

EE 252 YAGI-UDA ARRAYS

S&T Y-U ARRAYS, SECTION . 5.4

MUTUAL "Z," SECTION . 3.6

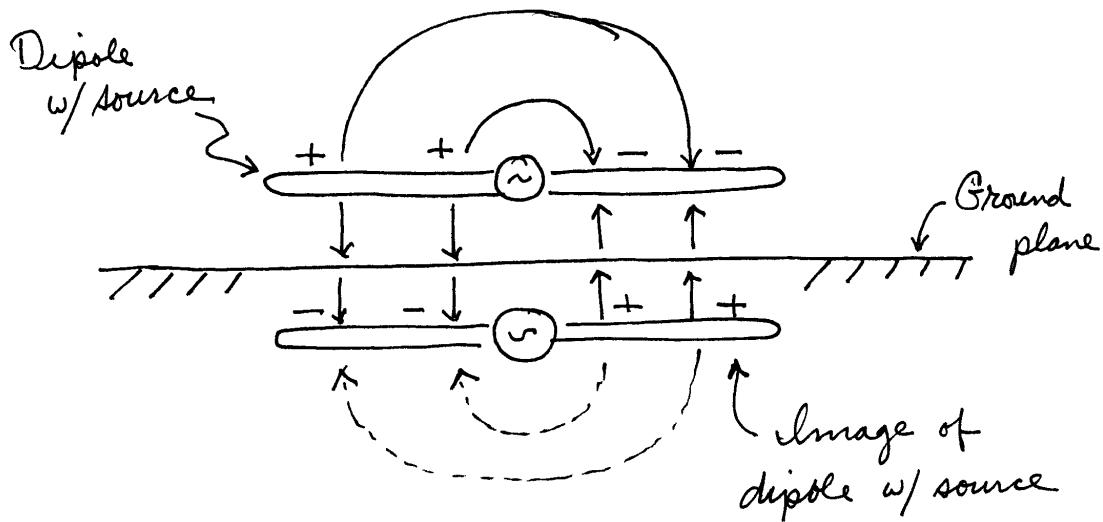
KRAUS Y-U ARRAYS, SECTION 11.9

MUTUAL "Z," SECTIONS 10.4-10.9

All that we say about this you can confirm
by MOM methods!

Yagi-Uda Arrays are both commonly
employed antennas and an instructive
lesson in applied electromagnetics. Beyond
this, they also form a jumping-off point
for understanding a large class of very
wideband antennas known as log-periodic
antennas or log-periodic structures. For
these reasons we will attempt to develop
a firm physical understanding of the
Yagi-Uda example.

Consider first the situation in which an active dipole element is brought close to a large, plane conductor.



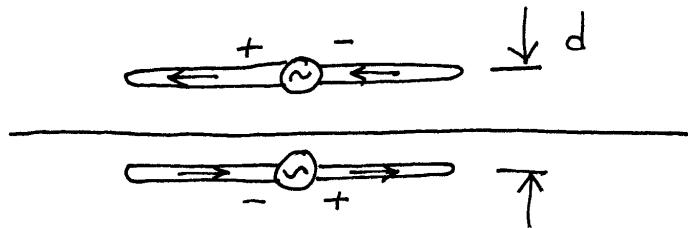
/...

behaves as 19-4

In the above, the "image" is a "coupled" parasitic element coupled by fields to the source. Above the ground plane the effective radiation is from the combination of the dipole and its image. While in the figure we only represent the charge on the dipole, note that the sign of the charge is reversed in the lateral direction. Hence, the direction of the horizontal dipole current and the image current are reversed!
horizontal

/...

What do you expect will occur as the separation between the dipole and ground plane is reduced to zero?

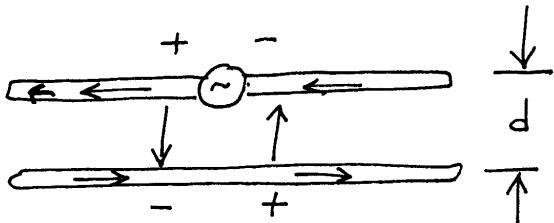


As $d \rightarrow 0$

- i) Radiation fields from dipole and image cancel.
- ii) Z_{11} decreases (input impedance to dipole)
- iii) R_{rad} decreases (effectively, for dipole + image)

/

What about two identical dipoles — one with and one without a source?

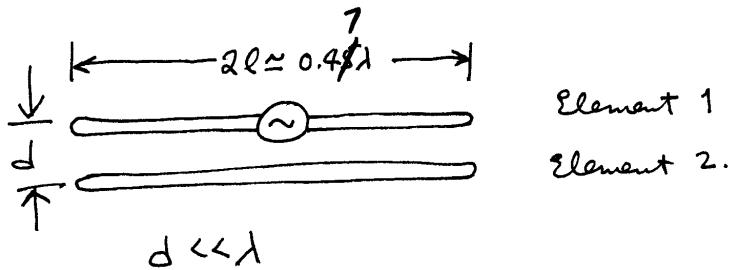


We expect \sim equal and opposite currents on the second member relative to the driven element; for very close spacing the currents become almost equal. (Recall Pocklington's Equation and apply it in this situation.) Also expect symmetry to develop!

