



---

# Navigation Accuracy and Interference Rejection for an Adaptive GPS Antenna Array

David S. De Lorenzo, Jason Rife, Per Enge  
*Stanford University GPS Lab*

Dennis Akos  
*University of Colorado*

27 Sept 2006

The authors gratefully acknowledge the support of the JPALS Program Office, and the Naval Air Warfare Center Aircraft Division through contract N00421-05-C-0068.



# Joint Precision Approach and Landing System (JPALS)

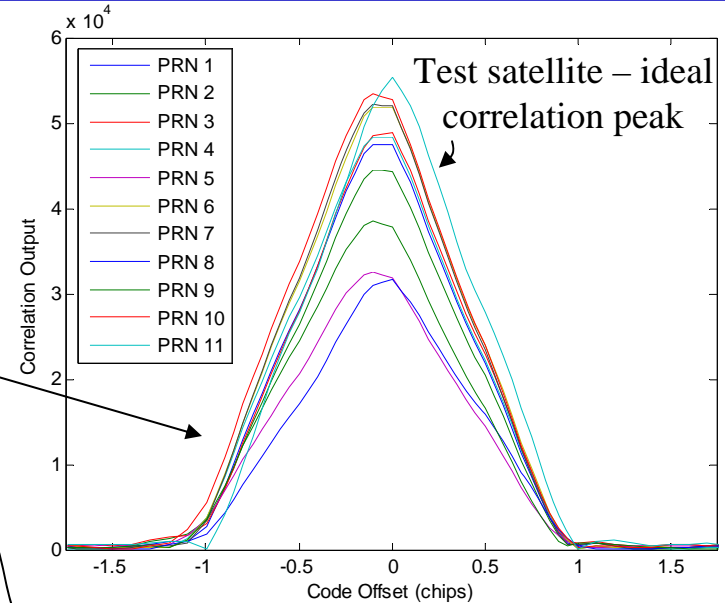
Navigation Accuracy  
Interference Rejection  
Adaptive GPS Antennas





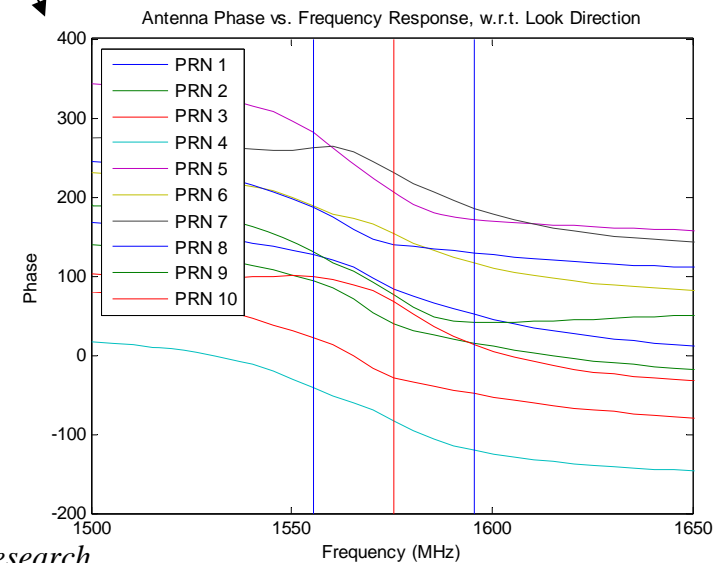
# Antenna Distortion, Code & Carrier Biases

- Antenna gain/phase response varies as a function of incoming signal azimuth, elevation, and frequency
  - Correlation peak distortion
  - Carrier-phase bias
  - Signal attenuation



**Pseudorange and carrier-phase biases for the center antenna of a 7-element array, as a function of incoming signal line-of-sight; isotropic signal power of 40 dB-Hz.**

PRN	Incoming Signal Line-of-Sight		Pseudorange Bias (m)	Carrier-Phase Bias (deg)	C/No (dB-Hz)
	Az	EI			
1	0	40	-2.0	85	37.5
2	30	30	-1.9	42	36.8
3	60	40	-1.5	-27	37.6
4	90	50	-2.3	-83	38.1
5	120	20	-2.8	-154	34.3
6	150	60	-2.2	154	38.7
7	210	70	-2.4	-129	38.9
8	240	20	-0.5	141	33.6
9	270	30	-3.0	76	35.9
10	300	80	-2.7	67	38.8

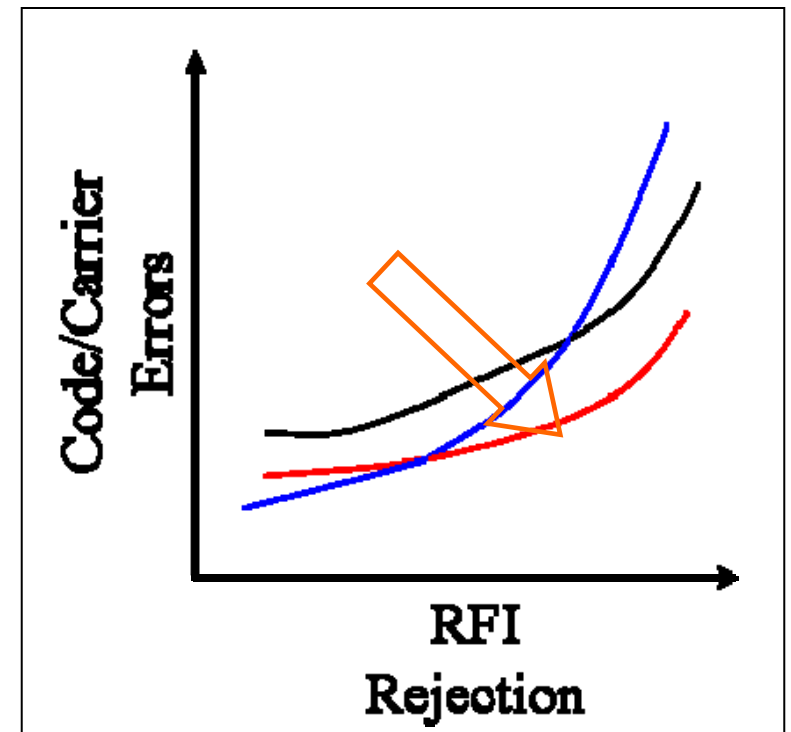




# Motivation – Biases vs. RFI Rejection

- Antennas:
  - Introduce biases in code-phase and carrier-phase
- Multi-Element Antenna Arrays:
  - Increase C/No
  - Reject RFI
  - Compound biases
- How to calibrate biases for STAP?

- Goal: Evaluate trade-space between RFI and biases





# Methodology – Overview

---

- STAP response depends on signal environment and receiver tracking implementation
- Therefore, we need to estimate bias and noise performance in the context of realistic GPS tracking scenarios

