Note. Here are some things to keep in mind as you plan your time for this assignment.

- There are math questions again!
- The total amount of pytorch code to write, and code complexity, of this assignment is lower than Assignment 4. However, you’re also given less guidance or scaffolding in how to write the code.
- This assignment involves a pretraining step that takes approximately 2 hours to perform on Azure, and you’ll have to do it twice.

This assignment is an investigation into Transformer self-attention building blocks, and the effects of pretraining. It covers mathematical properties of Transformers and self-attention through written questions. Further, you’ll get experience with practical system-building through repurposing an existing codebase. The assignment is split into a written (mathematical) part and a coding part, with its own written questions. Here’s a quick summary:

1. **Mathematical exploration**: What kinds of operations can self-attention easily implement? Why should we use fancier things like multi-headed self-attention? This section will use some mathematical investigations to illuminate a few of the motivations of self-attention and Transformer networks.

2. **Extending a research codebase**: In this portion of the assignment, you’ll get some experience and intuition for a cutting-edge research topic in NLP: teaching NLP models facts about the world through pretraining, and accessing that knowledge through finetuning. You’ll train a Transformer model to attempt to answer simple questions of the form “Where was person [x] born?” – without providing any input text from which to draw the answer. You’ll find that models are able to learn some facts about where people were born through pretraining, and access that information during fine-tuning to answer the questions.

Then, you’ll take a harder look at the system you built, and reason about the implications and concerns about relying on such implicit pretrained knowledge.
1. **Attention exploration (21 points)**

Multi-headed self-attention is the core modeling component of Transformers. In this question, we’ll get some practice working with the self-attention equations, and motivate why multi-headed self-attention can be preferable to single-headed self-attention.

(a) **Copying in attention:** Recall that attention can be viewed as an operation on a query \( q \in \mathbb{R}^d \), a set of value vectors \( \{v_1, \ldots, v_n\}, v_i \in \mathbb{R}^d \), and a set of key vectors \( \{k_1, \ldots, k_n\}, k_i \in \mathbb{R}^d \), specified as follows:

\[
c = \sum_{i=1}^{n} v_i \alpha_i
\]

\[
\alpha_i = \frac{\exp(k_i^\top q)}{\sum_{j=1}^{n} \exp(k_j^\top q)}.
\]

where \( \alpha_i \) are frequently called the “attention weights”, and the output \( c \in \mathbb{R}^d \) is a correspondingly weighted average over the value vectors.

We’ll first show that it’s particularly simple for attention to “copy” a value vector to the output \( c \). Describe (in one sentence) what properties of the inputs to the attention operation would result in the output \( c \) being approximately equal to \( v_j \) for some \( j \in \{1, \ldots, n\} \). Specifically, what must be true about the query \( q \), the values \( \{v_1, \ldots, v_n\} \) and/or the keys \( \{k_1, \ldots, k_n\} \)?

(b) **An average of two:** Consider a set of key vectors \( \{k_1, \ldots, k_n\} \) where all key vectors are perpendicular, that is \( k_i \perp k_j \) for all \( i \neq j \). Let \( \|k_i\| = 1 \) for all \( i \). Let \( \{v_1, \ldots, v_n\} \) be a set of arbitrary value vectors. Let \( v_a, v_b \in \{v_1, \ldots, v_n\} \) be two of the value vectors. Give an expression for a query vector \( q \) such that the output \( c \) is approximately equal to the average of \( v_a \) and \( v_b \), that is, \( \frac{1}{2}(v_a + v_b) \).\(^1\) Note that you can reference the corresponding key vector of \( v_a \) and \( v_b \) as \( k_a \) and \( k_b \).