Pattern of Two Closely Spaced Elements

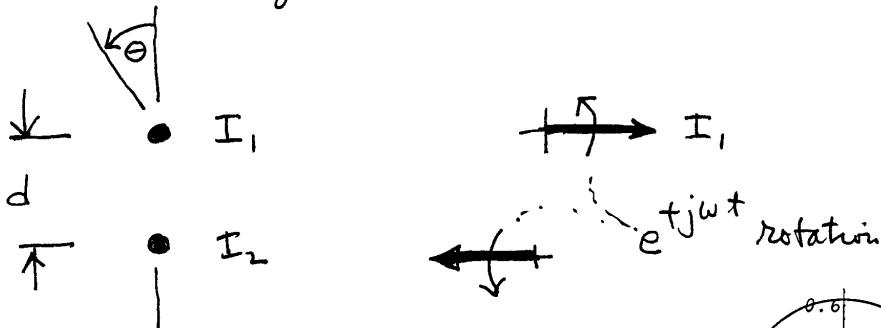
19-7

Assume resonance, identical elements.



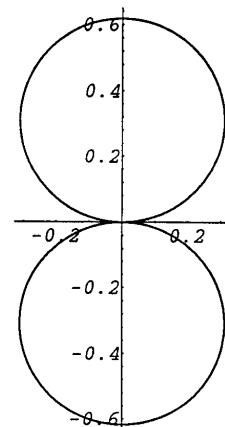
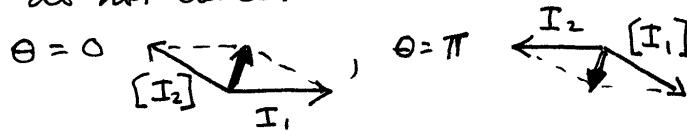
These two elements form a very closely spaced array driven by very nearly equal but oppositely directed currents. Perpendicular to the array axis the effects of these currents cancel; along the axis they do not quite do so.

So the array is configured like*



for $\Theta = \pm \frac{\pi}{2}$, the effects of I_1, I_2 cancel. The phasor diagram is \leftrightarrow .

for $\Theta = 0, \pi$, the effects of I_1, I_2 do not cancel



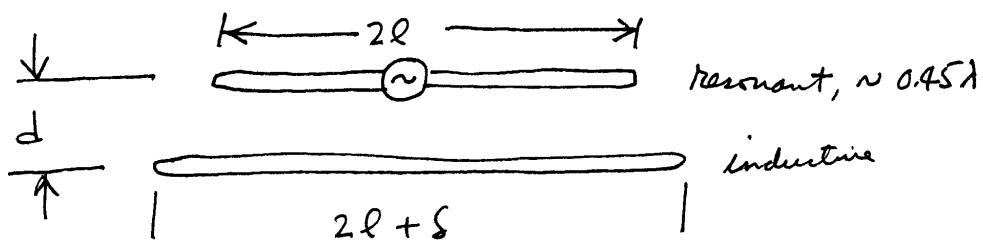
* the elements would be horizontal in this figure

Array Pattern Factor

19-8

In the above [] signifies a retarded quantity. For purpose of illustration I_1 is taken as the reference phasor for $\theta = 0$, while I_2 is used as the reference for $\theta = \pi$. Note that the $\theta = \pm \pi/2$ nulls are associated with the array factor. There is also a null in the element patterns at $\theta = \pm \pi/2$, because this is the direction of orientation of the dipoles and there is no radiation off the ends.

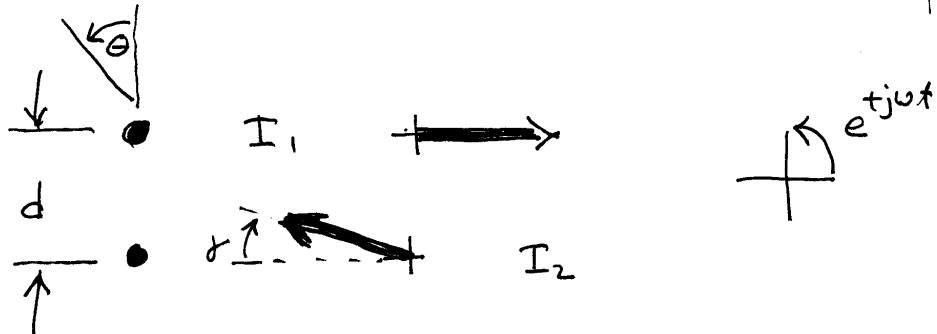
Now suppose that we change the length of the parasitic, or passive element? The new situation is



An element slight longer than the resonant length is "inductive" in that the current lags the applied \bar{E} field. The excitation is primarily through \bar{E} coupling, so I_2 now lags its previous phase. /...

So now our array and its excitation "looks like"

19-11



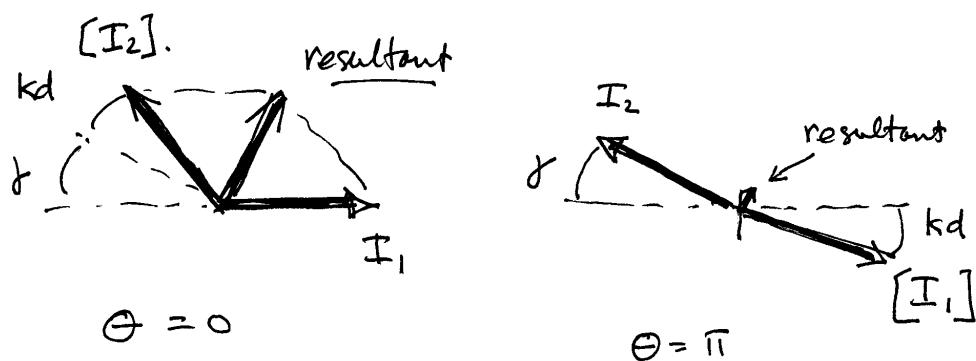
I_2 lags by γ .

