

Coverage Improvement for Dual Frequency SBAS

Todd Walter, Juan Blanch & Per Enge
Stanford University

<http://waas.stanford.edu>



Purpose

- ➔ GPS is adding a 2nd civil frequency in a protected aeronautical band
- ➔ WAAS and EGNOS already have plans to utilize new frequency
- ➔ India and Russia are developing their own SBAS systems
- ➔ Other regions have expressed interest in providing SBAS service
- ➔ Look ahead to possible future global coverage



Dual Frequency

- ➔ Two civil frequencies in the ARNS bands allow aircraft to directly estimate and remove ionospheric delays from their position estimates
 - ➔ *Removes the single largest source of uncertainty affecting today's GNSS*
- ➔ Most significant remaining threats are satellite failure based
 - ➔ *Design a new VPL equation targeting single satellite faults*



Single SV Fault VPL

- ➔ Single frequency VPL well suited for faults affecting multiple ranges
 - ➔ (e.g. *ionospheric threats*)
- ➔ Dual frequency VPL can leverage small probability of satellite fault
 - ➔ *While one SV may be faulted, others are expected to be nominal*
 - ➔ *Still need term for rare nominal and tropospheric threats*
- ➔ Also include terms for nominal biases



Nominal Biases

- ➔ Several error sources have been identified as creating potential bias terms for users
 - ➔ *Errors that will affect the user's range in a consistent manner*
 - ➔ Nominal signal deformations
 - ➔ Antenna group delay biases
- ➔ Bias terms also allow for bounding of non-Gaussian behavior¹

¹ Rife, et al. "Paired Overbounding and Application to GPS Augmentation," IEEE PLANS 2004



Dual Frequency VPL

$$VPL_{H_0} = K_{HMI} \sqrt{\sum_{i=1}^N s_{3,i}^2 \sigma_{ff,i}^2} + \sum_{i=1}^N |s_{3,i} \text{bias}_{nom,i}|$$

$$VPL_{H_1} = K_{fault} \sqrt{\sum_{i=1}^N s_{3,i}^2 \sigma_{ff,i}^2} + \sum_{i=1}^N |s_{3,i} \text{bias}_{nom,i}| + \max_i |s_{3,i} \text{bias}_{fault,i}|$$

$$VPL = \max[VPL_{H_0}, VPL_{H_1}]$$

$$\sigma_{ff,i}^2 = \sigma_{SV_ff,i}^2 + \sigma_{trop,i}^2 + \sigma_{DF_air,i}^2$$

$$\sigma_{DF_air,i}^2 = \left(\frac{f_1^2}{f_1^2 - f_5^2} \right)^2 \cdot \sigma_{L1,i}^2 + \left(\frac{f_5^2}{f_1^2 - f_5^2} \right) \cdot \sigma_{L5,i}^2$$



Simulation Setup

- Stanford's SBAS availability tool, MAAST², used to simulate SBAS
- 28 GPS satellite using almanac from April 8, 2009
 - *removed PRNs 1, 5, 25, & 32*
- Worldwide 5 degree x 5 degree grid
- 300 sec time steps for 1 sidereal day
- Only WAAS Geos provide ranging

2 Jan, et al., "Matlab Simulation Toolset for SBAS Availability Analysis," *ION GPS-2001*



Numerical Values

- σ_{ff} set to $\sigma_{flt}/3$ (includes $\delta UDRE$ term from MT28)
- σ_{trop} as in DO-229D WAAS MOPS
- σ_{L1} ($= \sigma_{L5}$) as in WAAS MOPS
- $K_{HMI} = 5.33$
- $bias_{nom} = 0.5 \text{ m}$
- $K_{fault} = 2.33$
- $bias_{fault} = 5.33 \times \sigma_{flt}$



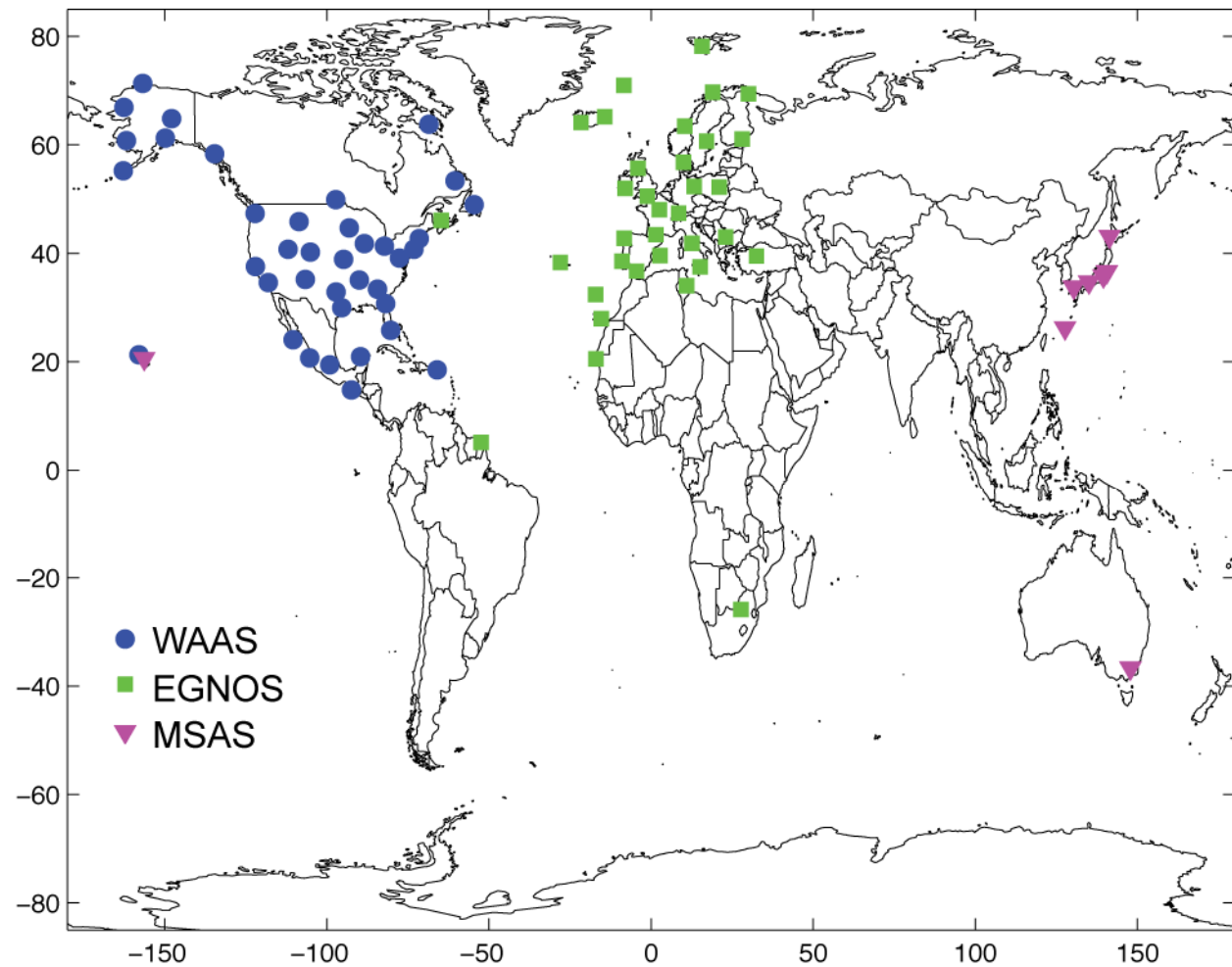
Caveats

- ➔ New and updated reference networks are subject to change
- ➔ MAAST simulates WAAS algorithms and is not as representative of the other SBASs
- ➔ Expansions into the southern hemisphere are speculative on the authors part
- ➔ Coverage plots do not represent official commitment