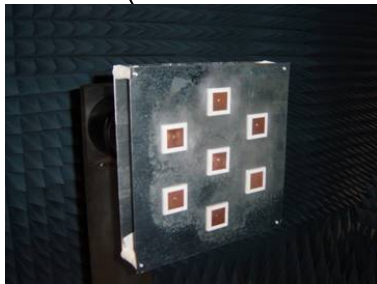
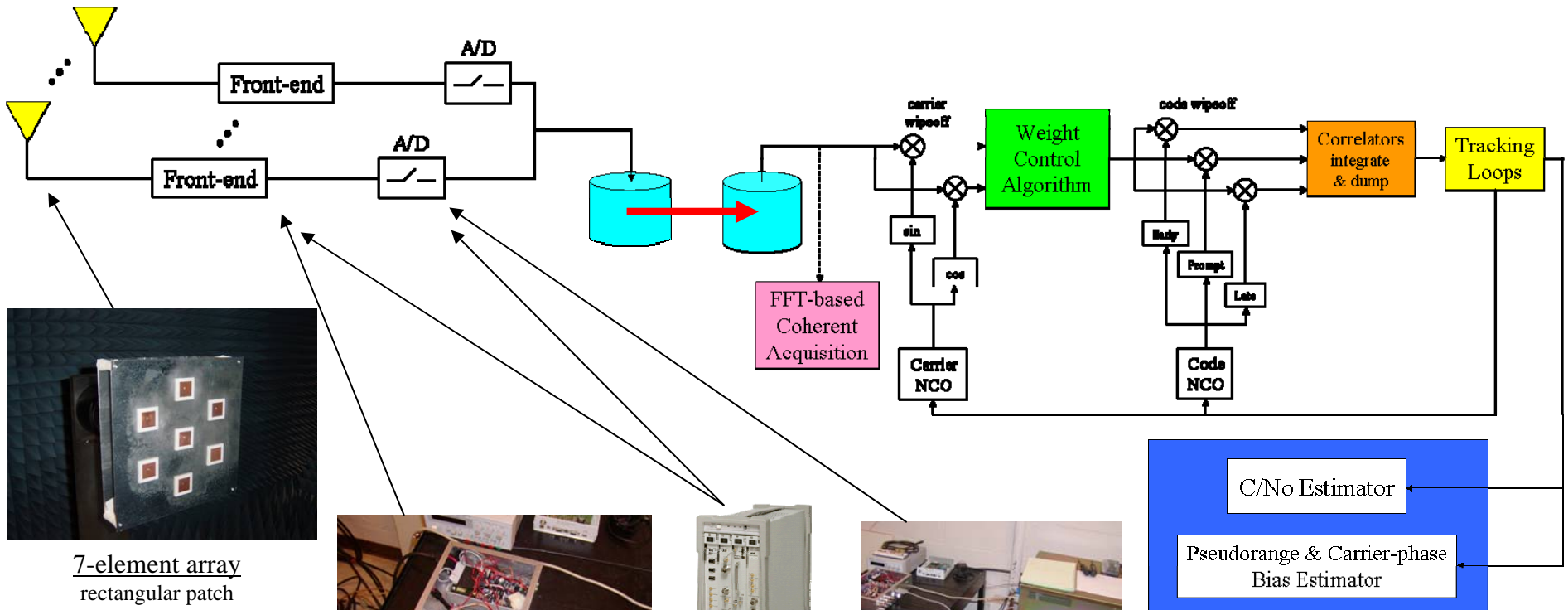
- End-to-end study

- Antenna characterization
- Signal generation
- Weight adaptation
- Signal tracking

- All variables are under direct control, allowing isolation and estimation of parameters of interest



# Stanford HW & SW Development



7-element array  
rectangular patch  
antennas manufactured  
at Stanford University



2m high-gain dish



Analog front-end  
4-channel GP2015 with  
10 MHz common clock

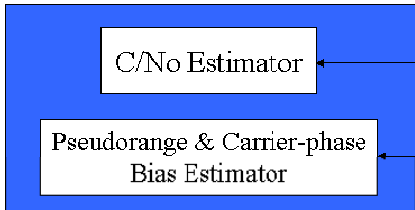


HP Vector  
Signal  
Analyzer



Data collection computer  
(2) ICS-650 cards  
sampling at 5-65 MHz  
and 12-bit A/D resolution

\* Possibility of including data from OSU's multi-element antenna array.

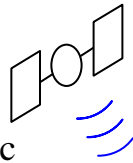


Software Receiver  
all-in view, multi-signal  
GNSS receiver  
with STAP array  
processing



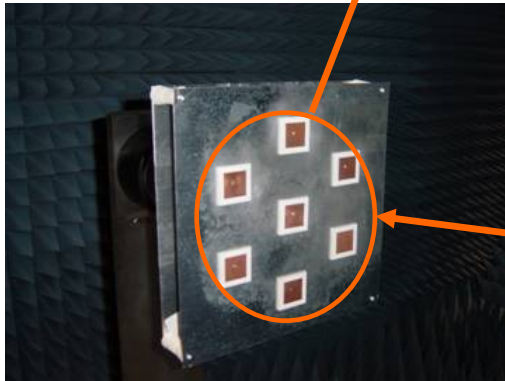
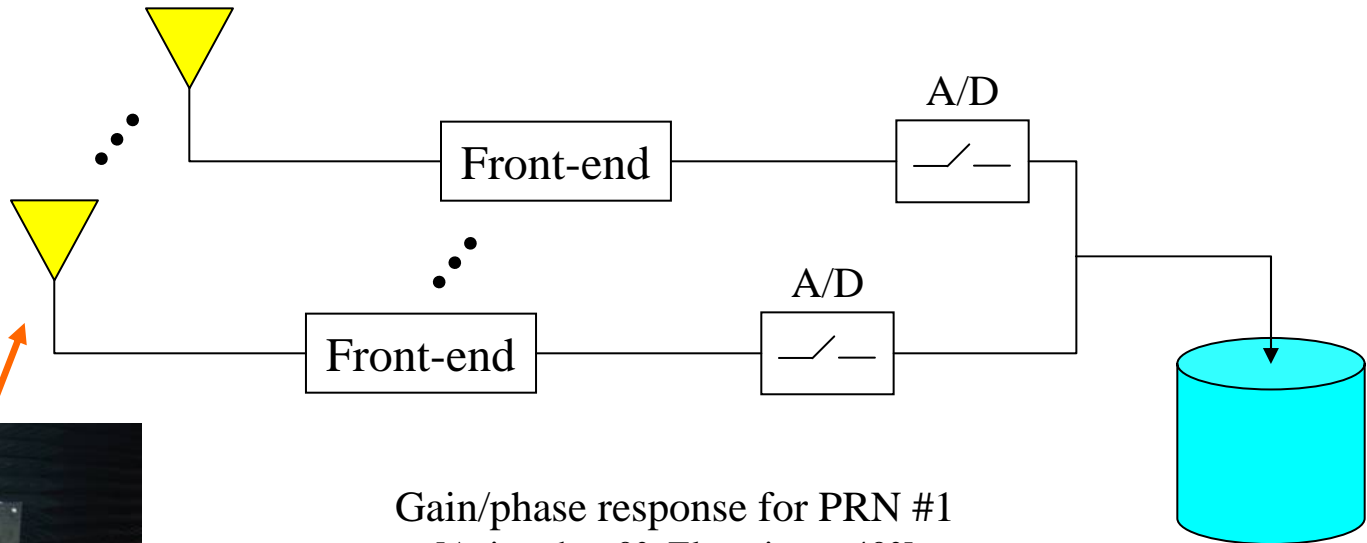
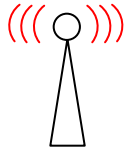
# Software-Based Signal Simulator

C/A & "P" code  
1.023 & 10.23 Mchip/sec

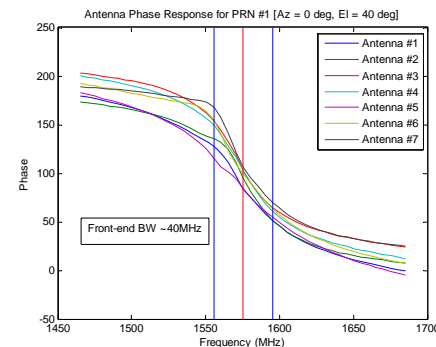
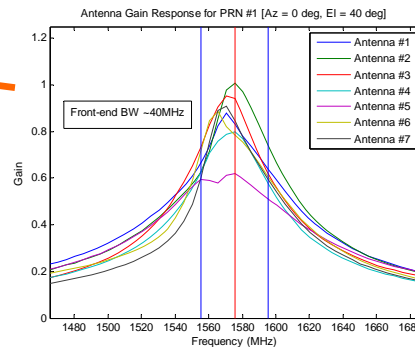


