# EE270

# Large scale matrix computation, optimization and learning

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Randomized Linear Algebra Lecture 5: Randomized Dimension Reduction: Johnson Lindenstrauss Lemma

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## Recap: Verifying Matrix Multiplication

Given three  $n \times n$  matrices A, B, M

 $\blacktriangleright$  verify whether

$$
AB=M
$$

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- Sample a random vector  $r = [r_1, ..., r_n]^T$
- $\triangleright$  Compute ABr by first computing Br and then  $A(Br)$
- $\blacktriangleright$  Compute Mr
- If  $A(Br) \neq Mr$ , then  $AB \neq M$
- $\triangleright$  Otherwise, return  $AB = M$

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- ▶ Complexity: three matrix-vector multiplications  $O(n^2)$ Freivalds' Algorithm (1977)

## Recap: Failure Probability

In Let  $r = [r_1, ..., r_n]^T$  be i.i.d. from a discrete distribution taking k distinct values each with probability  $\frac{1}{k}$ 

► Lemma  $\mathbb{P}[ABr = Mr] \leq \frac{1}{k}$ k

## Dimension Reduction

- $\triangleright$  map a high dimensional vector to low dimensions such that certain properites are preserved
- $\blacktriangleright$  examples so far:
- ▶ Approximate Matrix Multiplication  $AS<sup>T</sup>SB \approx AB$  where S is random

- $\triangleright$  Freivalds Algorithm ABr Mr where r is random
- Trace estimation  $r^T M r \approx \mathbf{tr}(M)$  where r is random

#### Dimension Reduction

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- $\blacktriangleright$  Generic dimension reduction problem
- ► Given vectors  $x_1, ..., x_n \in \mathbb{R}^d$ , compress the data points into low dimensional representation  $y_1, ..., y_n \in \mathbb{R}^m$  where  $m < d$
- $\triangleright$  another instance is Principal Component Analysis

# Randomized Dimension Reduction

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- $\triangleright$  S is chosen randomly
- Approximate Matrix Multiplication:  $AS<sup>T</sup>SB \approx AB$ where S is random matrix

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# Geometry of Random Projections



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#### Johnson Lindenstrauss Lemma

let  $\epsilon \in (0, \frac{1}{2})$  $\frac{1}{2}$ ). Given any set of points  $\{x_1, ..., x_n\}$  in  $\mathbb{R}^d$ , there exists a map  $S\,:\,\mathbb{R}^n\rightarrow\mathbb{R}^m$  with  $m=\frac{9\log(n)}{\epsilon^2-\epsilon^3}$  $\frac{\log(n)}{\epsilon^2 - \epsilon^3}$  such that

$$
1-\epsilon \leq \frac{\|Sx_i-Sx_j\|_2^2}{\|x_i-x_j\|_2^2} \leq 1+\epsilon
$$

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- $\blacktriangleright$  Note that the target dimension m is **independent of the** original dimension  $d$ , and depends only on the number of **points** *n* and the accuracy parameter.
- ▶ more surprises: picking an  $m \times d$  random matrix  $S = \frac{1}{\sqrt{2}}$  $\frac{1}{\overline{m}}$  G with  $G_{ii} \sim N(0, 1)$  standard normal works with high probability!

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# Johnson Lindenstrauss (JL) Lemma

\n- Define 
$$
u_{ij} \triangleq \frac{x_i - x_j}{\|x_i - x_j\|_2}
$$
.
\n- note that  $\|u_{ij}\|_2 = 1$ .
\n

\n- JL Lemma: 
$$
\mathbb{P}[\|Su_{ij}\|_2^2 \in (1 \pm \epsilon)
$$
 for all  $i, j \in \{1, ..., n\}]\geq 1-\delta$  where  $\delta \in (0,1)$  for large enough  $m$
\n

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## Proof of JL Lemma

- $\blacktriangleright$  We need to show  $\|S_{uj}\|_2^2$  is concentrated around 1
- ► Lemma Let  $S_{ij} \sim \frac{1}{\sqrt{N}}$  $\frac{1}{m}N(0,1)$  and  $u$  be any fixed vector. Then

$$
\mathbb{E}||Su||_2^2 = ||u||
$$

- $\triangleright$  implies that the distance between two points is preserved in expectation
- $\blacktriangleright$  Proof:

# Concentration of Measure for Uniform Distribution on the **Sphere**

- Suppose  $m = 1$ , i.e., we project to dimension one ► S is a row vector  $S = g^T \in \mathbb{R}^d \sim N(0, I)$
- $\blacktriangleright \mathbb{P} \left[ |g^T u| \geq \epsilon \right] = \mathbb{P} \left[ |g^T e_1| \geq \epsilon \right] = \mathbb{P} \left[ |g_1| \geq \epsilon \right]$ where  $e_1$  is the first ordinary basis vector

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- ▶ Lemma:  $\mathbb{P}\left[|s_1|\geq \frac{t||g||_2}{\sqrt{d}}\right]$ d  $\Big] \leq 2e^{-\frac{t^2}{2}}$  .
- Note that  $\frac{g}{\|g\|_2}$  is distributed uniformly on the unit sphere

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Concentration of Measure for Uniform Distribution on the Sphere

2 I Lemma: P h i − <sup>t</sup> |g1| ≥ <sup>t</sup><sup>k</sup> gk<sup>2</sup> ≤ 2e <sup>2</sup> . √ d I Note that <sup>g</sup> is distributed uniformly on the unit sphere kgk<sup>2</sup> q I Pythagorean theorem: <sup>t</sup> 2 2 2 t <sup>d</sup> + R cap = 1 implies Rcap = 1 − d <sup>d</sup>−<sup>1</sup> <sup>q</sup> 2 1− <sup>t</sup> area of the spherical cap I P h i g1 t | | ≥ √ ≤ area of the sphere <sup>≤</sup> d kgk<sup>2</sup> d−1 d 1 I using the fact (1 − x <sup>n</sup> ≤ e <sup>−</sup><sup>x</sup> we get ) n 2 h i − <sup>t</sup> P g1 t | | ≥ √ ≤ 2e <sup>2</sup> .kgk<sup>2</sup> d 

## Proof of JL Lemma

▶ Back to the general case  $S \in \mathbb{R}^{m \times d}$ 

Sonsider the probability that  $||Su||_2^2$  deviates from 1, i.e., projected vectors are stretched more than their expectation

$$
\mathbb{P}\left[\|S u\|_2^2 \geq (1+\epsilon)\|u\|_2^2\right]
$$

# Questions?

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#### References

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- ▶ Lecture notes, Jelani Nelson <https://www.sketchingbigdata.org/fall17/lec/lec3.pdf>
- $\blacktriangleright$  Lecture notes, Aleksander Madry <https://people.csail.mit.edu/madry/gems/notes/lecture21.pdf>

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