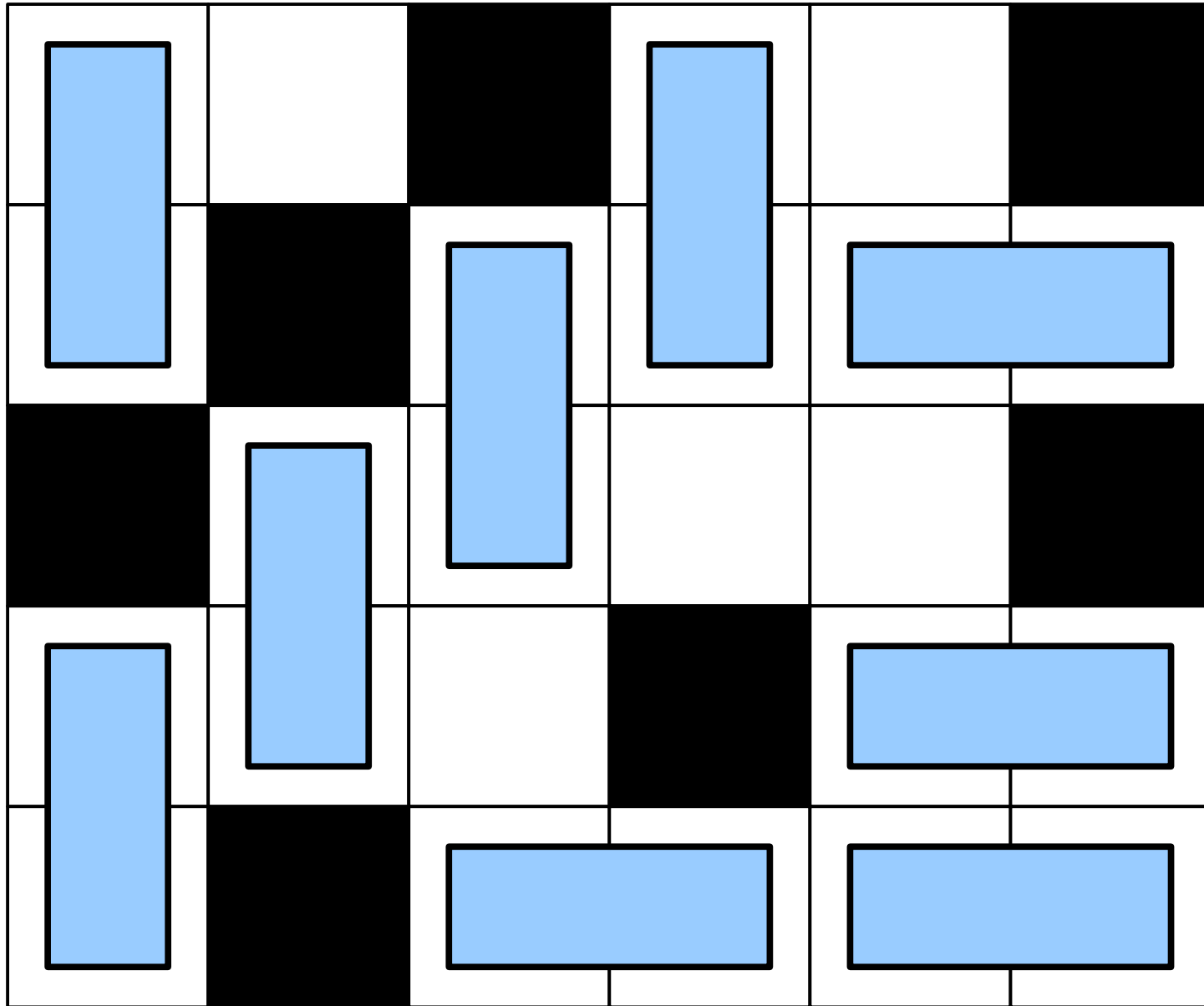
Maximum Matching

- Jack Edmonds' paper “Paths, Trees, and Flowers” gives a polynomial-time algorithm for finding maximum matchings.
 - (This is the same Edmonds as in “Cobham-Edmonds Thesis.”)
- Using this fact, what other problems can we solve?

