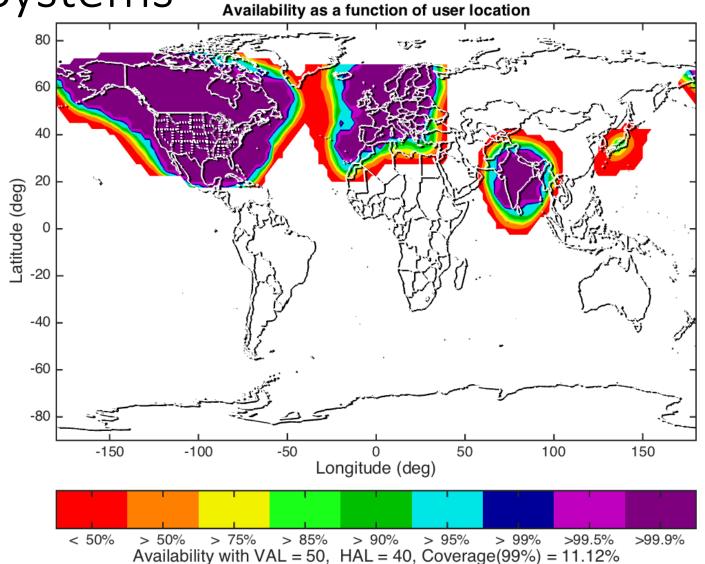
# Introduction to Advanced RAIM

Juan Blanch, *Stanford University*July 26, 2016

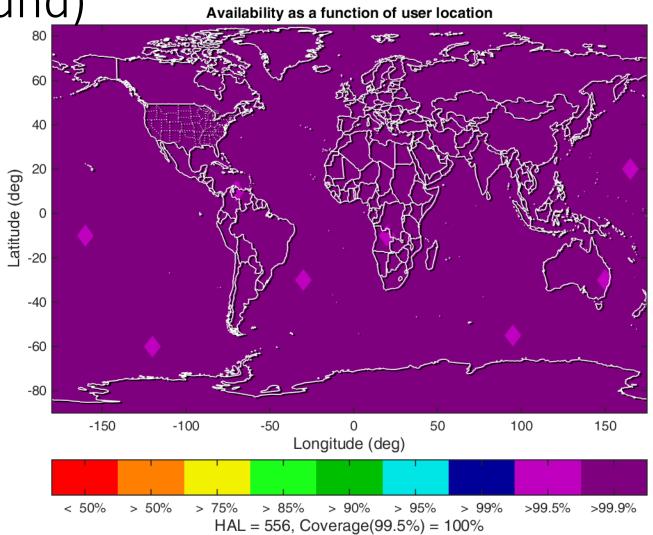
Satellite-based Augmentation
Systems

Availability as a function of user location

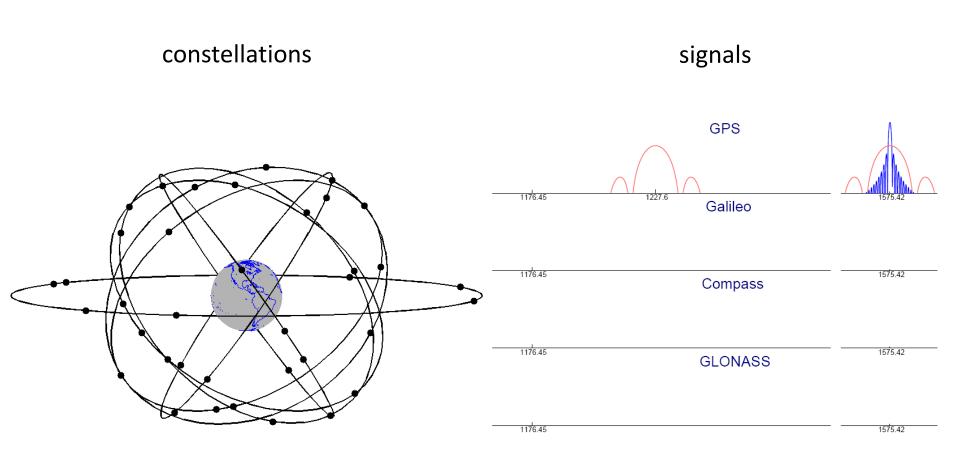


Receiver Autonomous Integrity
Monitoring (556 m Horizontal Error
Bound)