(c) **Drawbacks of single-headed attention:** In the previous part, we saw how it was possible for a single-headed attention to focus equally on two values. The same concept could easily be extended to any subset of values. In this question we’ll see why it’s not a practical solution. Consider a set of key vectors \( \{k_1, \ldots, k_n\} \) that are now randomly sampled, \( k_i \sim \mathcal{N}(\mu_i, \Sigma_i) \), where the means \( \mu_i \) are known to you, but the covariances \( \Sigma_i \) are unknown. Further, assume that the means \( \mu_i \) are all perpendicular; \( \mu_i^\top \mu_j = 0 \) if \( i \neq j \), and unit norm, \( \|\mu_i\| = 1 \).

i. (2 points) Assume that the covariance matrices are \( \Sigma_i = \alpha I \), for vanishingly small \( \alpha \). Design a query \( q \) in terms of the \( \mu_i \) such that as before, \( c \approx \frac{1}{2}(v_a + v_b) \), and provide a brief argument as to why it works.

ii. (3 points) Though single-headed attention is resistant to small perturbations in the keys, some types of larger perturbations may pose a bigger issue. Specifically, in some cases, one key vector \( k_a \) may be larger or smaller in norm than the others, while still pointing in the same direction as \( \pi_a \). As an example, let us consider a covariance for item \( a \) as \( \Sigma_a = \alpha I + \frac{1}{2}(\mu_a \mu_a^\top) \) for vanishingly small \( \alpha \) (as shown in figure 1). Further, let \( \Sigma_i = \alpha I \) for all \( i \neq a \).

When you sample \( \{k_1, \ldots, k_n\} \) multiple times, and use the \( q \) vector that you defined in part i., what qualitatively do you expect the vector \( c \) will look like for different samples?

(d) **Benefits of multi-headed attention:** Now we’ll see some of the power of multi-headed attention. We’ll consider a simple version of multi-headed attention which is identical to single-headed self-attention as we’ve presented it in this homework, except two query vectors \( (q_1, q_2) \) are defined, which leads to a pair of vectors \( (c_1, c_2) \), each the output of single-headed attention given its respective query vector. The final output of the multi-headed attention is their average, \( \frac{1}{2}(c_1 + c_2) \). As in question 1(c), consider a set of key vectors \( \{k_1, \ldots, k_n\} \) that are randomly sampled,

\(^1\)Hint: while the softmax function will never exactly average the two vectors, you can get close by using a large scalar multiple in the expression.
Figure 1: The vector $\mu_a$ (shown here in 2D as an example), with the range of possible values of $k_a$ shown in red. As mentioned previously, $k_a$ points in roughly the same direction as $\mu_a$, but may have larger or smaller magnitude.

$k_i \sim \mathcal{N}(\mu_i, \Sigma_i)$, where the means $\mu_i$ are known to you, but the covariances $\Sigma_i$ are unknown. Also as before, assume that the means $\mu_i$ are mutually orthogonal; $\mu_i^\top \mu_j = 0$ if $i \neq j$, and unit norm, $\|\mu_i\| = 1$.

i. (1 point) Assume that the covariance matrices are $\Sigma_i = \alpha I$, for vanishingly small $\alpha$. Design $q_1$ and $q_2$ such that $c$ is approximately equal to $\frac{1}{2} (v_a + v_b)$.

ii. (2 points) Assume that the covariance matrices are $\Sigma_a = \alpha I + \frac{1}{2} (\mu_a \mu_a^\top)$ for vanishingly small $\alpha$, and $\Sigma_i = \alpha I$ for all $i \neq a$. Take the query vectors $q_1$ and $q_2$ that you designed in part i.

What, qualitatively, do you expect the output $c$ to look like across different samples of the key vectors? Please briefly explain why. You can ignore cases in which $q_i^\top k_a < 0$.

(e) (7 points) **Key-Query-Value self-attention in neural networks:** So far, we’ve discussed attention as a function on a set of key vectors, a set of value vectors, and a query vector. In Transformers, we perform self-attention, which roughly means that we draw the keys, values, and queries from the same data. More precisely, let $\{x_1, \ldots, x_n\}$ be a sequence of vectors in $\mathbb{R}^d$. Think of each $x_i$ as representing word $i$ in a sentence. One form of self-attention defines keys, queries, and values as follows. Let $V, K, Q \in \mathbb{R}^{d \times d}$ be parameter matrices. Then

\[
  v_i = V x_i \quad i \in \{1, \ldots, n\} \tag{3}
\]

\[
  k_i = K x_i \quad i \in \{1, \ldots, n\} \tag{4}
\]

\[
  q_i = Q x_i \quad i \in \{1, \ldots, n\} \tag{5}
\]

Then we get a context vector for each input $i$; we have $c_i = \sum_{j=1}^{n} \alpha_{ij} v_j$, where $\alpha_{ij}$ is defined as $\alpha_{ij} = \frac{\exp(k_i^\top q_j)}{\sum_{l=1}^{n} \exp(k_i^\top q_l)}$. Note that this is single-headed self-attention.