The result of this is to introduce asymmetry into the pattern, thus creating a "beaming" effect in the $\theta = 0$ direction relative to $\theta = \pi$.

To see how this works, draw the phasor

19-12

diagram for $\theta = 0, \pi$



for $\theta = \pi$, the kd retardation of I_1 moves I_1 toward the $-I_2$ location. The "sign" of the resultant depends on relative values of γ and kd .

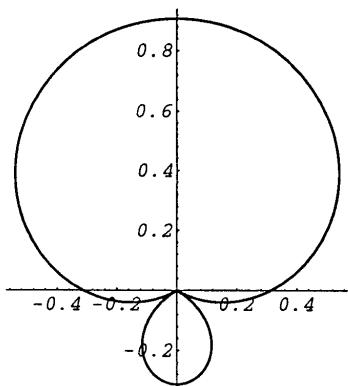
The figure at the right depicts the magnitude of the array factor for

$\gamma = -9^\circ$, $kd = 36^\circ$; and equal magnitude I_1 and I_2

Note that the null is located at $\Theta \approx \pm 100^\circ$; it need not be at $\pm 90^\circ$. (For $|H| > kd$ there is no null!).

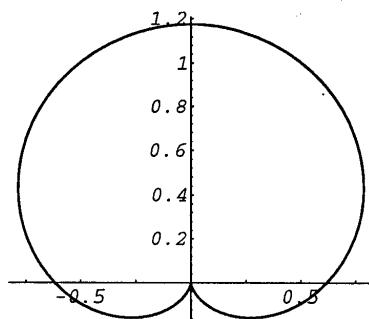
Because the beam is formed in the direction opposite the location of the passive element, this element is called a reflector.

Here are two more examples of dipole + ^{array} reflector patterns



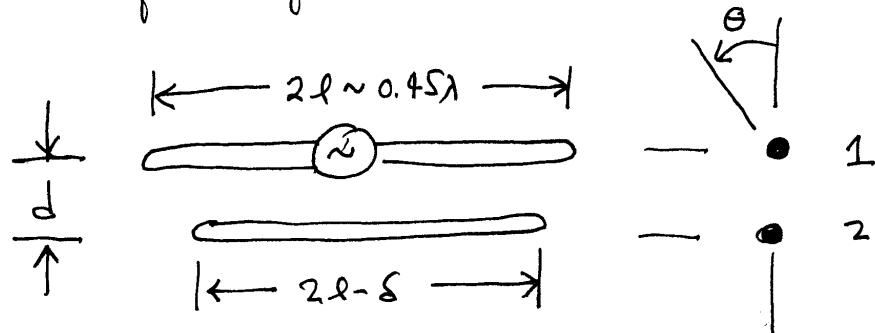
$$\gamma = -18^\circ$$

$$kd = 36^\circ$$



$$\gamma = -36^\circ$$

What if we repeat the analysis, this time for a passive element that is shorter than that required for resonance? 19-15



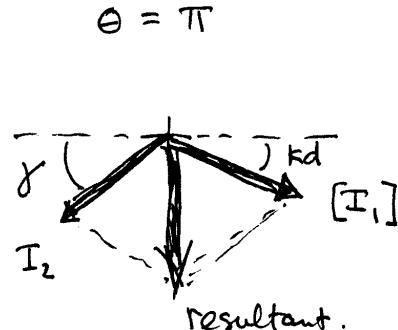
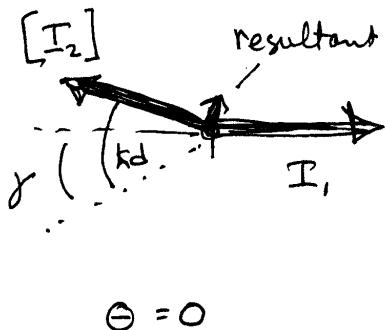
Now we find the relative currents to have

I_2 phase advanced
by γ

$$I_1$$



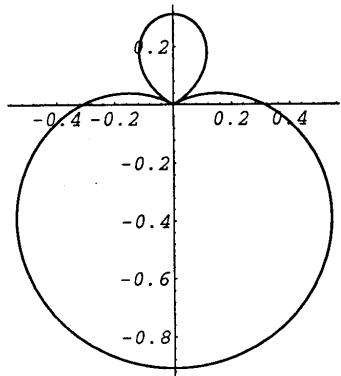
Again sketching the relative currents as viewed by an observer in the $\theta = 0, \pi$ directions 19-16



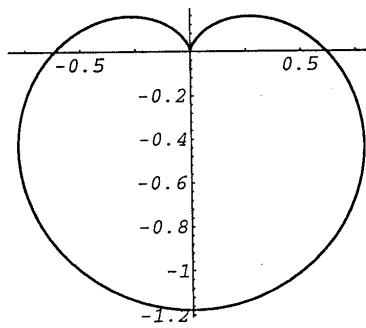
In this case a beam is formed in the $\theta = \pi$ direction.