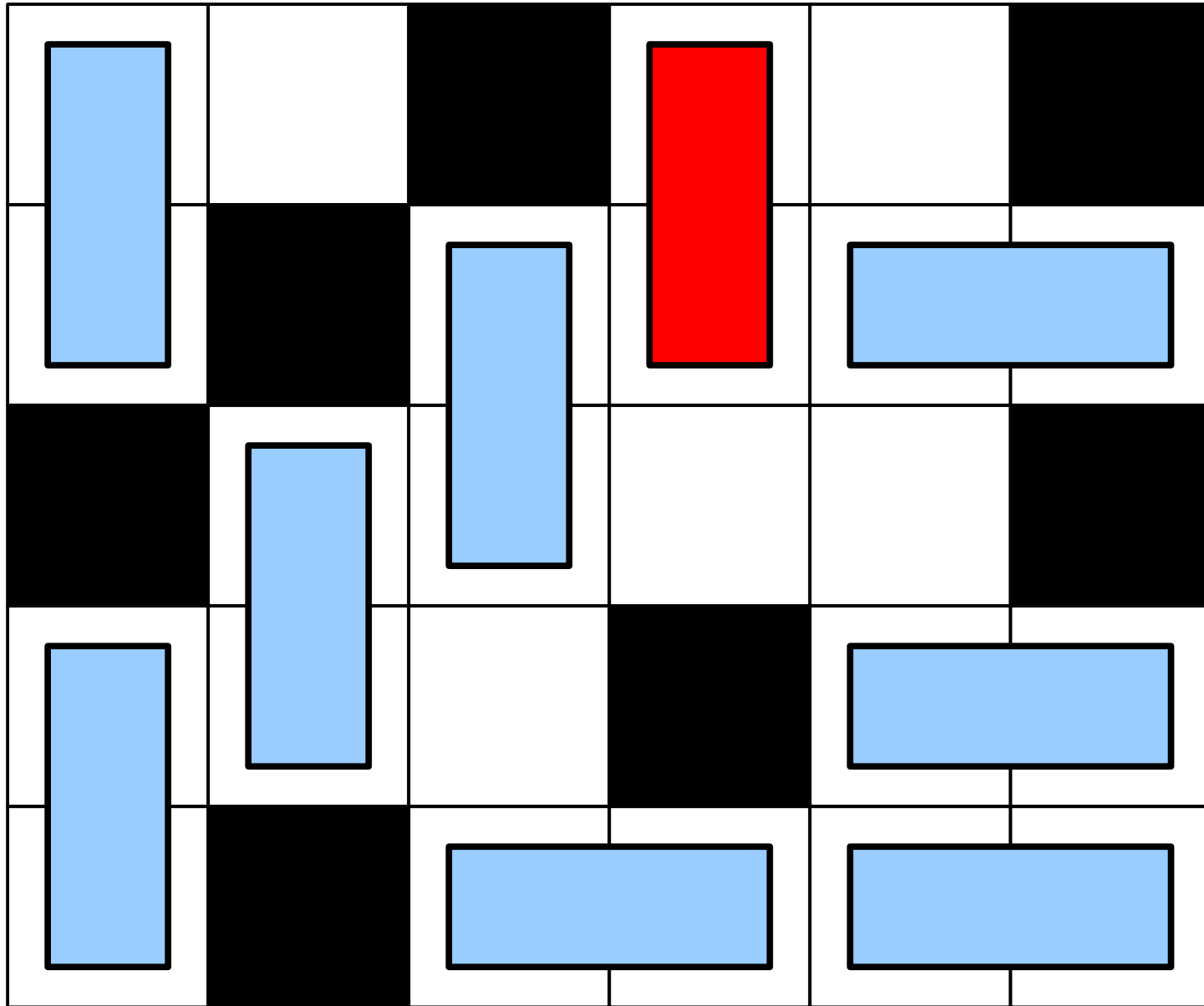
Domino Tiling



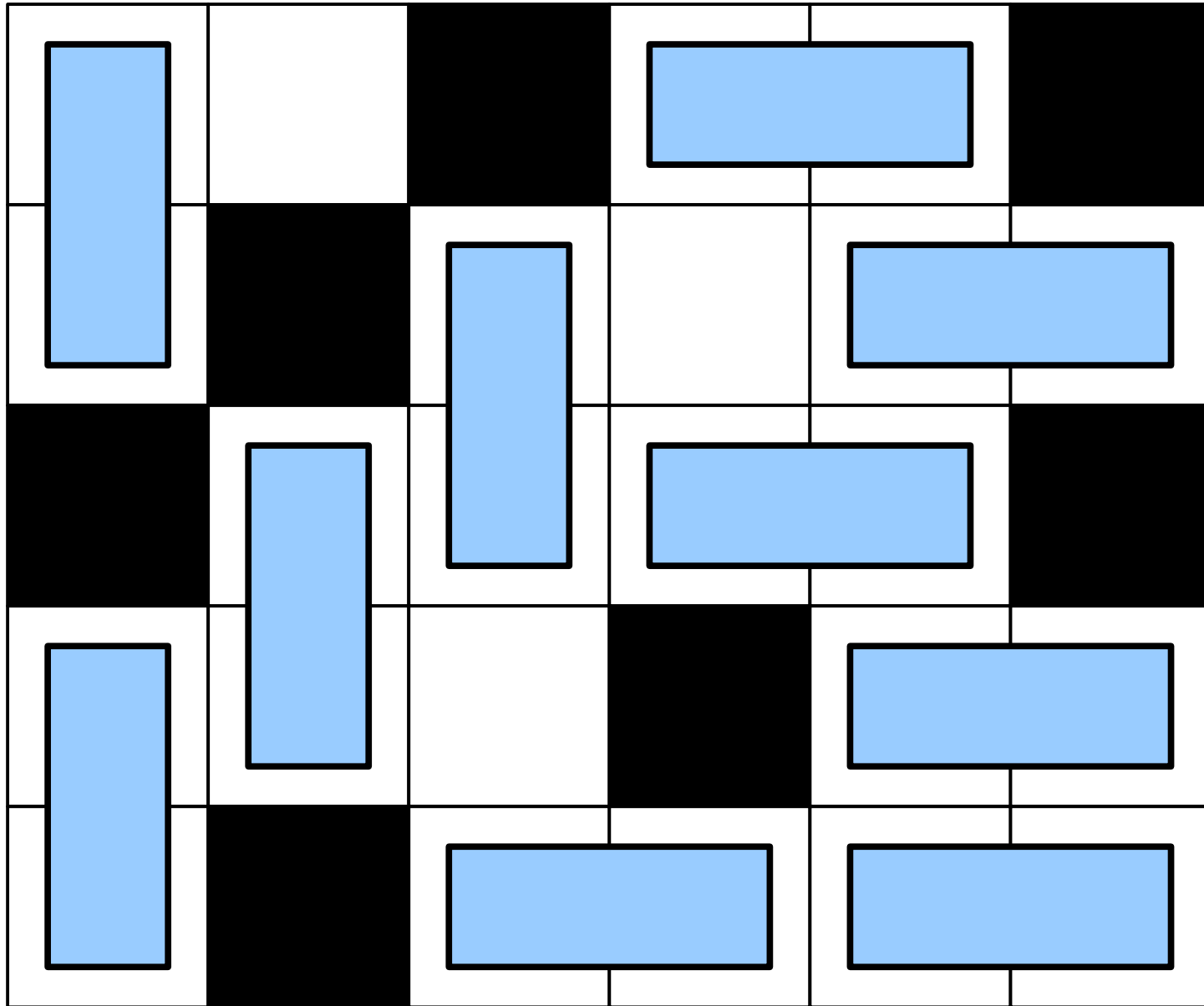