- Gain/phase data for each look direction (10 S/V constellation) and antenna (7 rectangular patches)
  - Data courtesy Ung-Suok Kim

Bandlimited WGN  
& CW interference

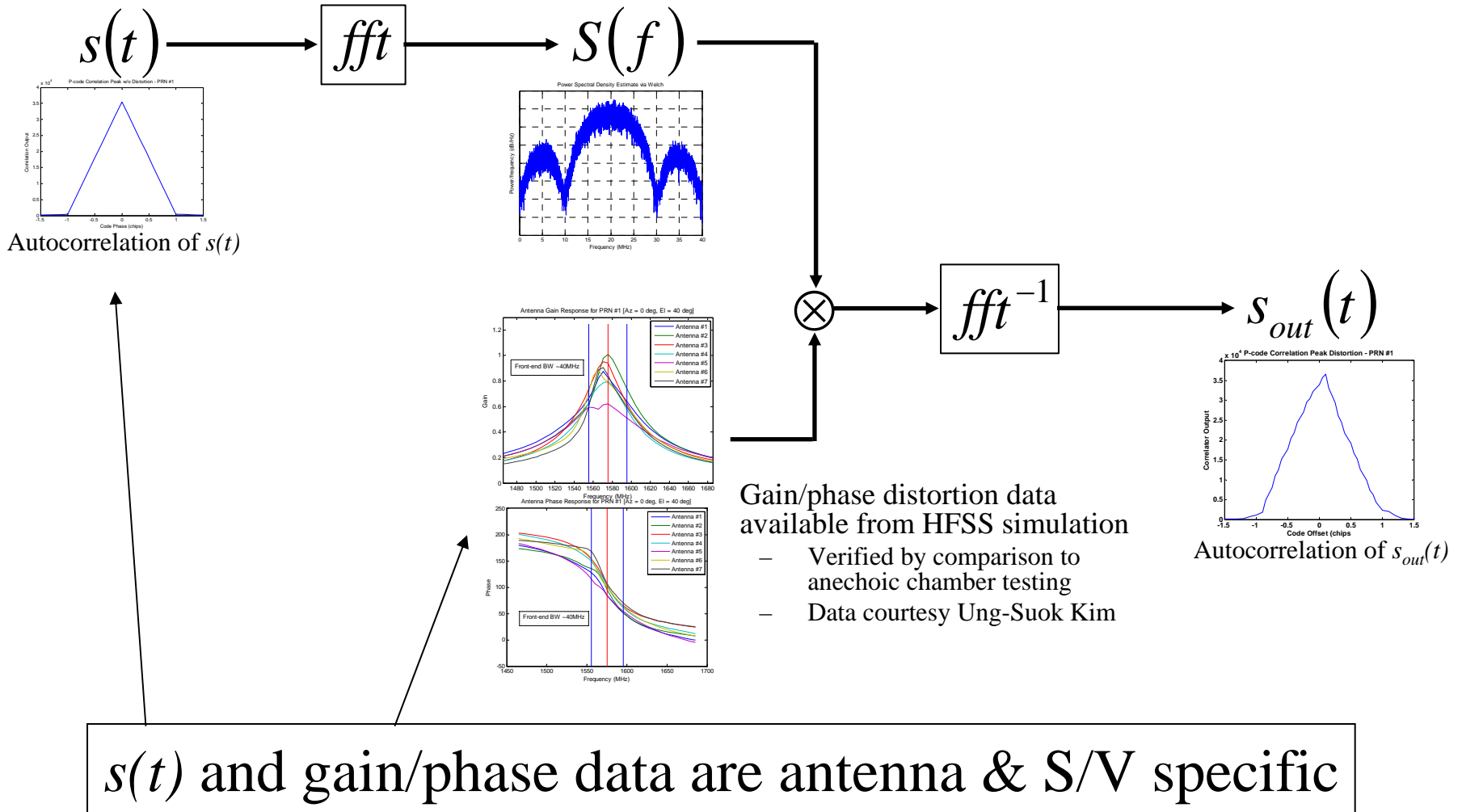


Gain/phase response for PRN #1  
[Azimuth = 0°, Elevation = 40°]





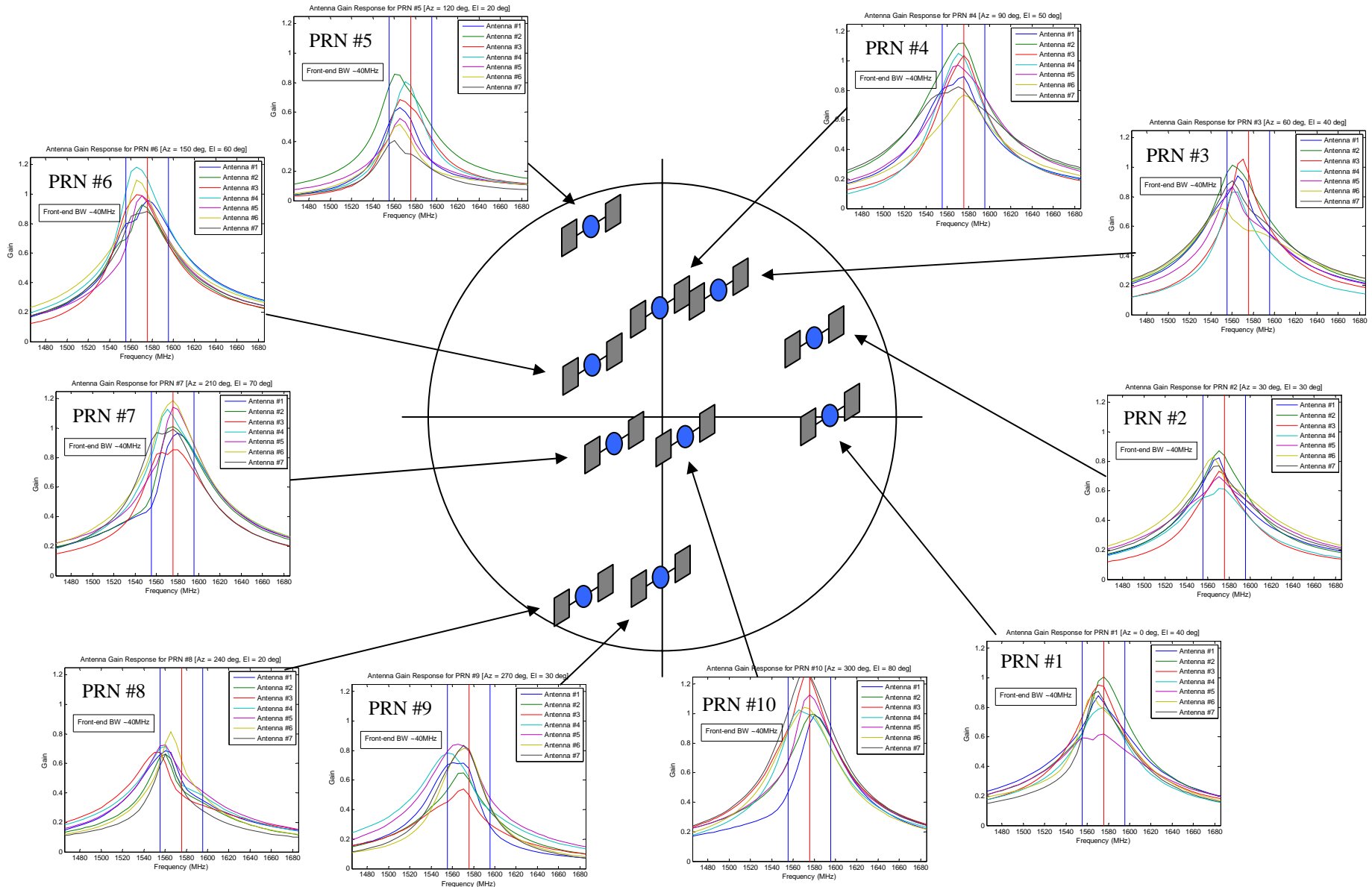
# Signal Generation w/ Antenna Distortion







