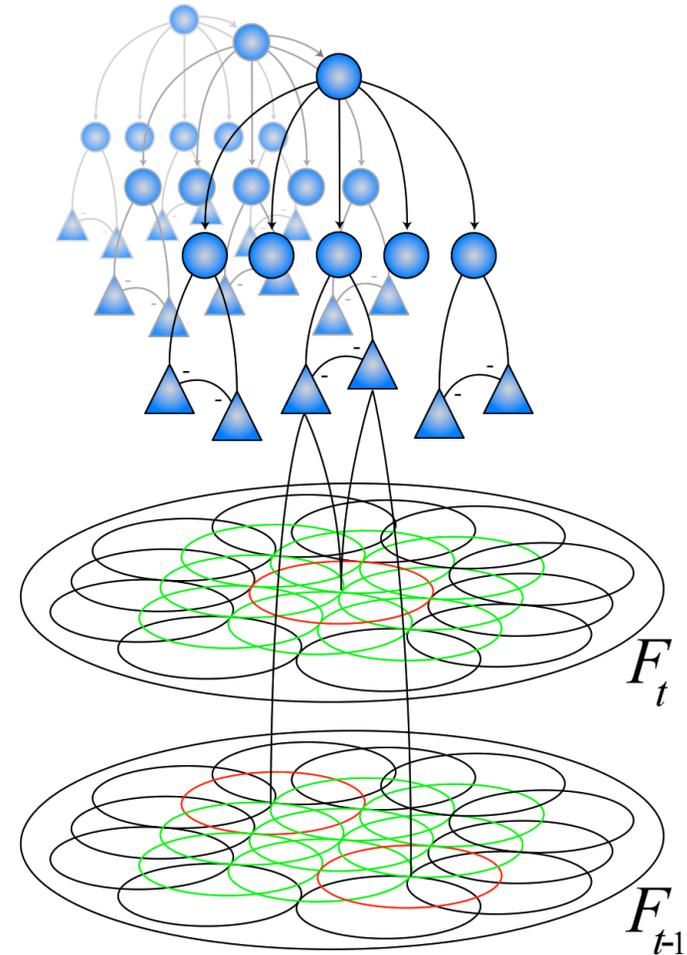
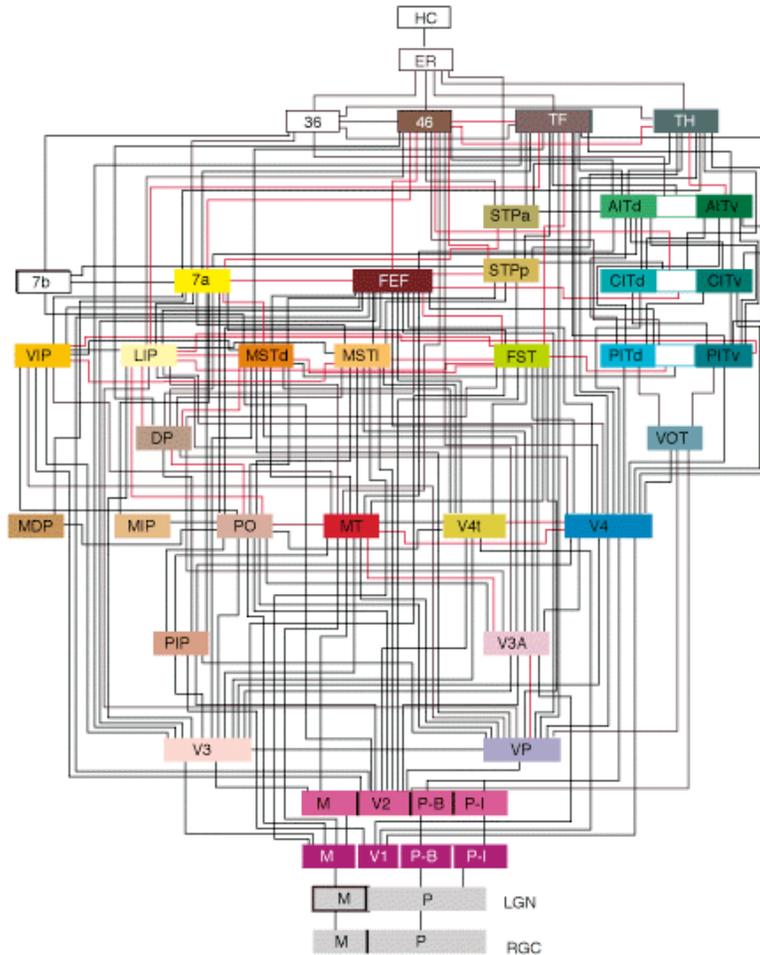


Computational Models of the Primate Visual Cortex

Thomas Dean

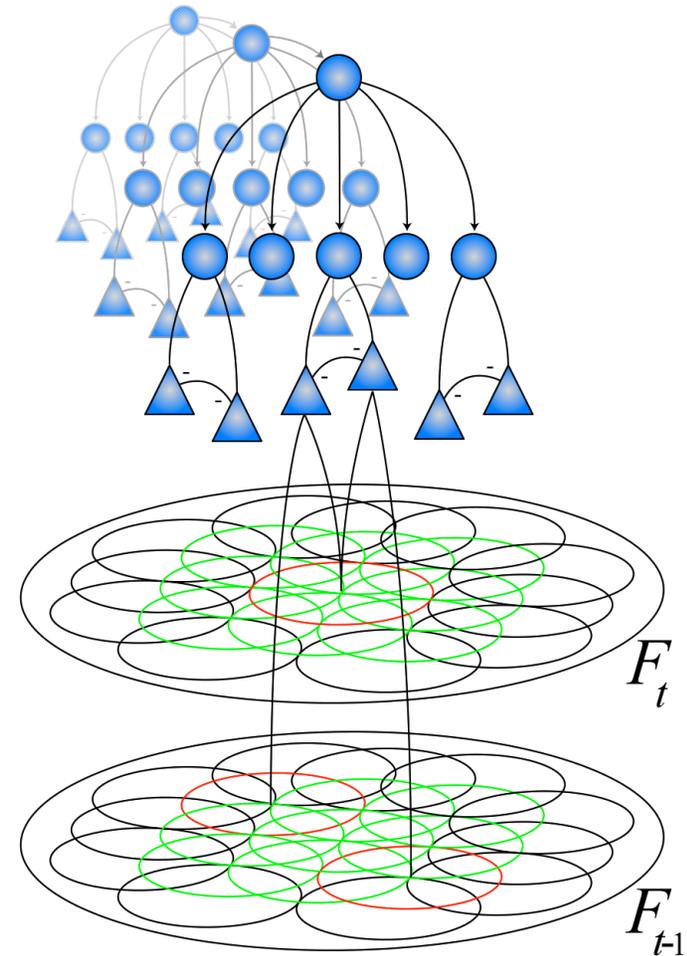
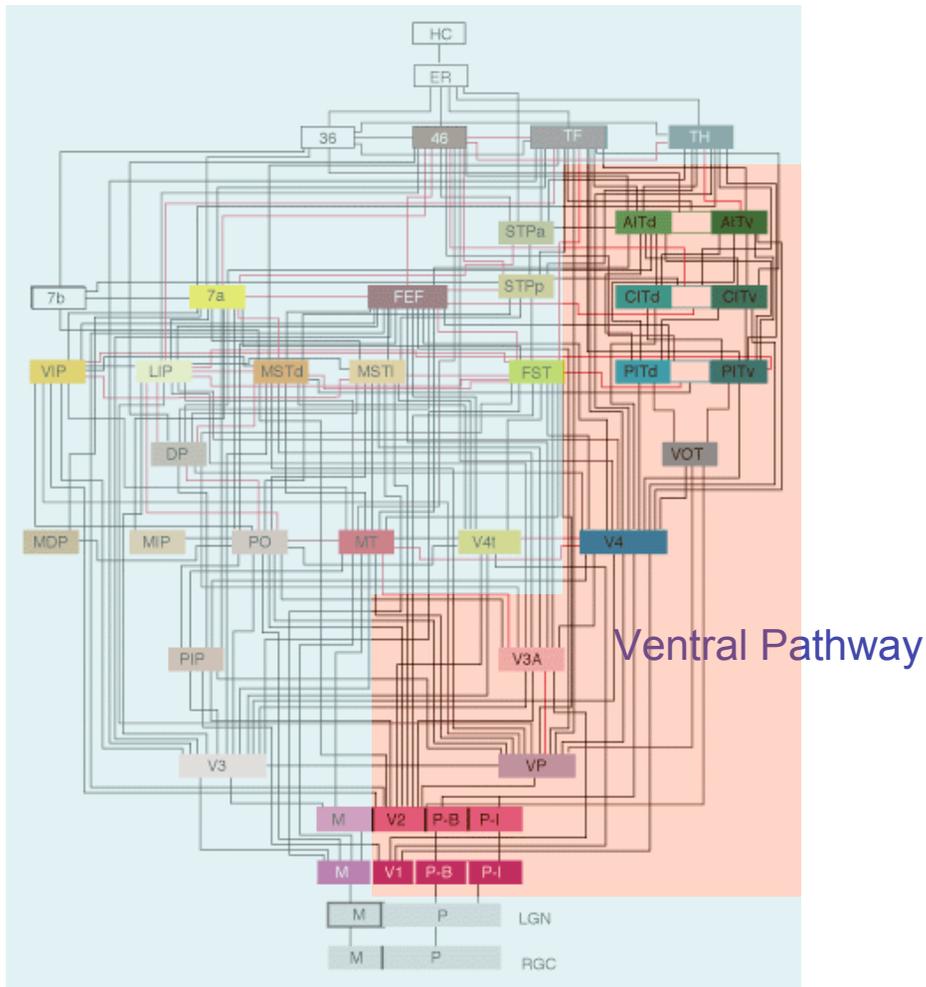

Hierarchical Graphical Models



Felleman, D. J. and Van Essen, D. C. *Distributed hierarchical processing in primate cerebral cortex*. Cerebral Cortex, 1:1-47, 1991.

Thomas Dean. *Learning invariant features using inertial priors*. Annals of Mathematics and Artificial Intelligence, 47(3-4):223-250, 2006.

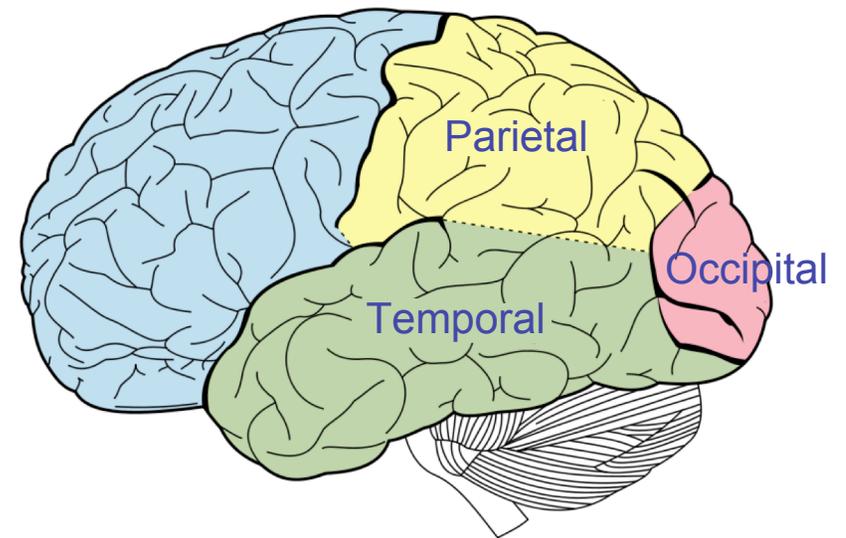
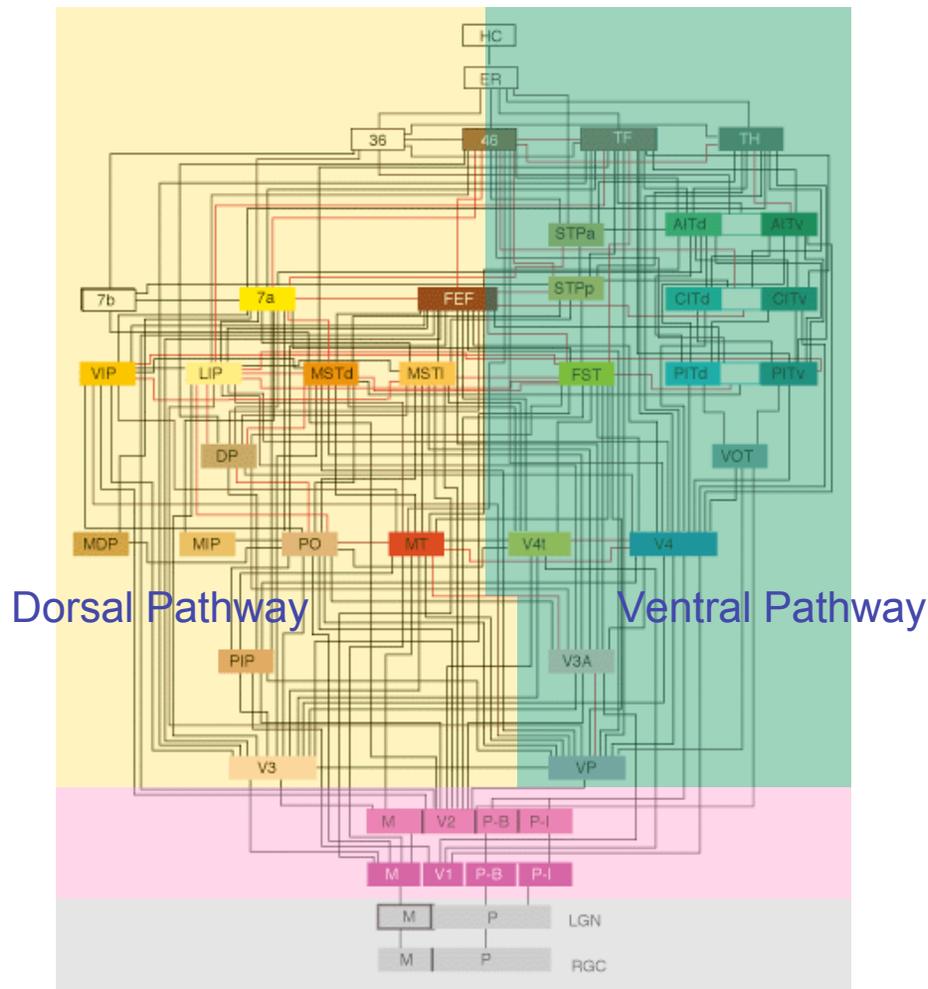
Hierarchical Graphical Models



Felleman, D. J. and Van Essen, D. C. *Distributed hierarchical processing in primate cerebral cortex*. Cerebral Cortex, 1:1-47, 1991.

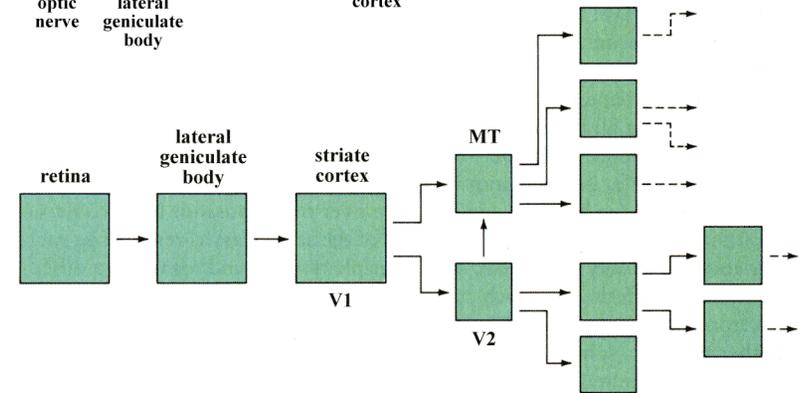
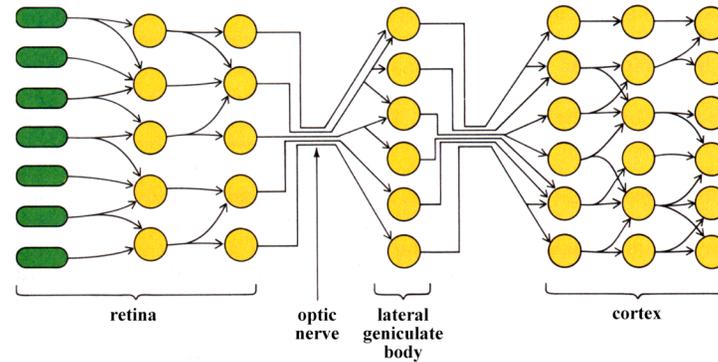
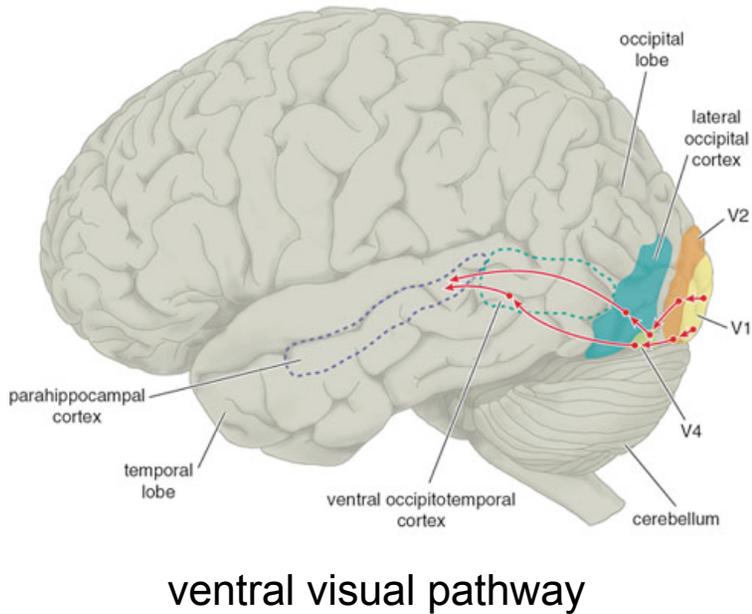
Thomas Dean. *Learning invariant features using inertial priors*. Annals of Mathematics and Artificial Intelligence, 47(3-4):223-250, 2006.

Hierarchical Graphical Models



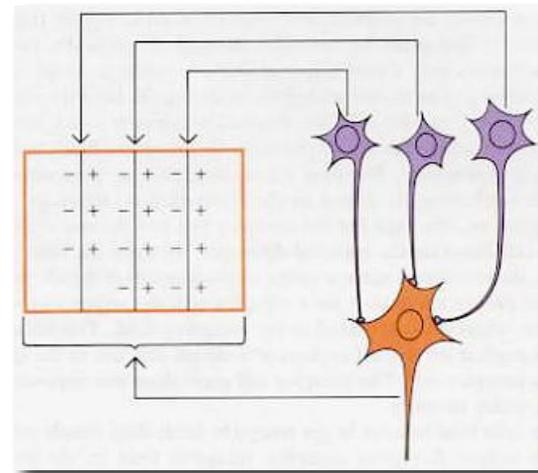
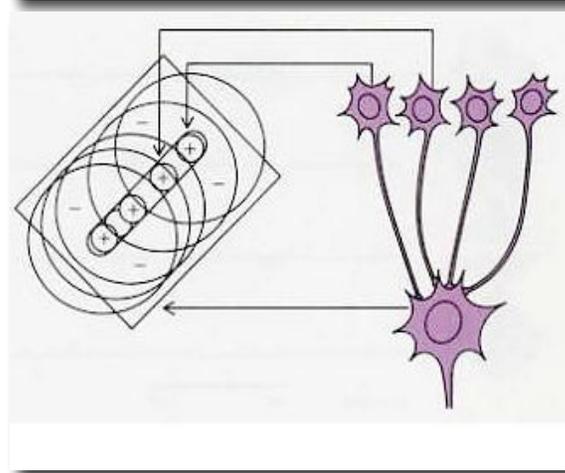
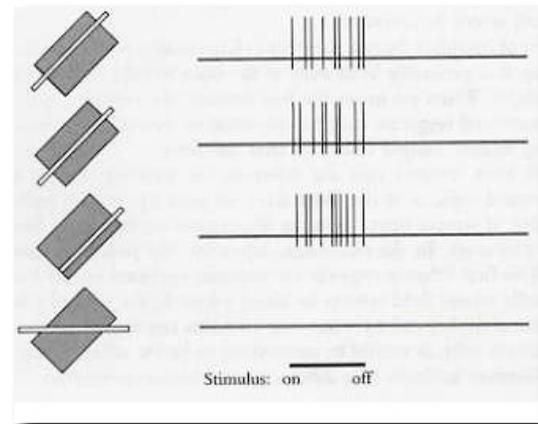
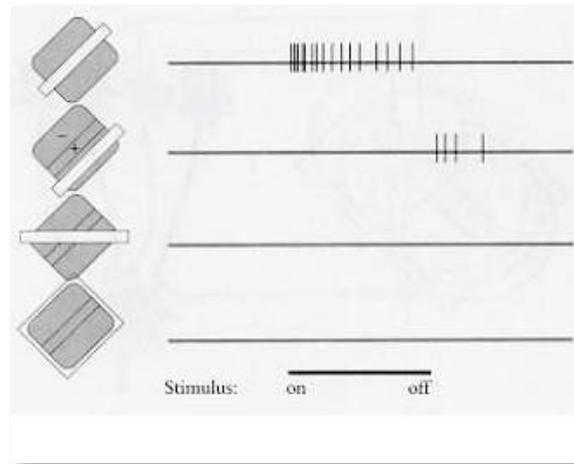
Felleman, D. J. and Van Essen, D. C. *Distributed hierarchical processing in primate cerebral cortex*. Cerebral Cortex, 1:1-47, 1991.