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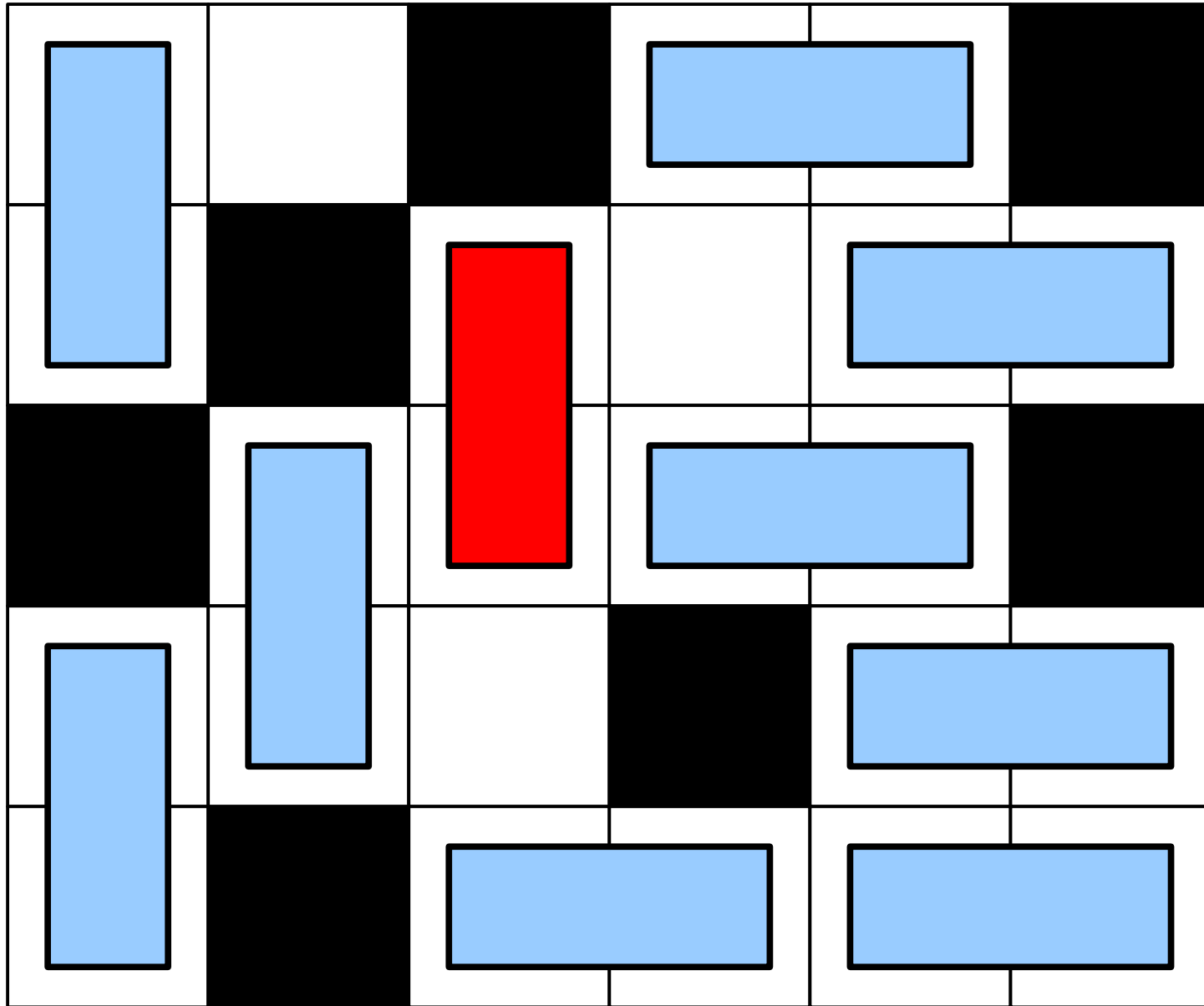
Domino Tiling