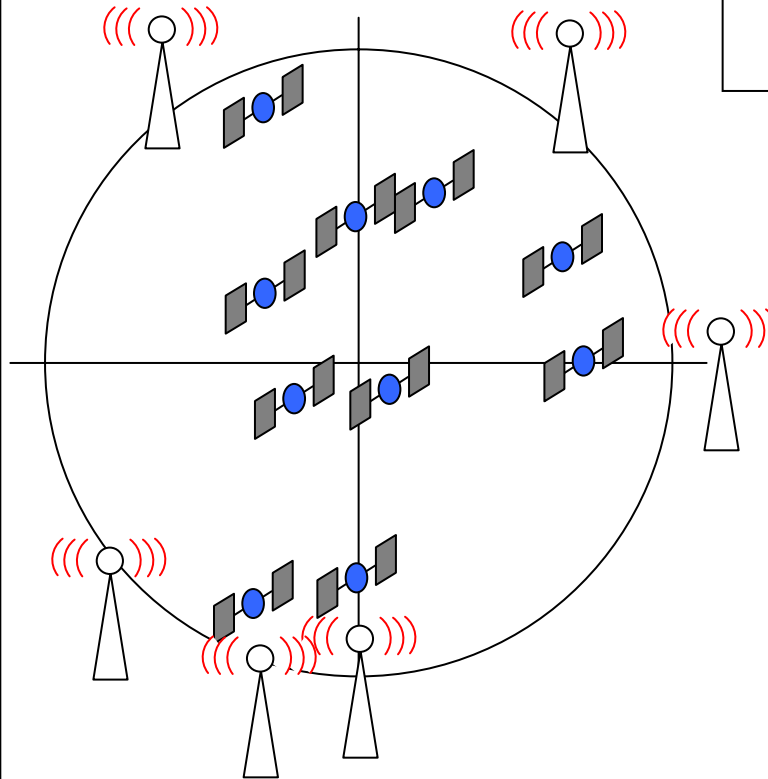
# Standard Satellite Constellation





# Satellite & RFI Constellation

PRN	Azimuth	Elevation
1	0	40
2	30	30
3	60	40
4	90	50
5	120	20
6	150	60
7	210	70
8	240	20
9	270	30
10	300	80