Terminology: Retinotopic Maps



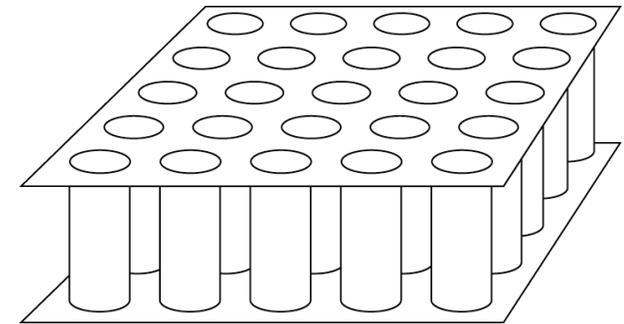
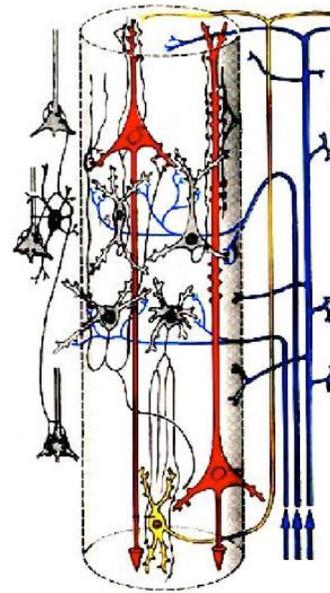
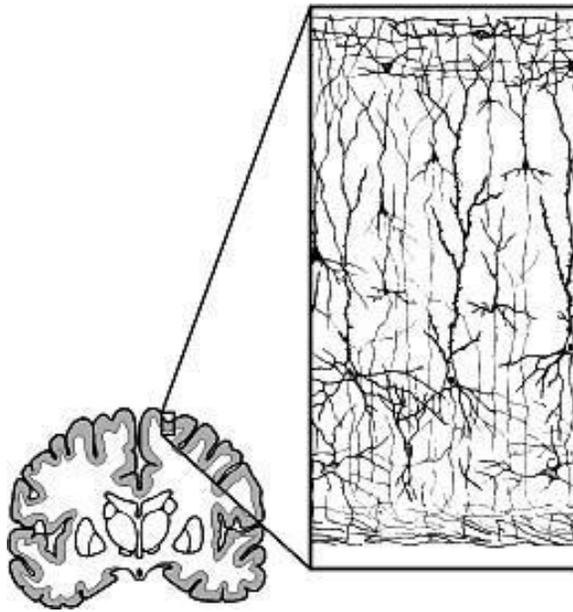
† [Hubel and Wiesel, 1962]

Simple and Complex Cells



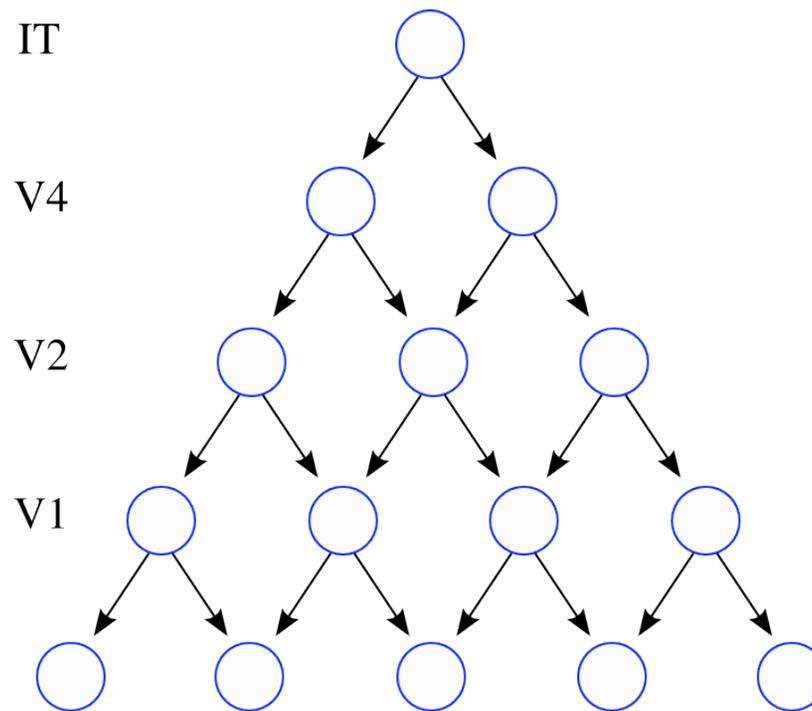
† [Hubel, 1988]

Terminology: Cortical Columns



† [Mountcastle, 1957]

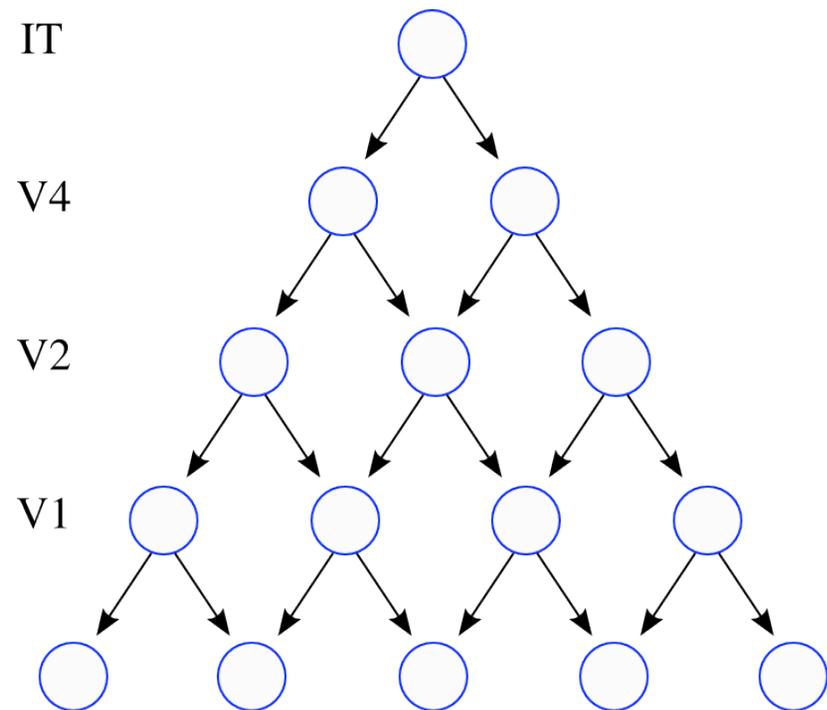
Simple Hierarchical Cortex Model¹



-
1. Ignores intra-layer edges, edges that span layers, explicit feedback, locality, and organization reflecting spatial relationships in peripheral nervous system.

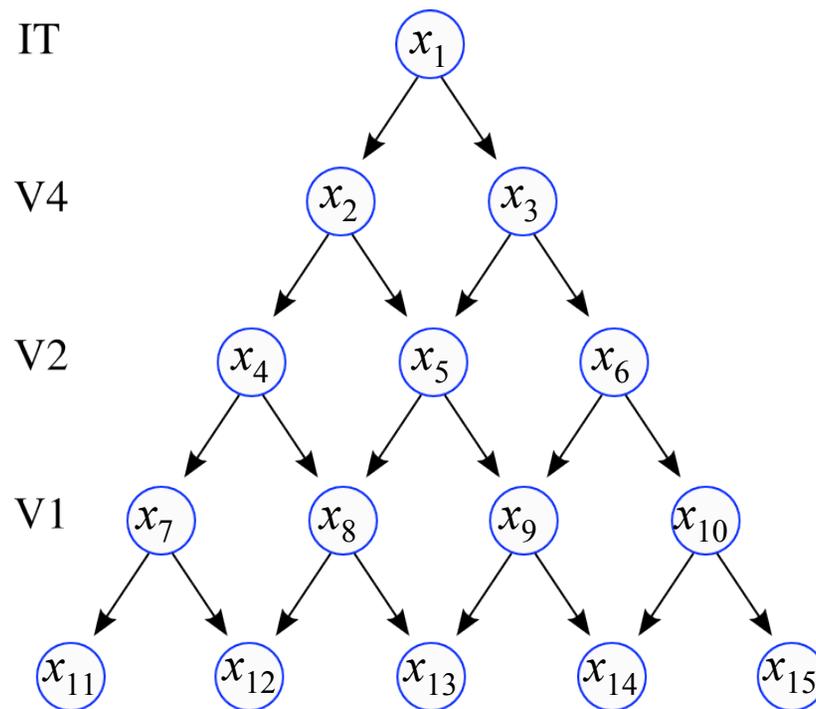
Simple Hierarchical Cortex Model¹

Specify a predefined¹
network structure
capable of encoding a
simple hierarchy



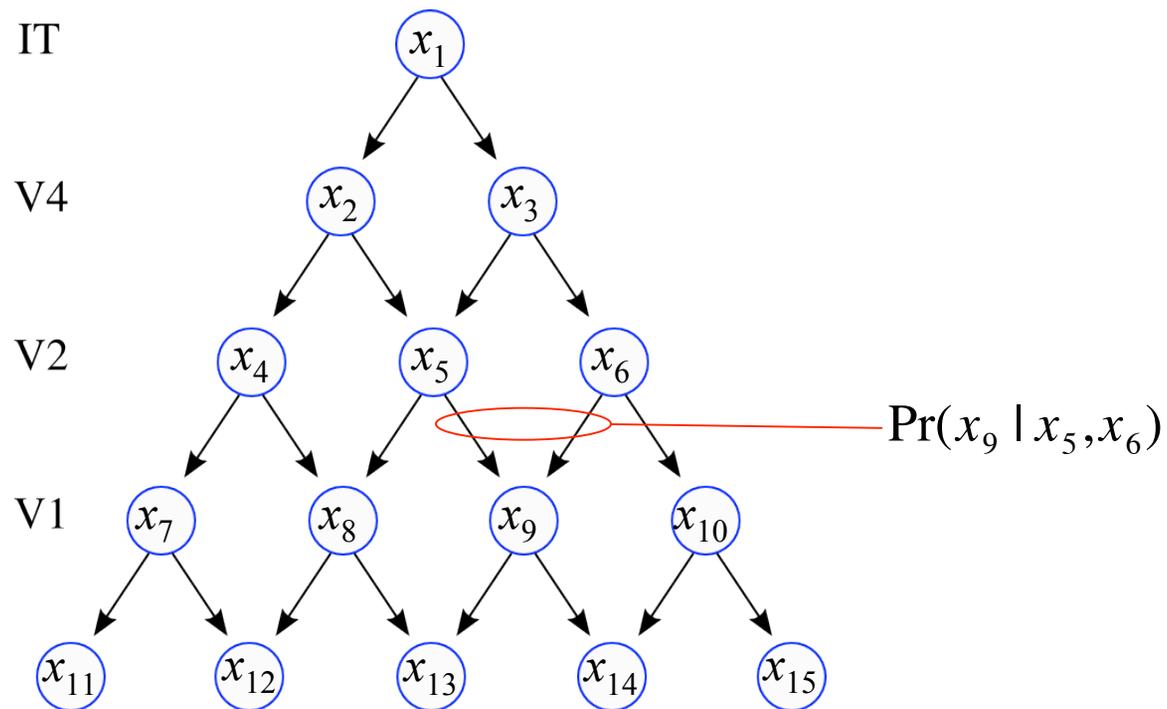
-
1. One approach is to over determine the network structure by generating a *small-world* graph and using parameter learning to quantify connections.

Probabilistic Graphical Models¹



-
1. Graph in which nodes correspond to random variables and edges correspond to dependency relations quantified by specifying conditional probability functions.

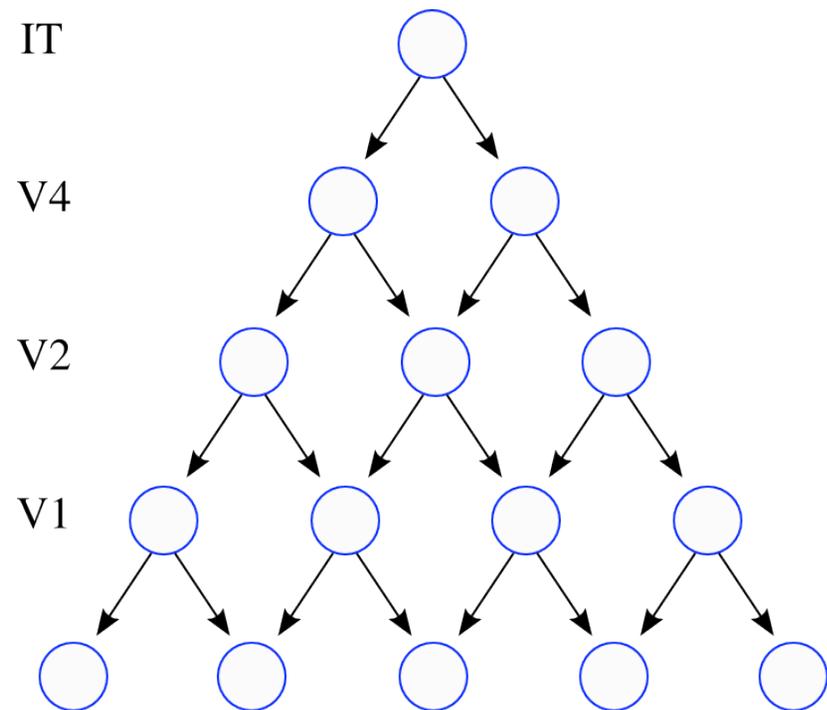
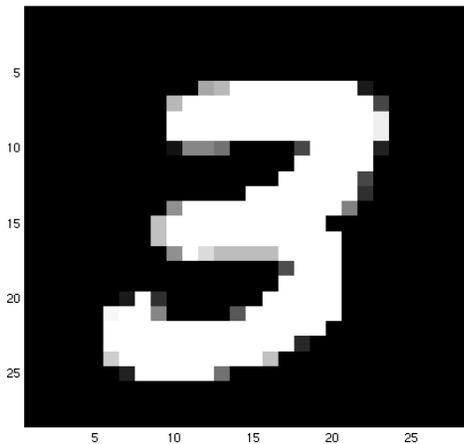
Probabilistic Graphical Models¹



-
1. Compactly describes the full joint probability: $\Pr(x_1, \dots, x_n) = \prod_{i=1}^n \Pr(x_i | \text{Parents}(x_i))$

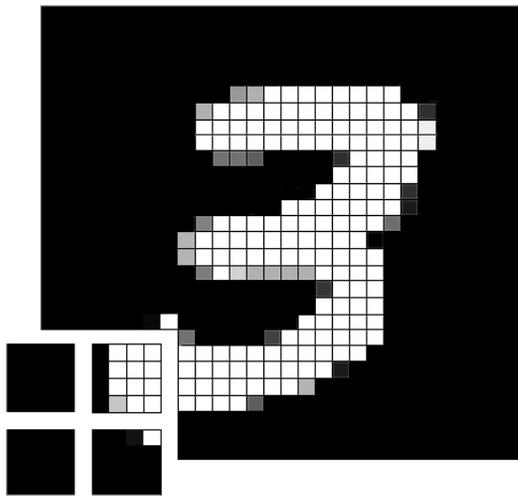
Inference in Graphical Models

- Learn to recognize hand-written digits

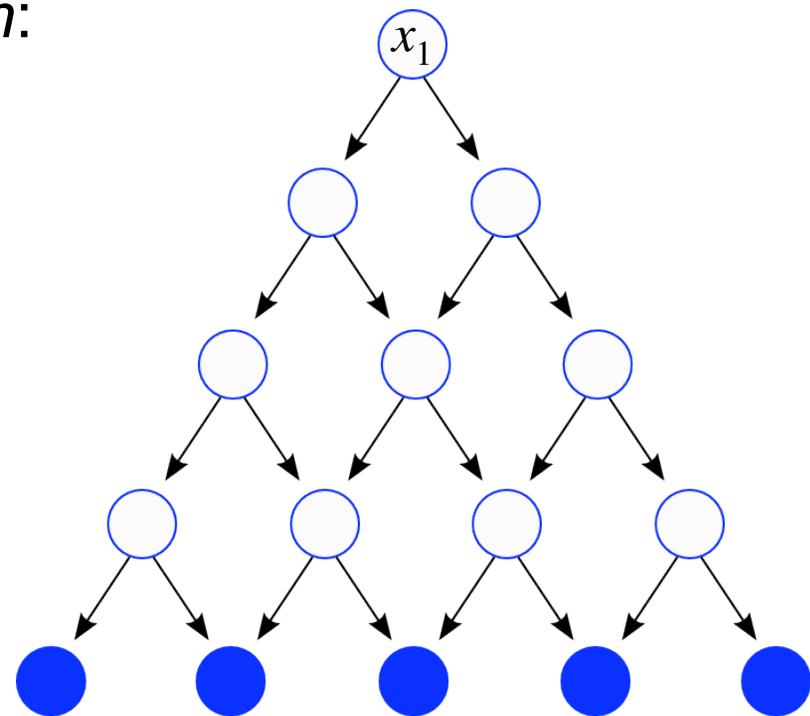


Inference in Graphical Models

- Observe input sensor data S
- Compute¹ the *belief function*:
 $\forall i, \text{Bel}(x_i) = P(x_i | S)$



$$\Omega_{x_1} = \{0,1,2,\dots,9\}$$



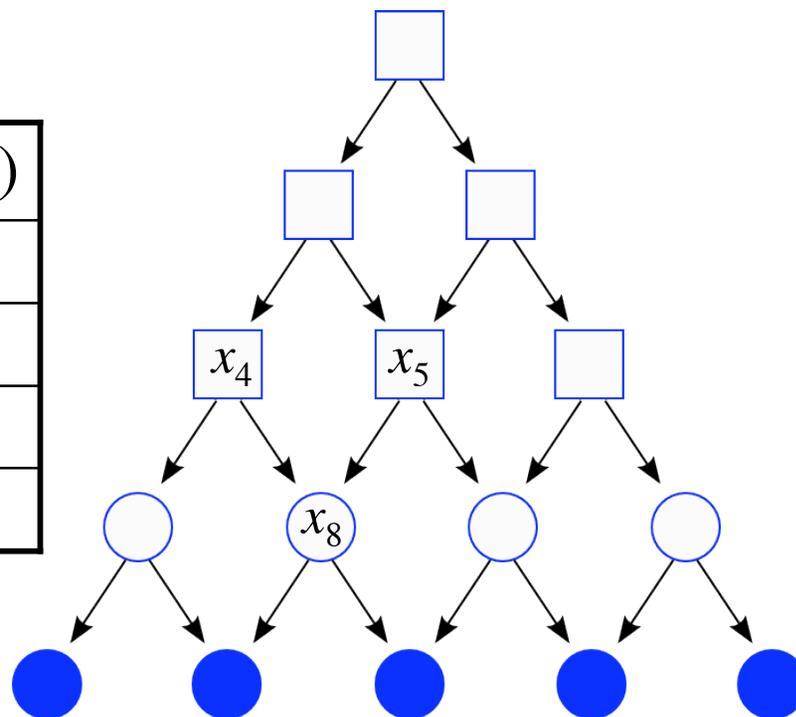
-
1. Loopy belief propagation and nonparametric belief propagation / particle filtering are ideally suited for iteratively updating this belief function.