The figures below provide two example array factor patterns for a dipole + capacitive passive element.

19-17



$$\gamma = +18^\circ$$



$$\gamma = +36^\circ$$

$$kd = 36^\circ$$

19-18

Thus we see that a "short," or capacitive passive element forms a beam on the same side as the passive element location. For this reason such elements are referred to as directors.

In the above, the function plotted is

$$f(\theta; d, \gamma) = 1 - \exp\left\{j\left[\gamma - \frac{2\pi}{\lambda} d \cos \theta\right]\right\}$$

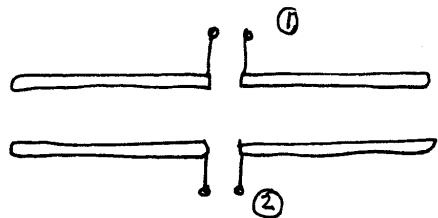
corresponding to

$$f(\theta) = 1 + \frac{I_2}{I_1} e^{-j kd \cos \theta}; \quad \frac{I_2}{I_1} = -e^{+j\gamma}$$

How to analyze the Yagi-Uda Array?

19-19

Consider the two element array as a two-port network!



$$V_1 = Z_{11} I_1 + Z_{12} I_2$$

$$V_2 = Z_{21} I_1 + Z_{22} I_2$$

V, I relationship
at the terminals
can be completely
specified by the
 Z_{ij} 's.

19-20

For one element driven and the other
coupled parasitically, $\underline{V_2} = 0$.

$$V_1 = Z_{11} I_1 + Z_{12} I_2$$

$$0 = Z_{21} I_1 + Z_{22} I_2$$

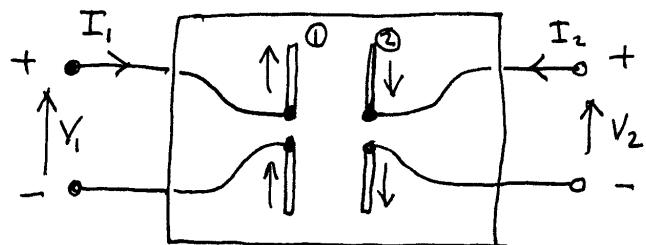
The second equation $\Rightarrow \frac{I_2}{I_1} = -\frac{Z_{21}}{Z_{22}}$

$$f(\theta) = I_1 + I_2 e^{-jkd \cos \theta} = I_1 \left(1 + \frac{I_2}{I_1} e^{-jkd \cos \theta} \right)$$

Evidently, array performance is controlled by

$$\frac{Z_{21}}{Z_{22}}, d, \lambda$$

It is important to be clear on the sign conventions. Drawing our antenna as part of a two-port network -



$$V_2 \left|_{I_2=0} \right. = Z_{21} I_1 ; \quad Z_{21} > 0 \Rightarrow ?$$

What is the direction of current flow in dipole #2, and hence the direction of I_2 relative to the circuit convention?

Below we give curves showing the mutual impedance between two closely spaced $\lambda/2$ dipoles (from Kraus), and a table of values for dipoles of slightly different lengths (from Elliott). You need not take these curves on faith, as you now are able to compute these by the method of moments.

From Kraus, 2nd Edition

426 10 SELF AND MUTUAL IMPEDANCES

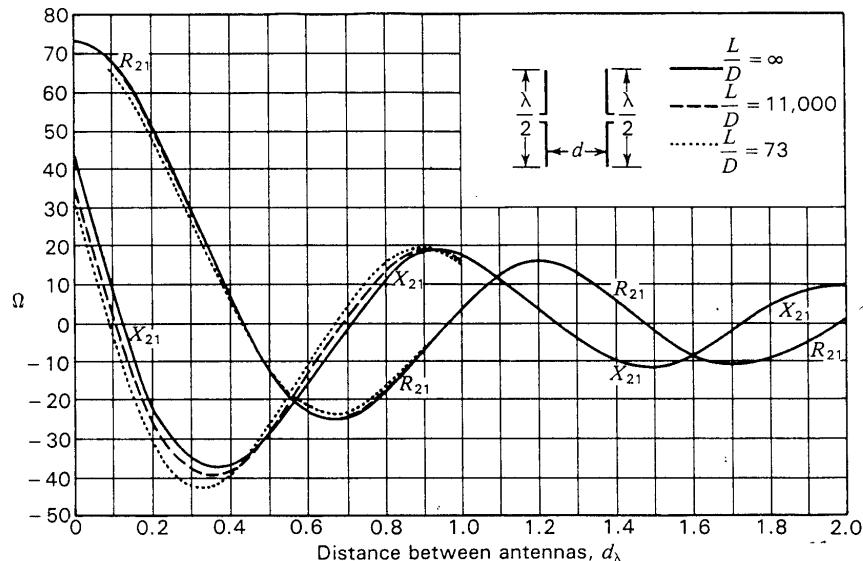
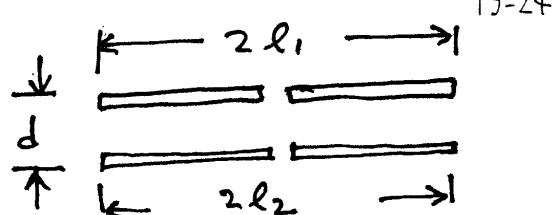


Figure 10-12 Curves of mutual resistance (R_{21}) and reactance (X_{21}) of two parallel side-by-side linear $\lambda/2$ antennas as a function of distance between them. Solid curves are for infinitesimally thin antennas as calculated from Carter's formulas. Dashed and dotted curves between 0 and 1.0λ spacing are from Tai's data for antennas with L/D ratios of 11 000 and 73 respectively.