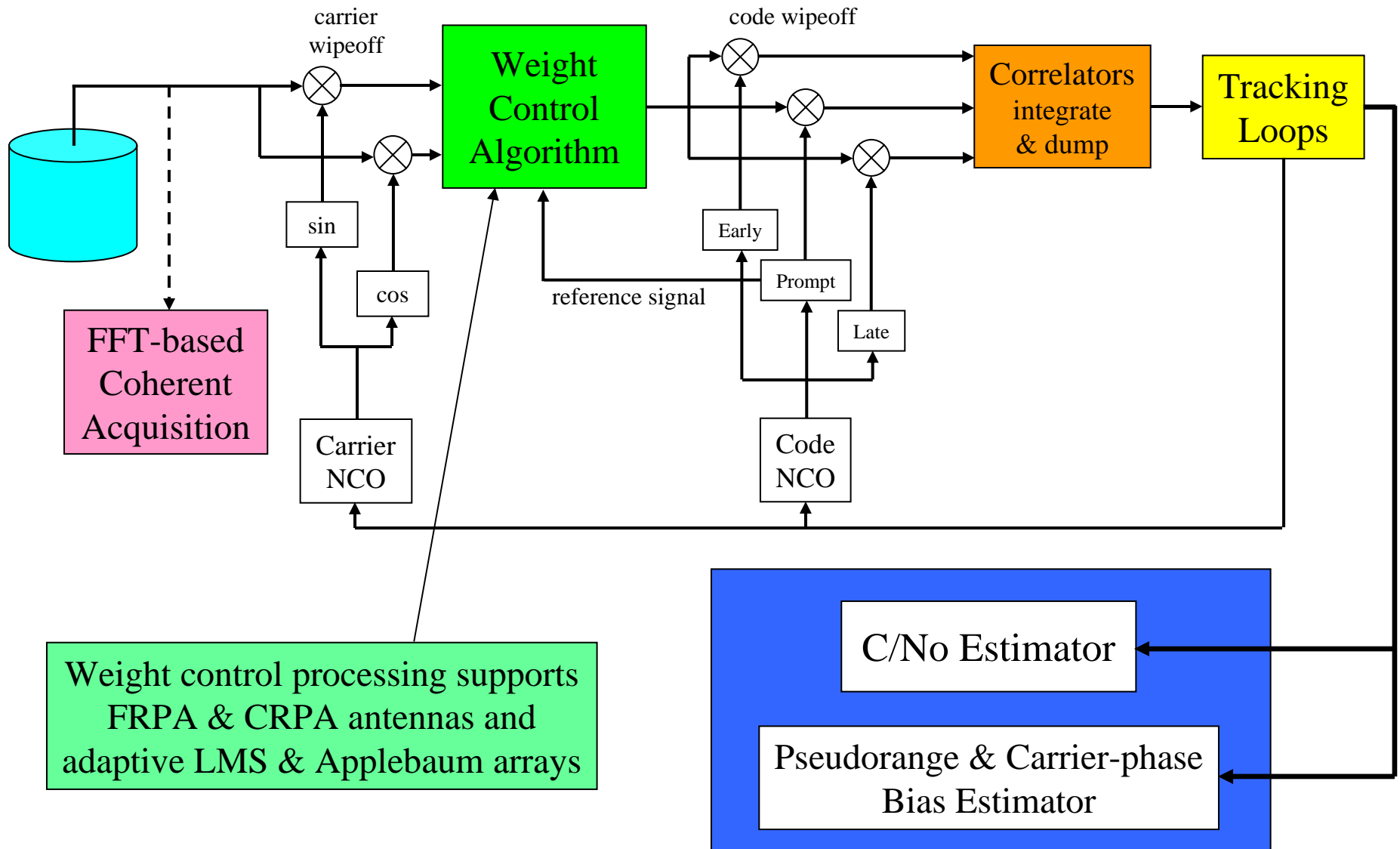


Bandlimited WGN  
and/or  
CW interference

RFI	Azimuth	Elevation
1	0	0
2	45	0
3	120	0
4	225	0
5	250	0
6	270	10



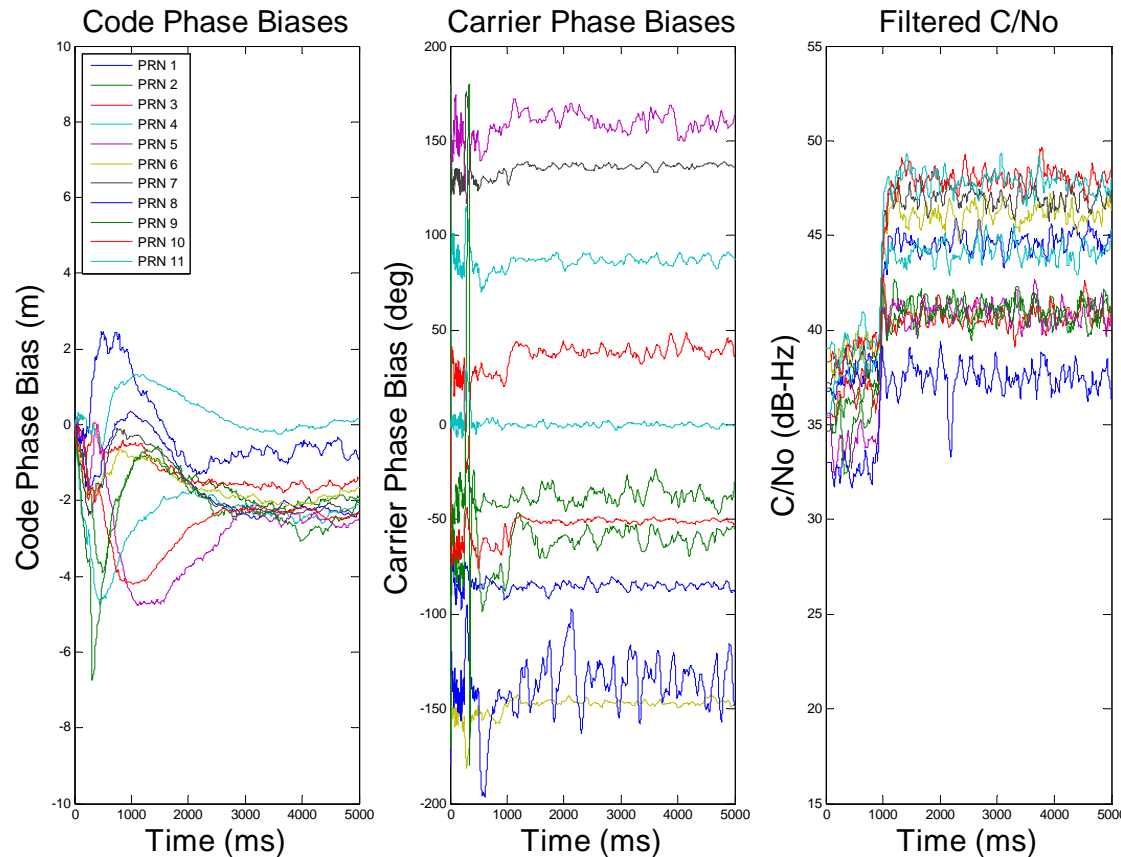
# Multi-signal Software GNSS Receiver





# SW Receiver Output & Bias Estimation

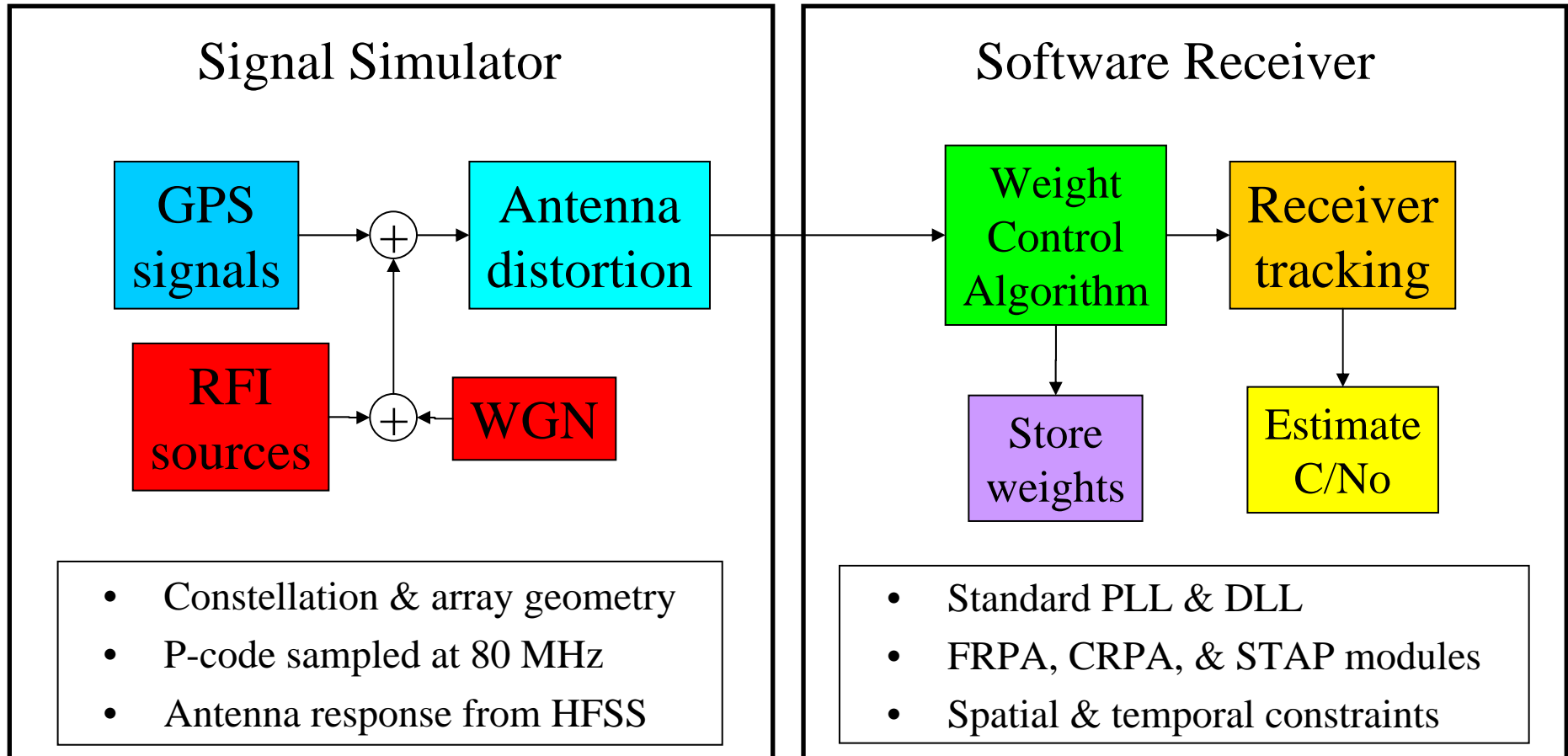
- Tracking signals containing noise & RFI produces noisy estimates of code- and carrier-phase bias