WAAS
EGNOS
MSAS

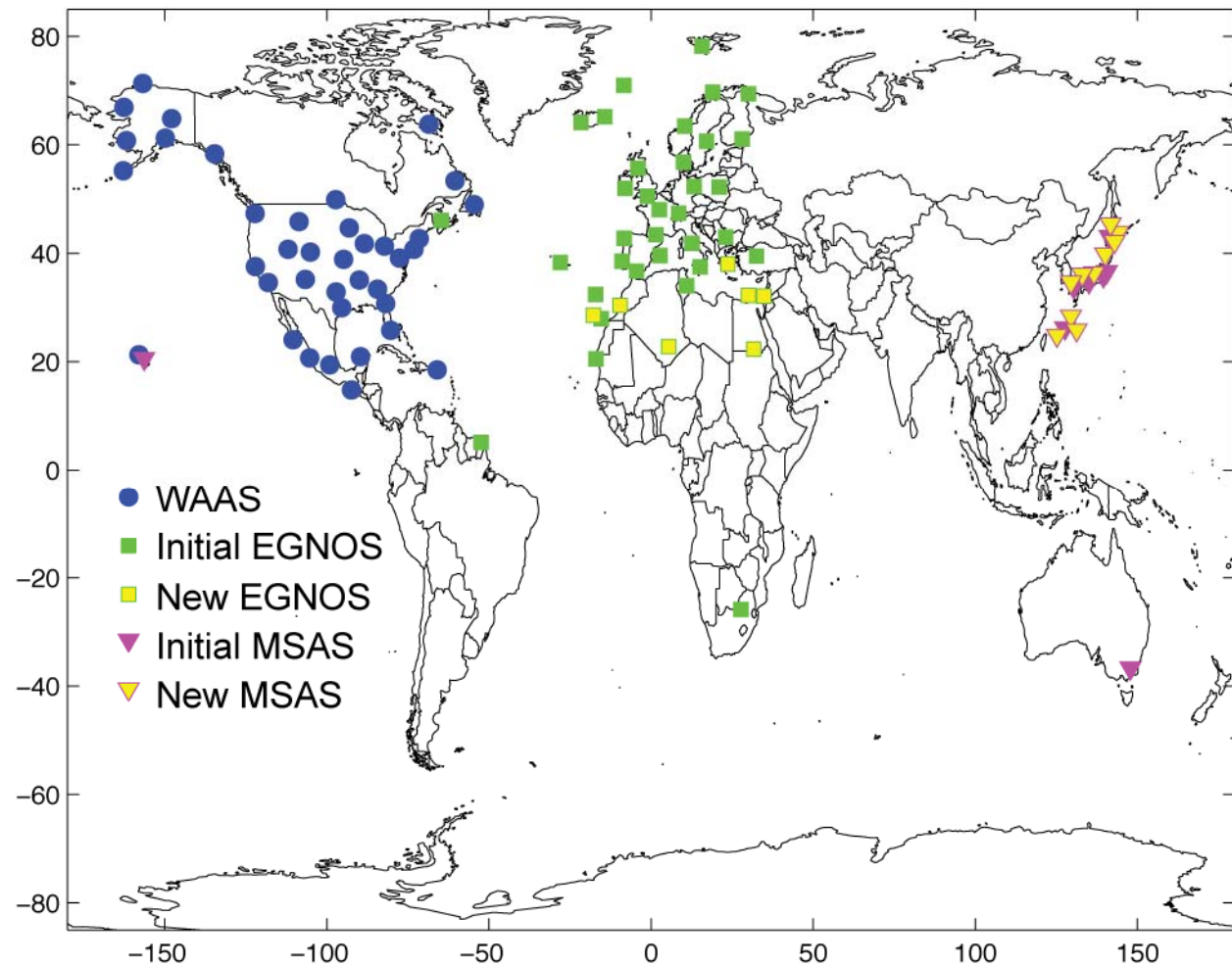
Current Reference Networks





WAAS
EGNOS
MSAS

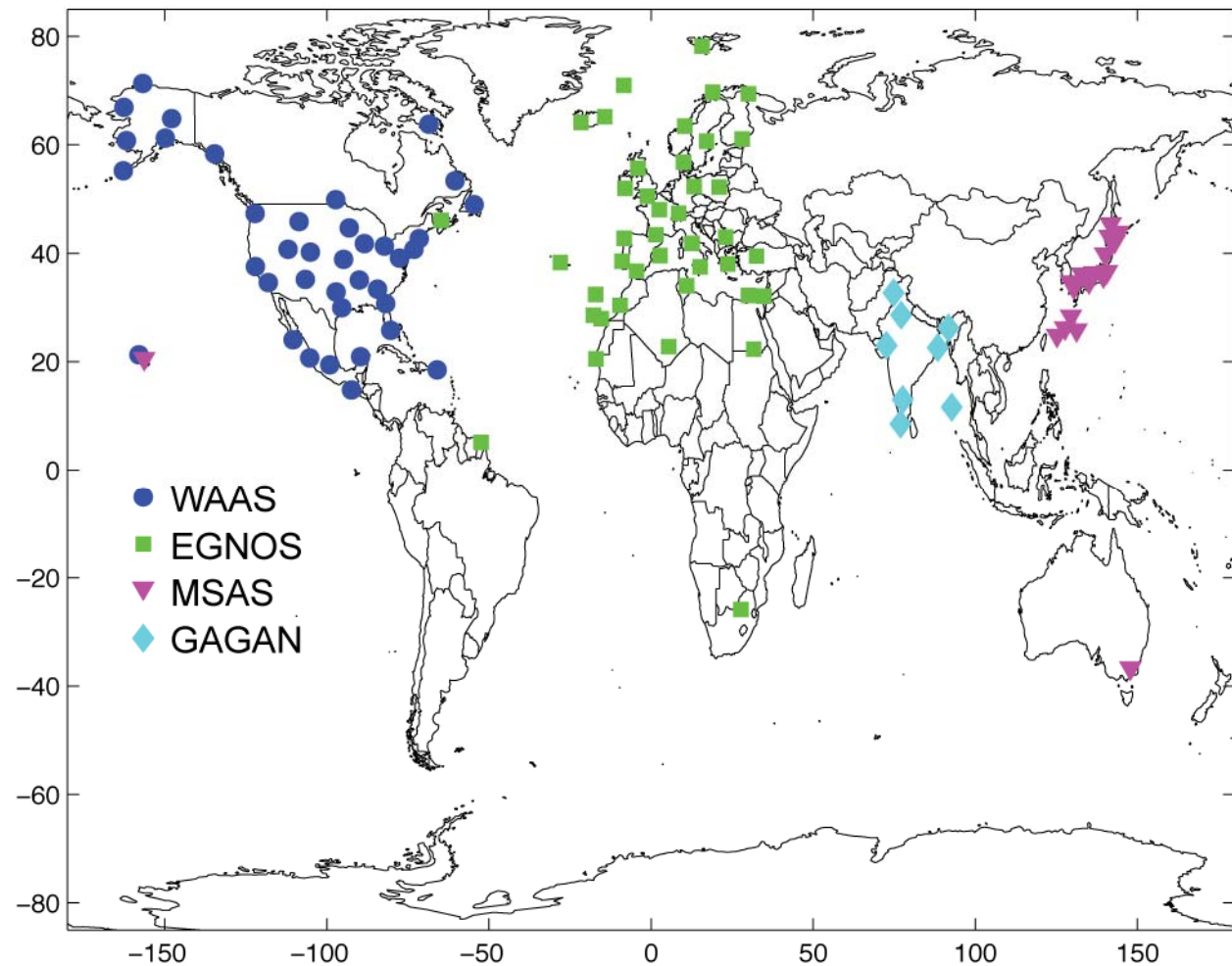
Improved Reference Networks





WAAS
EGNOS
MSAS