In this question, we’ll show how key-value-query attention like this allows the network to use different aspects of the input vectors $x_i$ in how it defines keys, queries, and values. Intuitively, this allows networks to choose different aspects of $x_i$ to be the “content” (value vector) versus what it uses to determine “where to look” for content (keys and queries.)

i. (3 points) First, consider if we didn’t have key-query-value attention. For keys, queries, and values we’ll just use $x_i$; that is, $v_i = q_i = k_i = x_i$. We’ll consider a specific set of $x_i$. In particular, let $u_a, u_b, u_c, u_d$ be mutually orthogonal vectors in $\mathbb{R}^d$, each with equal norm $\|u_a\| = \|u_b\| = \|u_c\| = \|u_d\| = \beta$, where $\beta$ is very large. Now, let our $x_i$ be:

\[
  x_1 = u_d + u_b \tag{6}
\]

\[
  x_2 = u_a \tag{7}
\]

\[
  x_3 = u_c + u_b \tag{8}
\]
If we perform self-attention with these vectors, what vector does $c_2$ approximate? Would it be possible for $c_2$ to approximate $u_b$ by adding either $u_d$ or $u_c$ to $x_2$? Explain why or why not (either math or English is fine).

ii. (4 points) Now consider using key-query-value attention as we’ve defined it originally. Using the same definitions of $x_1$, $x_2$ and $x_3$ as in part i, specify matrices $K, Q, V$ such that $c_2 \approx u_b$, and $c_1 \approx u_b - u_c$. There are many solutions to this problem, so it will be easier for you (and the graders), if you first find $V$ such that $v_1 = u_b$ and $v_3 = u_b - u_c$, then work on $Q$ and $K$. Some outer product properties may be helpful (as summarized in this footnote)².

2. Pretrained Transformer models and knowledge access (35 points)

You’ll train a Transformer to perform a task that involves accessing knowledge about the world – knowledge which isn’t provided via the task’s training data (at least if you want to generalize outside the training set). You’ll find that it more or less fails entirely at the task. You’ll then learn how to pretrain that Transformer on Wikipedia text that contains world knowledge, and find that finetuning that Transformer on the same knowledge-intensive task enables the model to access some of the knowledge learned at pretraining time. You’ll find that this enables models to perform considerably above chance on a held out development set.

The code you’re provided with is a fork of Andrej Karpathy’s minGPT. It’s nicer than most research code in that it’s relatively simple and transparent. The “GPT” in minGPT refers to the Transformer language model of OpenAI, originally described in this paper [1].

As in previous assignments, you will want to develop on your machine locally, then run training on Azure. You can use the same conda environment from previous assignments for local development, and the same process for training on Azure (see the CS224n Azure Guide for a refresher). Specifically, you’ll still be running “conda activate py37-pytorch” on the Azure machine. You’ll need around 5 hours for training, so budget your time accordingly!

Your work with this codebase is as follows:

(a) (0 points) Check out the demo.

In the mingpt-demo/ folder is a Jupyter notebook that trains and samples from a Transformer language model. Take a look at it (locally on your computer) to get somewhat familiar with how it defines and trains models. Some of the code you’re writing below will be inspired by what you see in this notebook.

Note that you do not have to write any code or submit written answers for this part.

(b) (0 points) Read through NameDataset, our dataset for reading name-birth place pairs.

The task we’ll be working on with our pretrained models is attempting to access the birth place of a notable person, as written in their Wikipedia page. We’ll think of this as a particularly simple form of question answering:

Q: Where was [person] born?
A: [place]

From now on, you’ll be working with the src/ folder. The code in mingpt-demo/ won’t be changed or evaluated for this assignment. In dataset.py, you’ll find the the class NameDataset, which reads a TSV (tab-separated values) file of name/place pairs and produces examples of the above form that we can feed to our Transformer model.