Applebaum-based STAP  
C/No = 40 dB-Hz  
plus six RFI sources  
at J/S = 20dB



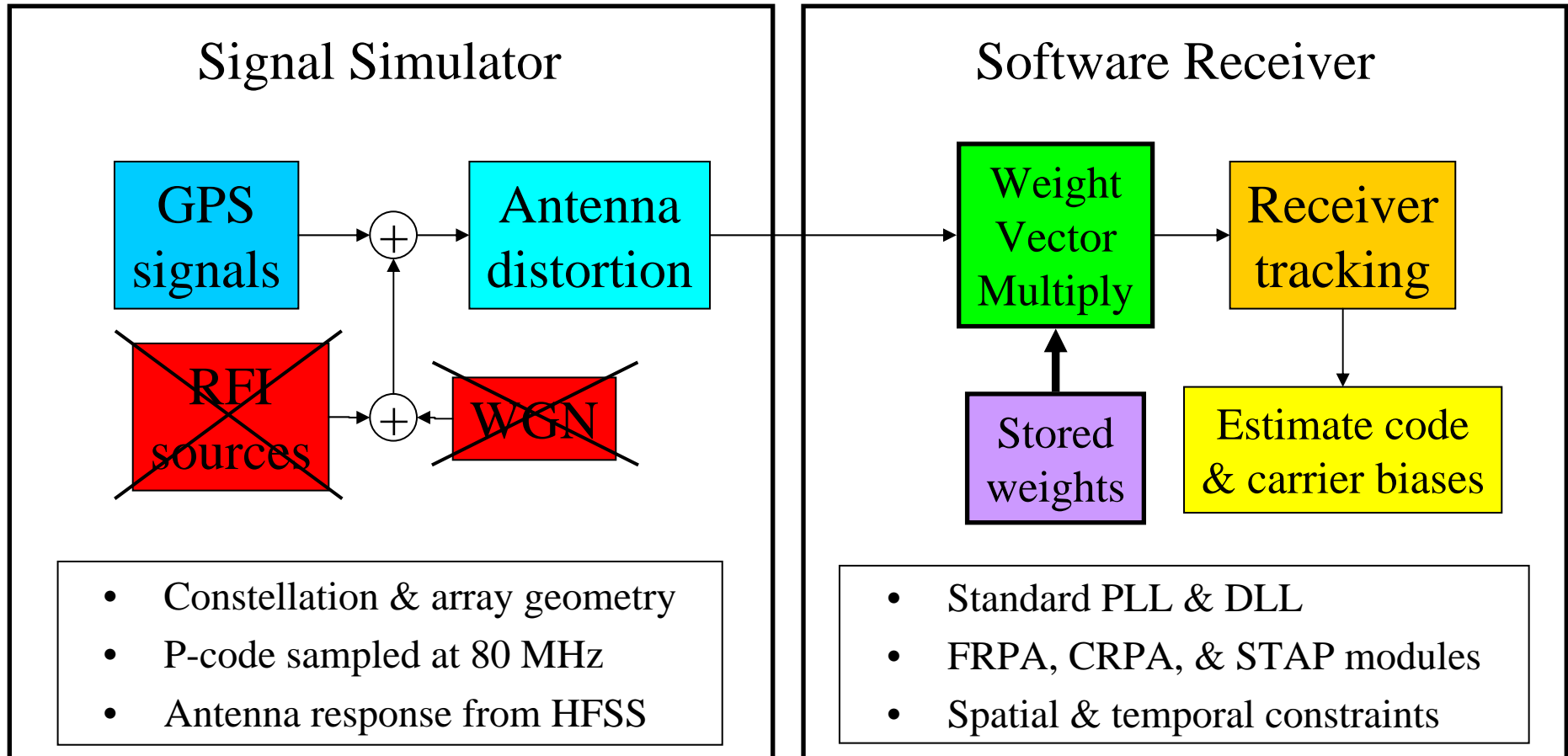
# Methodology – Step 1 (of 2)



- Track signals containing RFI & noise
- Save weight vector for STAP algorithms
- Determine noise performance: C/No



# Methodology – Step 2 (of 2)



- Track noise-free signals
- Use stored weight vector for STAP algorithms
- Determine code & carrier biases



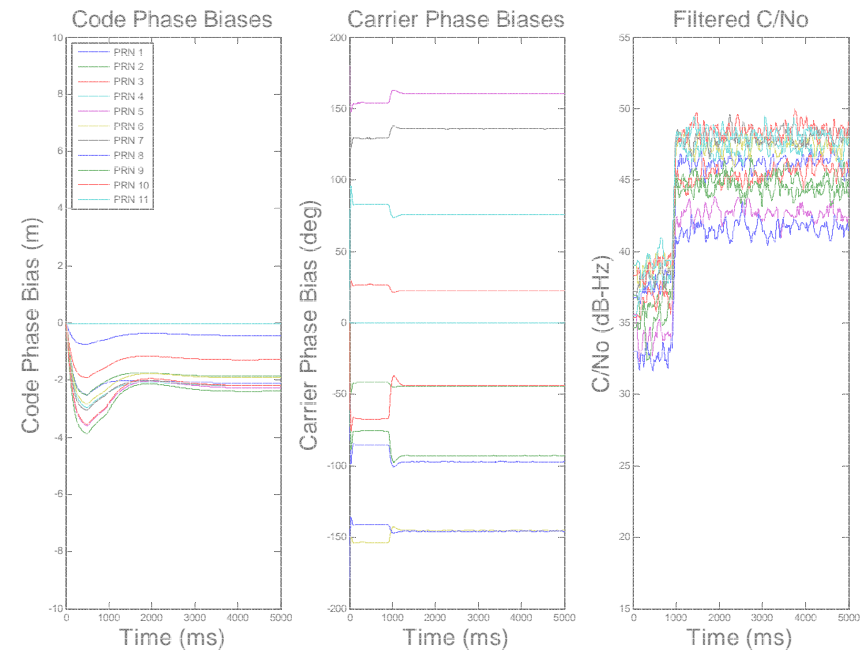
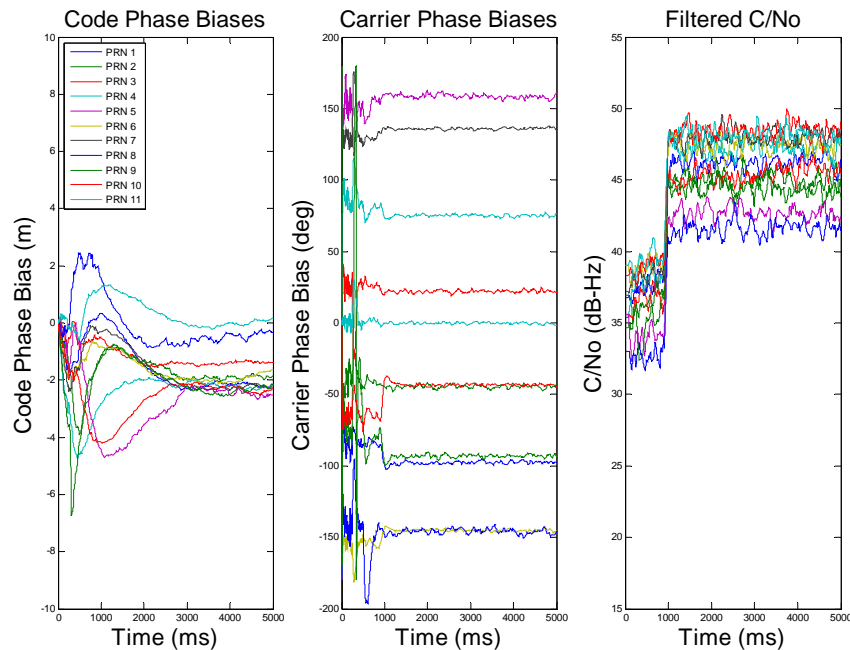
# Methodology – Tracking Output & Biases

## Step 1:

- Track signals containing RFI & noise
- Save weight vector for STAP algorithms
- Determine noise performance: C/No

## Step 2:

- Track noise-free signals
- Use stored weight vector for STAP algorithms
- Determine code & carrier biases