GAGAN

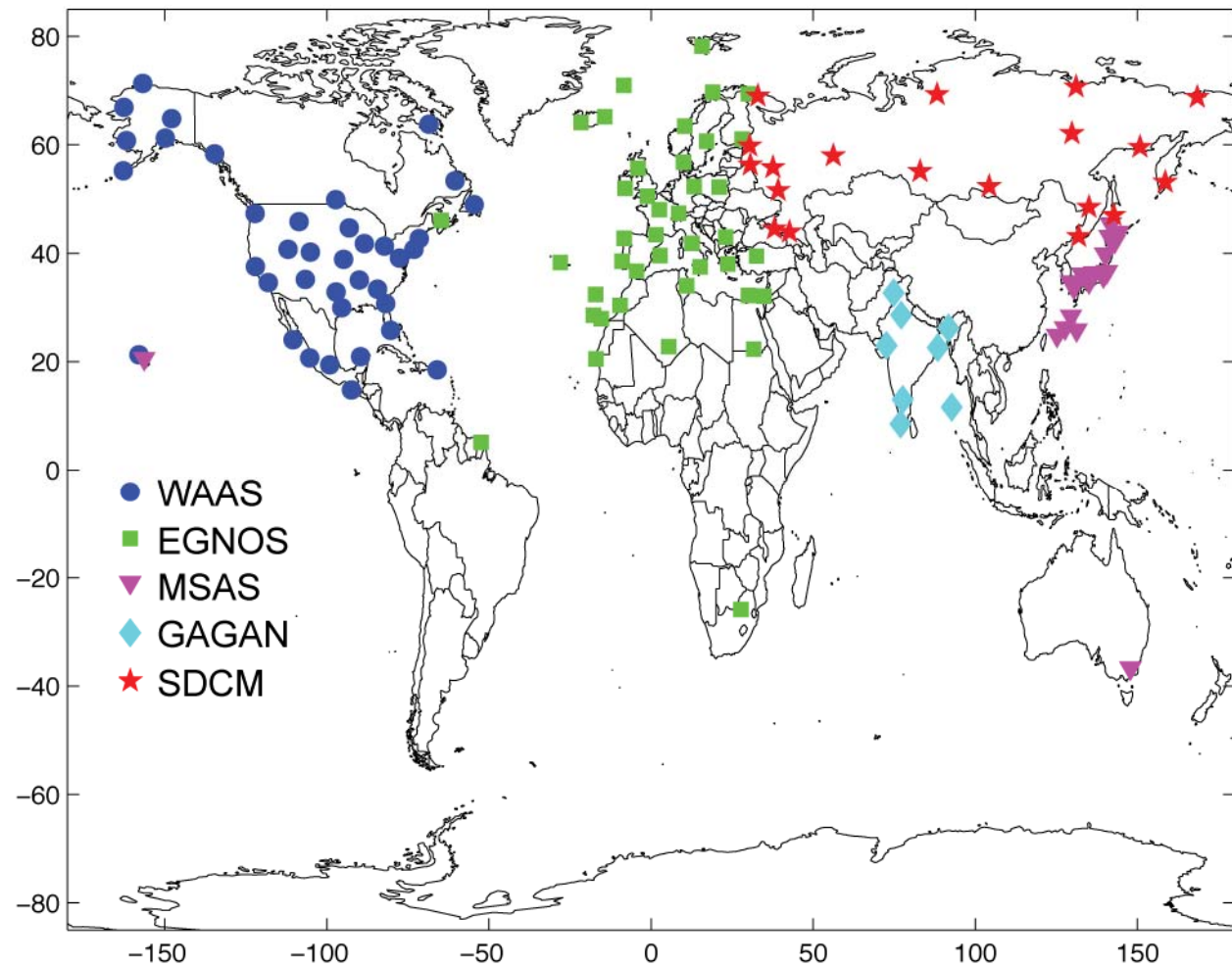
Reference Networks with GAGAN





WAAS
EGNOS
MSAS
GAGAN
SDCM

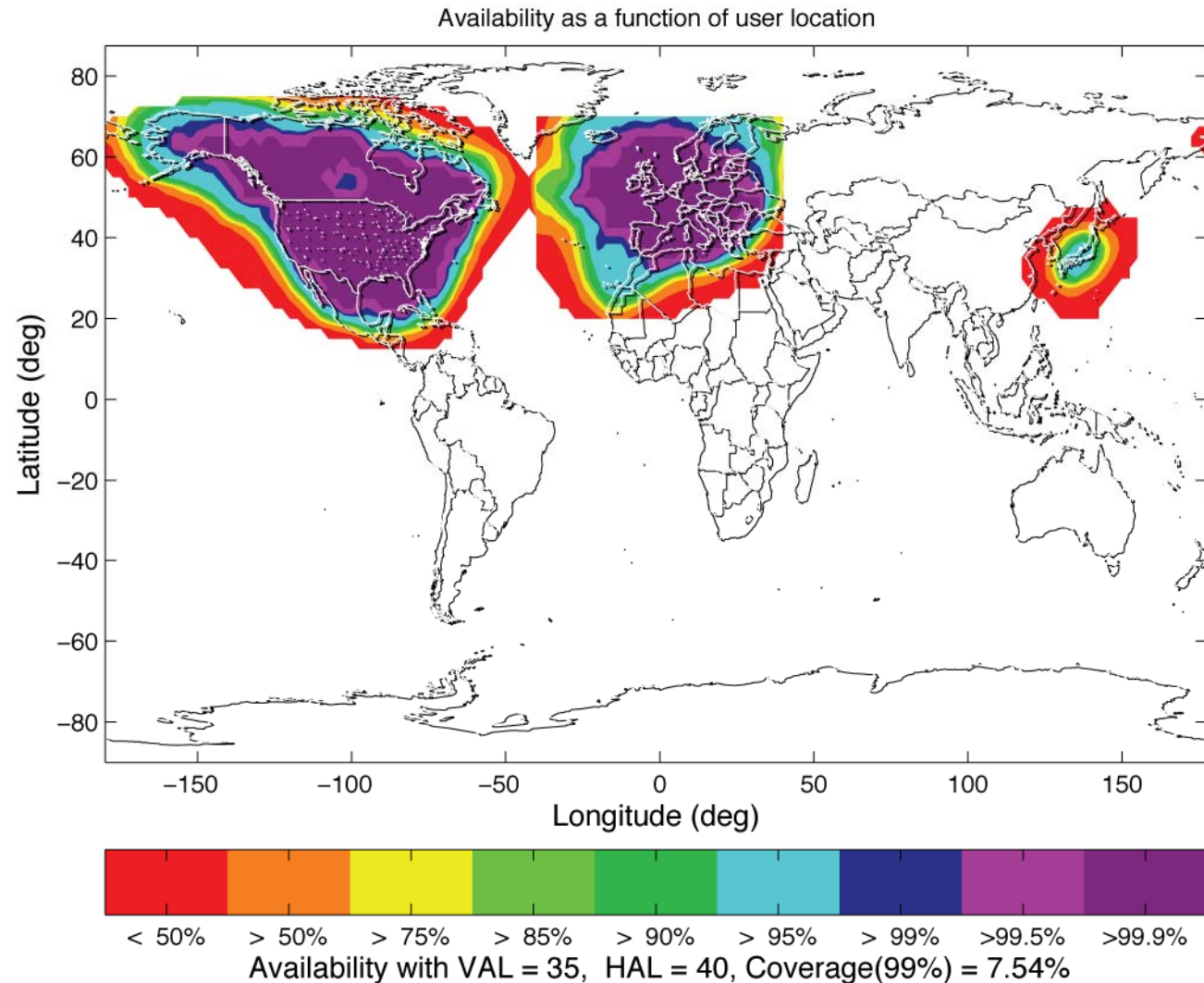
Reference Networks with GAGAN and SDCM





