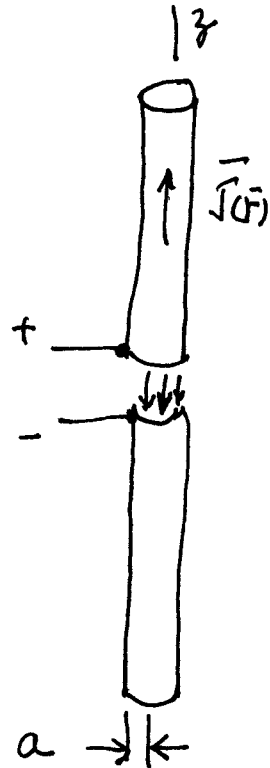


How to solve?



$$\underbrace{(\nabla_r \nabla_r + k^2) \int_{\text{vol}} \frac{\vec{J}(\vec{r}') e^{-jkR}}{4\pi R} dV'}_{\text{Pocklington's Equation}} = j\omega\epsilon_0 \vec{E}$$

Pocklington's Equation

↓

$$\int_{-l/2}^{l/2} \frac{I(z') e^{-jkR}}{4\pi R} dz' = C \cos kz - j \frac{\omega\epsilon_0 \sin k|z|}{2k}$$

$$R^2 = a^2 + (z - z')^2 \quad *$$

Hallen's Equation

* current on z-axis,
observation point on dipole, or v.v.

Solutions to Hallen's Integral Equation

Rewrite equation in the form

$$\int_0^{a/2} G(z, z') I(z') dz' = C \cos kz - \frac{j k^2 \sin kz}{2\eta}$$

$$\text{where } G(z, z') = \frac{e^{-jkr}}{4\pi r} + \frac{e^{-jkr'}}{4\pi r'}$$

$$r = \sqrt{a^2 + (z - z')^2}, \quad r' = \sqrt{a^2 + (z + z')^2}$$

Moment Method Soln

$$\int_a^b G(z, z') f(z') dz' = g(z) \quad \text{F. H. 1st kind}$$

Expand $f(z) \approx c_1 f_1(z) + c_2 f_2(z) + \dots + c_N f_N(z) = \hat{f}(z)$

$f_n(z)$ are basis functions chosen heuristically —

$$\underbrace{\sum_{n=1}^N c_n \int G(z, z') f_n(z') dz'}_{\hat{f}(z)} \approx g(z)$$

Progressing of form of $\hat{f}_N(z)$ because of the integration. /...

/...

While the true sol'n $f(z)$ gives equality for every value of z , $\hat{f}(z)$ cannot do so. But it can do so approximately.

This approach is a gross simplification of classical orthogonal expansions, such as Fourier expansions.

It is also extremely efficacious !!
(and pretty accurate as well)

Point Matching Solution - the grossest form of
 MoM - enforces equality at fixed points,
 z_m ,

$$\sum_{n=1}^M c_n \int_a^b G(z_m, z') f_n(z') dz' = g(z_m)$$

$$\sum a_{mn} c_n = \underline{b_m}, \quad \underline{c_n} \text{ are } \underline{\underline{\text{unknowns}}}$$

$$a_{mn} = \int_a^b G(z_m, z') f_n(z') dz', \quad b_m = g(z_m)$$

in this case.

match point
 index

source point index

/...