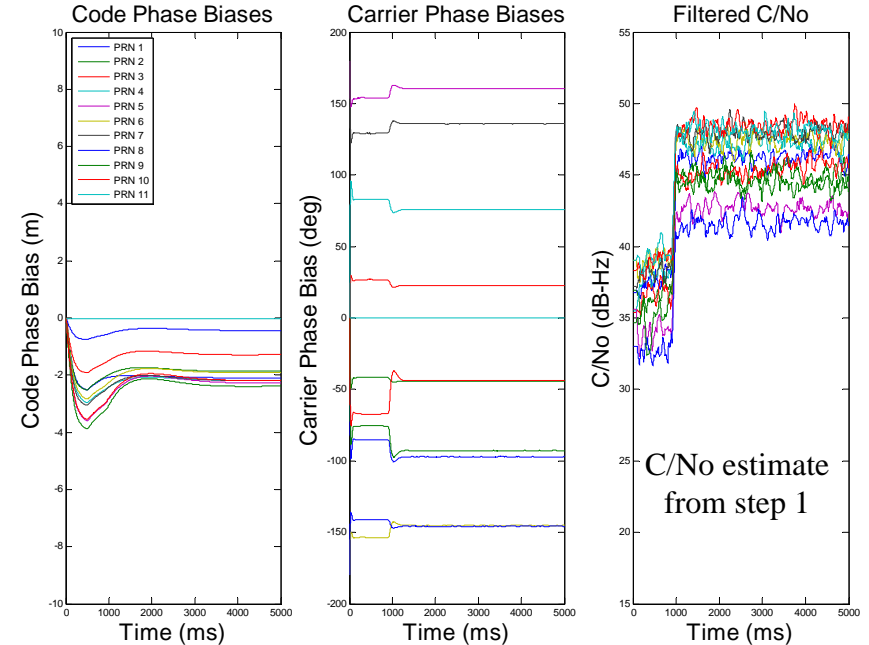
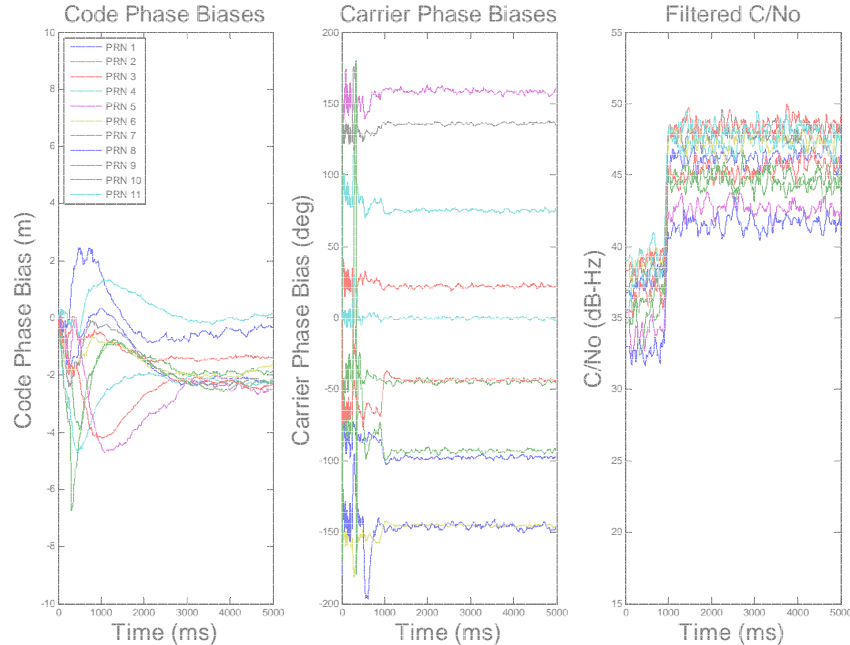
# Methodology – Tracking Output & Biases

## Step 1:

- Track signals containing RFI & noise
- Save weight vector for STAP algorithms
- Determine noise performance: C/No

## Step 2:

- Track noise-free signals
- Use stored weight vector for STAP algorithms
- Determine code & carrier biases







# Uncompensated Code & Carrier Biases

- Pseudorange biases  $\sim 2\text{m}$
- Carrier-phase biases uniformly distributed
- 7-element arrays yield  $\sim 8.5$  dB-Hz improvement in C/No

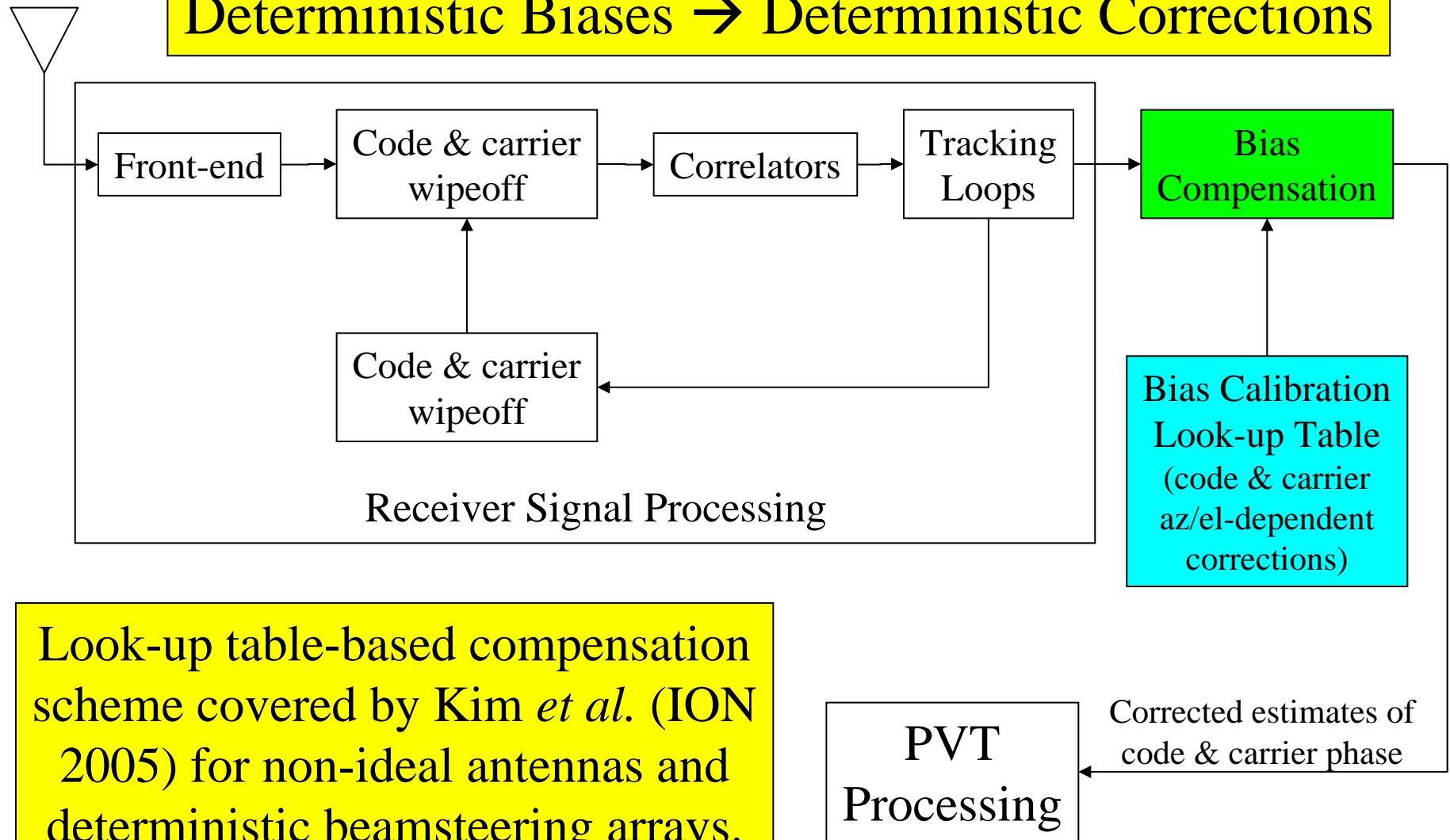
- Biases unacceptable for high-integrity carrier-phase differential navigation!

Uncompensated pseudorange and carrier-phase biases; isotropic signal power of 40 dB-Hz.				
Averages over 10-satellite constellation	Single-element FRPA	7-element deterministic CRPA	Blind-adaptive STAP beam/null steering (LMS-based)	Steering-vector STAP beam/null steering (Applebaum-based)
Pseudorange bias (m)	2.13	1.88	1.94	1.88
Carrier-phase bias (deg)	96	96	96	96
C/No (dB-Hz)	37.0	45.7	45.7	45.7



# Pseudorange & Carrier Bias Compensation

Deterministic Biases  $\rightarrow$  Deterministic Corrections



Look-up table-based compensation scheme covered by Kim *et al.* (ION 2005) for non-ideal antennas and deterministic beamsteering arrays.