WAAS
EGNOS
MSAS

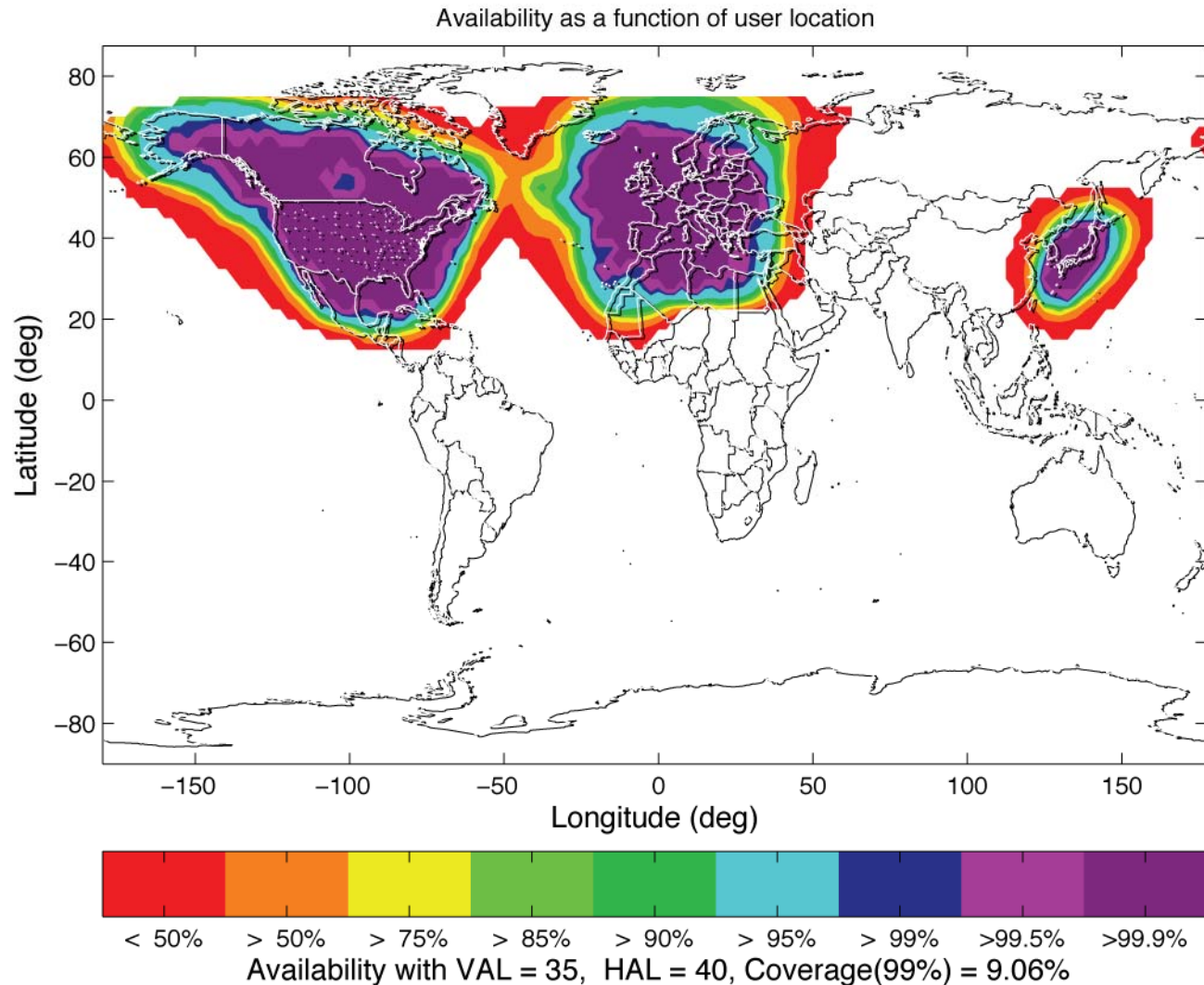
Current Coverage





WAAS
EGNOS
MSAS

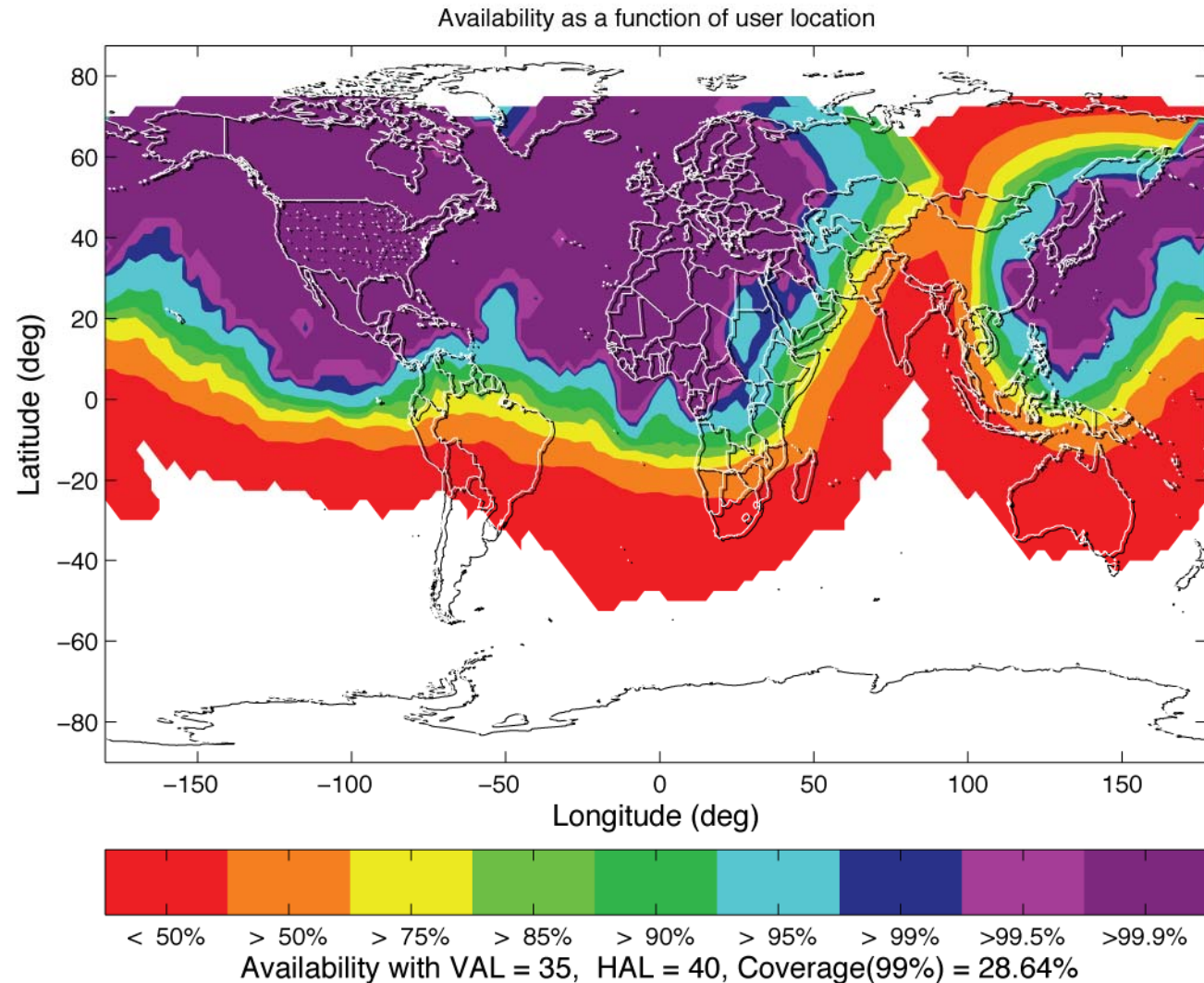
Improved Single Frequency Coverage





WAAS
EGNOS
MSAS