Mutual impedance
between two closely
spaced dipoles .



$$\frac{d}{\lambda} = 0.0032$$

TABLE 8.4 Mutual impedance versus spacing between two parallel dipoles: $2l_1/\lambda = 0.475$

d/λ	Z_{12} ohms		
	$2l_2/\lambda = 0.450$	$2l_2/\lambda = 0.475$	$2l_2/\lambda = 0.500$
0.10	53.94 1.52°	58.19 3.22°	62.78 4.98°
0.15	49.08 -9.38°	52.73 -8.45°	56.62 -7.50°
0.20	44.42 -21.93°	47.67 -21.42°	51.12 -20.90°
0.25	40.23 -35.53°	43.18 -35.28°	46.30 -35.02°
0.30	36.55 -49.91°	39.26 -49.82°	42.11 -49.73°
0.35	33.35 -64.87°	35.84 -64.89°	38.47 -64.91°
0.40	30.57 -80.32°	32.86 -80.40°	35.31 -80.48°
0.45	28.14 -96.14°	30.28 -96.26°	32.56 -96.38°
0.50	26.04 -112.25°	29.02 -112.40°	30.16 -112.56°

Observe that in terms of the induced open circuit voltage it is the spacing, d , of the dipoles that is important. This validates (at some level) our previous handwaving regarding the direct effects.

From Elliott's table the steps are $\Delta d = 0.05$ or $1/20$ cycle $\Rightarrow 18^\circ$. The angle $\angle Z_{12}$ varies more slowly than this. The variation in $\angle Z_{12}$ is more like $10^\circ/\text{step}$ when d small, then $\sim 15^\circ/\text{step}$ for $d/\lambda > 0.15$. Also note the insensitivity in $|Z_{12}|$, and that the $t=0$ catastrophe is avoided!

What about Z_{22} ? This is different, as we already know.

TABLE 8.5 Self-impedance of a cylindrical dipole versus length (King-Middleton corrected second-order approximation;
 $(a_2/\lambda = 0.0032)$

$2l_2/\lambda$	Z_{22} ohms	
-8	$60.56 - j29.58 = 67.40 \angle -26.03^\circ$	capacitive
resonant	$72.06 + j4.04 = 72.17 \angle 3.21^\circ$	
+8	$83.60 + j41.34 = 93.26 \angle 26.31^\circ$	inductive

Thinking back over our preliminary calculations, we saw that we could form a beam either on the side opposite the passive element ($2l + \delta$, inductive, current lags, reflector), or on the same side ($2l - \delta$, capacitive, current leads, director). How do we relate this to the Table 8.6 from Elliott?

First, consider that there are two ways in which we can "form" beams. 1) We can arrange for the radiation from our two elements to add constructively in the desired direction, or

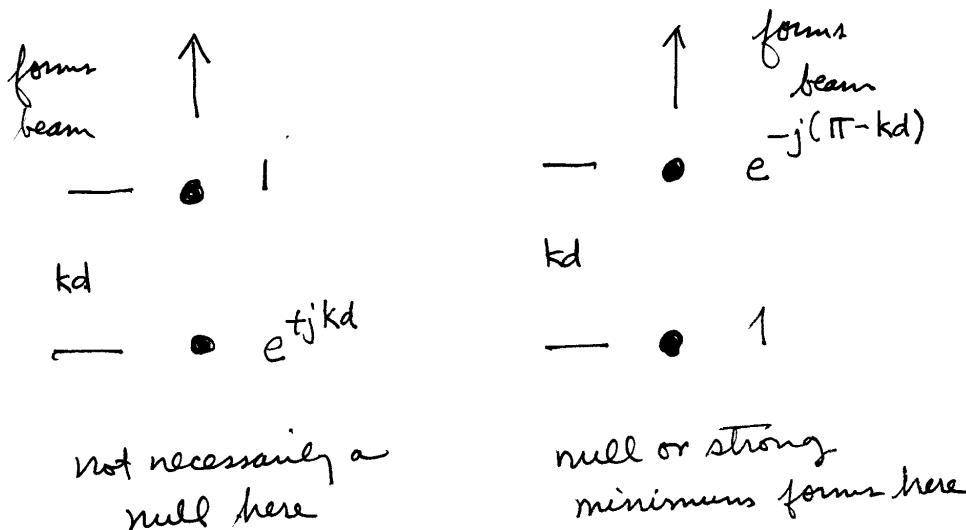
...

- 2) we can arrange for destructive interference in the direction opposite that of the desired beam.

In the first instance we need the relative phase between the two elements to equal kd , with the lag in the direction of the intended beam.