Galerkin's Method

$$w_m = f_m$$

Point - Matching method

$$w_m(z) = \delta(z - z_m)$$

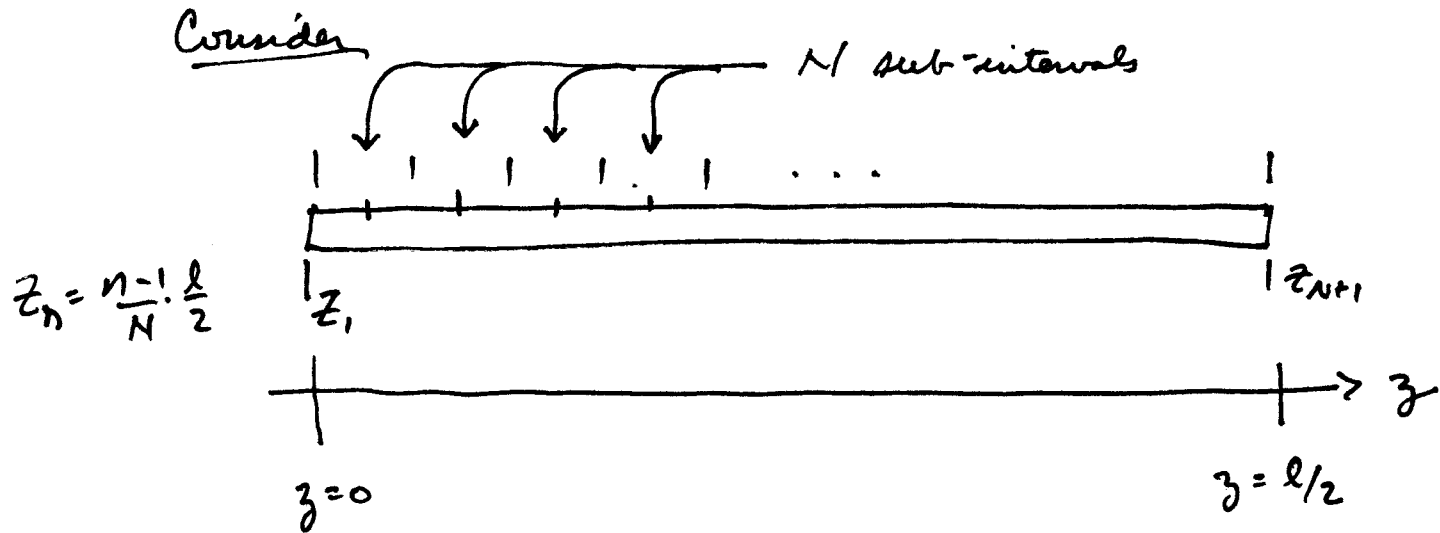
But other choices are possible .

MOM

- based on mathematics of linear vector spaces and includes the theory of errors
- still an active area of research
- generally validated by experiments
- being displaced by finite element methods
 - sparse matrices
 - efficient computation.

Example: Application to Hallen's Eq. for dipole.

Consider



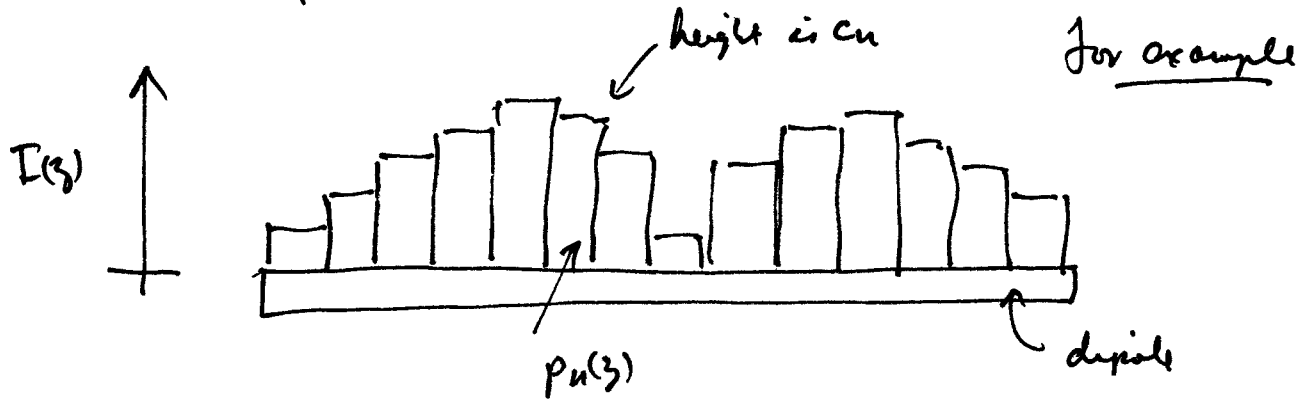
$\Delta z_n = z_{n+1} - z_n$ is n^{th} sub-interval

Use sub-sectional basis functions \rightarrow
$$p_n(z) = \begin{cases} 1 & z \in \Delta z_n \\ 0 & z \notin \Delta z_n \end{cases}$$
 } these are just pulses !!! /...