To get a sense of the examples we’ll be working with, if you run the following code, it’ll load your NameDataset on the training set birth_places_train.tsv and print out a few examples.

²For orthogonal vectors $u, v, w \in \mathbb{R}^d$, the outer product $uv^\top$ is a matrix in $\mathbb{R}^{d \times d}$, and $(uv^\top)v = u(v^\top v) = u\|v\|_2^2$, and $(uv^\top)w = u(v^\top w) = u \ast 0$. (The last equality is because $v$ and $w$ are orthogonal.)
(c) (0 points) Implement finetuning (without pretraining).

Take a look at run.py. It has some skeleton code specifying flags you’ll eventually need to handle as command line arguments. In particular, you might want to pretrain, finetune, or evaluate a model with this code. For now, we’ll focus on the finetuning function, in the case without pretraining.

Taking inspiration from the training code in the play_char.ipynb file, write code to finetune a Transformer model on the name/birth place dataset, via examples from the NameDataset class. For now, implement the case without pretraining (i.e. create a model from scratch and train it on the birth-place prediction task from part (b)). You’ll have to modify two sections, marked [part c] in the code: one to initialize the model, and one to finetune it. Note that you only need to initialize the model in the case labeled “vanilla” for now (later in section (g), we will explore a model variant).

Use the hyperparameters for the Trainer specified in the run.py code.

Also take a look at the evaluation code which has been implemented for you. It samples predictions from the trained model and calls evaluate_places() to get the total percentage of correct place predictions. You will run this code in part (d) to evaluate your trained models.

This is an intermediate step for later portions, including Part d, which contains commands you can run to check your implementation. No written answer is required for this part.

(d) (5 points) Make predictions (without pretraining).

Train your model on wiki_places_train.tsv, and evaluate on birth_dev.tsv. Specifically, you should now be able to run the following three commands:

```
# Train on the names dataset
python src/run.py finetune vanilla wiki.txt \
    --writing_params_path vanilla.model.params \
    --finetune_corpus_path birth_places_train.tsv

# Evaluate on the dev set, writing out predictions
python src/run.py evaluate vanilla wiki.txt \
    --reading_params_path vanilla.model.params \
    --eval_corpus_path birth_dev.tsv \
    --outputs_path vanilla.nopretrain.dev.predictions

# Evaluate on the test set, writing out predictions
python src/run.py evaluate vanilla wiki.txt \
    --reading_params_path vanilla.model.params \
    --eval_corpus_path birth_test_inputs.tsv \
    --outputs_path vanilla.nopretrain.test.predictions
```

Training will take less than 10 minutes (on Azure). Report your model’s accuracy on the dev set (as printed by the second command above). Don’t be surprised if it is well below 10%; we will be digging into why in Part 3. As a reference point, we want to also calculate the accuracy the model would have achieved if it had just predicted “London” as the birth place for everyone in the dev set. Fill in london_baseline.py to calculate the accuracy of that approach and report your result in your write-up. You should be able to leverage existing code such that the file is only a few lines long.

(e) (10 points) Define a span corruption function for pretraining.

In the file src/dataset.py, implement the __getitem__() function for the dataset class CharCor-
ruptionDataset. Follow the instructions provided in the comments in dataset.py. Span corruption is explored in the T5 paper [2]. It randomly selects spans of text in a document and replaces them with unique tokens (noising). Models take this noised text, and are required to output a pattern of each unique sentinel followed by the tokens that were replaced by that sentinel in the input. In this question, you’ll implement a simplification that only masks out a single sequence of characters. This question will be graded via autograder based on your whether span corruption function implements some basic properties of our spec. We’ll instantiate the CharCorruptionDataset with our own data, and draw examples from it.

To help you debug, if you run the following code, it’ll sample a few examples from your CharCorruptionDataset on the pretraining dataset wiki.txt and print them out for you.

```python
python src/dataset.py charcorruption
```

No written answer is required for this part.