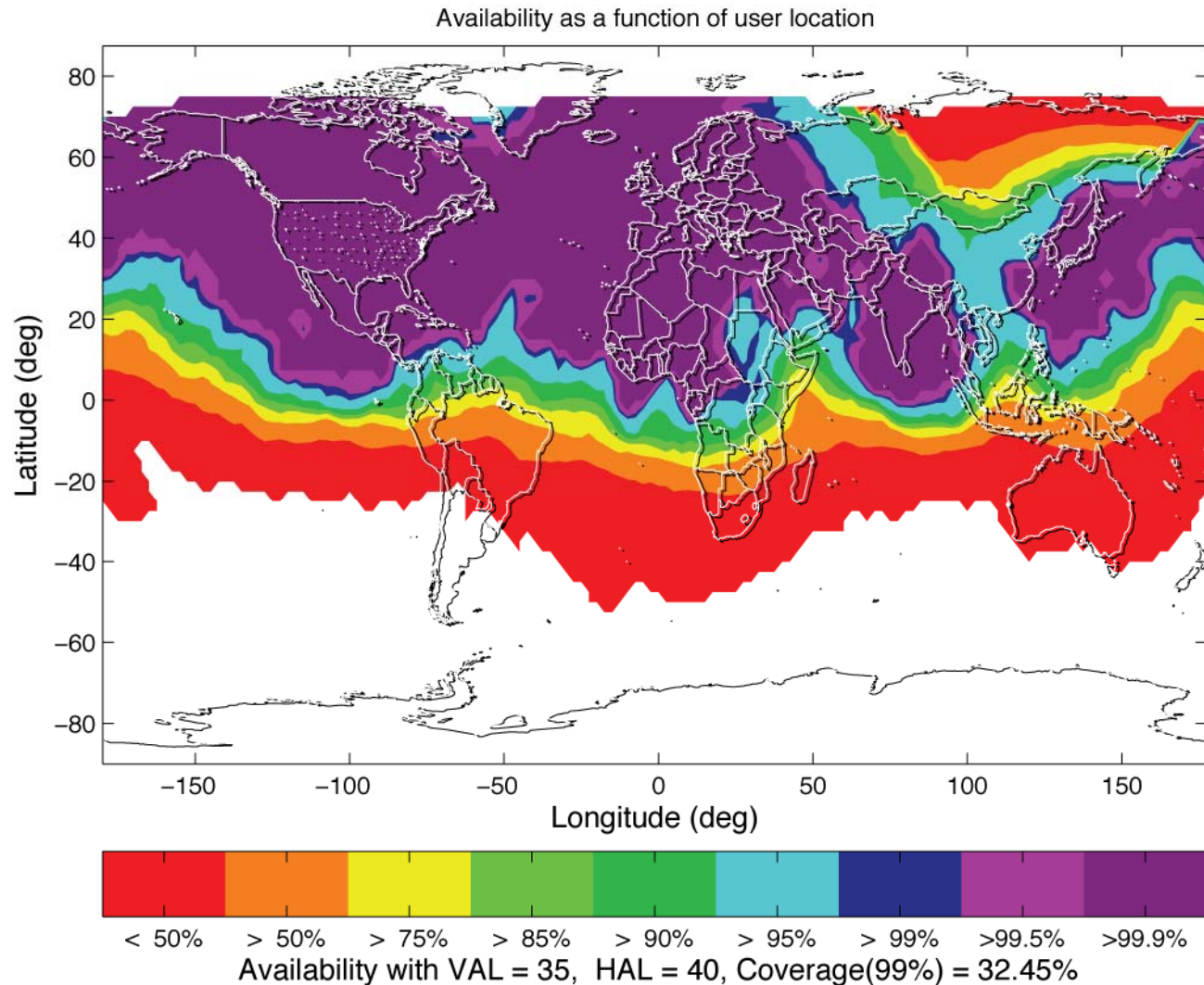
Dual Frequency Coverage (WAAS, EGNOS, MSAS)





WAAS
EGNOS
MSAS
GAGAN

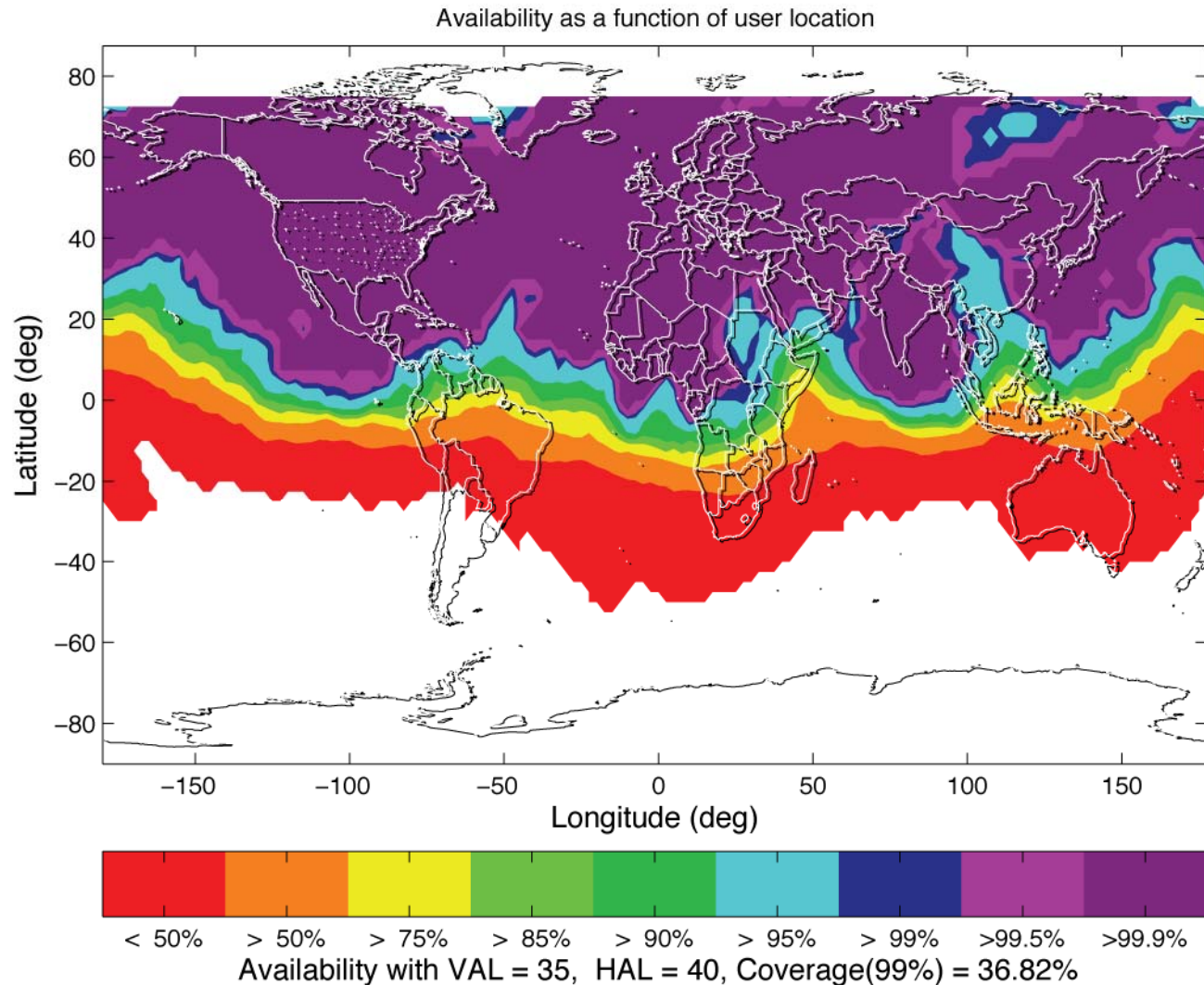
Dual Frequency Coverage (with GAGAN)