In the second instance we need the relative phase between the two elements to equal $\pi - kd$, with the lag opposite the direction of the beam.

Sketching this,



Examining Table 8.6, Elliott, ... we see 19-30

1. That Case 2 is satisfied for the capacitive element for $d/\lambda \approx 10^\circ$. There is no entry that will satisfy Case 1 for a capacitive element. ($l_2 < l_1$)
2. That Case 1 is satisfied for the inductive element for $d/\lambda \approx 0.3$. There is no entry that will satisfy Case 2 for an inductive element. ($l_2 > l_1$)

Rather than just searching the Table 8.6, as we have just done, it is possible (straight-forward in fact) to calculate the effectiveness of the two element arrays corresponding to the "director" and "reflector" columns for all spacings. Elliott presents such a calculation in his Fig 8.14, below. You can see that even a ^{simple} two element array with element separations $\sim 0.15 \lambda$ gives marked performance improvement over a simple dipole!

Combining these results we find - $\frac{Z_{21}}{Z_{22}}$

TABLE 8.6 Relative current versus spacing for two parallel dipoles, one driven, one parasitic : $2l_1/\lambda = 0.475$

d/λ	$I_2/I_1 = -Z_{21}/Z_{22}$		
	$2l_2/\lambda = 0.450$	$2l_2/\lambda = 0.475$	$2l_2/\lambda = 0.500$
36	0.10 0.800 -152.45°	0.806 180.01°	0.673 158.67°
54	0.15 0.728 -163.35°	0.731 168.34°	0.607 146.19°
72	0.20 0.659 -175.90°	0.661 155.37°	0.548 132.79°
90	0.25 0.597 170.50°	0.598 141.51°	0.496 118.67°
108	0.30 0.542 156.12°	0.544 126.97°	0.452 103.96°
126	0.35 0.495 141.16°	0.497 111.90°	0.413 88.78°
144	0.40 0.454 125.71°	0.455 96.39°	0.379 73.21°
162	0.45 0.418 109.89°	0.420 80.53°	0.349 57.31°
180	0.50 0.386 93.78°	0.388 64.39°	0.323 41.13°

$l_2 \rightarrow$ $\underbrace{\text{capacitive}}$ $\underbrace{\text{resonant}}$ $\underbrace{\text{inductive}}$

Elliott, p. 370

Result of calculating gain for each entry in Table 8.6

19-33

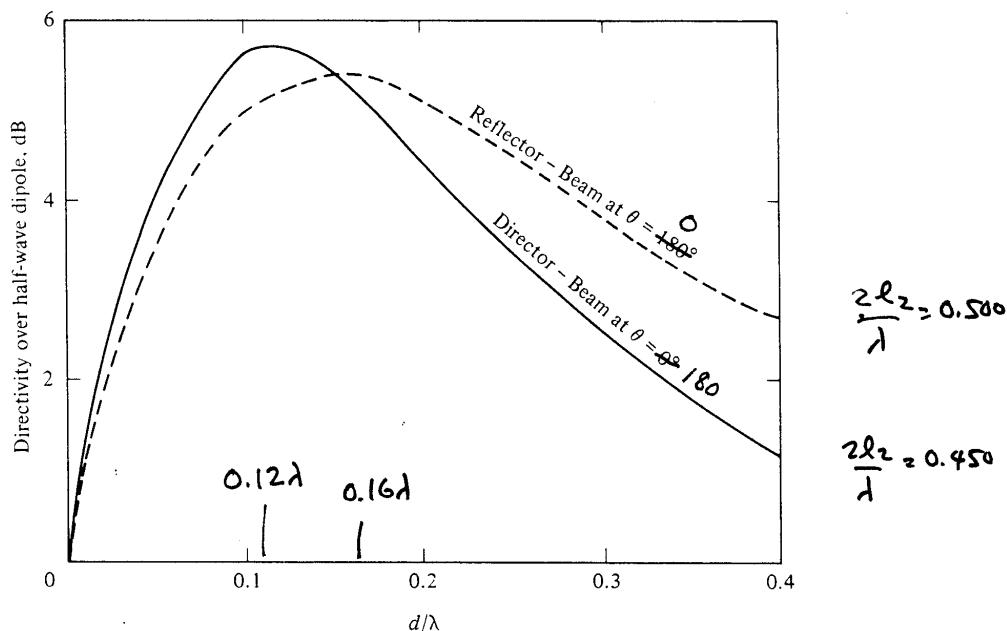


Fig. 8.14 Peak Directivity versus Element Spacing for an Array of Two Parallel Dipoles; One Element Driven, the Other Parasitic

Elliott, p. 371

So. —

19-34

Shorted dipole placed at an appropriate distance from a driven dipole can act as a

or a director (parasite is shorter)
 *
 (" " longer)

thereby generating an "end-fire" array beam.

* than resonant length

What is input Z?

19-35

Assume Z_{12} is insensitive to small changes in $2l_1/\lambda$. This is reasonable ($Z_{12} = Z_{21}$)

then knowing that $Z_{IN} = \frac{V_1}{I_1} = Z_{11} + \frac{I_2}{I_1} Z_{12}$

$$Z_{IN} = Z_{11} - \frac{Z_{12}^2}{Z_{22}}$$

For optimum director $-\frac{Z_{12}^2}{Z_{22}} = -38 - j14$

...