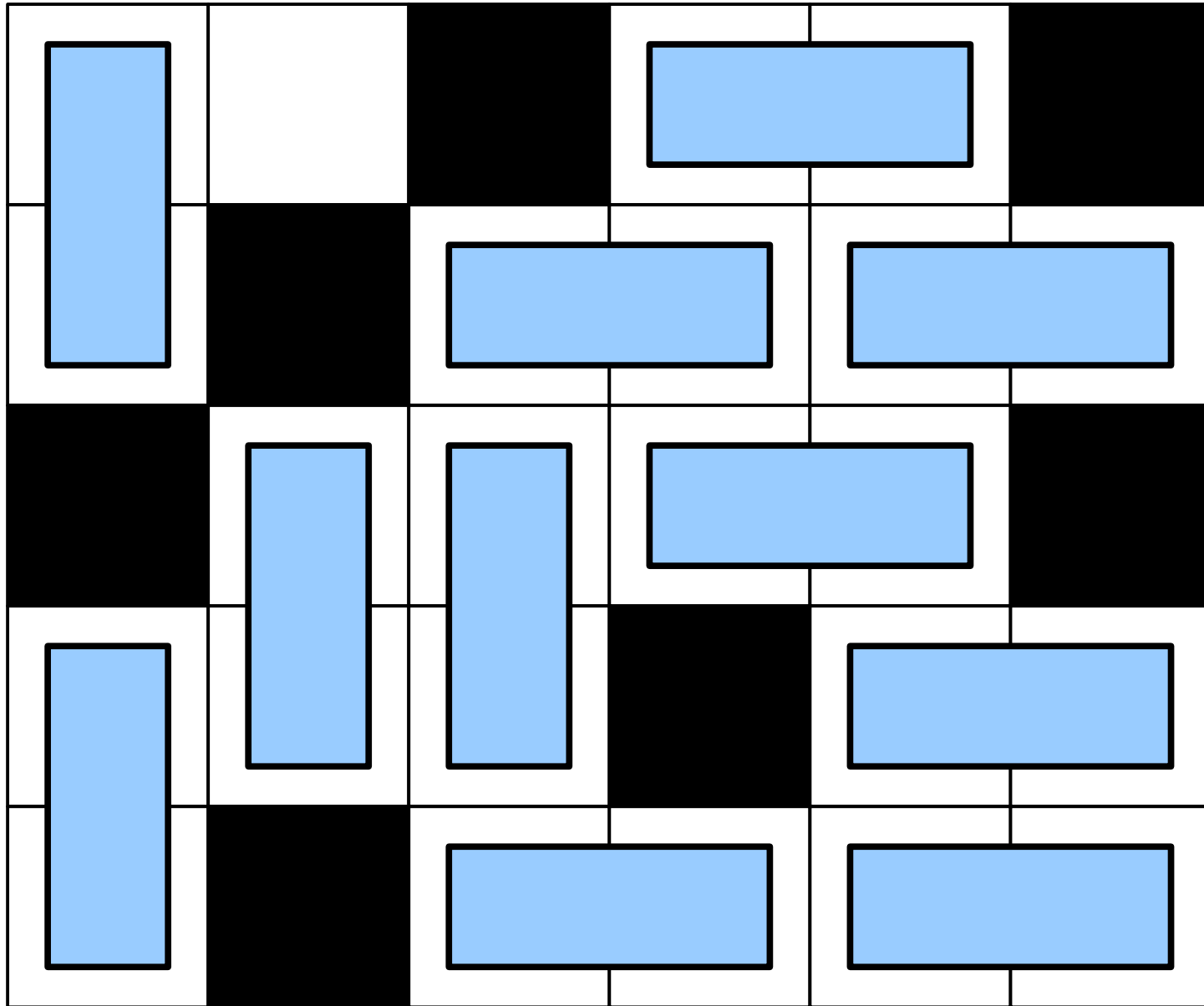
Domino Tiling



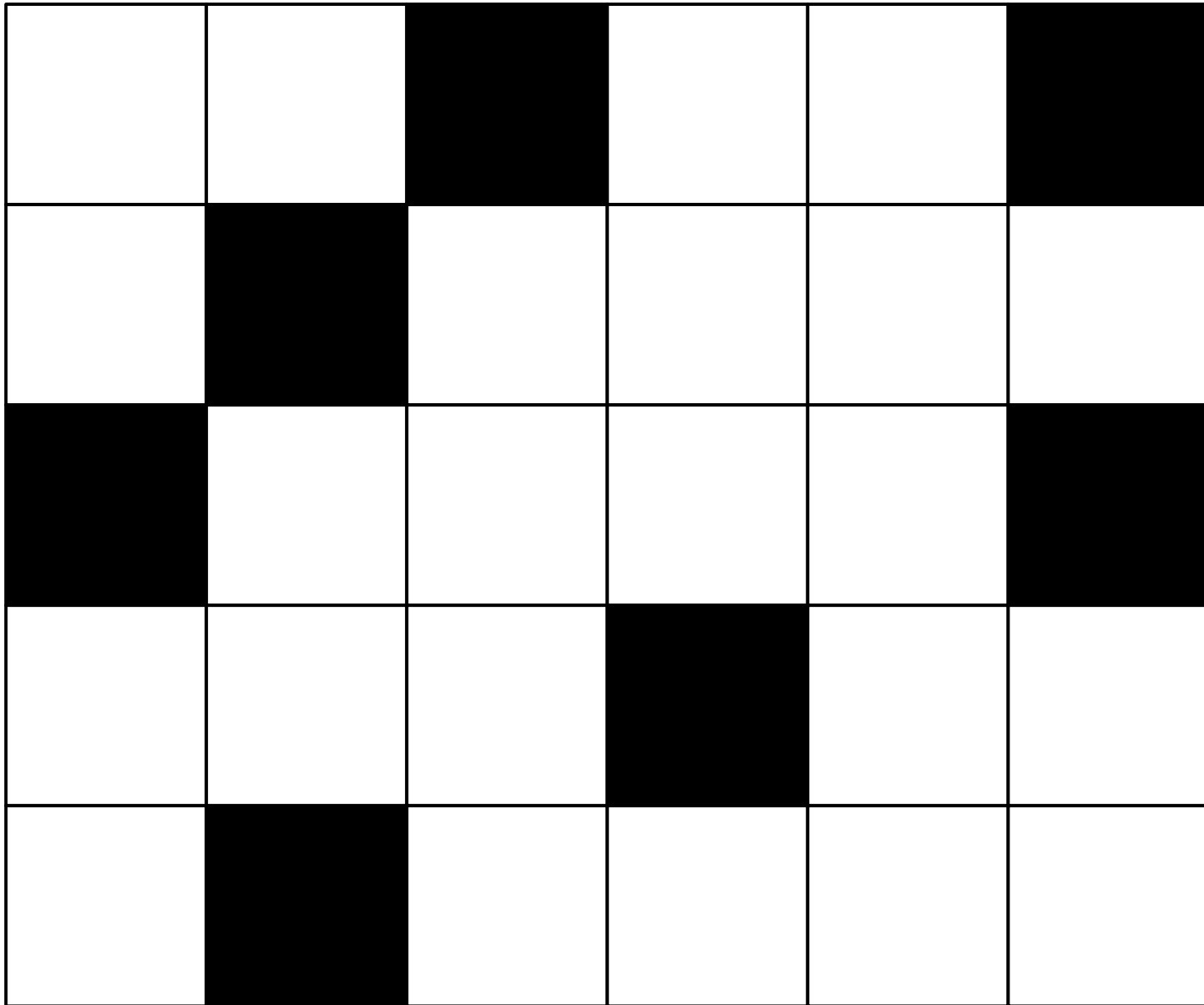
Domino Tiling



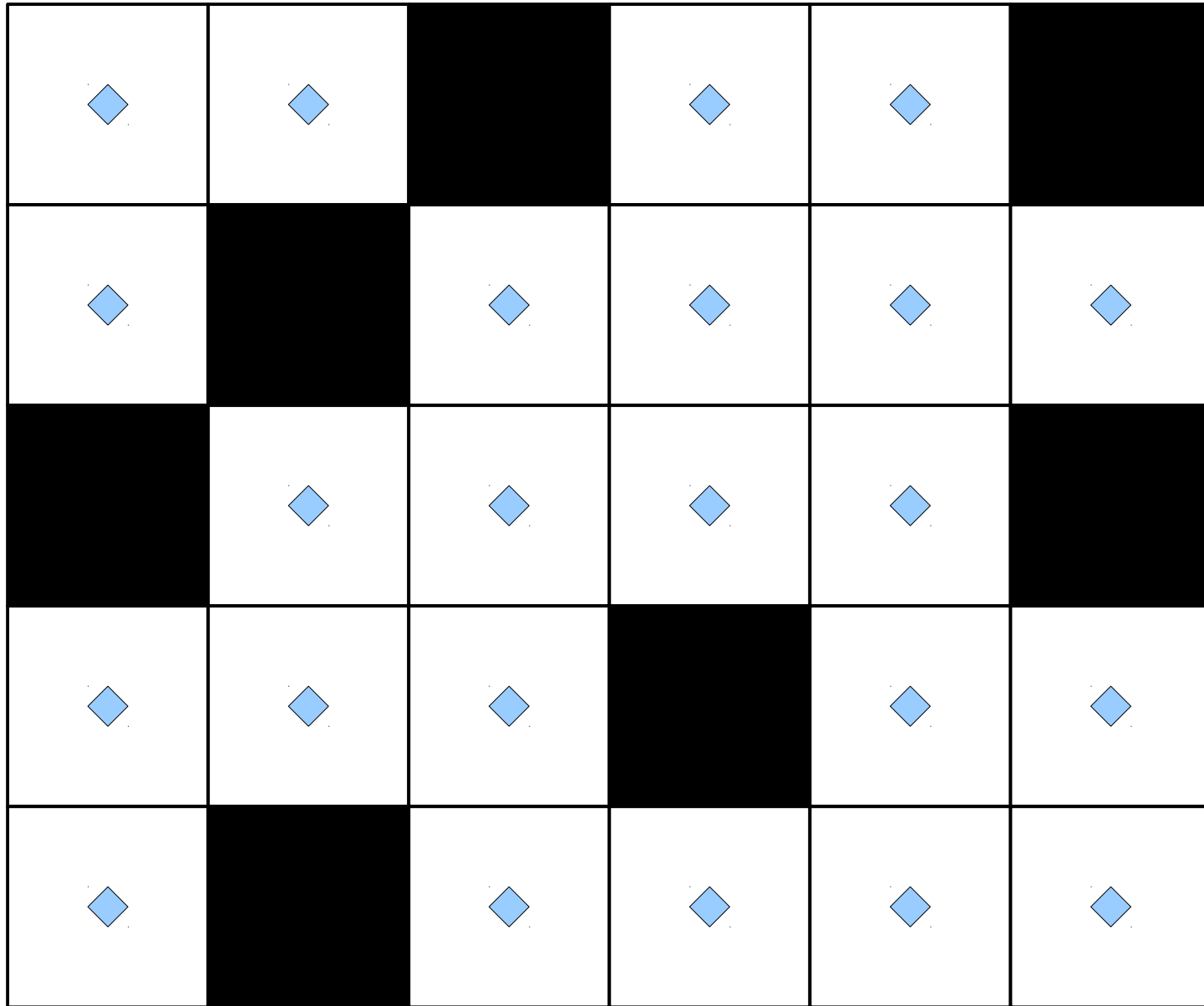
Domino Tiling