WAAS
EGNOS
MSAS
GAGAN
SDCM

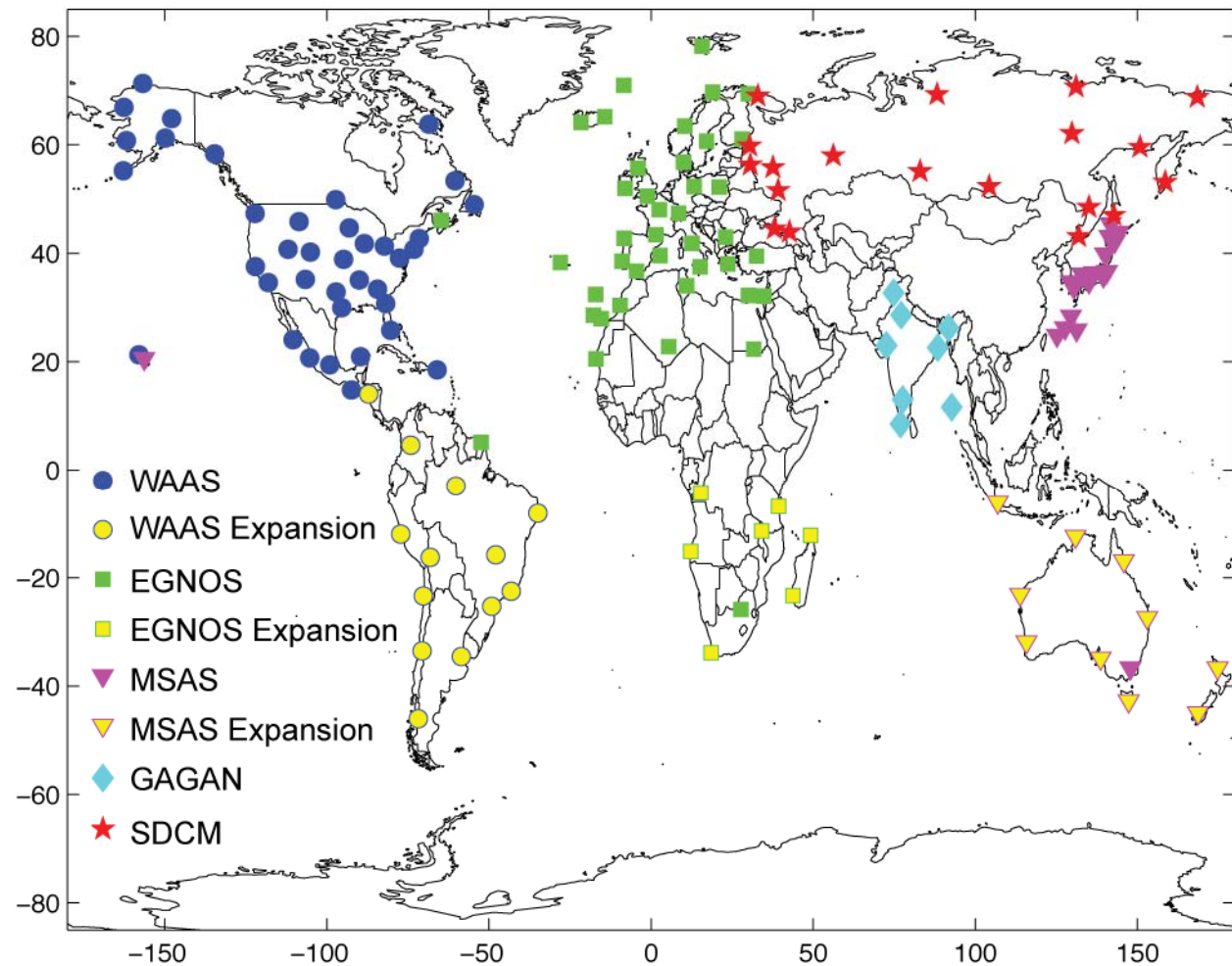
Dual Frequency Coverage (with GAGAN + Russia)