Learning in Graphical Models

- Learn the remaining layers using bottom-up layer-by-layer method¹

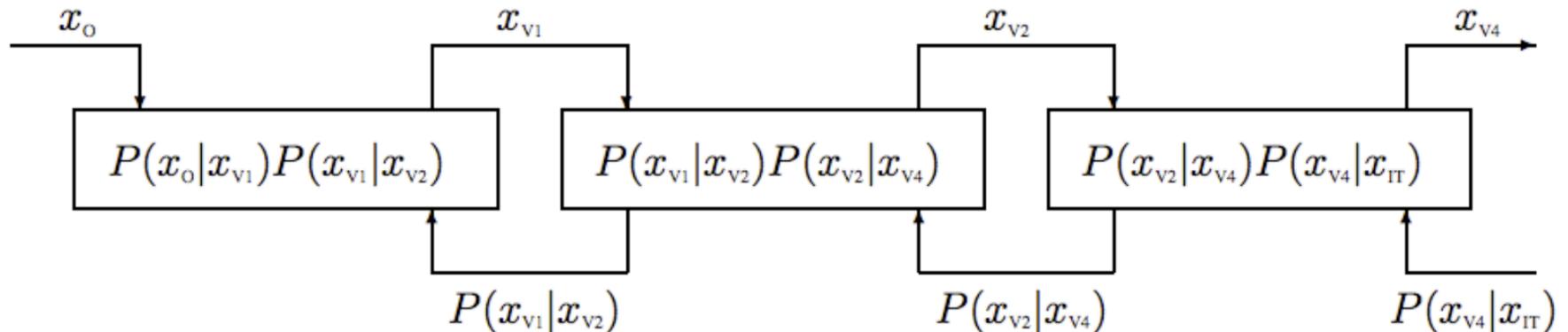
$$\Omega_{x_i}, \Pr(x_i | \text{Parents}(x_i))$$

x_4	x_5	x_8	$P(x_8 x_4, x_5)$
1	1	1	0.147
2	1	1	0.053
3	1	1	0.238
...	



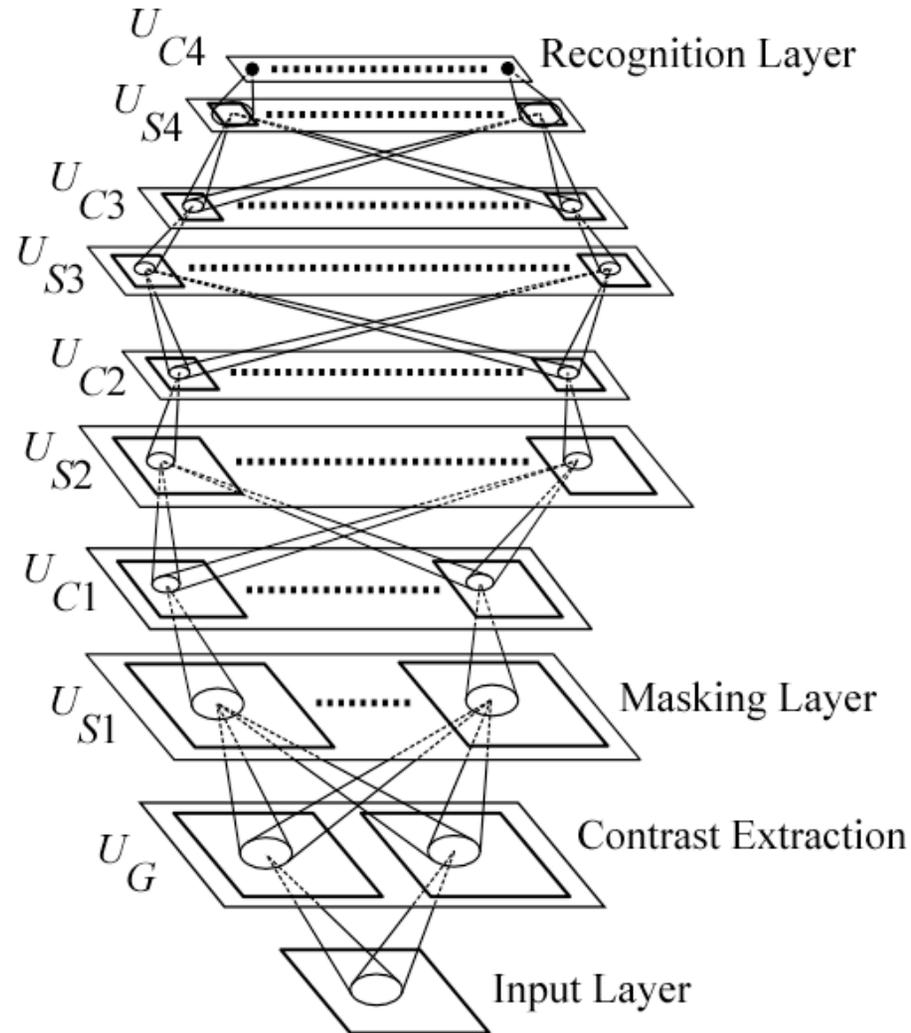
-
- This layer-by-layer strategy has a long history in artificial neural networks and machine learning and currently a focus of interest in *deep belief networks*.

Lee and Mumford Model



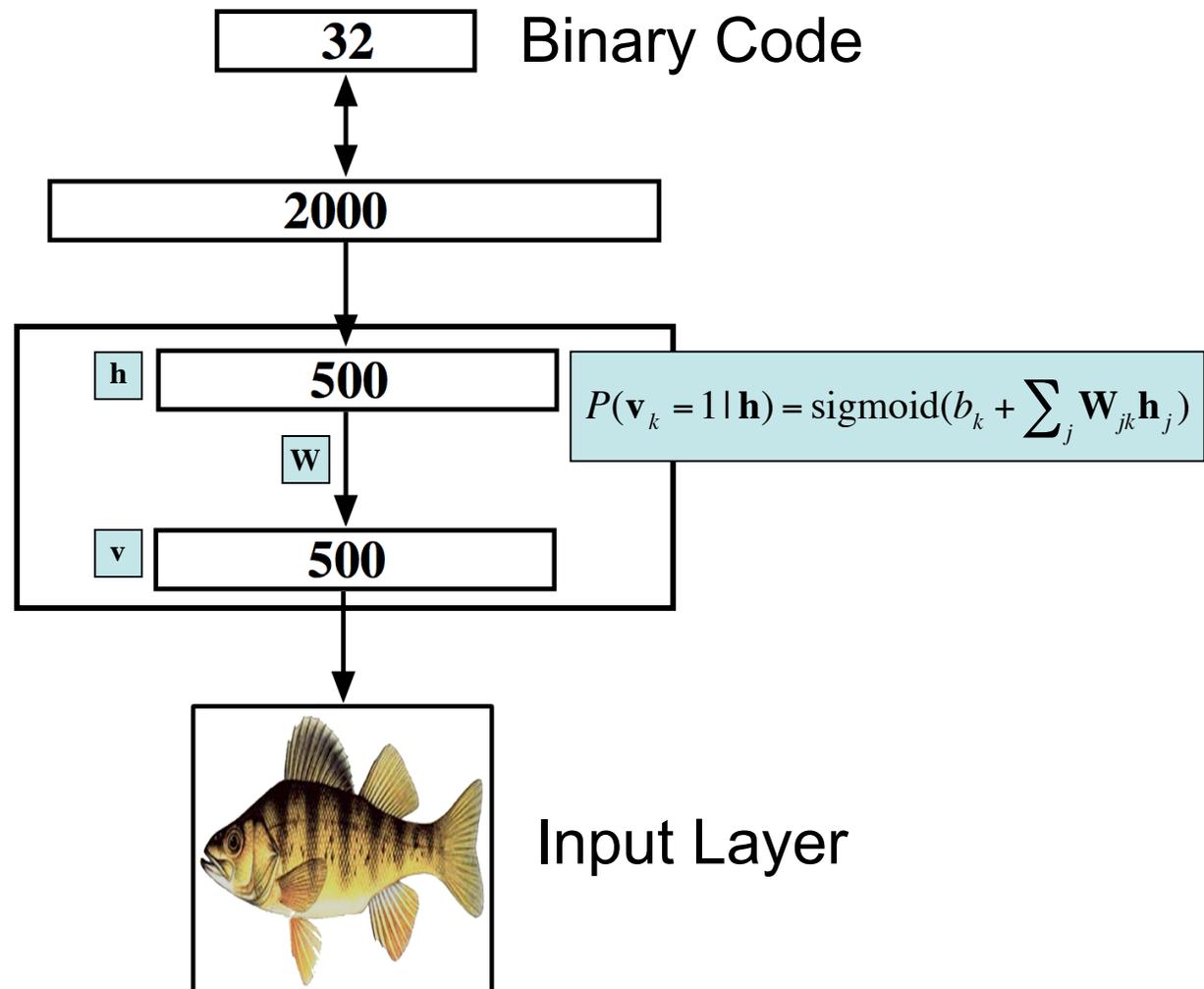
- Hierarchical model of the visual cortex
- Generative Bayesian statistical model
- Bottom-up data $\{x_i\}$ are fed forward
- Top-down priors $\{P(x_i|x_{i+1})\}$ are fed back

Multilayer Perceptron Models



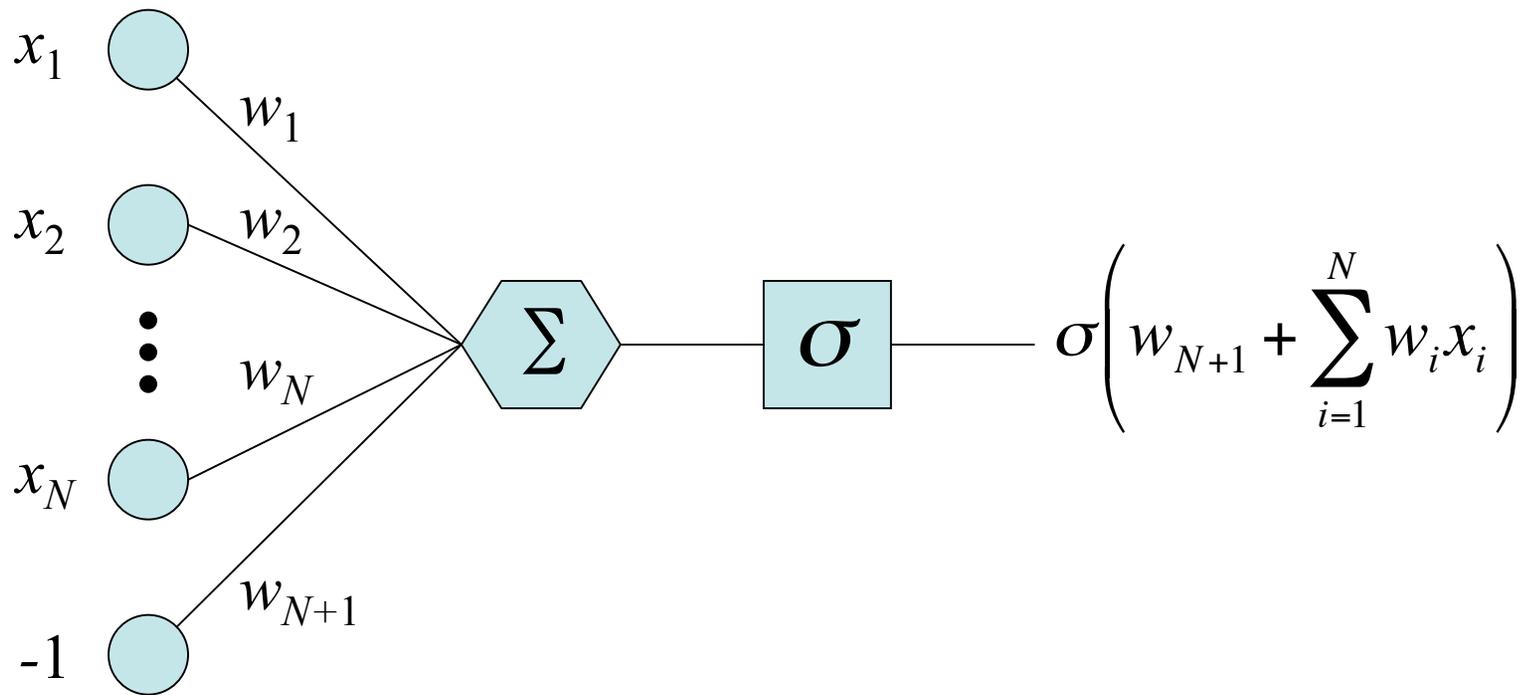
K. Fukushima. Neocognitron: A self organizing neural network model for a mechanism of pattern recognition unaffected by shift in position. *Biological Cybernetics*, 36(4):93–202, 1980.

Deep Belief Networks



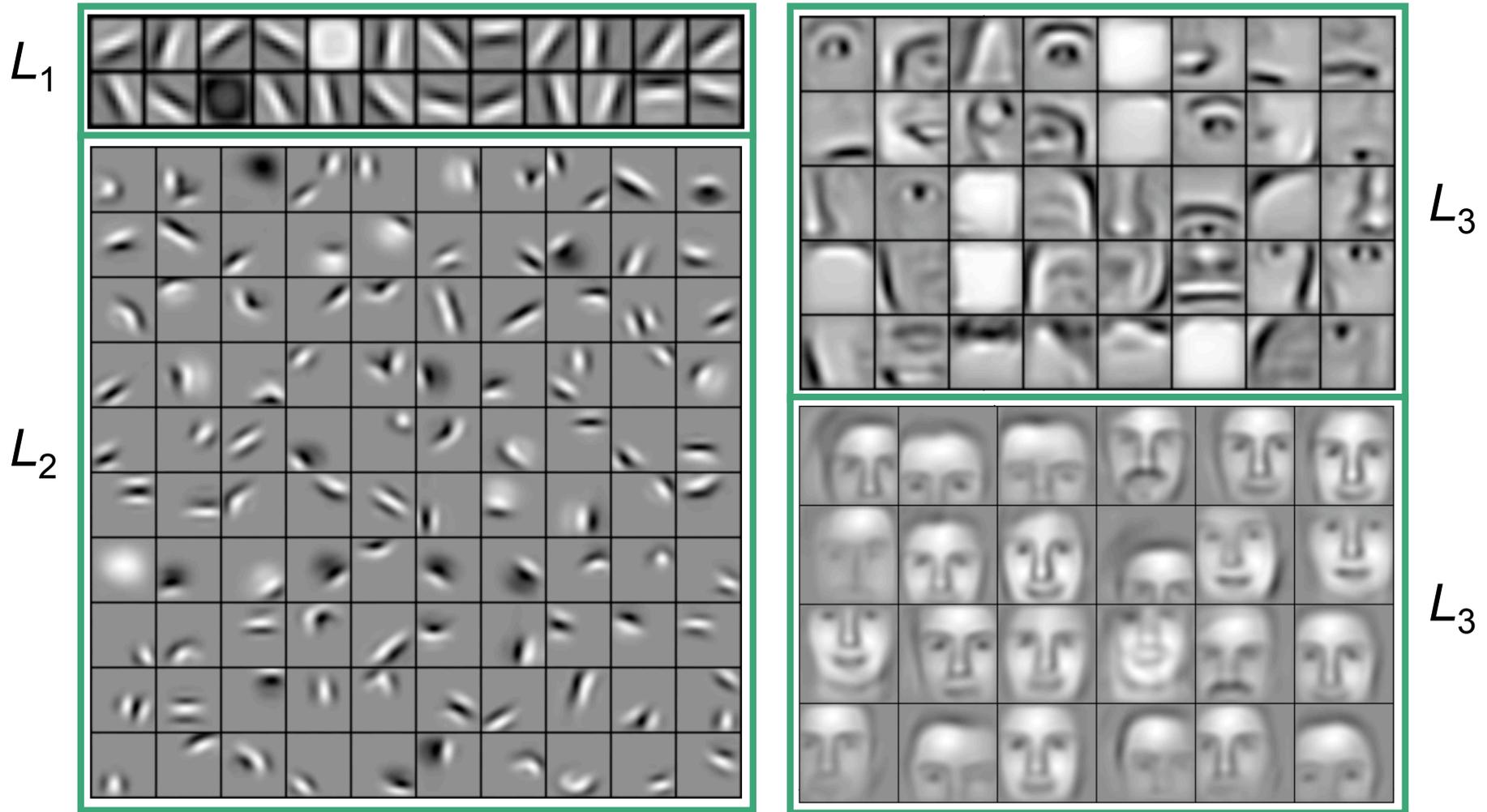
Hinton, Geoffrey. E. (2005). What kind of a graphical model is the brain? In the Proceedings of the 19th International Joint Conference on Artificial Intelligence.

McCulloch and Pitts Neuron

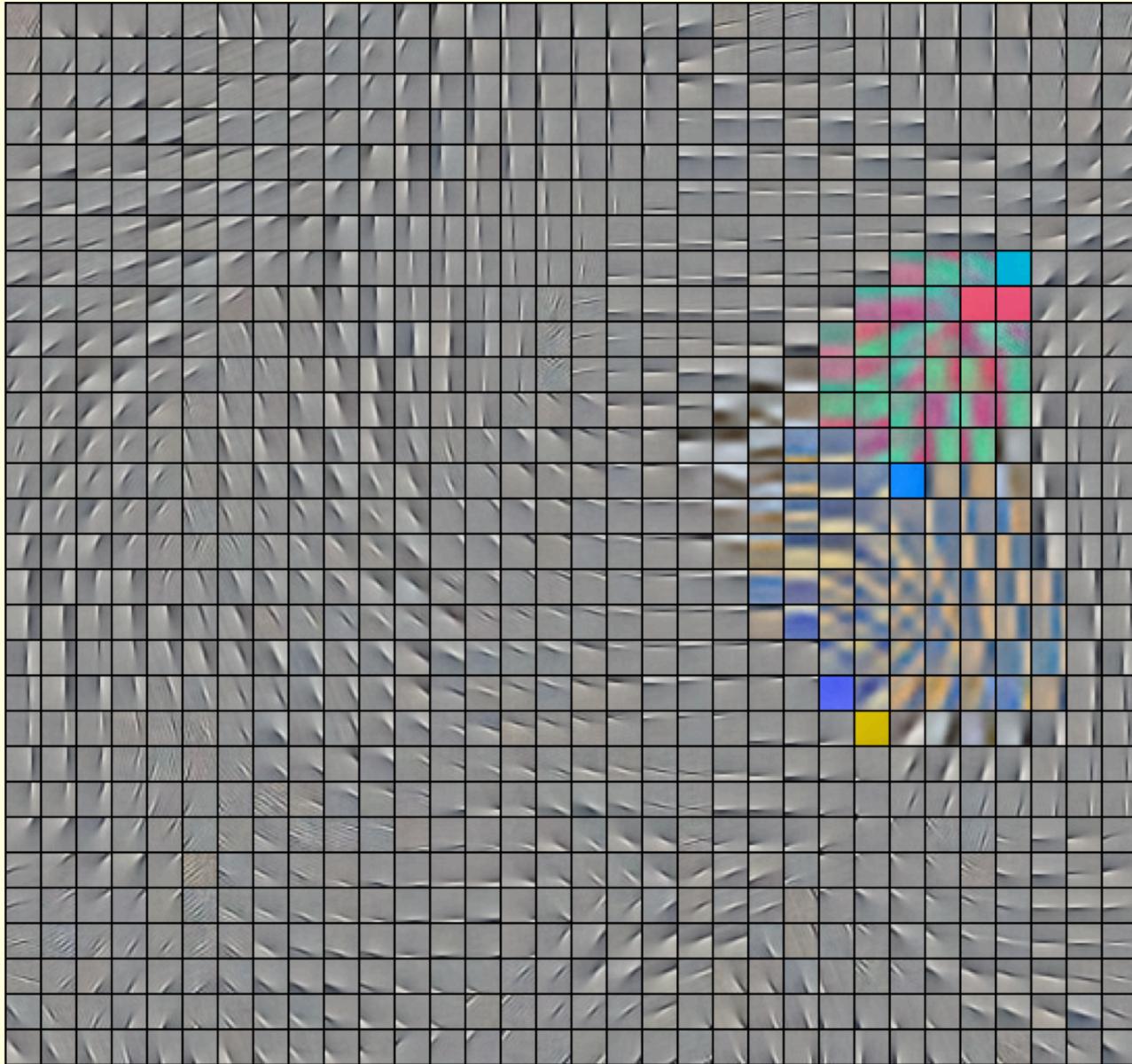


McCulloch, W. and Pitts, W. (1943). A logical calculus of the ideas immanent in nervous activity. *Bulletin of Mathematical Biophysics*. 7:115-133.