... Input Z?

19-36

To resonate the system lengthen l_1 ,
adjust $\text{Im}(Z_{11}) \approx +j14$. This occurs
for $\frac{2l_1}{\lambda} = 0.482$ ($a_1/d = 0.0032$),

where $Z_{11} = 76 + j14$

$$Z_{IN} = \underbrace{76 + j14}_{Z_{11}} - \underbrace{38 - j14}_{Z_{22}} = 38 \Omega$$

Driven element must be slightly longer than
in absence of a director. Note that

...

the input Z is lower than before, which is again consistent with our ideas of the behavior of a dipole in the presence of a conductor.

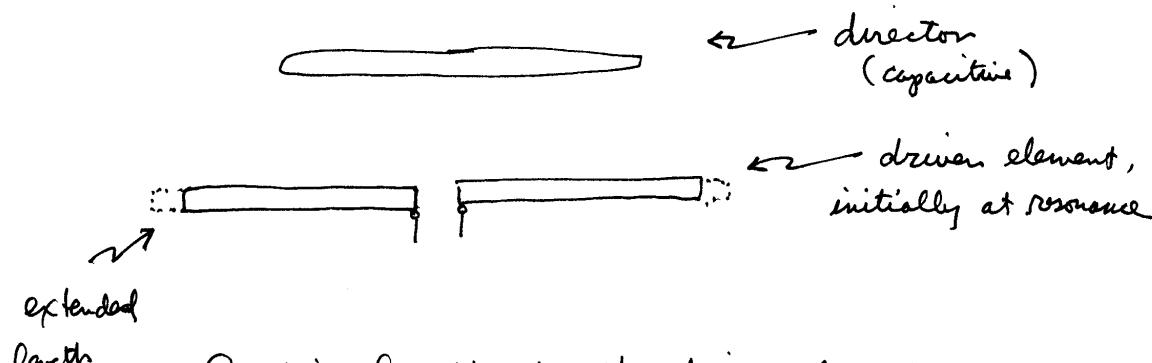
Repeating above for an optimum reflector

$$-\frac{Z_{12}^2}{Z_{22}} = -23 + j24 \quad (\text{inductive})$$

$$2l_1/\lambda = 0.454, Z_{11} = 62.5 - j24, Z_{in} = 40.52$$



Example of the Director + Driver Element



Adding length to the driven element

increases the overall inductance, cancelling the capacitance introduced by the director.

(In the case of a reflector, the driven element must be made shorter than resonance.)

Example: Z_1 , when $d/\lambda = 0.1$, with one driven element plus director

Table 8.6, Elliott, $L/\lambda = 0.450$

$$d/\lambda = 0.1 \Rightarrow -Z_{12}/Z_{22} = 0.800 \angle -152.45^\circ$$

Table 8.4, Elliott, $L/\lambda = 0.450$

$$d/\lambda = 0.1 \Rightarrow Z_{12} = 53.94 \angle 1.52^\circ$$

$$-Z_{12}^2/Z_{22} = 43.15 \angle -151^\circ$$

$$= -37.7 - j 21 \text{ } \Omega$$

/...

$$Z_1 = Z_{11} - Z_{12}^2/Z_{22}$$

Table 8.5, Elliott, $L/\lambda = 0.475$

$$Z_{22} = Z_{11} = 72.06 + j 4.04 \quad \left. \begin{array}{l} \text{approx.} \\ \text{resonance} \end{array} \right\}$$

$$Z_1 = 72.06 + j 4.04 - 37.7 - j 21$$

$$\approx 34 - j 17 \text{ } \Omega$$

/...

19-41

By interpolation from Table 8.5, Elliott

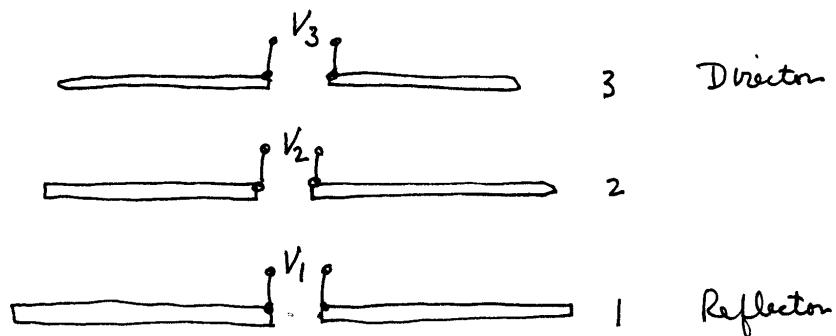
$$\frac{L}{\lambda} = 0.49 \Rightarrow Z_{11} \approx 78 + j21$$

Use of an element of this length will yield

$$Z_1 \approx 78 + j21 - 37.7 - j21$$

$$= 40 \Omega \quad (+j0)$$

19-42



$$V_1 = Z_{11} I_1 + Z_{12} I_2 + Z_{13} I_3 \quad \text{etc.}$$

$$Z_{12} = \left| \frac{V_1}{I_2} \right| \quad \text{typ.}$$

$I_1 = I_3 = 0$

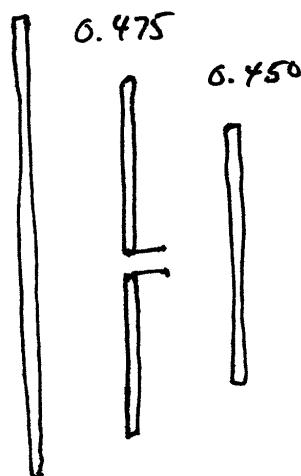
Adding more elements . . .