# Bias Residuals After Compensation

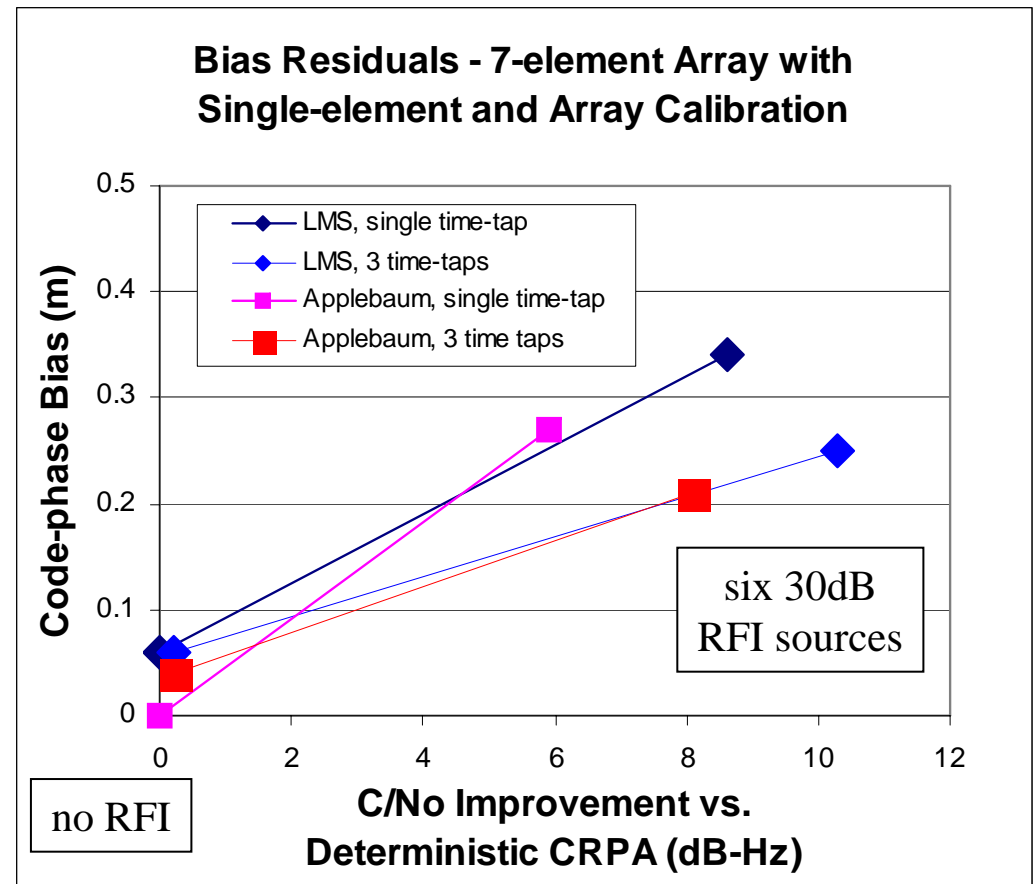
- Two types of LOS-based (az/el) calibration are possible:
  - Single-Element (FRPA) calibration
  - Multi-Element (CRPA) beamforming calibration
- Best calibration option depends on STAP algorithm

Pseudorange and carrier-phase biases; isotropic signal power of 40 dB-Hz.			
Averages over 10-satellite constellation		Blind-adaptive STAP beam/null steering (LMS-based)	Steering-vector STAP beam/null steering (Applebaum-based)
Bias residuals w.r.t. single-element FRPA calibration	Pseudorange bias (m)	0.23	0.28
	Carrier-phase bias (deg)	0.5	9.2
Bias residuals w.r.t. 7-element CRPA calibration	Pseudorange bias (m)	0.06	0.00
	Carrier-phase bias (deg)	9.3	0.0



# Compensation vs. RFI Tradeoffs (1)

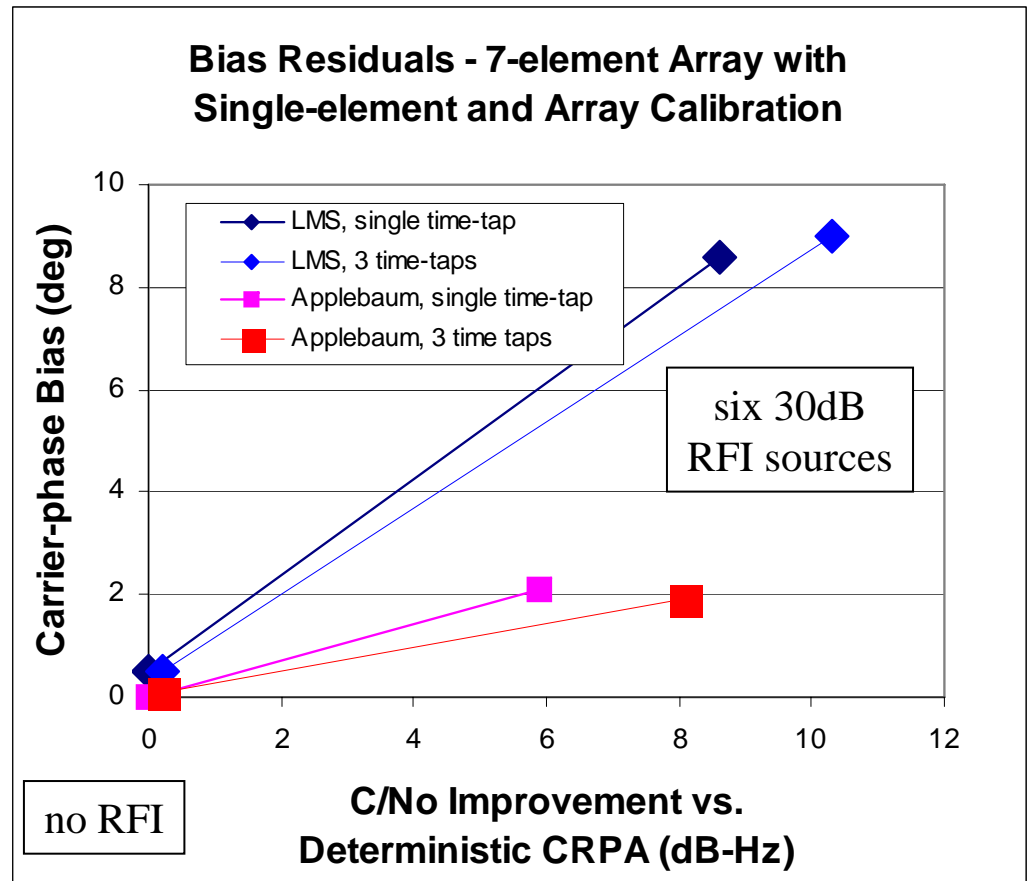
- Two cases considered: No RFI case and 30 dB RFI on six sources
- STAP enables noise rejection at expense of biases
- Code-phase biases equivalent for both STAP algorithms





## Compensation vs. RFI Tradeoffs (2)

- Carrier-phase biases lower for Applebaum than for LMS
- Maximum achievable noise rejection better for LMS than for Applebaum





# Conclusions

- Deterministic corrections (LOS-based lookup table) will reduce pseudorange and carrier-phase biases in the tracking output
  - Carrier-phase residual is likely livable
  - Code-phase biases appear troubling – need further work
- As RFI power increases, STAP algorithms become more desirable

• There is a balance between the ability to reject interference and the necessity of limiting errors

Bias Residuals After Compensation, 7-element Adaptive Array	
Code-phase	10s of cm
Carrier-phase	0-10 deg.