Modeling Interesting Phenomena



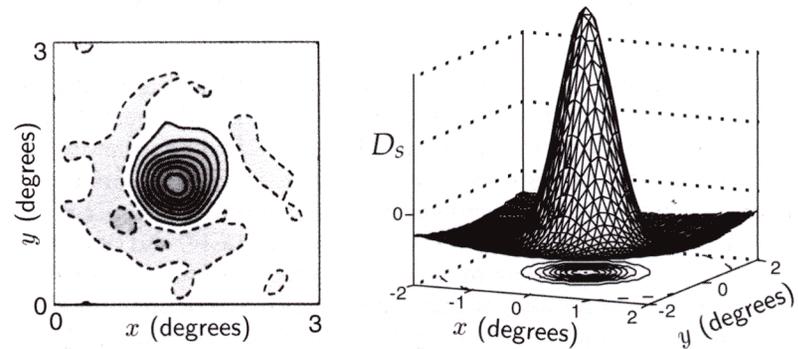
Honglak Lee, Roger Grosse, Rajesh Ranganath, and Andrew Y. Ng. Convolutional deep belief networks for scalable unsupervised learning of hierarchical representations. Proceedings of the 26th Annual International Conference on Machine Learning, 2009.



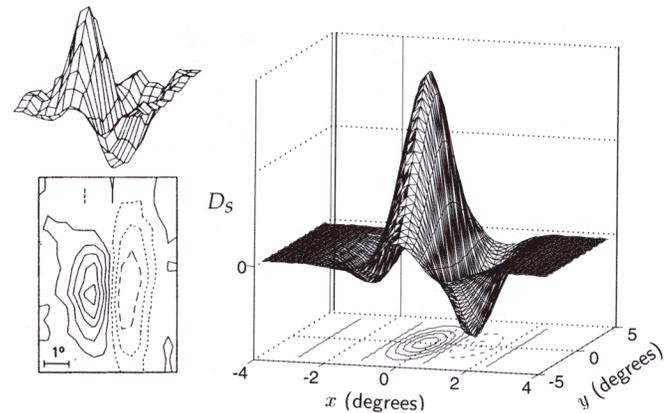
Marc' Aurelio Ranzato and Geoffrey Hinton. Deep learning with multiplicative interactions. In the Proceedings of the *IEEE Computer Society Conference on Computer Vision and Pattern Recognition*. IEEE Computer Society, 2010.

Simple Cell Receptive Fields

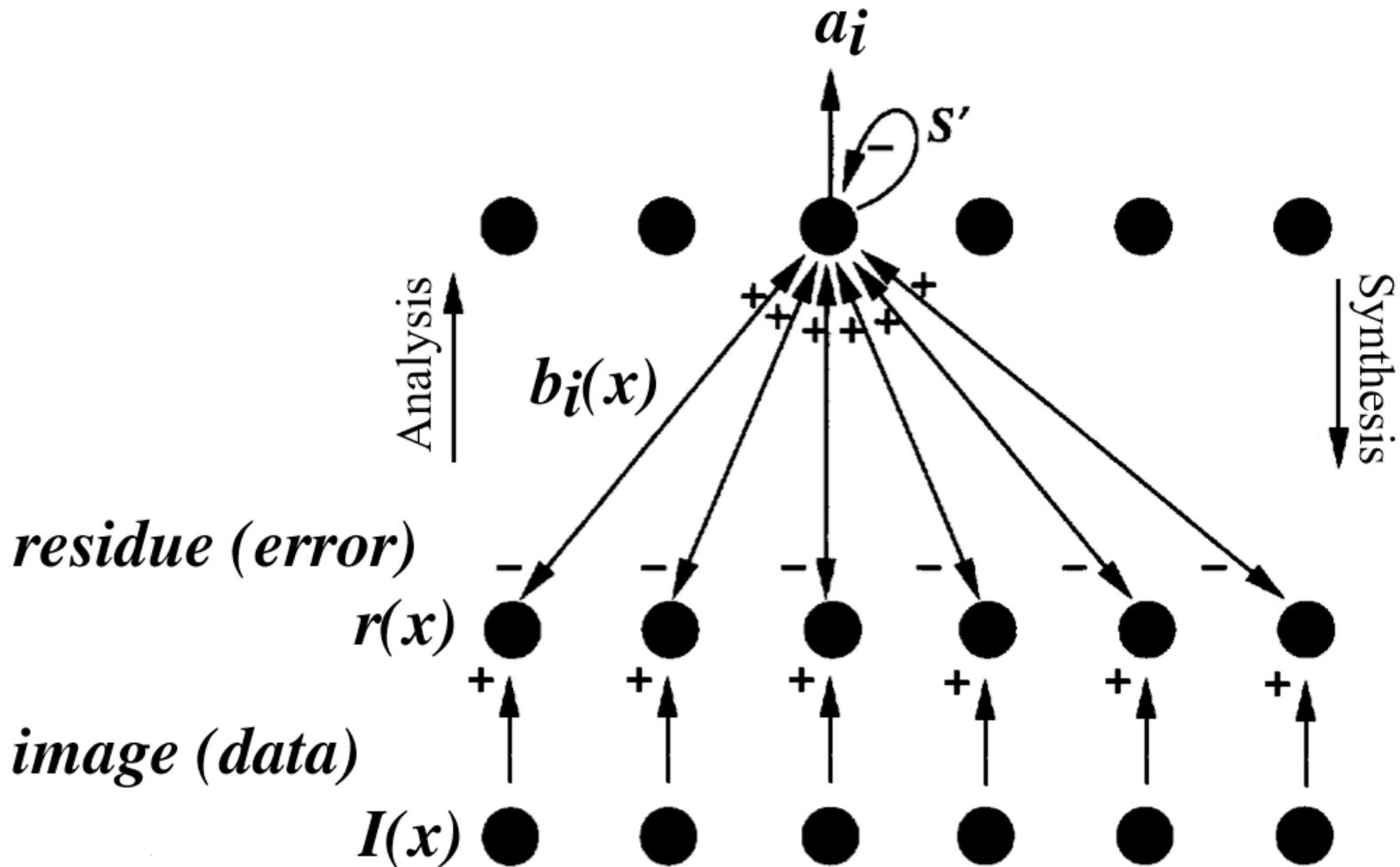
- Center-surround cells in the retina and lateral geniculate nuclei — difference of Gaussians



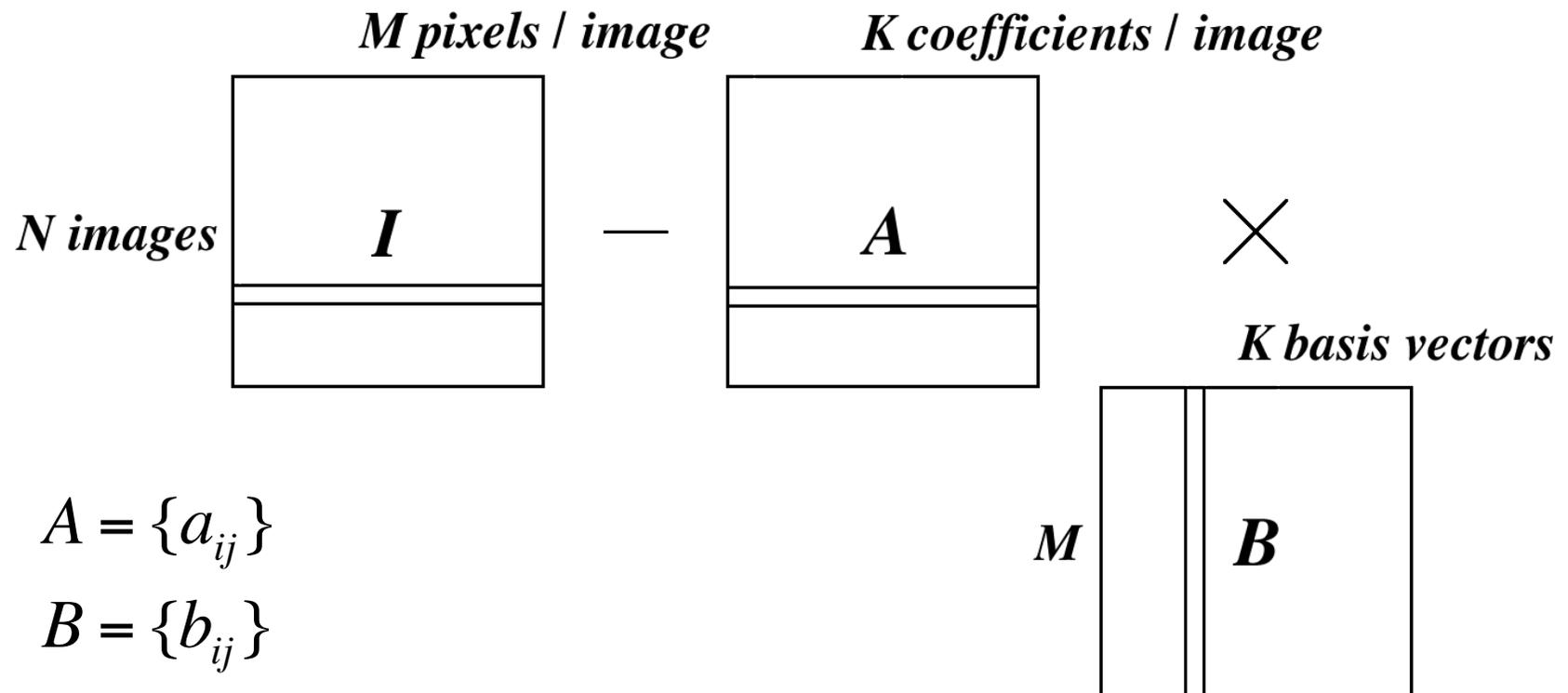
- Edge-sensitive cells in V1 — product of Gaussian and sinusoidal functions called Gabor functions



Analysis Synthesis Loop



Reconstruction (Residual) Error



Analysis-Synthesis Iteration

Analysis step: solve for B holding A constant

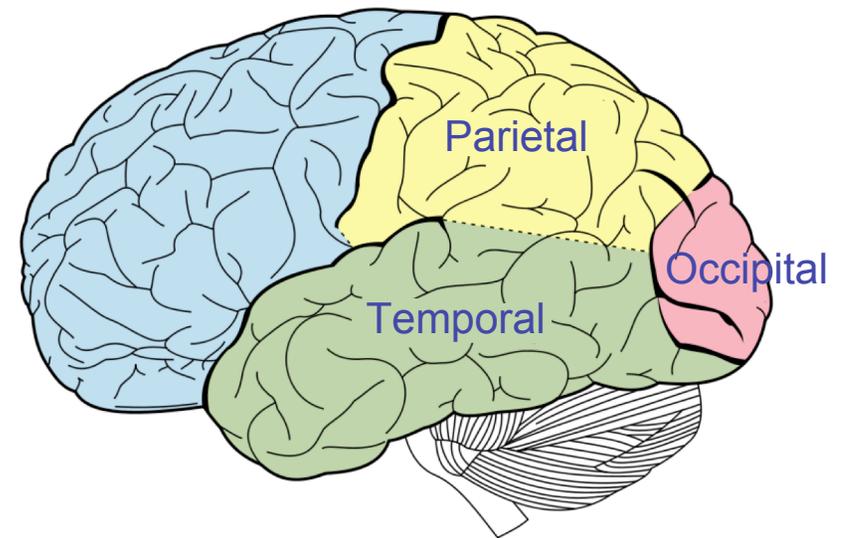
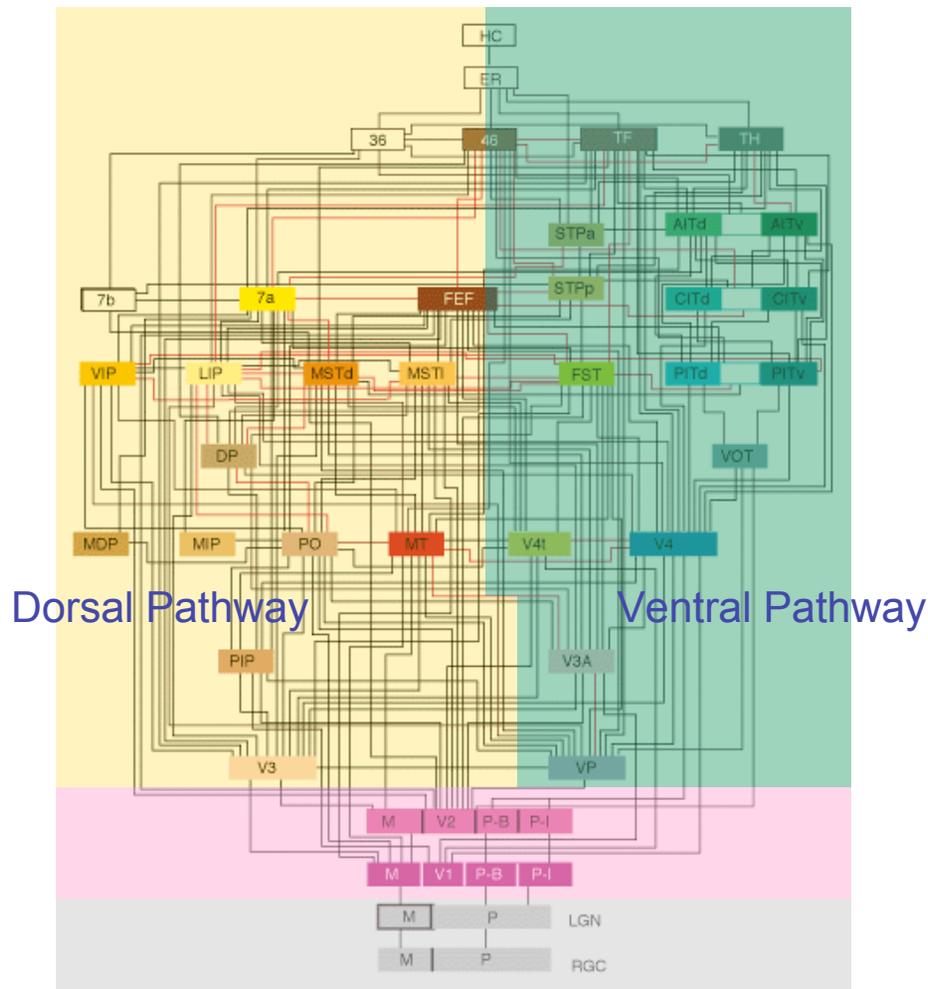
$$\text{minimize}_B J(B|A) = \|X - AB\|_2^2$$

$$\text{subject to } \sum_{i=1}^L B_{i,j}^2 < c$$

Synthesis step: solve for A holding B constant

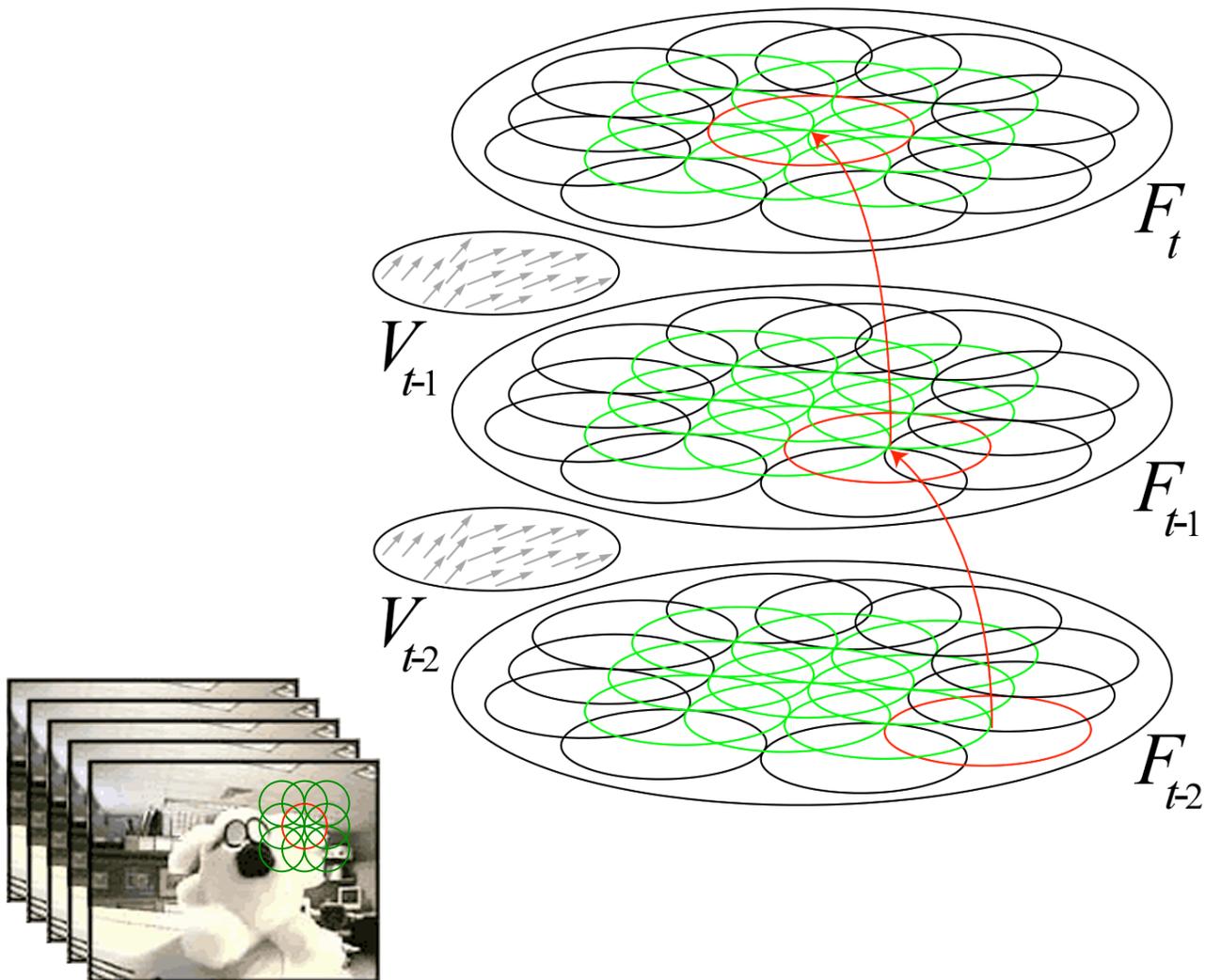
$$\text{minimize}_A J(A|B) = \|X - AB\|_2^2 + \lambda \|A\|_1$$

Hierarchical Graphical Models

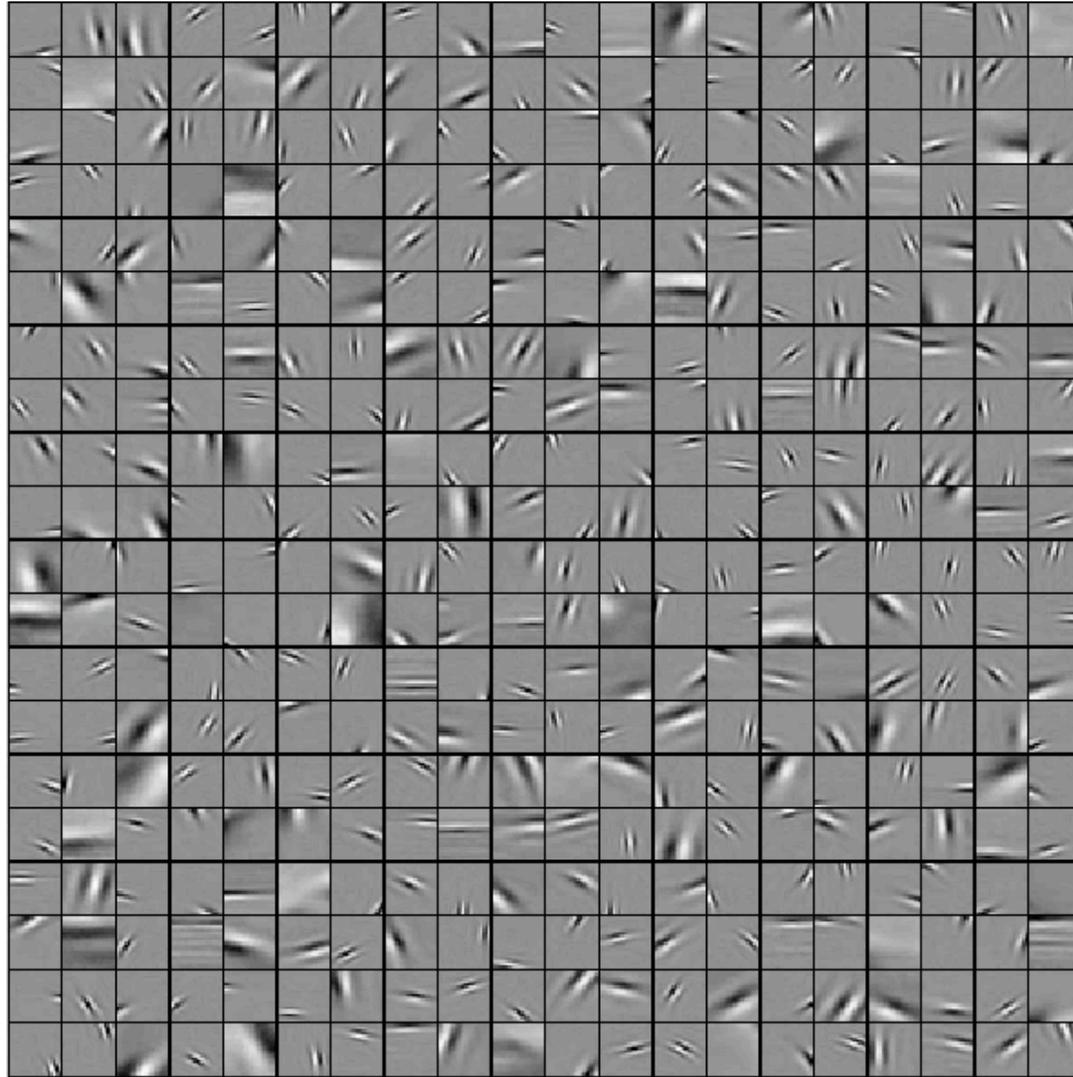


Felleman, D. J. and Van Essen, D. C. *Distributed hierarchical processing in primate cerebral cortex*. Cerebral Cortex, 1:1-47, 1991.