WAAS
EGNOS
MSAS
GAGAN
SDCM

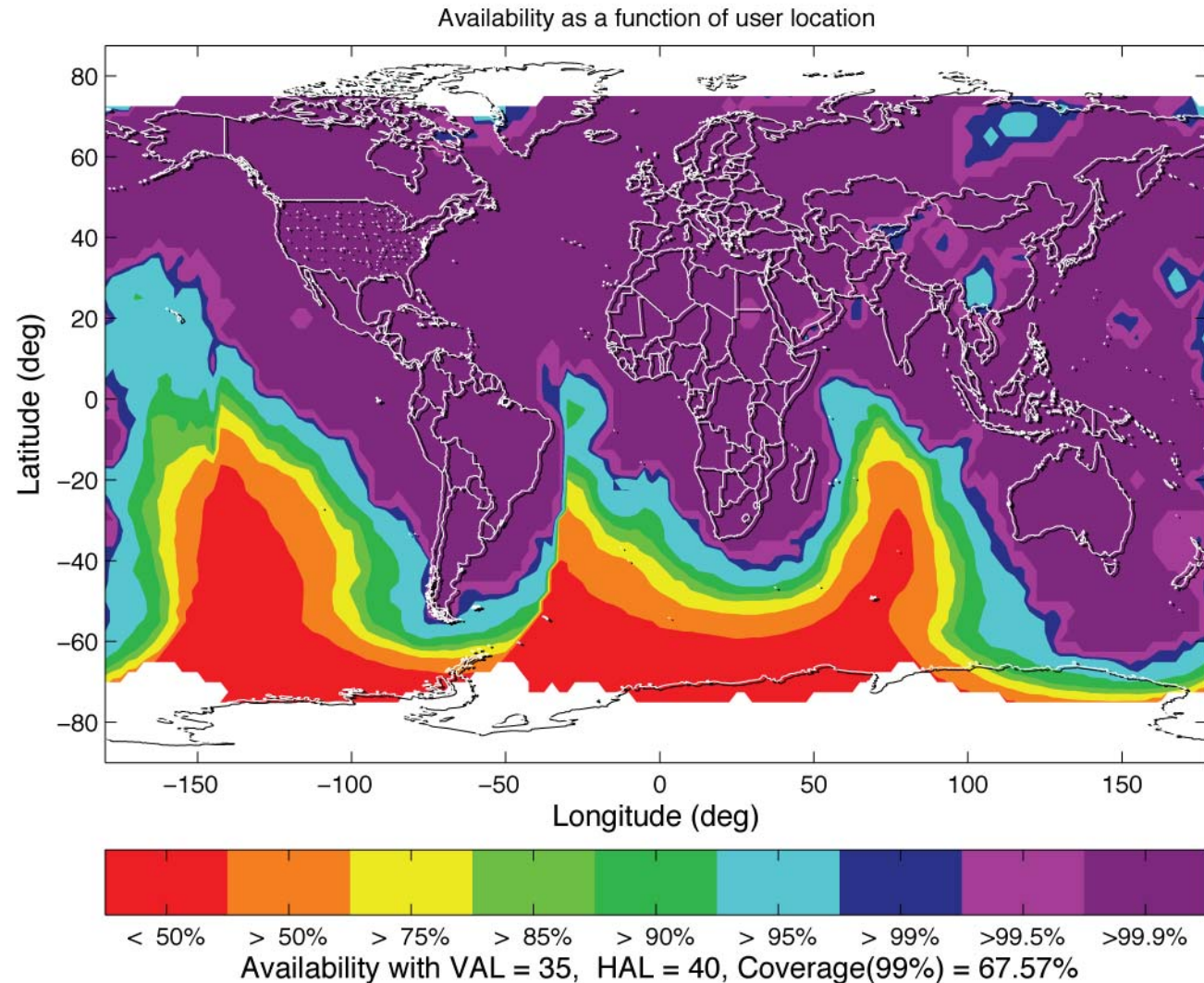
Expanded Networks





WAAS
EGNOS
MSAS
GAGAN
SDCM

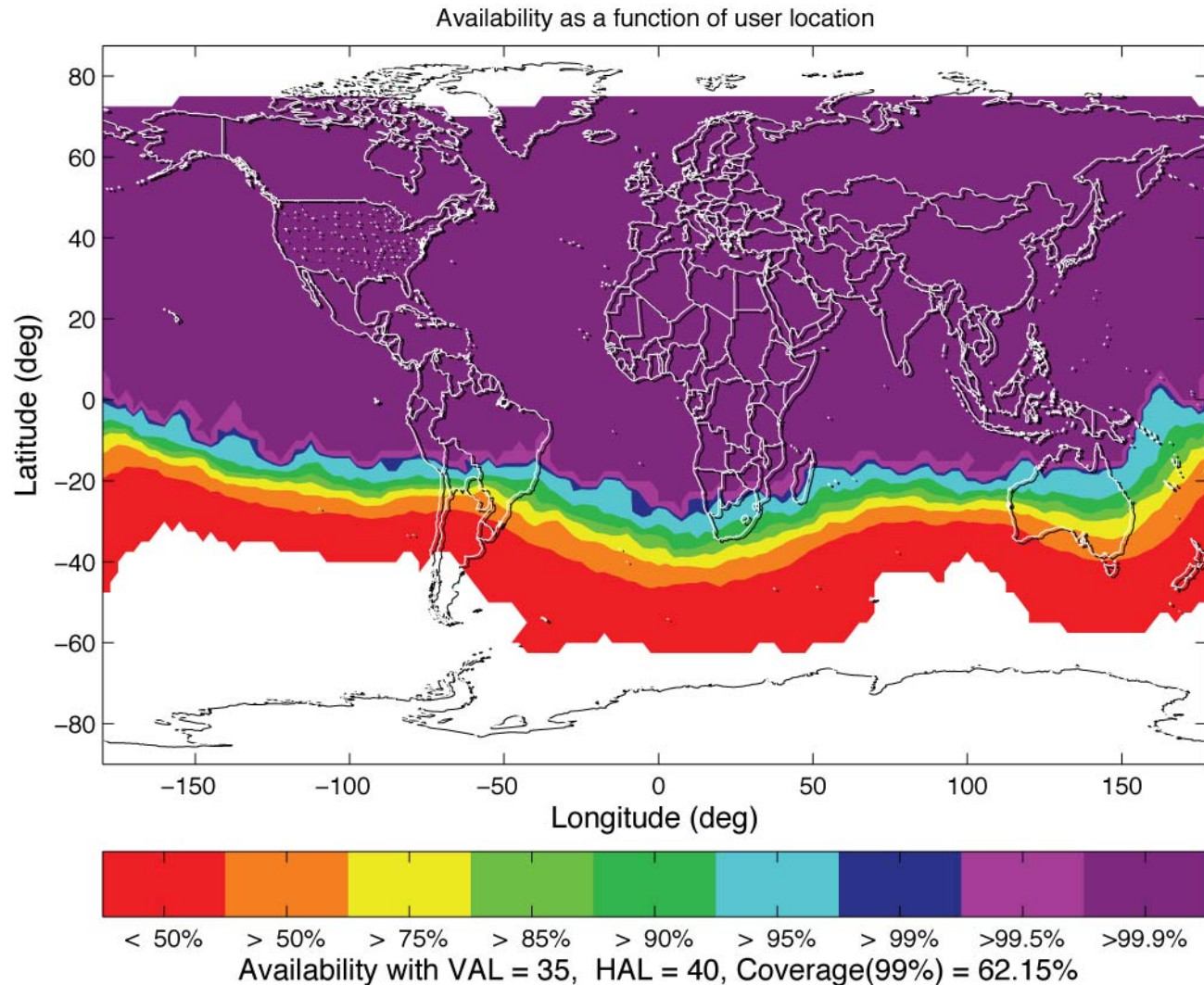
Dual Frequency, Expanded Networks





WAAS
EGNOS
MSAS
GAGAN
SDCM

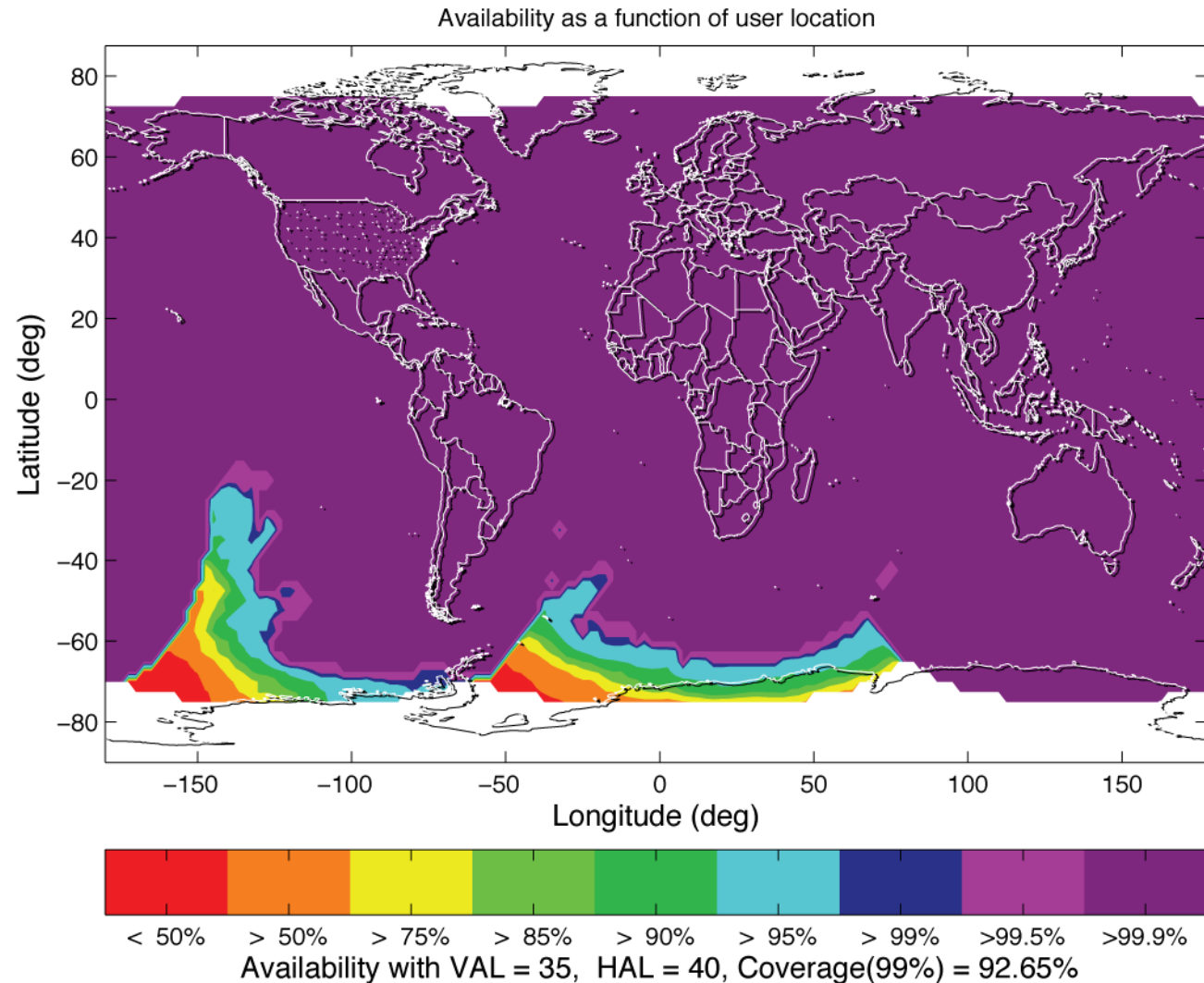
Dual Frequency + Second Constellation (Galileo)