(f) (10 points) **Pretrain, finetune, and make predictions. Budget 2 hours for training.**

Now fill in the `pretrain` portion of `run.py`, which will pretrain a model on the span corruption task. Additionally, modify your `finetune` portion to handle finetuning in the case with pretraining. In particular, if a path to a pretrained model is provided in the bash command, load this model before finetuning it on the birth-place prediction task. Pretrain your model on `wiki.txt` (which should take approximately two hours), finetune it on NameDataset and evaluate it. Specifically, you should be able to run the following three four commands: (Don’t be concerned if the loss appears to plateau in the middle of pretraining; it will eventually go back down.)

```bash
# Pretrain the model
python src/run.py pretrain vanilla wiki.txt \
    --writing_params_path vanilla.pretrain.params

# Finetune the model
python src/run.py finetune vanilla wiki.txt \
    --reading_params_path vanilla.pretrain.params \
    --writing_params_path vanilla.finetune.params \
    --finetune_corpus_path birth_places_train.tsv

# Evaluate on the dev set; write to disk
python src/run.py evaluate vanilla wiki.txt \
    --reading_params_path vanilla.finetune.params \
    --eval_corpus_path birth_dev.tsv \
    --outputs_path vanilla.pretrain.dev.predictions

# Evaluate on the test set; write to disk
python src/run.py evaluate vanilla wiki.txt \
    --reading_params_path vanilla.finetune.params \
    --eval_corpus_path birth_test_inputs.tsv \
    --outputs_path vanilla.pretrain.test.predictions
```

Report the accuracy on the dev set (printed by the third command above). We expect the dev accuracy will be at least 10%, and will expect a similar accuracy on the held out test set.
(g) (10 points) **Research! Write and try out the synthesizer variant (Budget 2 hours for pretraining!)**

We’ll now go to changing the Transformer architecture itself – specifically, the self-attention module. While we’ve been using a self-attention scoring function based on dot products, this involves a rather intensive computation that’s quadratic in the sequence length. This is because the dot product between \( \ell^2 \) pairs of word vectors is computed in each computation. **Synthesized attention** [3] is a very recent alternative that has potential benefits by removing this dot product (and quadratic computation) entirely. It’s a promising idea, and one way for us to ask, “What’s important/right about the Transformer architecture, and where can we improve/prune aspects of it?” In attention.py, implement the forward() method of SynthesizerAttention, which implements a variant of the Synthesizer proposed in the cited paper.

The provided CausalSelfAttention implements the following attention for each head of the multiheaded attention: Let \( X \in \mathbb{R}^{\ell \times d} \) (where \( \ell \) is the block size and \( d \) is the total dimensionality, \( d/h \) is the dimensionality per head.). \(^3\) Let \( Q, K, V \in \mathbb{R}^{d \times d/h} \). Then the output of the self-attention head is

\[
Y_i = \text{softmax} \left( \frac{(XQ_i)(XK_i)^T}{\sqrt{d/h}} \right) (XV_i)
\]

where \( Y_i \in \mathbb{R}^{\ell \times d/h} \). Then the output of the self-attention is a linear transformation of the concatenation of the heads:

\[
Y = [Y_1; \ldots; Y_h] A
\]

where \( A \in \mathbb{R}^{d \times d} \) and \( [Y_1; \ldots; Y_h] \in \mathbb{R}^{\ell \times d} \). The code also includes dropout layers which we haven’t written here. We suggest looking at the provided code and noting how this equation is implemented in PyTorch.

Your job is to implement the following variant of attention. Instead of Equation 9, implement the following in SynthesizerAttention:

\[
Y_i = \text{softmax} \left( \text{ReLU}(XA_i + b_1)B_i + b_2 \right) (XV_i),
\]

where \( A_i \in \mathbb{R}^{d \times d/h} \), \( B_i \in \mathbb{R}^{d/h \times \ell} \), and \( V_i \in \mathbb{R}^{d \times d/h} \). \(^4\) One way to interpret this is as follows: The term \( (XQ_i)(XK_i)^T \) is an \( \ell \times \ell \) matrix of attention scores, computed as all pairs of dot products between word embeddings. The synthesizer variant eschews the all-pairs dot product and directly computes the \( \ell \times \ell \) matrix of attention scores by mapping each \( d \)-dimensional vector of each head for \( X \) to an \( \ell \)-dimensional vector of unnormalized attention weights.