Space-Time Features



Spatiotemporal Features



Bruno Olshausen and Charles Cadieu. Learning invariant and variant components of time-varying natural images. *Journal of Vision*. 7(9):964–964, 2007.

Tasks of Biological Vision

- Recognition

- Faces, predators, landmarks, *etc.*

- Navigation

- Localizing, orienting, pursuing, *etc.*

- Manipulation

- Grasping, throwing, assembling, *etc.*

J. Aloimonos, A. Bandyopadhyay and I. Weiss. *Active vision*. In the Proceedings of the First International Conference on Computer Vision, pages 35–55, 1987.

Ruzena Bajcsy. *Active perception*. Proceedings of the IEEE, 76(8):966–1005, 1988.

James J. Gibson. *The Ecological Approach to Visual Perception*. Houghton Mifflin, Boston, 1979.

The PASCAL Visual Object Classes Challenge 2007 *Too Hard?*

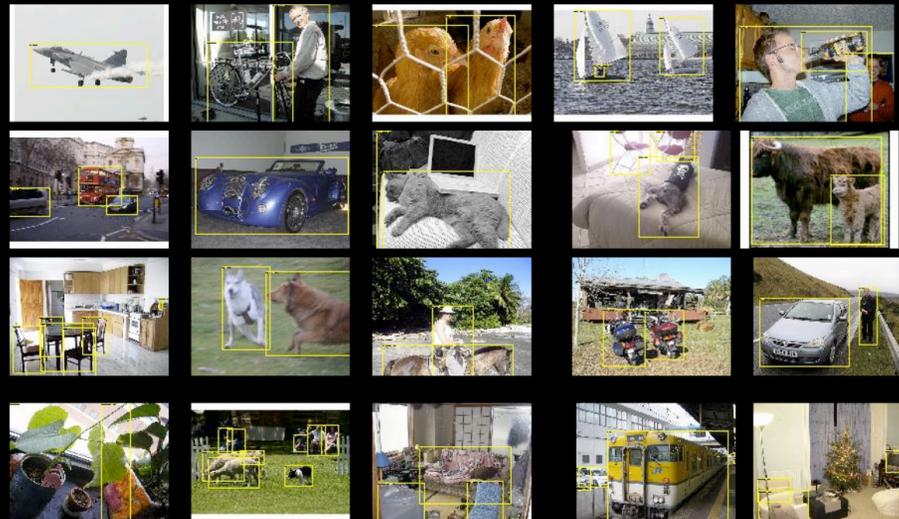
The twenty object classes that have been selected are:

Person: person

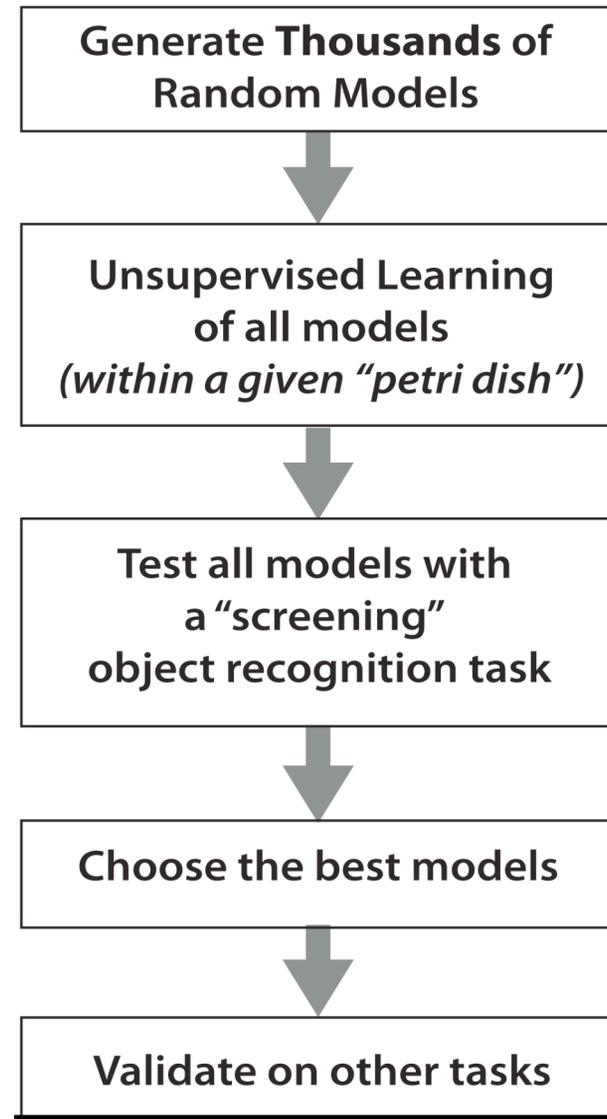
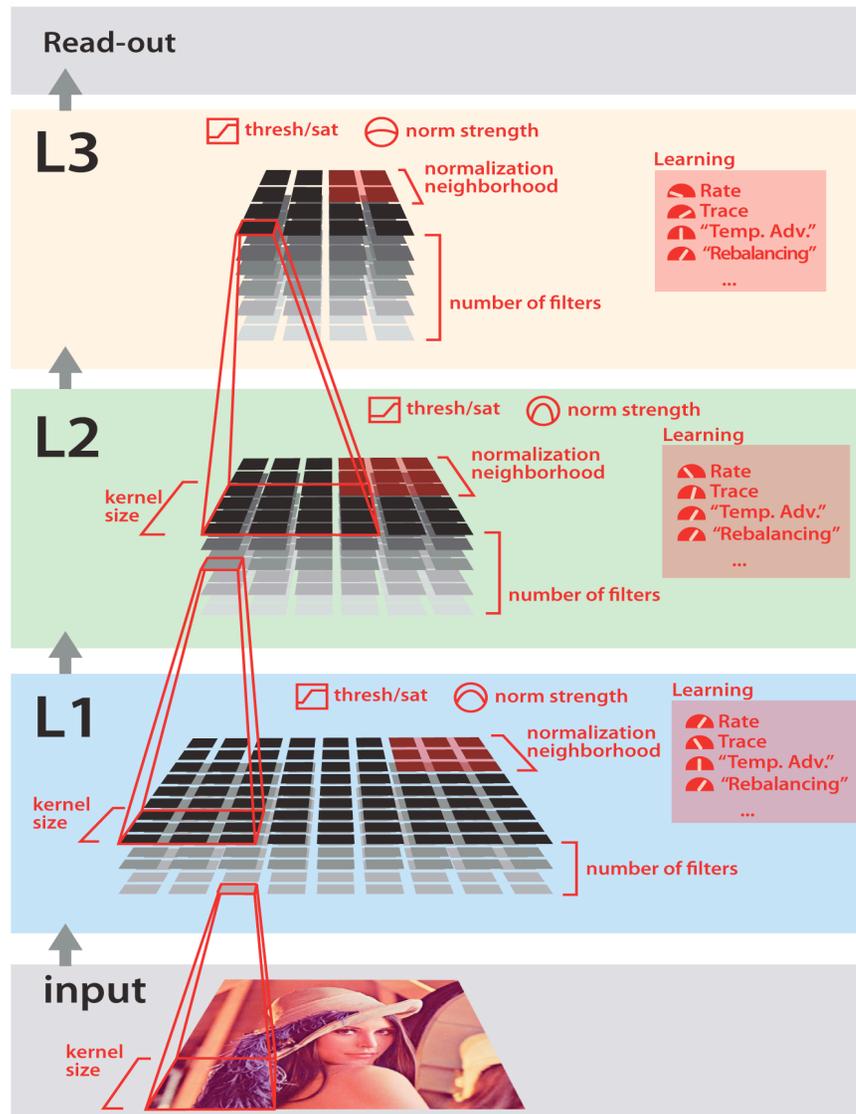
Animal: bird, cat, cow, dog, horse, sheep

Vehicle: aeroplane, bicycle, boat, bus, car, motorbike, train

Indoor: bottle, chair, dining table, potted plant, sofa, tv/monitor

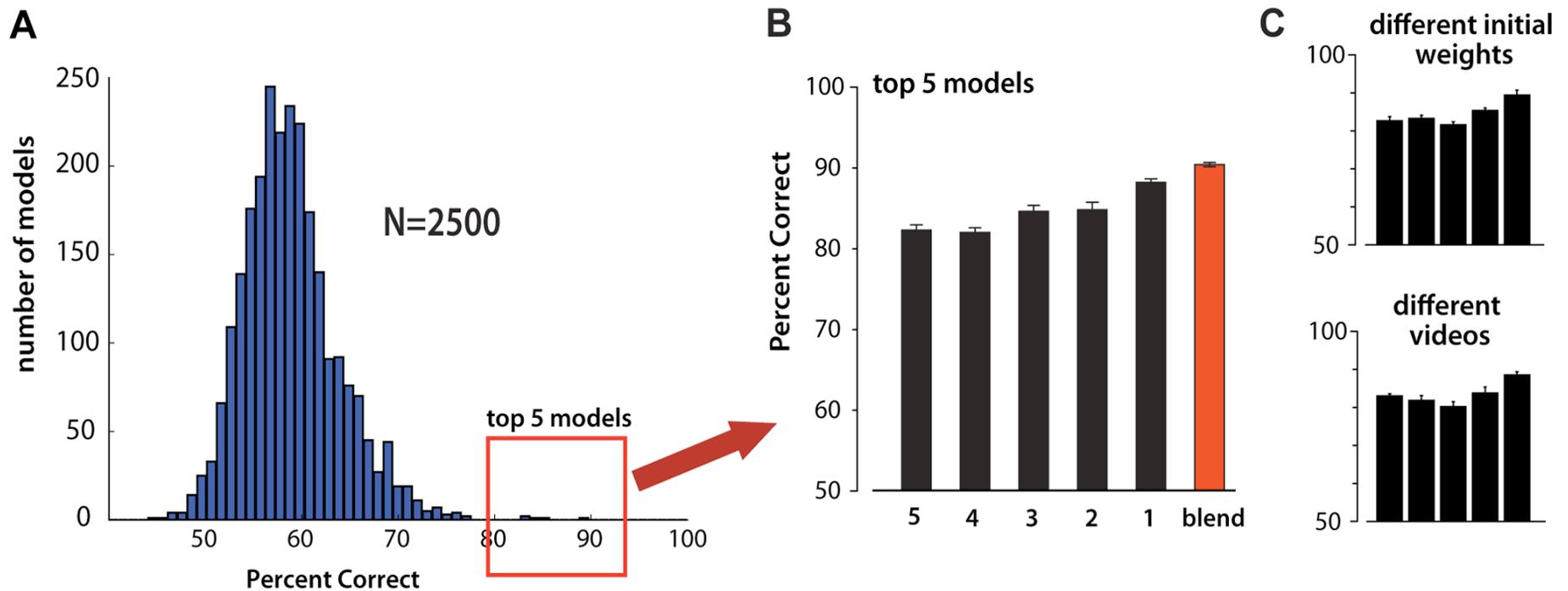


M. Everingham, Luc van Gool , C. Williams, J. Winn, A. Zisserman 2007

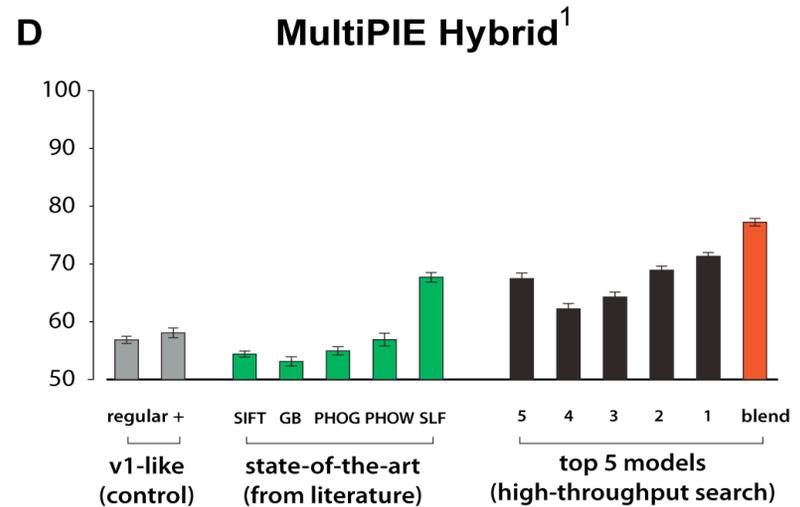
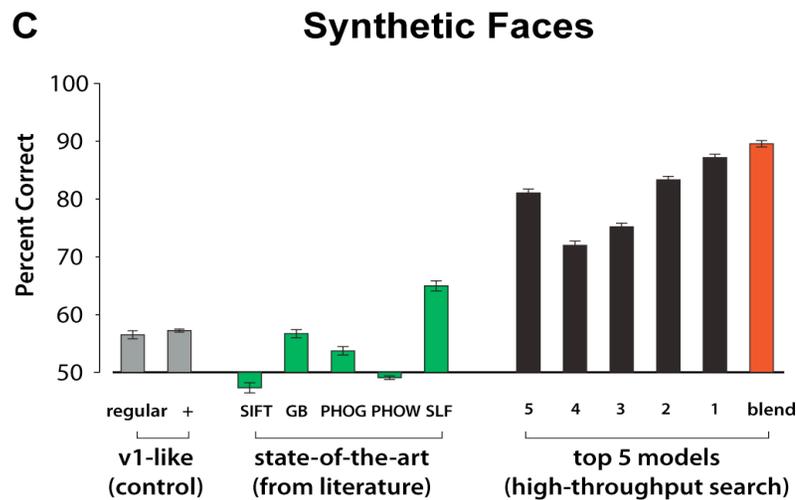
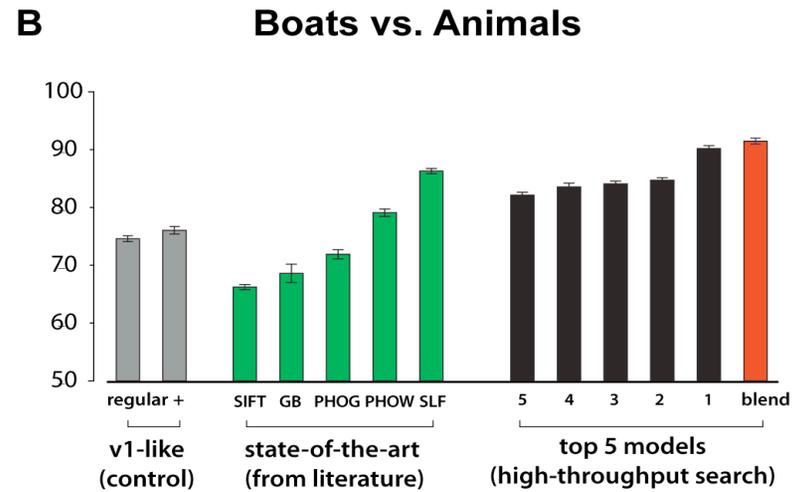
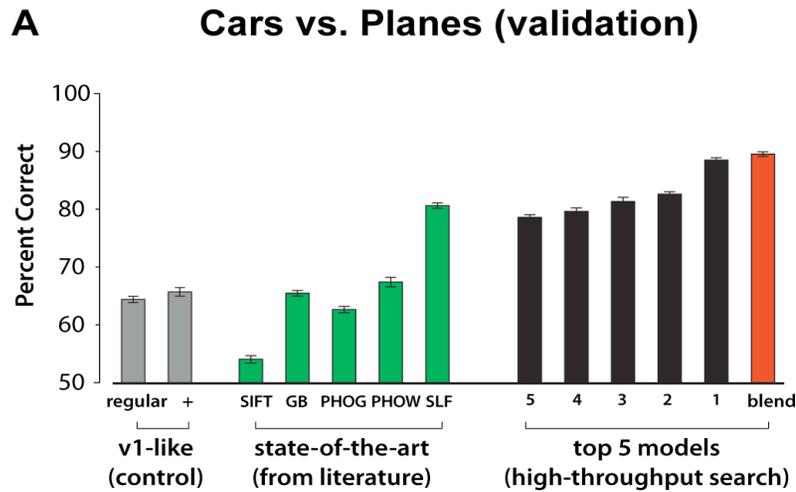


Nicolas Pinto, David Doukhan, James DiCarlo, and David Cox. A high-throughput screening approach to discovering good forms of biologically inspired visual representation. *PLoS Computational Biology*, 5(11):e1000579, November 2009.

Searching for Top Performing Models in the Long Tail



Nicolas Pinto, David Doukhan, James DiCarlo, and David Cox. A high-throughput screening approach to discovering good forms of biologically inspired visual representation. *PLoS Computational Biology*, 5(11):e1000579, November 2009.