WAAS
EGNOS
MSAS
GAGAN
SDCM

Dual Frequency, Dual GNSS, Expanded Networks





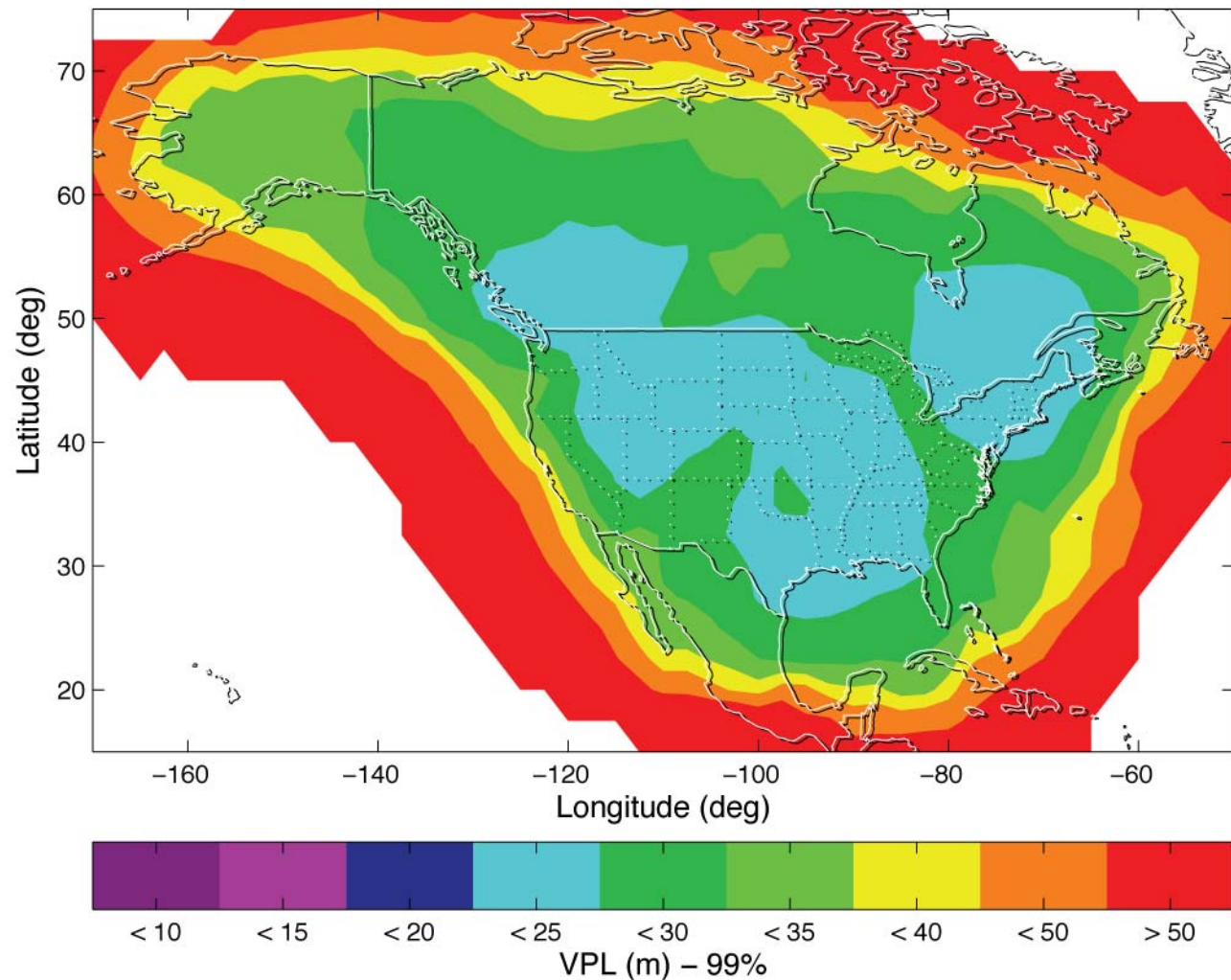
Conclusions

- ➔ Single frequency coverage is good within the countries fielding SBAS
- ➔ Dual frequency extends coverage outside reference networks & allows LPV operation in equatorial areas
- ➔ Expanding networks into southern hemisphere could allow global coverage of land masses
- ➔ Additional constellations allow even greater coverage with fewer stations



WAAS Single Frequency 99% VPL

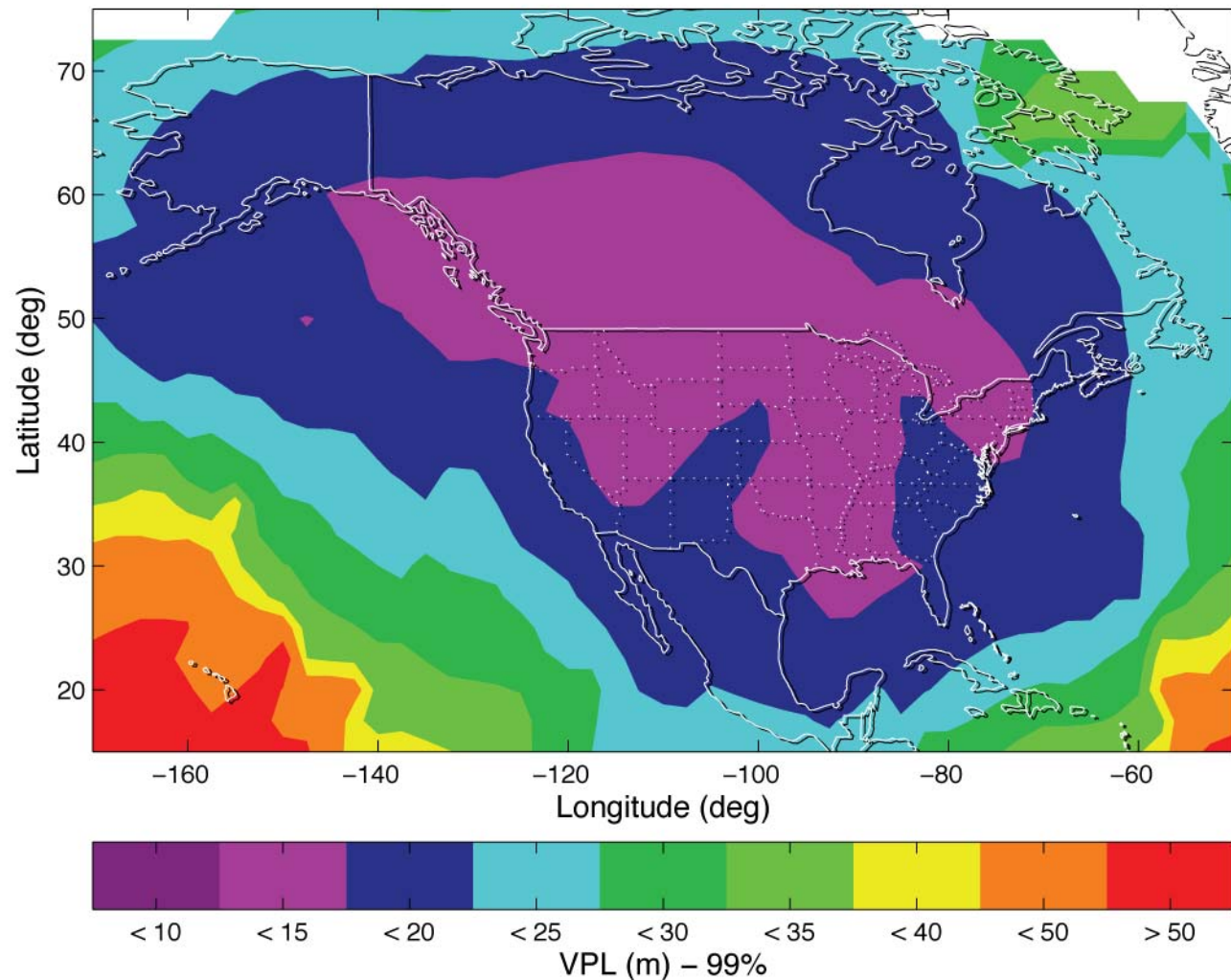
VPL as a function of user location





WAAS Dual Frequency 99% VPL

VPL as a function of user location





WAAS Dual Frequency, Dual GNSS 99% VPL

VPL as a function of user location