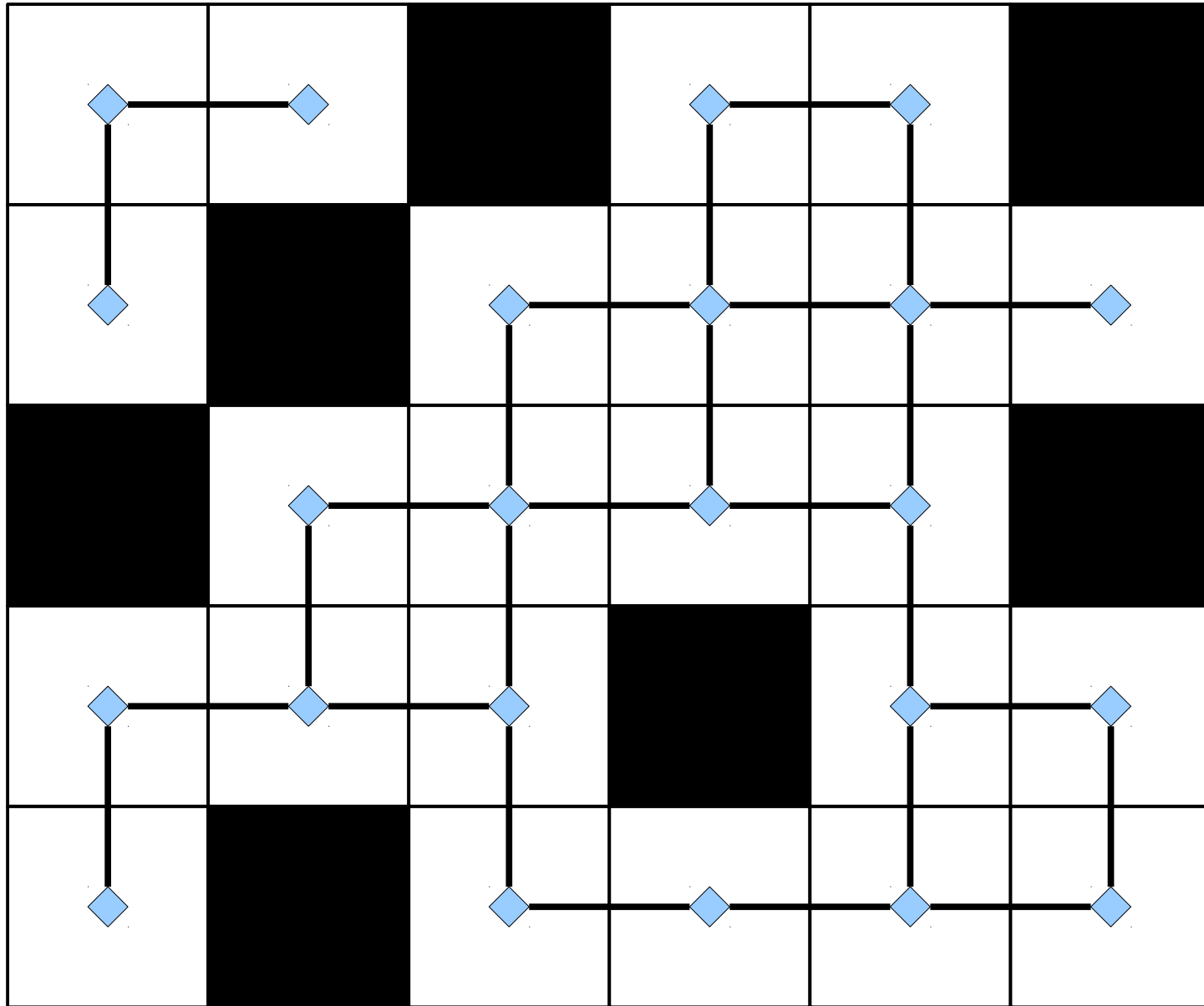
Solving Domino Tiling



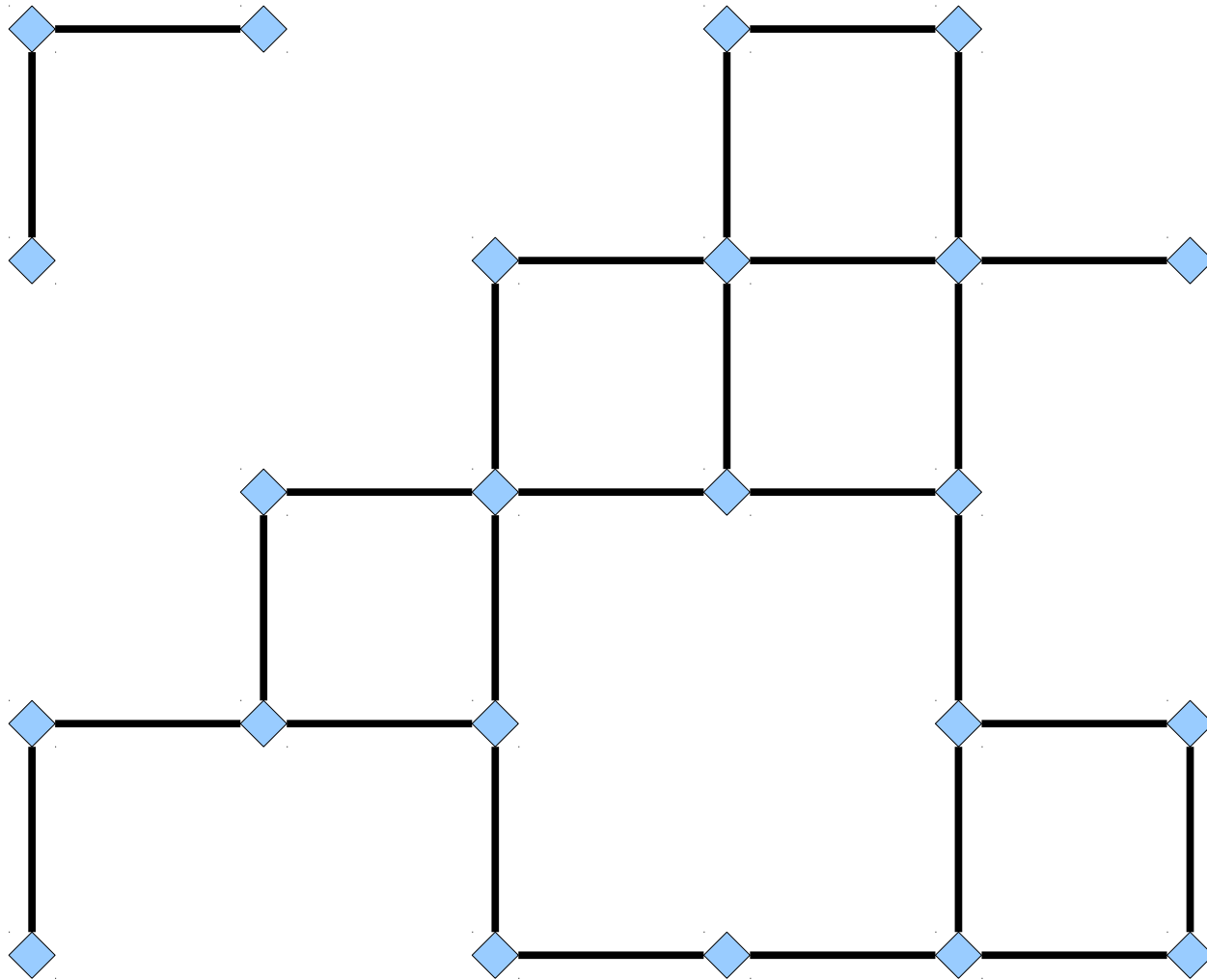
Solving Domino Tiling



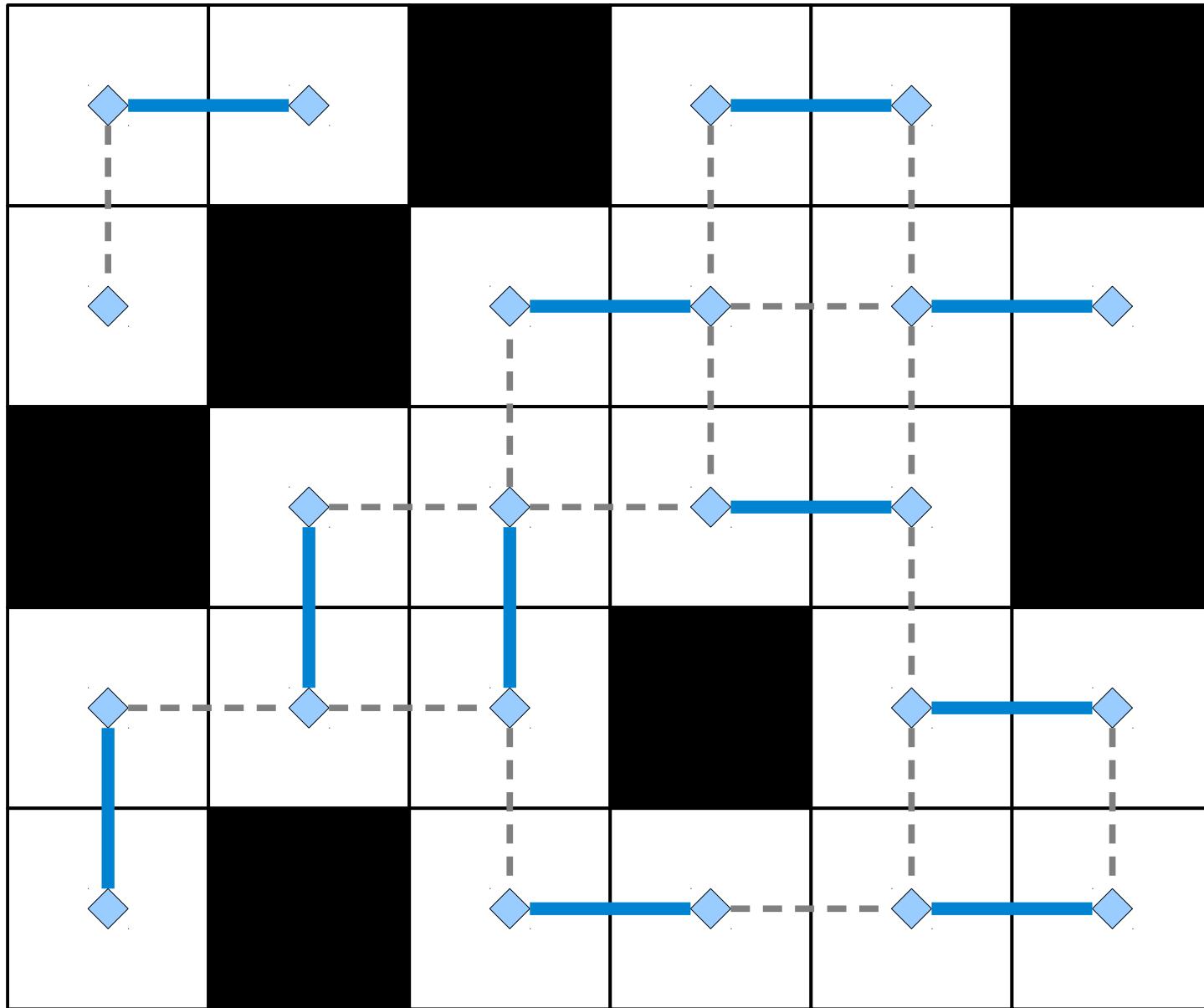