SIFT: Scale Invariant Feature Transform [Lowe, 2004]

GB: Geometric Blur [Berg & Malik, 2001]

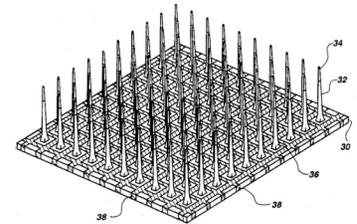
PHOG: Pyramidal Histogram of Gradients [Lazebnik *et al*, 2006]

PHOW: Pyramidal Histogram of Words [Bosch *et al*, 2007]

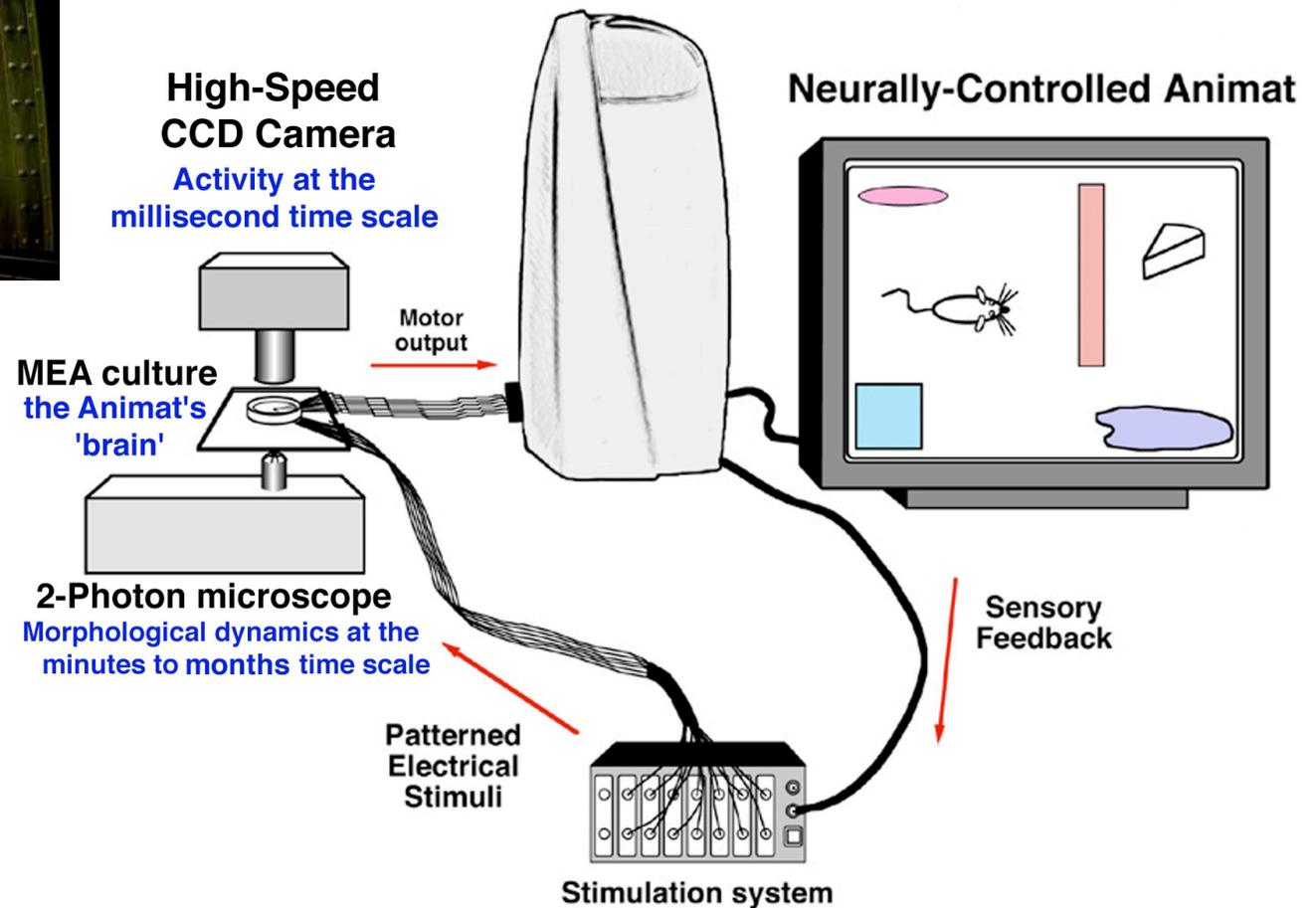
SLF: Sparse Localized Features [Mutch & Lowe, 2008]

Imaging, Recording Activity and Stimulating Cortical Tissue

- Positron Emission Tomography (PET)
- Functional Magnetic Resonance Imagery
- Single Neuron Spike Recordings
- Multielectrode Implantable Arrays
- Two-Photon Microscope Imaging
- Magnetoencephalography (MEG)
- Transcranial magnetic stimulation (TMS)

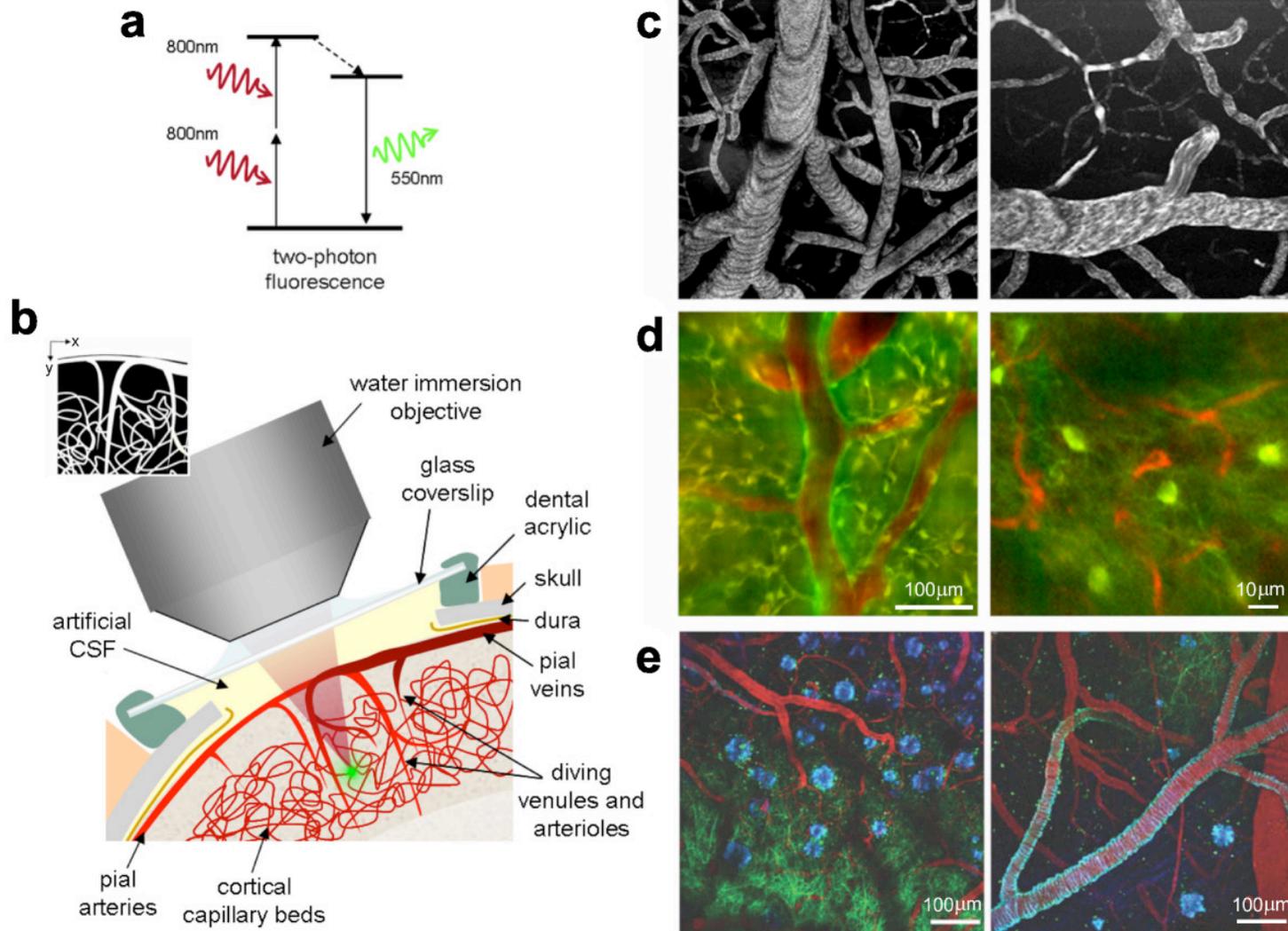


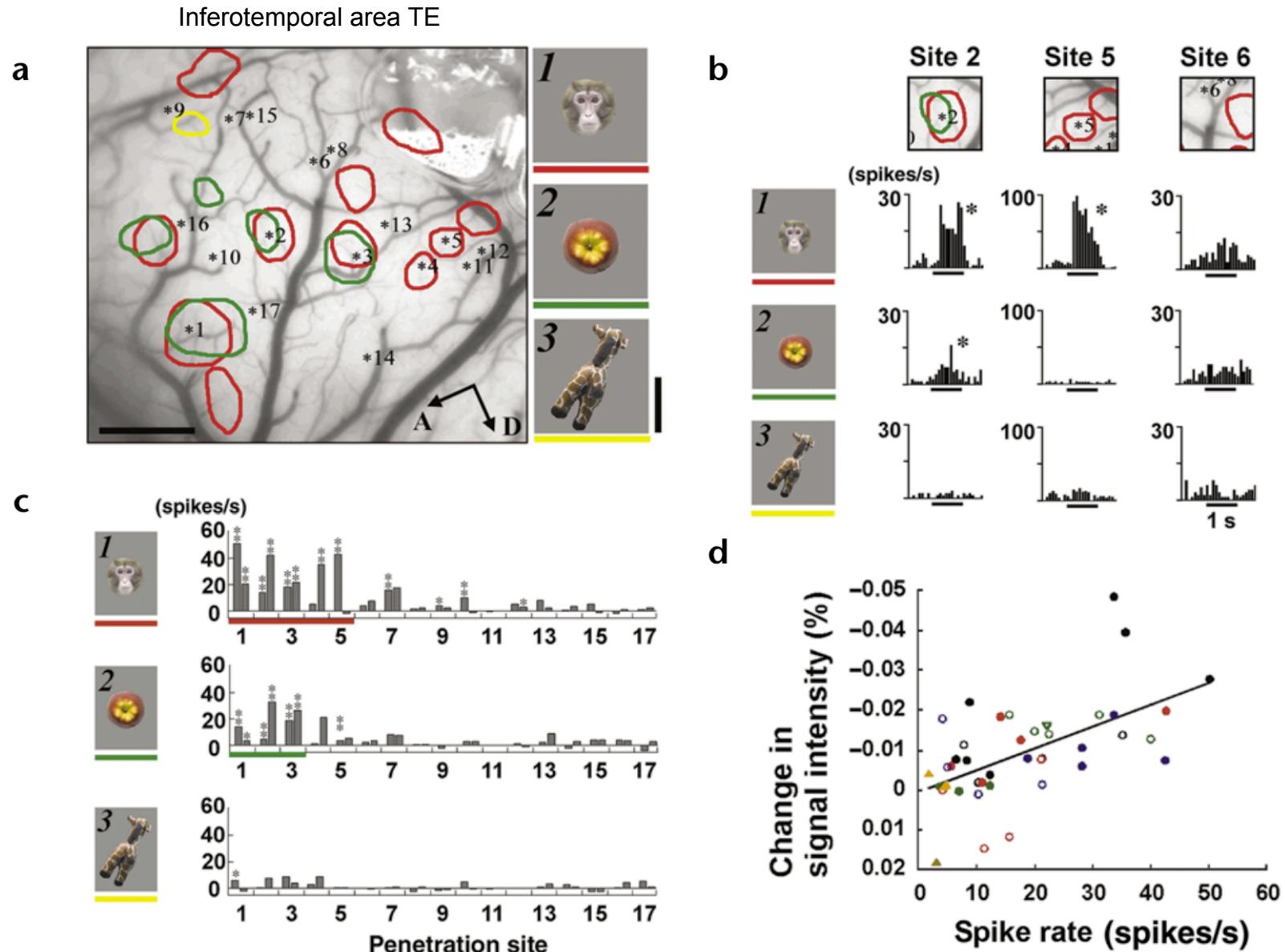
Brain in a Vat *in vitro* Experiment



Thomas B. DeMarse, Daniel A. Wagenaar, Axel W. Blau, and Steve M. Potter. The neurally controlled animat: Biological brains acting with simulated bodies. *Autonomous Robots*, 11(3):1573–7527, 2001.

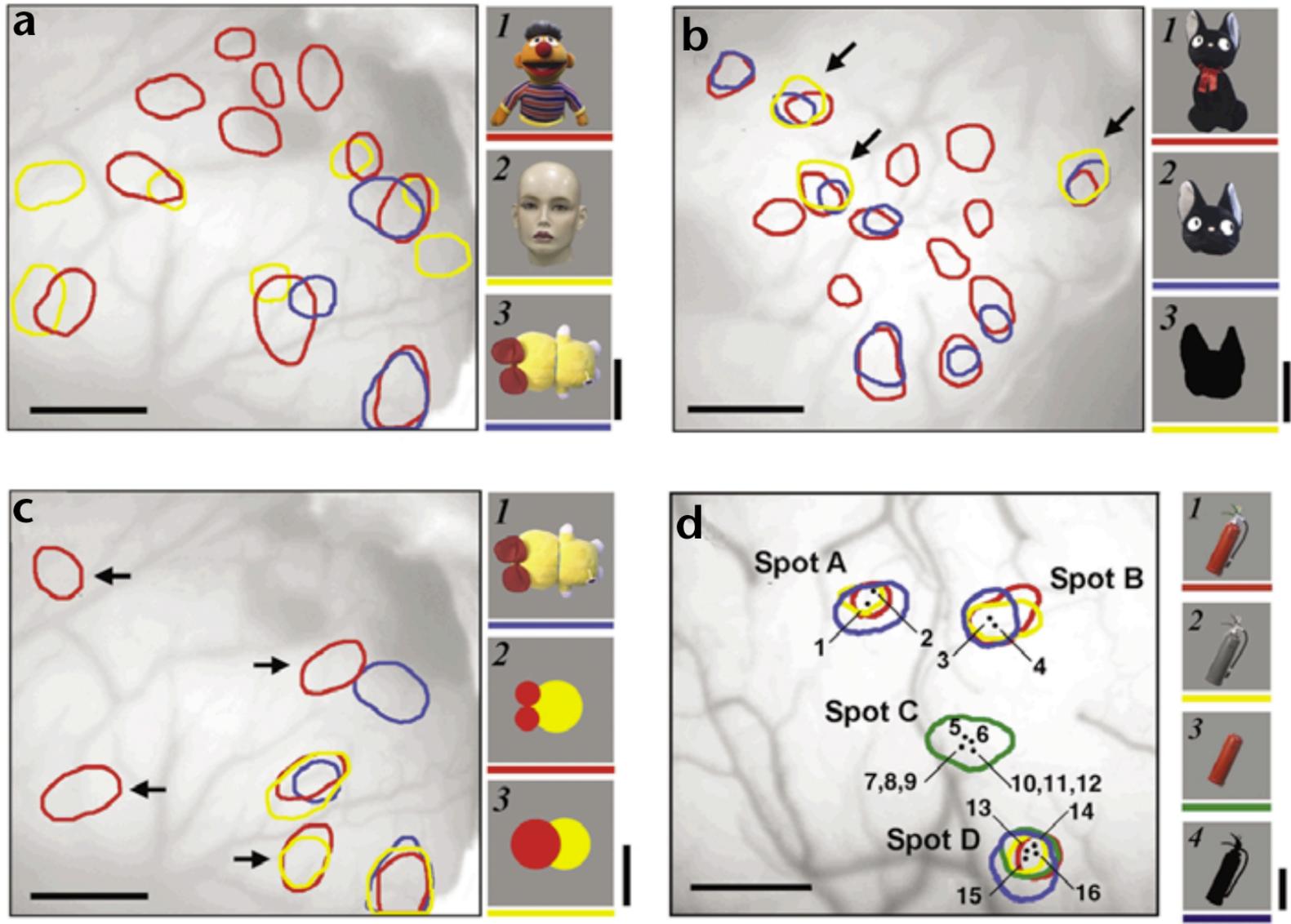
In Vivo Two-Photon Microscopy





Y. Yamane, K. Tsunoda, M. Matsumoto, N. A. Phillips, and M. Tanifuji. Representation of the spatial relationship among object parts by neurons in macaque inferotemporal cortex. *Journal Neurophysiology*, 96:3147–3156, 2006.

K. Tsunoda, Y. Yamane, M. Nishizaki, and M. Tanifuji. Complex objects are represented in macaque inferotemporal cortex by the combination of feature columns. *Nature Neuroscience*, 4:832–838, 2001.



Y. Yamane, K. Tsunoda, M. Matsumoto, N. A. Phillips, and M. Tanifuji. Representation of the spatial relationship among object parts by neurons in macaque inferotemporal cortex. *Journal Neurophysiology*, 96:3147–3156, 2006.

K. Tsunoda, Y. Yamane, M. Nishizaki, and M. Tanifuji. Complex objects are represented in macaque inferotemporal cortex by the combination of feature columns. *Nature Neuroscience*, 4:832–838, 2001.

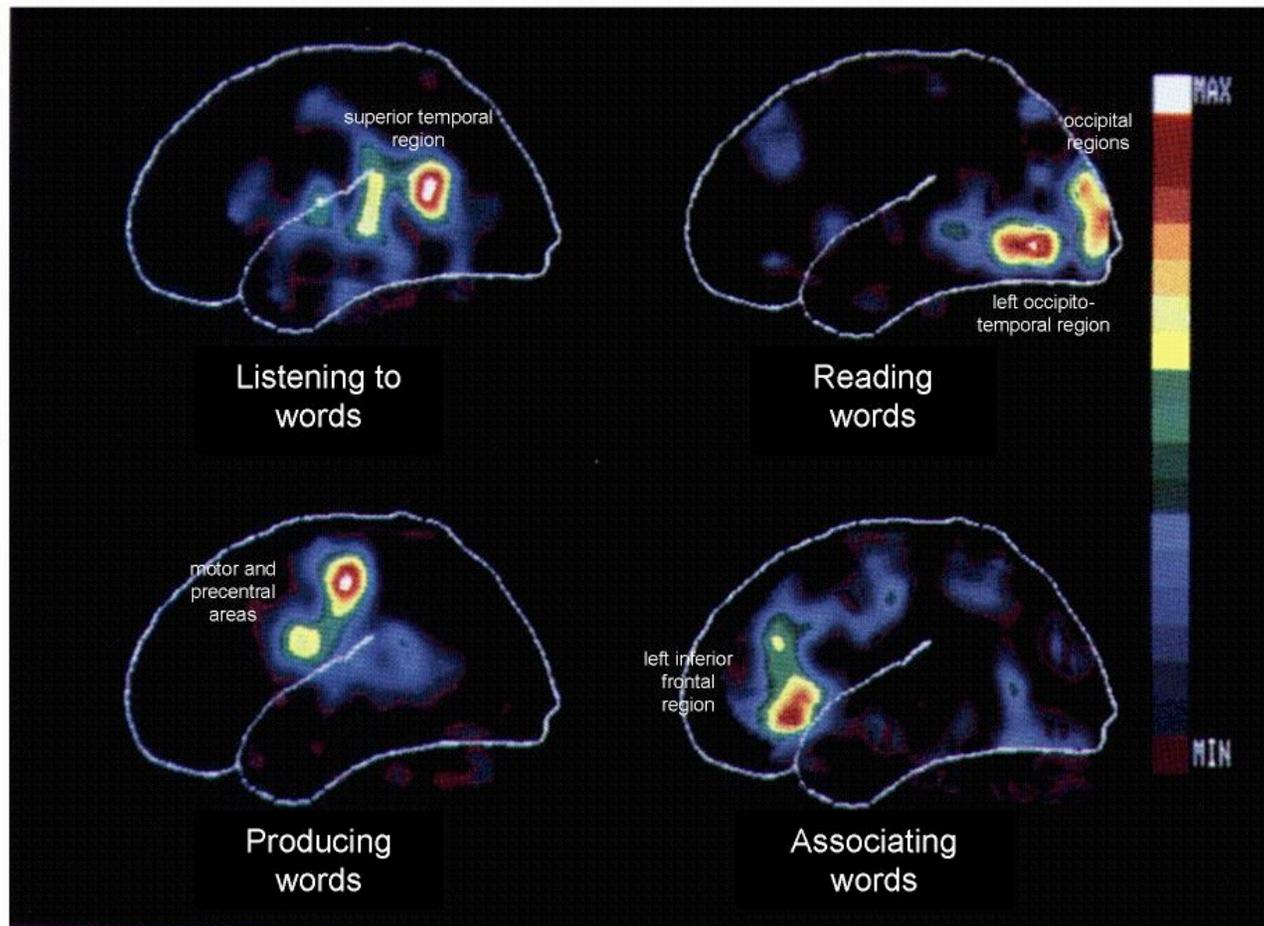


Figure 2.3. A historical image: the brain areas for language, as first revealed by PET scanning (data from Petersen et al., 1989; image courtesy of Marcus Raichle). Relative to the fixation of a small dot, silent reading (top right) activates processes of visual word recognition located in the rear part of the left hemisphere. Depending on the task, information is then transmitted to regions coding for speech sounds (top left), speech production (bottom left), or the manipulation of word meanings (bottom right).