$$\begin{bmatrix} V_1 \\ V_2 \\ V_3 \end{bmatrix} = \begin{bmatrix} Z \end{bmatrix} \begin{bmatrix} I_1 \\ I_2 \\ I_3 \end{bmatrix}$$

$$\frac{I_1}{I_2} = \frac{Z_{13}Z_{23} - Z_{12}Z_{33}}{Z_{11}Z_{33} - Z_{13}^2}, \text{ etc}$$

$$\frac{I_3}{I_2} = \frac{Z_{13}Z_{12} - Z_{23}Z_{11}}{Z_{11}Z_{33} - Z_{13}^2} \quad / \dots$$

0.500

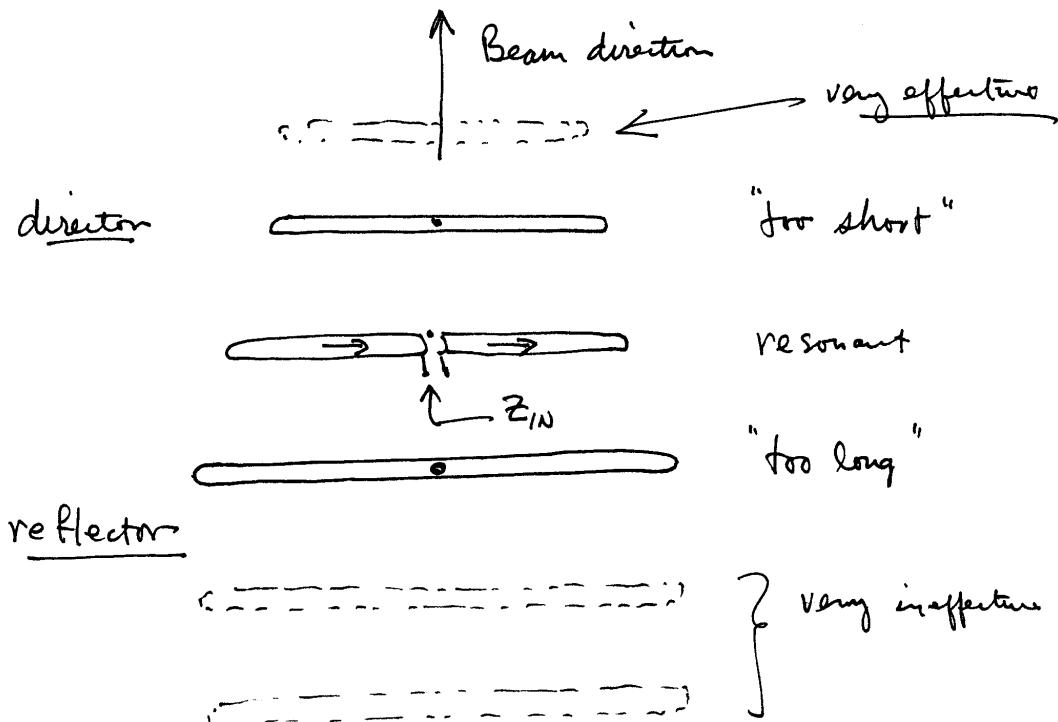


$$Z_{in} = 26 \angle 10^\circ$$

$$\frac{d_1}{l} = \frac{d_2}{l} = 0.20$$

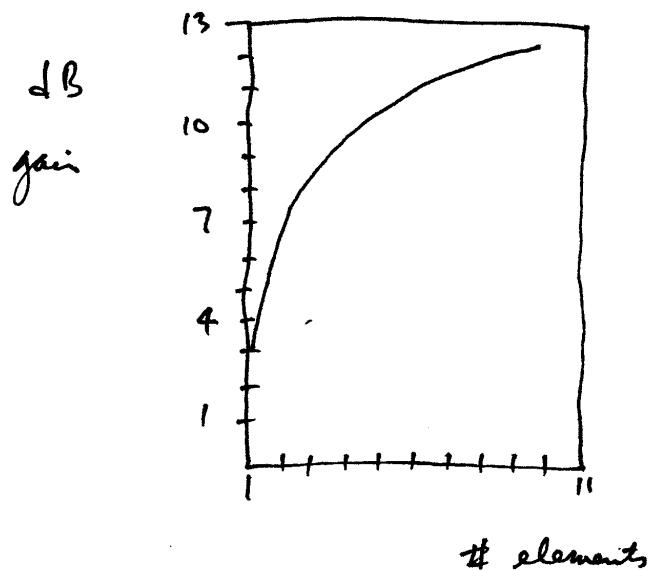
Commonly use driver, $Z_{in} \rightarrow 4Z_{in}$ |
single dipole

19-45



19-46

from S&T 5-32, p 225



Generally adding directors buys $\approx 1-18$ per element up to 10-13 dB. Adding reflectors doesn't help v. much after the first. Why should this be so?

The Yagi-Uda and similar antennas can be readily designed through use of MoM codes