In the rest of the code in the src/ folder, modify your model to support using either CausalSelfAttention or SynthesizerAttention. Add the ability to switch between these attention variants depending on whether “vanilla” (for causal self-attention) or “synthesizer” (for the synthesizer variant) is selected in the command line arguments (see the section marked [part g] in src/run.py). You are free to implement this functionality in any way you choose, so long as it supports these command line arguments.

Below are bash commands that your code should support in order to pretrain the model, finetune it, and make predictions on the dev and test sets. Note that the pretraining process will take approximately 2 hours.

```
# Pretrain the model
python src/run.py pretrain synthesizer wiki.txt \ 
    --writing_params_path synthesizer.pretrain.params
```

\(^3\)Note that these dimensionalities do not include the minibatch dimension.

\(^4\)Hint: copy over the CausalSelfAttention class, and modify it minimally for this.
# Finetune the model
```
python src/run.py finetune synthesizer wiki.txt \
    --reading_params_path synthesizer.pretrain.params \
    --writing_params_path synthesizer.finetune.params \
    --finetune_corpus_path birth_places_train.tsv
```

# Evaluate on the dev set; write to disk
```
python src/run.py evaluate synthesizer wiki.txt \
    --reading_params_path synthesizer.finetune.params \
    --eval_corpus_path birth_dev.tsv \
    --outputs_path synthesizer.pretrain.dev.predictions
```

# Evaluate on the test set; write to disk
```
python src/run.py evaluate synthesizer wiki.txt \
    --reading_params_path synthesizer.finetune.params \
    --eval_corpus_path birth_test_inputs.tsv \
    --outputs_path synthesizer.pretrain.test.predictions
```

Report the accuracy of your synthesizer attention model on birth-place prediction on birth_dev.tsv after pretraining and fine-tuning.

i. (8 points) We’ll score your model as to whether it gets at least 5% accuracy on the held-out test set; we’ll get the model’s predictions on the held-out test set using the bash script above.

ii. (2 points) Why might the synthesizer self-attention not be able to do, in a single layer, what the key-query-value self-attention can do?

3. Considerations in pretrained knowledge (5 points)

(a) (1 point) Succinctly explain why the pretrained (vanilla) model was able to achieve an accuracy of above 10%, whereas the non-pretrained model was not.

(b) (2 points) Take a look at some of the correct predictions of the pretrain+finetuned vanilla model, as well as some of the errors. We think you’ll find that it’s impossible to tell, just looking at the output, whether the model retrieved the correct birth place, or made up an incorrect birth place. Consider the implications of this for user-facing systems that involve pretrained NLP components. Come up with two reasons why this indeterminacy of model behavior may cause concern for such applications.

(c) (2 points) If your model didn’t see a person’s name at pretraining time, and that person was not seen at fine-tuning time either, it is not possible for it to have “learned” where they lived. Yet, your model will produce something as a predicted birth place for that person’s name if asked. Concisely describe a strategy your model might take for predicting a birth place for that person’s name, and one reason why this should cause concern for the use of such applications.

Submission Instructions
You will submit this assignment on GradeScope as two submissions – one for Assignment 5 [coding] and another for Assignment 5 [written]:

1. Verify that the following files exist at these specified paths within your assignment directory:
   - The no-pretraining model and predictions: vanilla.model.params, vanilla.nopretrain.dev.predictions, vanilla.nopretrain.test.predictions
   - The pretrain-finetune model and predictions: vanilla.finetune.params, vanilla.pretrain.dev.predictions, vanilla.pretrain.test.predictions
• The synthesizer model and predictions: synthesizer.finetune.params, synthesizer.pretrain.dev.predictions, synthesizer.pretrain.test.predictions

2. Run the collect_submission.sh script to produce your assignment5.zip file.

3. Upload your assignment5.zip file to GradeScope to Assignment 5 [coding].

4. Check that the public autograder tests passed correctly.

5. Upload your written solutions, for questions 1, parts of 2, and 3, to GradeScope to Assignment 5 [written]. Tag it properly!

References