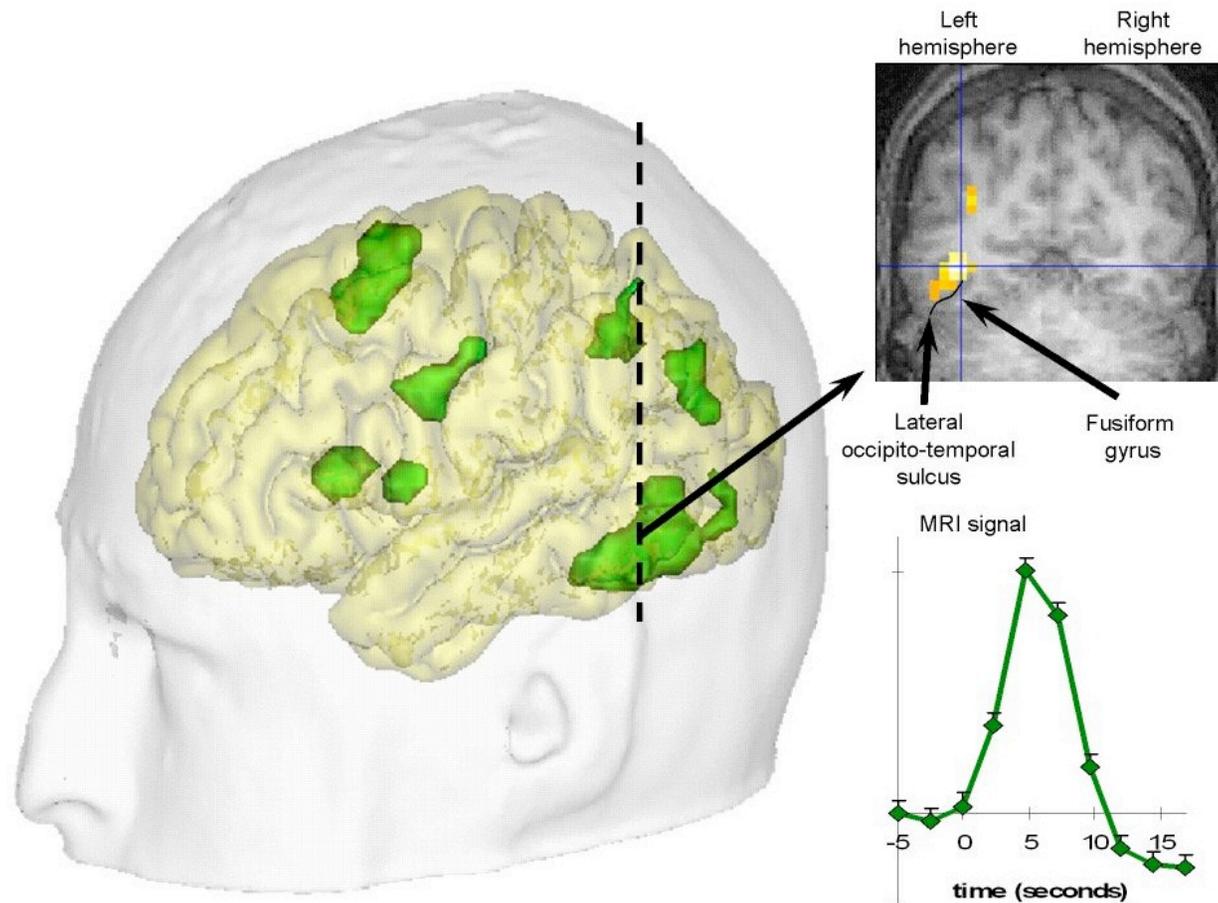
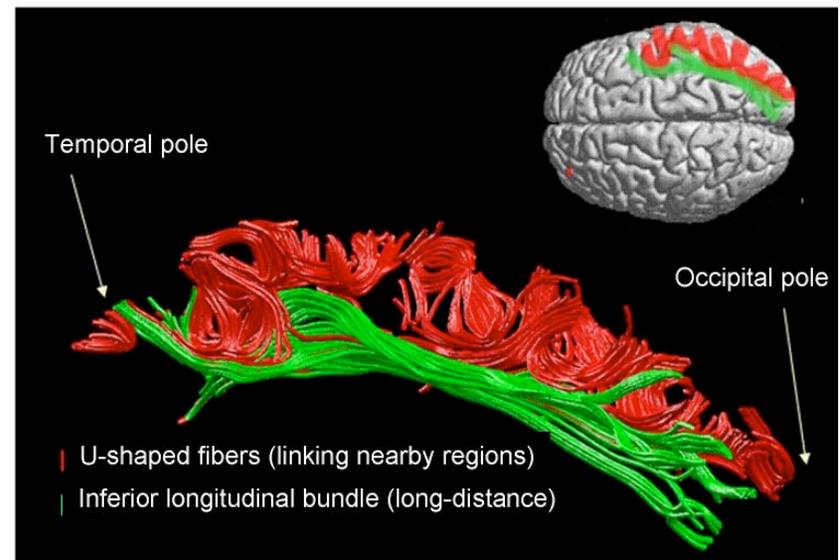
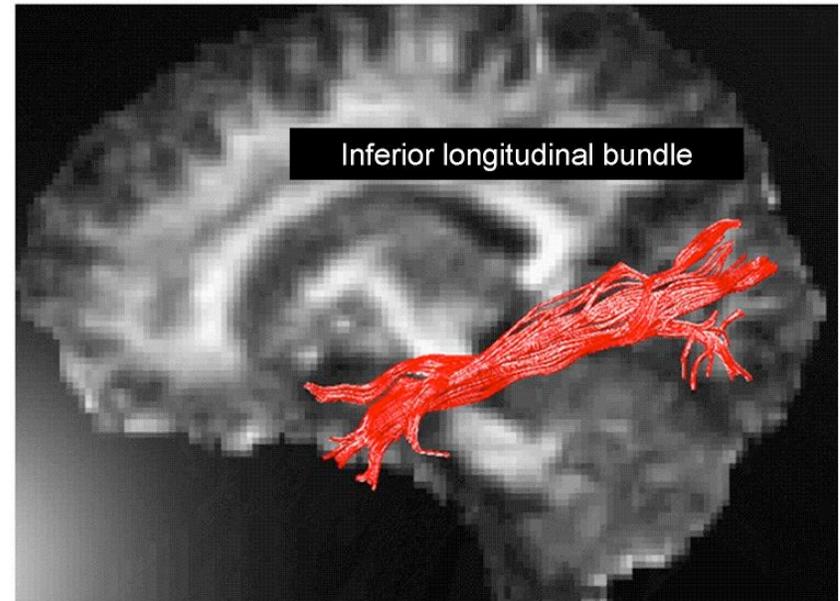
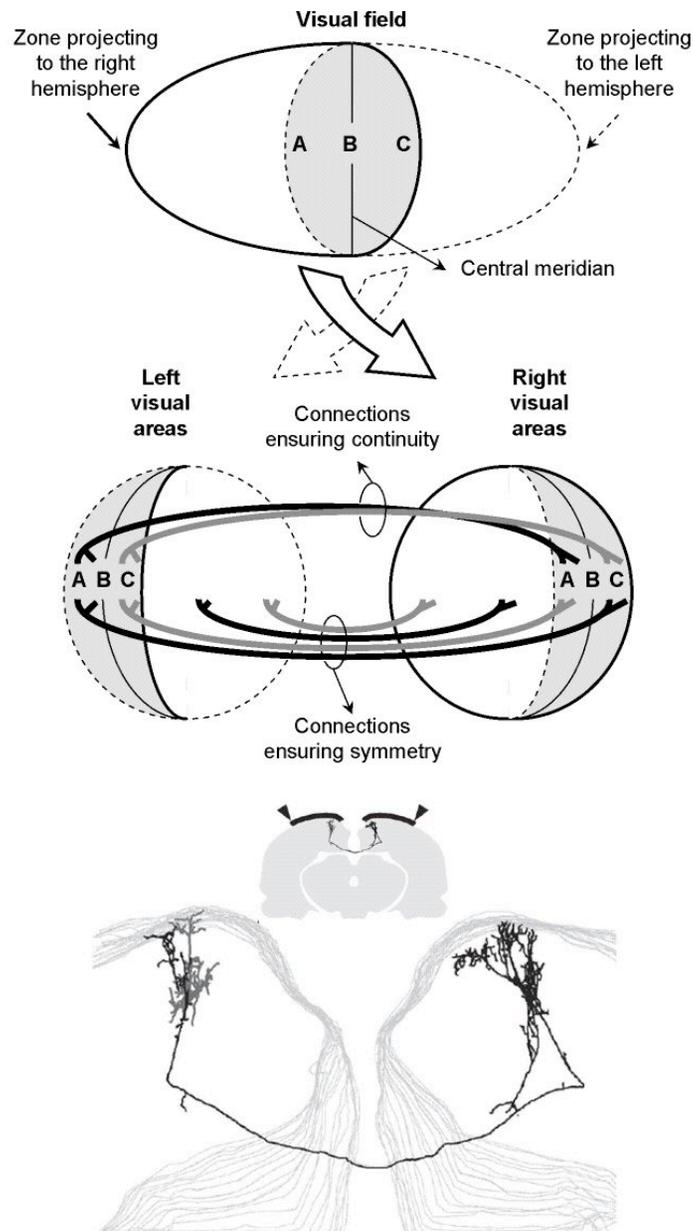


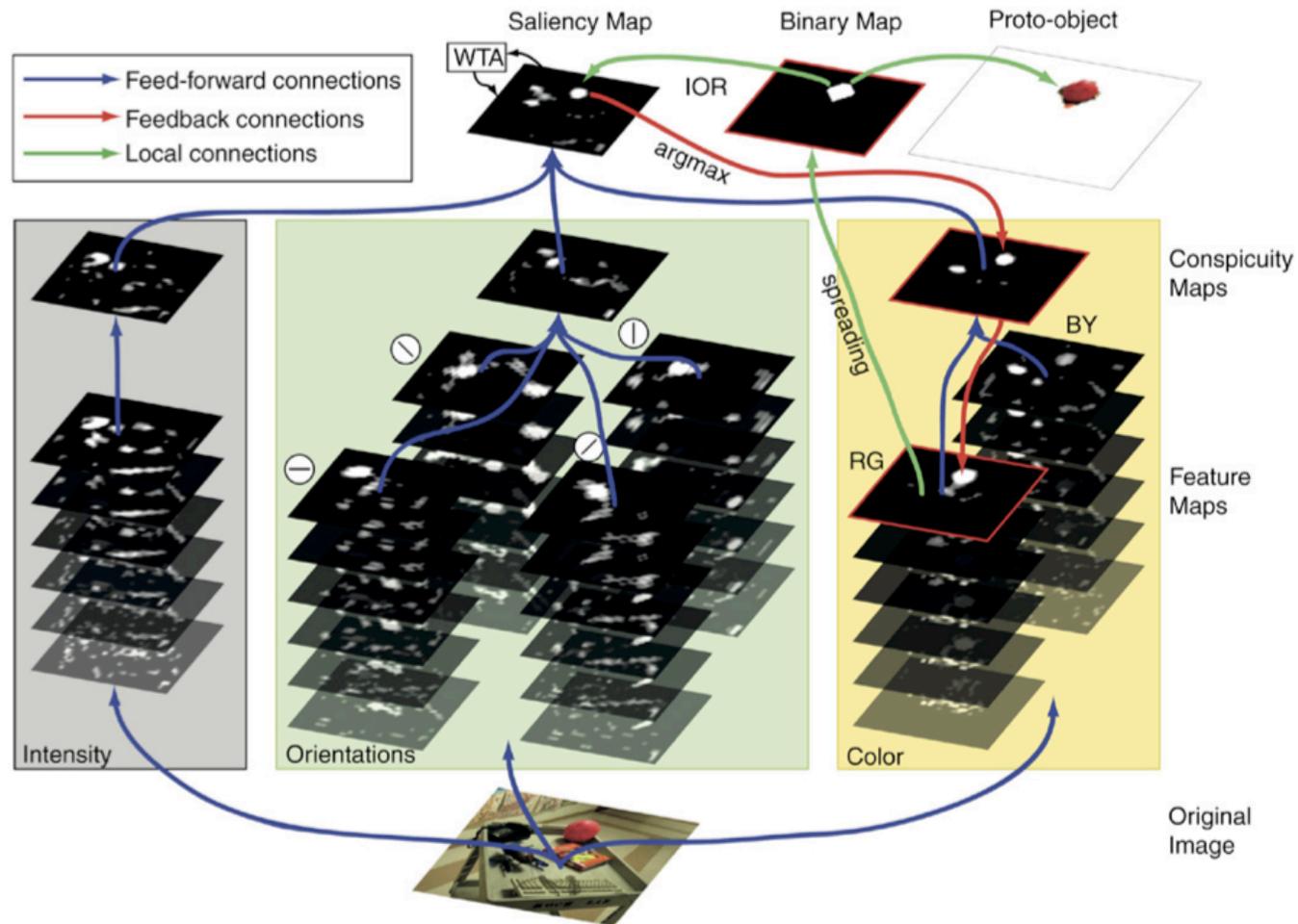
Figure 2.4. Functional magnetic resonance imaging (fMRI) can locate the brain areas involved in reading in just a few minutes. Participants read words presented at random intervals. After each word, reading areas show a characteristic increase in MRI signal which reaches a peak about five seconds later. The active network varies depending on the exact task and the nature of the control state. However, it always includes the visual word form area, the “brain’s letterbox”. This region is systematically located deep in the left lateral occipito-temporal sulcus, next to the fusiform gyrus.



Tyranny of Retinotopic Maps

- Images on the retina are ephemeral
 - Saccades, ego and other motion, *etc.*
- Integrating these fleeting glimpses
 - Stitching, remembering, inventing, *etc.*
- Moving between coordinate frames
 - Our head, body, car, bicycle, *etc.*
 - Other people, objects, locations, *etc.*

Attention and Saliency



Laurent Itti and Christof Koch. *A saliency-based search mechanism for overt and covert shifts of visual attention*. *Vision Research* 40(10–12):1489–1506, 2000.

Dirk Walther and Christof Koch. *Modeling attention to salient proto-objects*.

Neural Networks 19:1395-1407, 2006.



Free examination.

1



Estimate material circumstances of the family

2



Give the ages of the people.

3



Surmise what the family had been doing before the arrival of the unexpected visitor.

4



Remember the clothes worn by the people.

5



Remember positions of people and objects in the room.

6

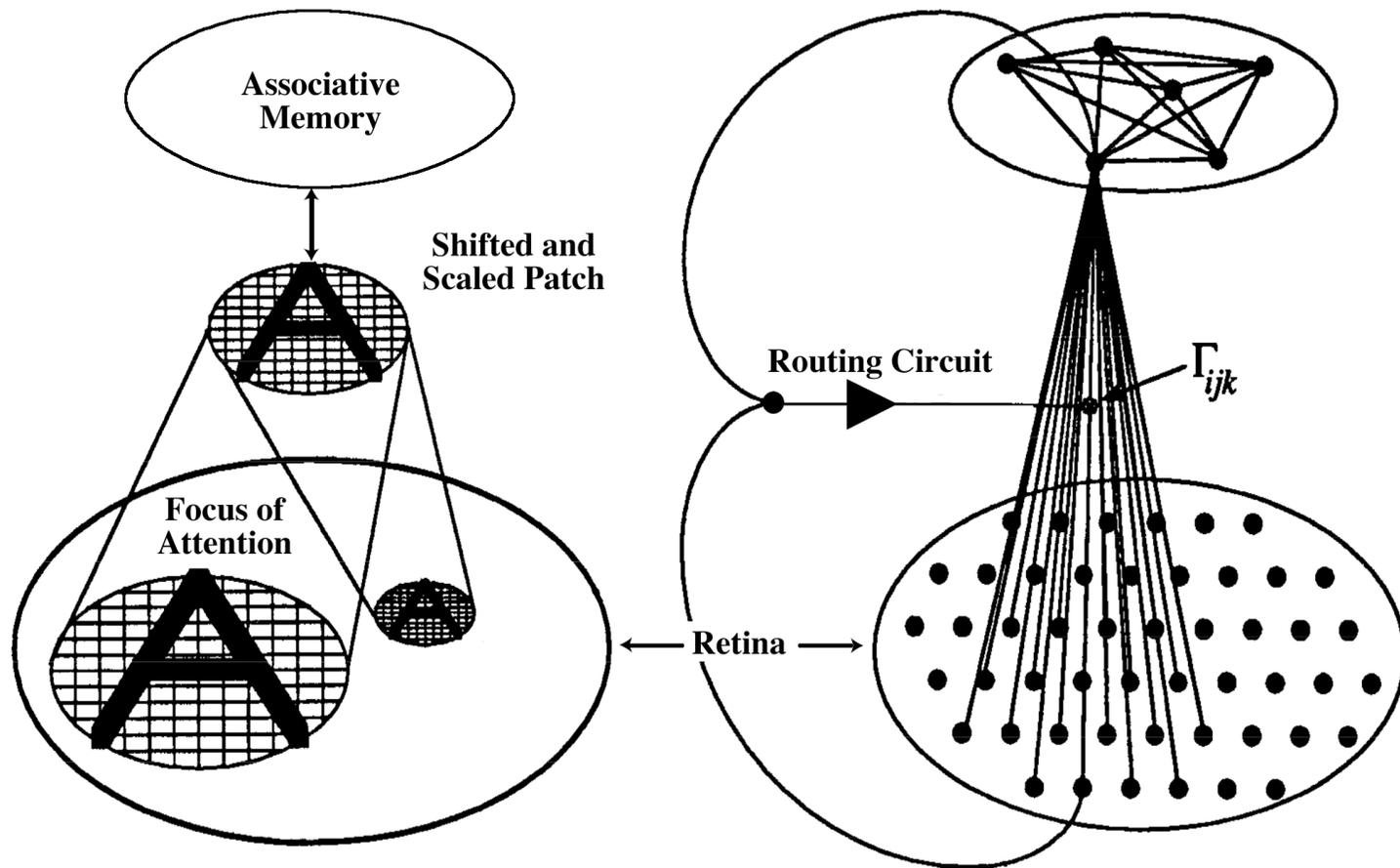


Estimate how long the visitor had been away from the family.

7

3 min. recordings of the same subject

Routing Circuit Model of Invariant Pattern Recognition

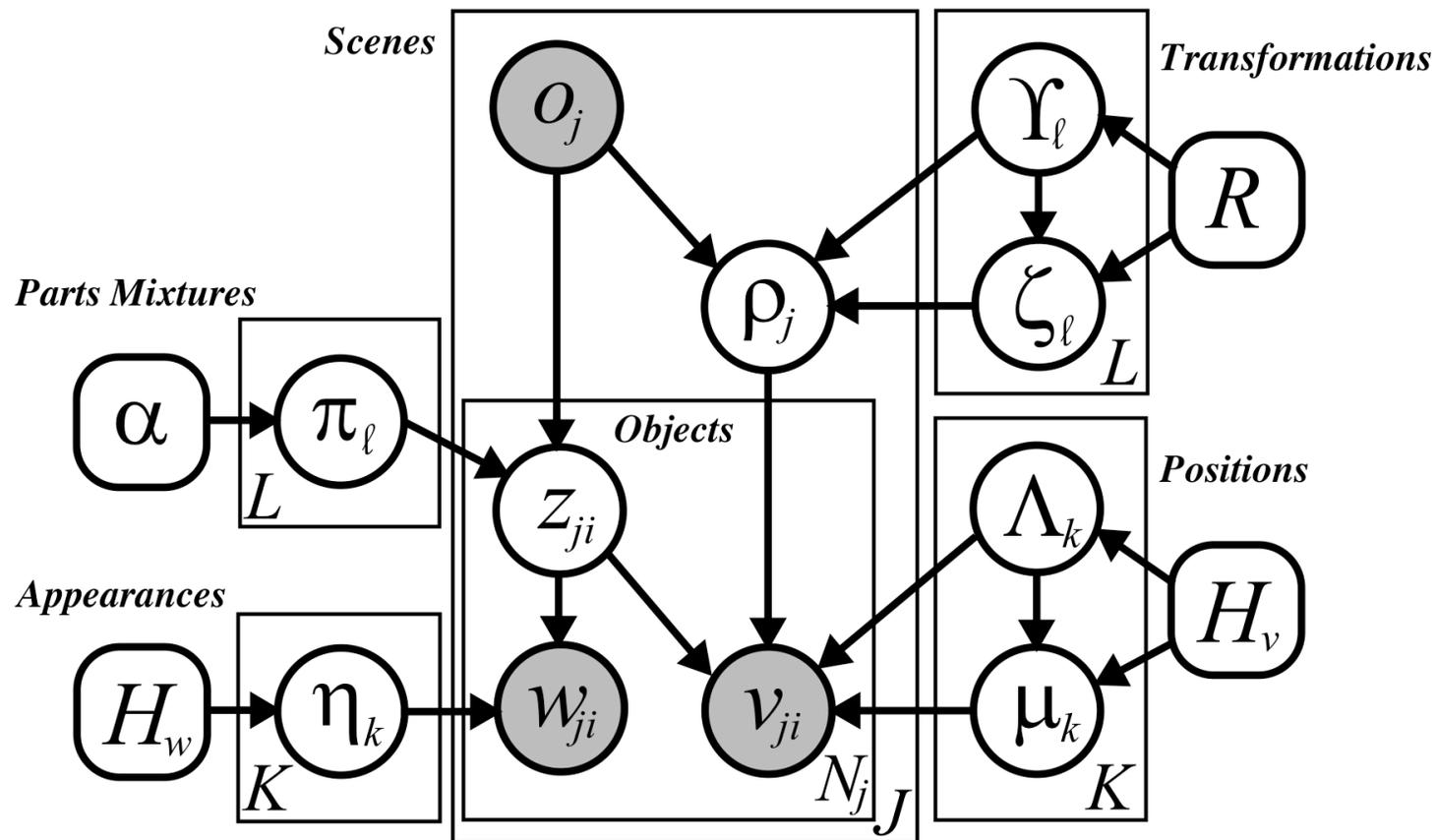


Bruno Olshausen, Charles Anderson and David Van Essen. A Neurobiological Model of Visual Attention and Invariant Pattern Recognition Based on Dynamic Routing of Information. *The Journal of Neuroscience*, November 1993, 13(11): 4700-4719.
Geoffrey F. Hinton. A parallel computation that assigns canonical object-based frames of reference. In *Proceedings of the 7th International Joint Conference on Artificial intelligence*, pages 683-685, 1981. Morgan Kaufmann.