Solving Domino Tiling



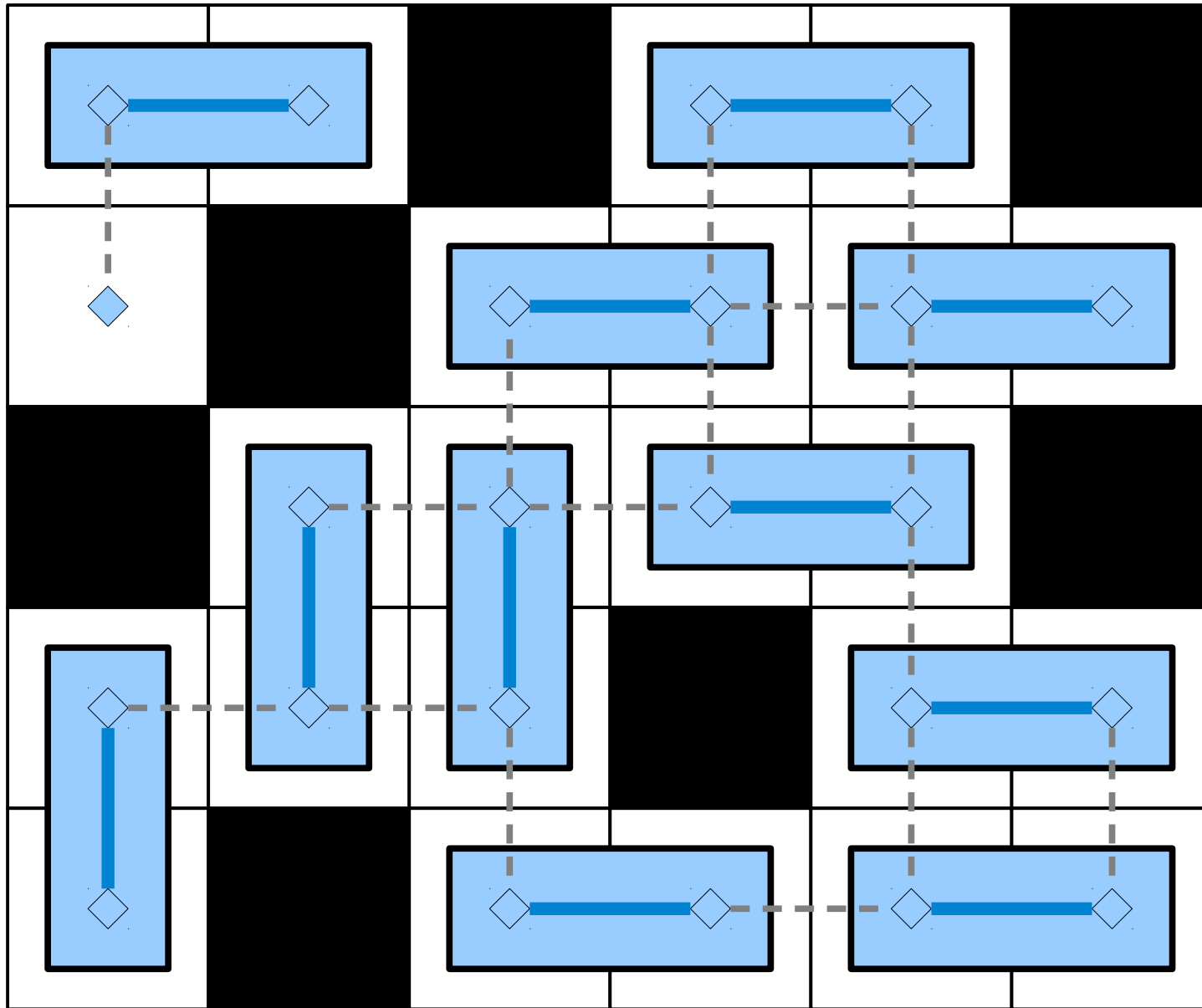
Solving Domino Tiling



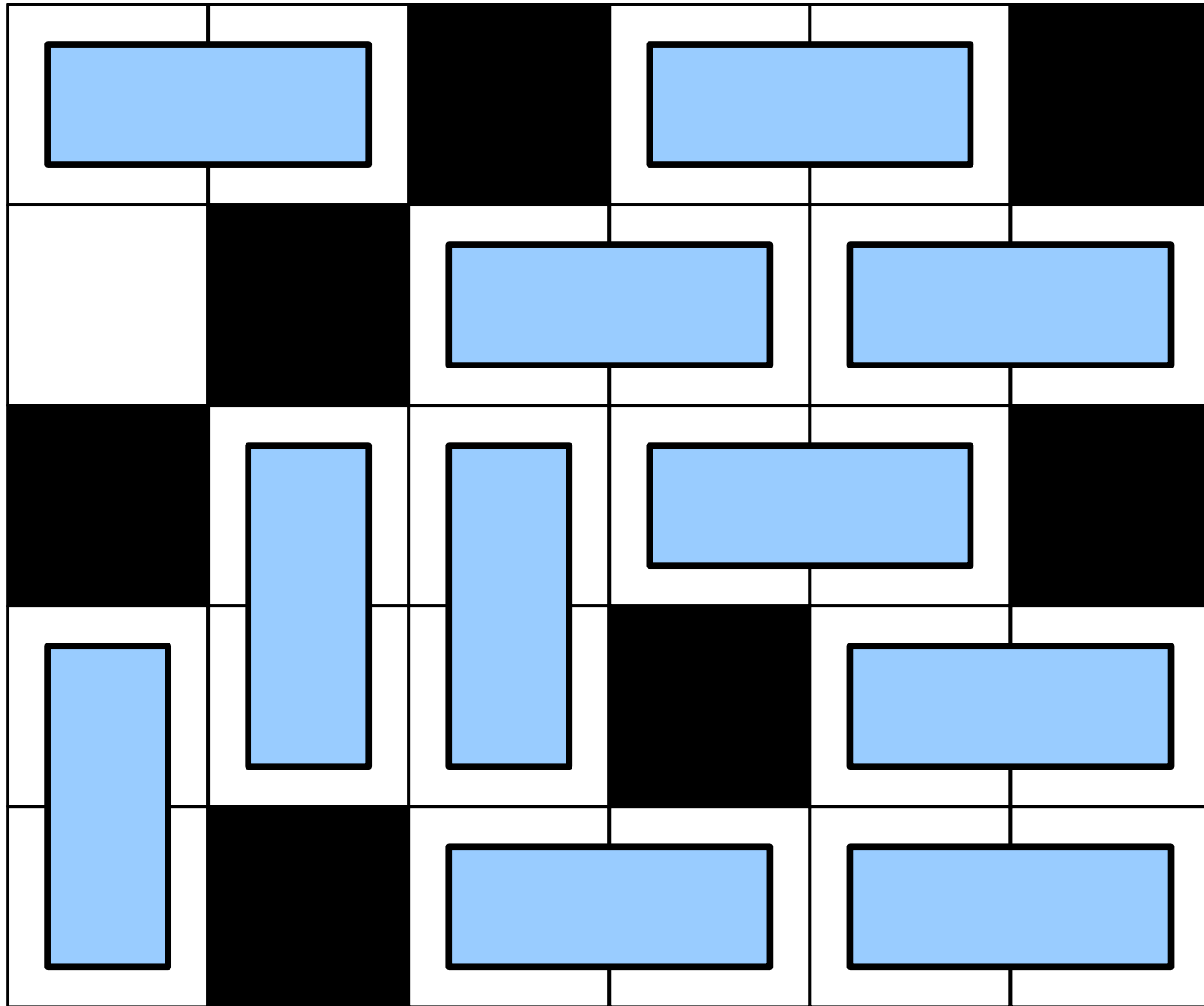
Solving Domino Tiling



Solving Domino Tiling



Solving Domino Tiling



In Pseudocode

```
boolean canPlaceDominos(Grid  $G$ , int  $k$ ) {  
    return hasMatching(gridToGraph( $G$ ),  $k$ );  
}
```

Intuition:

Tiling a grid with dominoes can't be “harder” than solving maximum matching, because if we can solve maximum matching efficiently, we can solve domino tiling efficiently.