/...

$$\text{So } I(z) \approx \sum_{n=1}^N c_n p_n(z) \quad \begin{array}{l} \text{not a complete} \\ \text{set -} \\ \text{but an orthogonal} \\ \text{set!} \end{array}$$

We will attempt to solve for current on the dipole in terms of the stepped pulse approximation. This corresponds physically to an approximation by a series of ideal dipoles



/...

How to form the equations

choose z_m at midpoints of Δz_n .

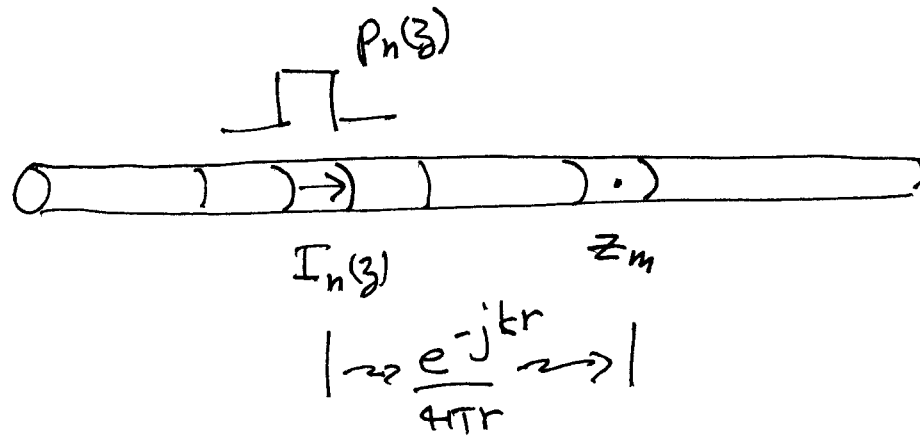
$$z_m = \left(\frac{2m-1}{2N}\right) \frac{l}{2}$$

divide length into $2N$
intervals and then take only
the odd points, beginning with 1.

$$\sum_{n=1}^N c_n \int_0^{l/2} G(z_m, z') p_n(z') dz' = \underbrace{C \cos k z_m - \frac{j \sin k |z_m|}{z_m}}_{A_3(z_m)}$$

$$a_{mn} = \int_{z'_n}^{z'_{n+1}} G(z_m, z') dz'$$

/...



Sum of all such effects, $P_n(z)$ on $A_z(z_m)$
 must equal total $A_z(z_m)$

∴ ...

$$\begin{bmatrix} a_{11} & a_{12} & a_{13} & \dots & a_{1N} \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ a_{N1} & & & & a_{NN} \end{bmatrix} \begin{bmatrix} C_1 \\ \vdots \\ C_N \end{bmatrix} = \begin{bmatrix} C \cos k z_1 - \frac{j\mu}{2\eta} \sin k|z_1| \\ \vdots \\ \vdots \\ \vdots \end{bmatrix}$$

B.C. is $C_N = 0$

So this can be re-arranged and simplified further, as ...

/...

$$\begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1N-1} & d_1 \\ a_{21} & a_{22} & \cdots & a_{2N-1} & d_2 \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ a_{N1} & a_{N2} & \cdots & a_{NN-1} & d_N \end{bmatrix} \begin{bmatrix} c_1 \\ c_2 \\ \vdots \\ c_{N-1} \\ G \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2 \\ \vdots \\ b_N \end{bmatrix}$$

$$d_m = -\cos k z_m$$

$$b_m = -j \frac{\mu}{2\eta} \sin k z_m$$

↑ here is unknown
C from expression
for $A_z(z)$.

Find c_1, \dots, c_{N-1}, G by standard methods.

↓