Models and Metaphors

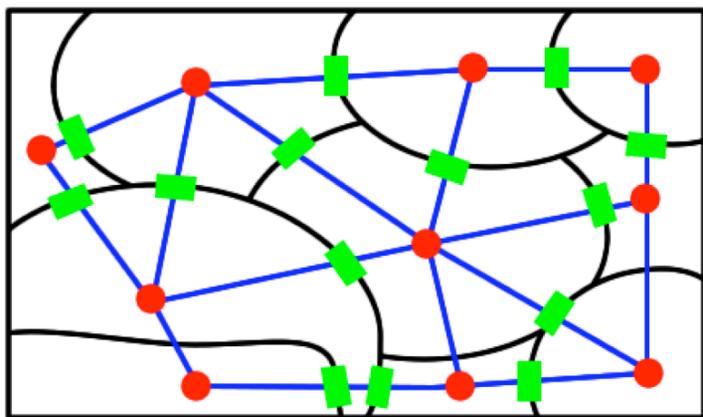
- Hydraulics — pipes, pumps, valves
- Clocks — gears, ratchets, springs
- Automata — logic circuits, computers
- Linear systems — filters, vector spaces
- Probabilistic graphical models —
 - Graphs mirror biological networks
 - Compact distributed representations
 - Computation using message passing

Modeling Shared Features with Transformed Dirichlet Processes

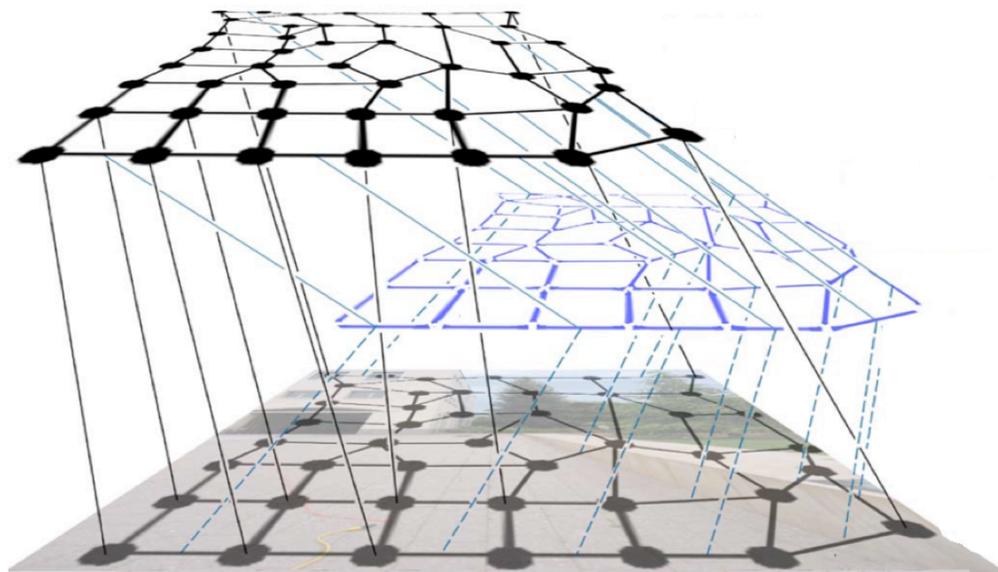


Erik B. Sudderth, Antonio Torralba, William T. Freeman, and Alan S. Willsky. Describing visual scenes using transformed objects and parts. *International Journal of Computer Vision*, 77(1-3):291–330, 2008.

Modeling Spatial Layout with Markov Random Fields



$$P(\mathbf{e} | \mathbf{x}_t) = \frac{1}{Z} \prod_i \varphi(e_i) \prod_j \phi(\mathbf{c}_j)$$

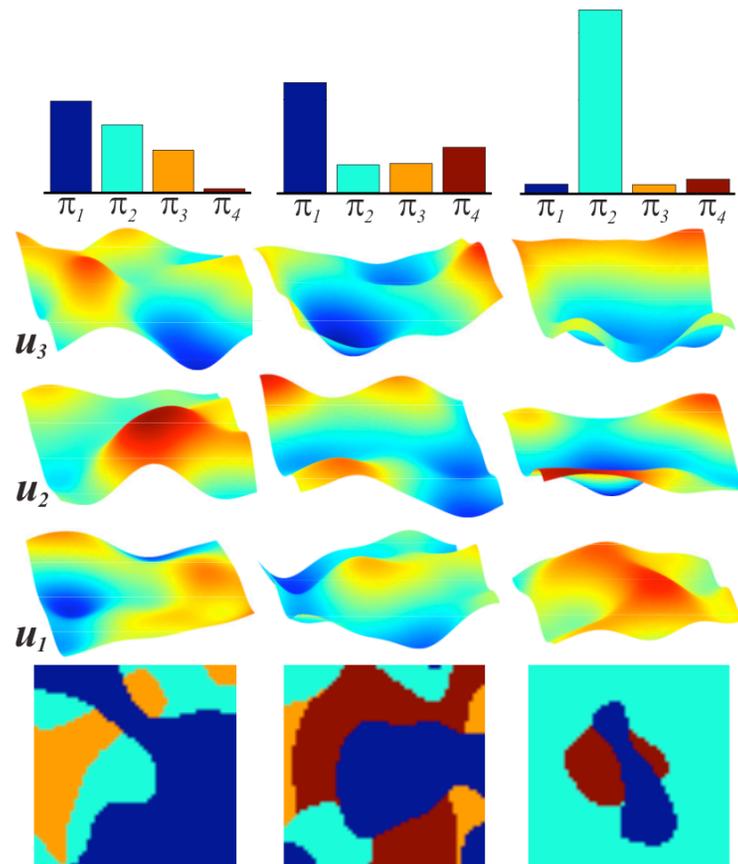


Derek Hoiem, Alexei Efros, and Martial Hebert. Putting objects in perspective. *Conference on Computer Vision and Pattern Recognition*, IEEE, 2137–2144, 2006.

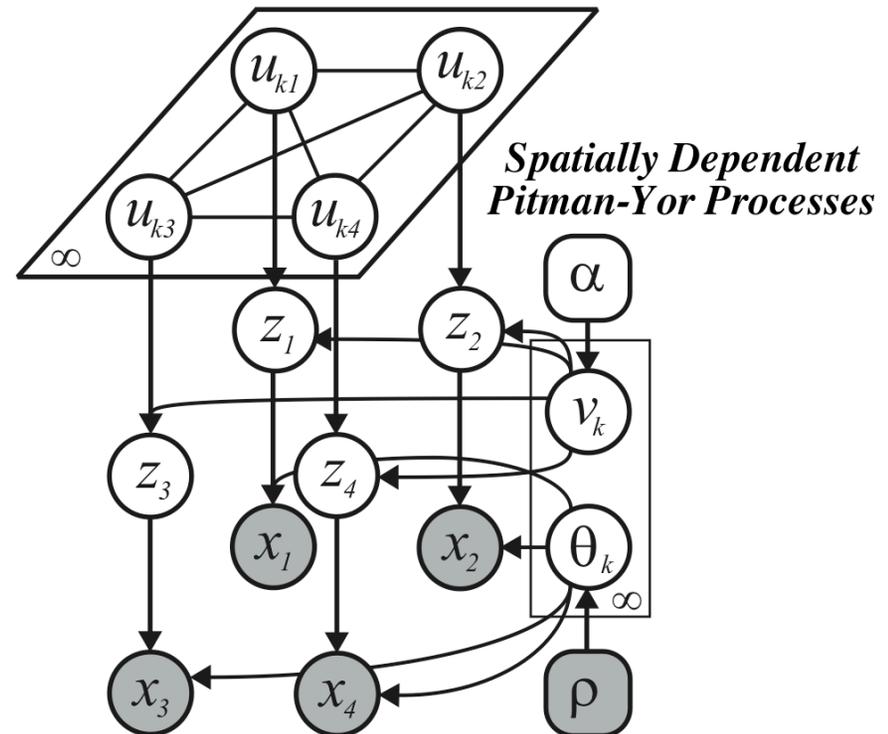
Ashutosh Saxena, Sung Chung, and Andrew Ng. 3-D depth reconstruction from a single still image. *International Journal of Computer Vision*, 76(1):53–69, 2007.

Stephen. Gould, Richard Fulton, and Daphne Koller. Decomposing a scene into geometric and semantically consistent regions. *International Conference on Computer Vision*, 2009.

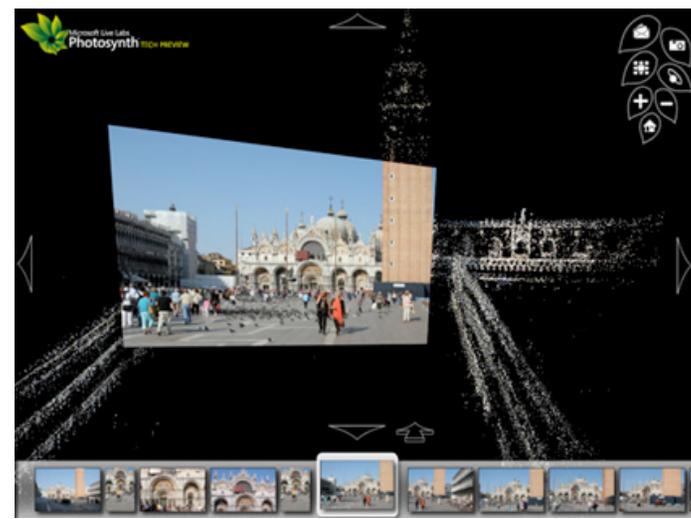
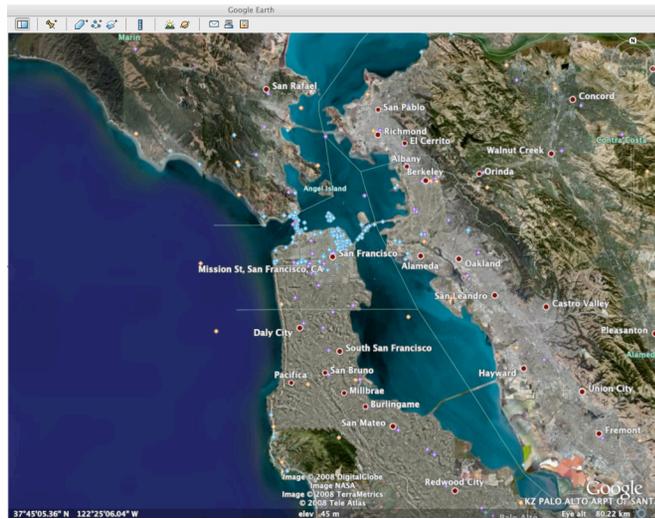
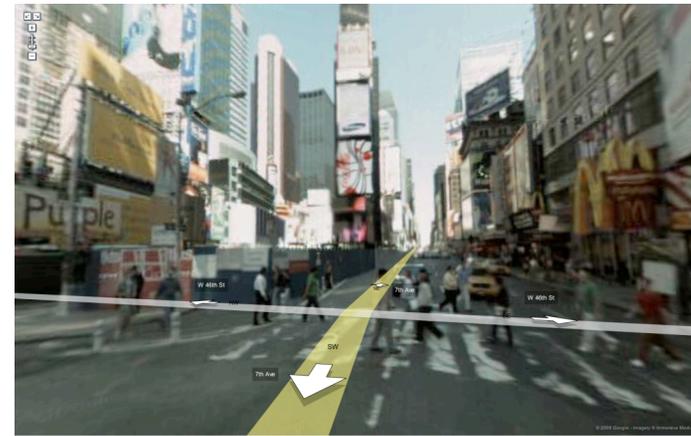
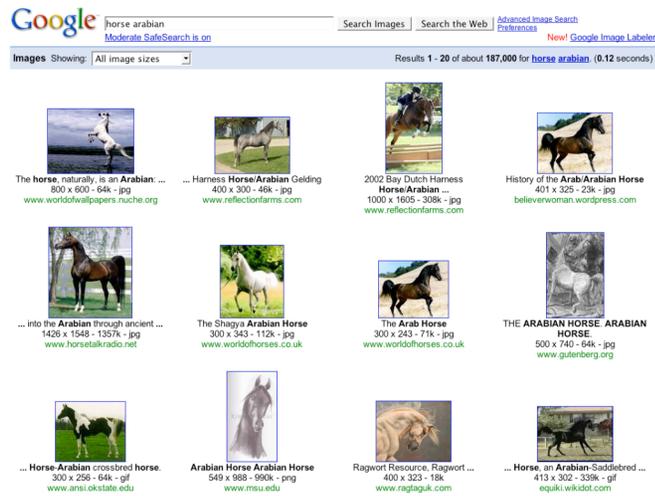
Modeling Spatial Layout with Dependent Pitman-Yor Processes



Thresholded Gaussian Processes



World Wide Visual Memory



World Wide Visual Memory

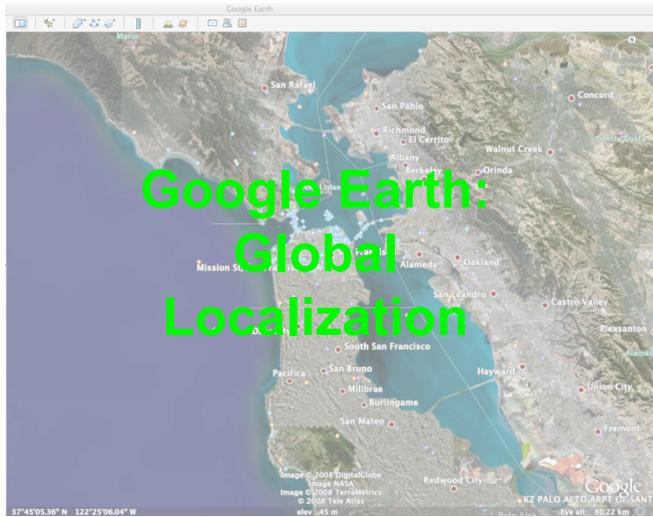
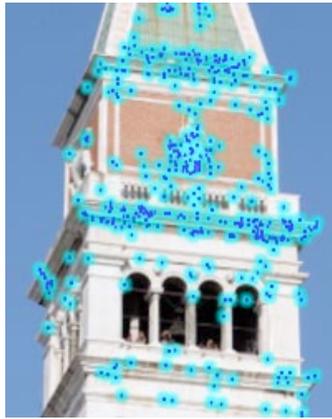


Image Stitching Writ Large

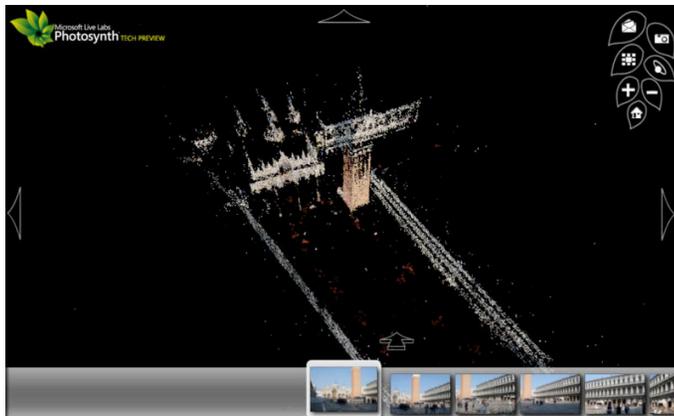
Interest Points



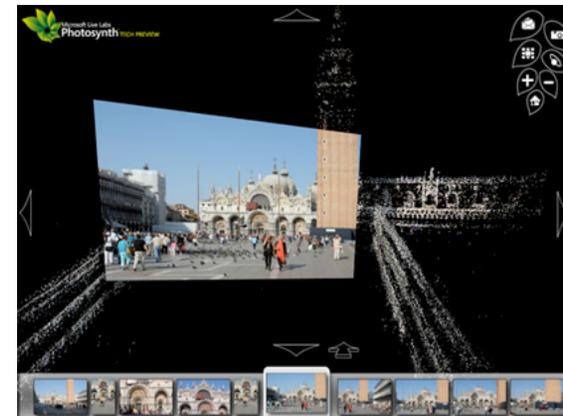
Rectification



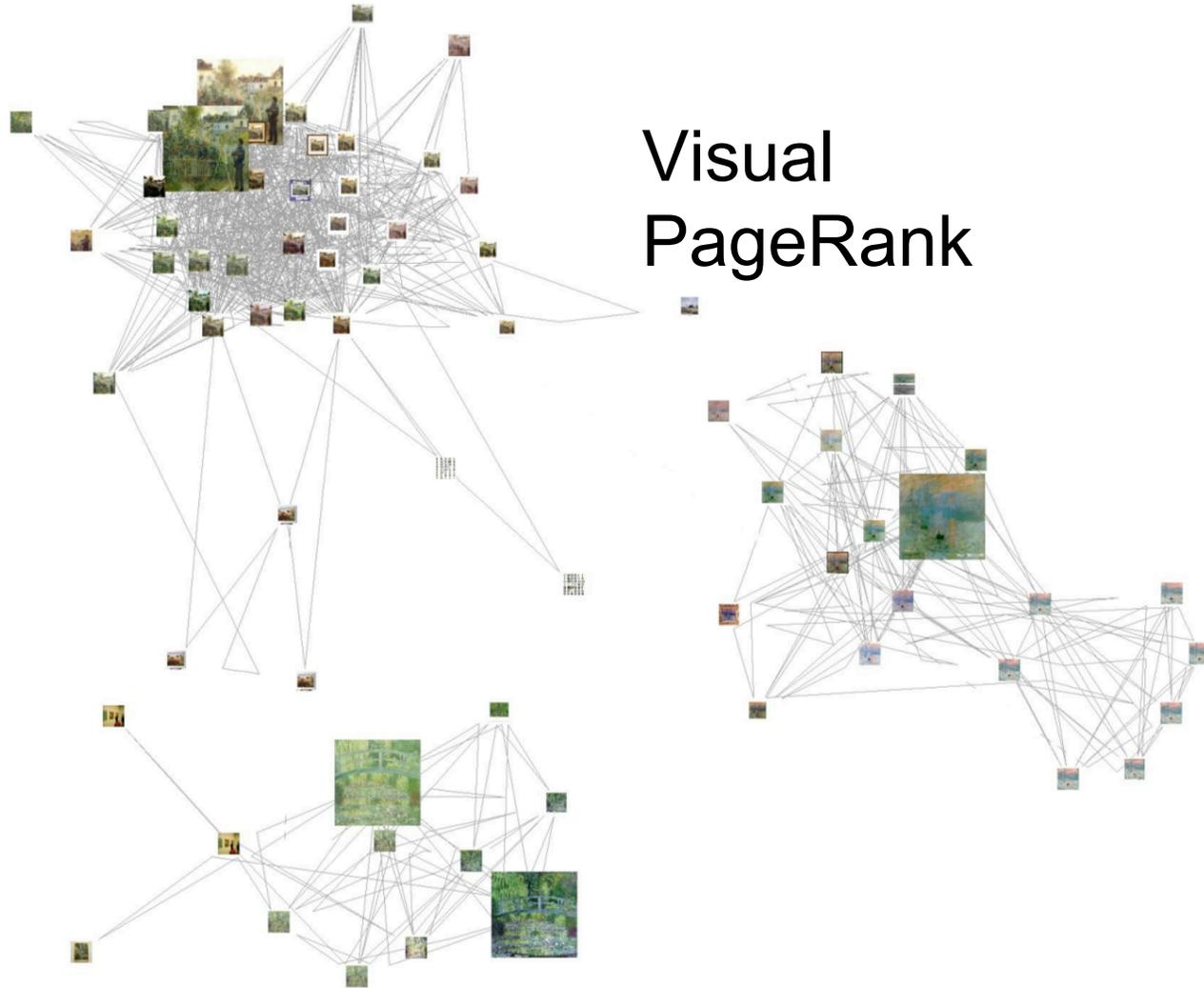
Point Clouds



Interpolation



Parallel Graph Algorithms



Jing, Yushi and Baluja, Shumeet. *PageRank for Product Image Search*. In Proceedings of the 17th World Wide Web Conference. Beijing, China, 2008.

CS379C Administrivia

- Background lectures by the instructor¹
- Student presentations on select papers
- Project discussions led by instructor
- Class grades based on
 - Class participation including presentation (20%)
 - Project proposal due around midterm (20%)
 - Project documentation and demonstration (60%)

1. I've also invited several experts to come and discuss key issues; more about this as we work out the schedule of papers and coordinate with the invitees.