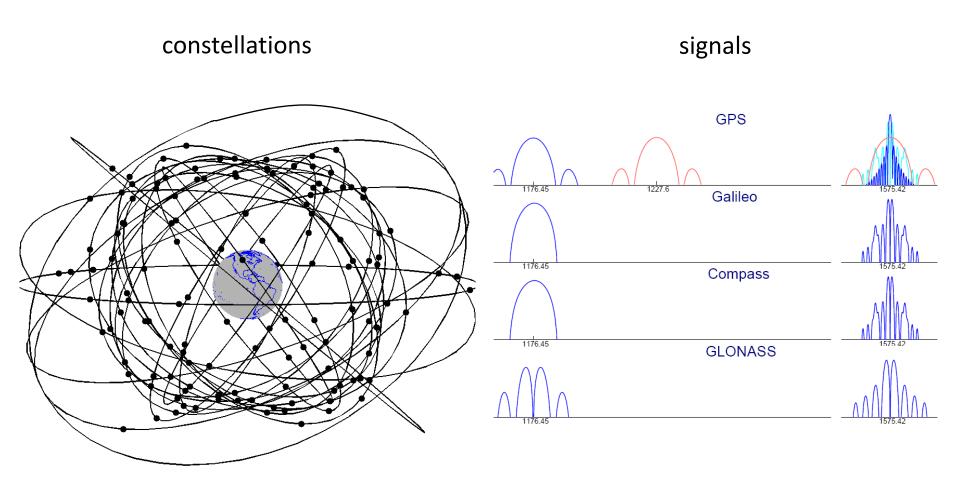
Availability as a function of user location



### Signals used by aviation in 2016



### Signals that may be used by aviation users in 2025



+ better clocks and orbit determination

## Best use of multi-constellation multi-frequency for aviation?

If RAIM could be extended to vertical navigation:

- Worldwide coverage of the most stringent operations
- Arctic Navigation
- No need for GEO satellites
- No real time ground monitoring network

#### What do we want?

$$std(\hat{x}_{v} \quad x_{v})$$
 1.8 m

- Accuracy
- Integrity

$$P(|\hat{x}_v - x| > \text{Alert Limit \& no alert}) \le 10^{-7}$$

Continuity

$$P(alert) \le 8 \times 10^{-6}$$

#### What do we fear?

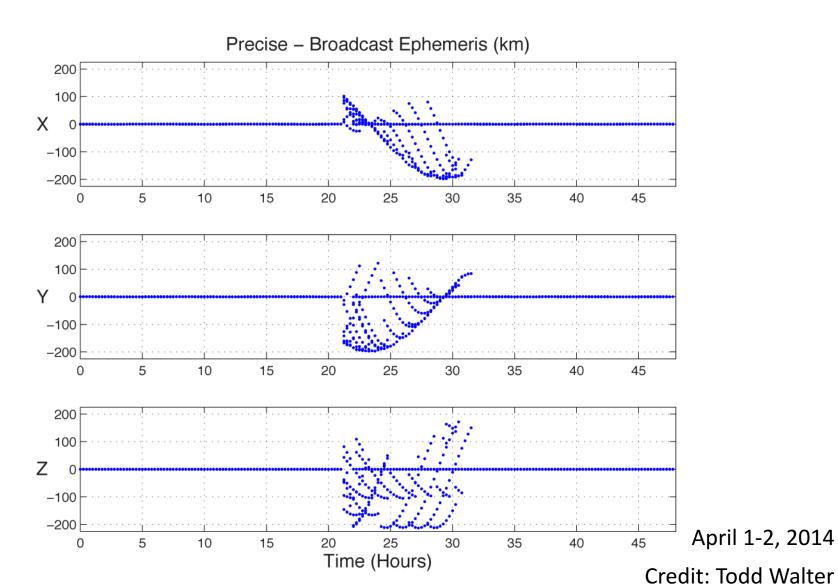
- Faults
- Nominal conditions



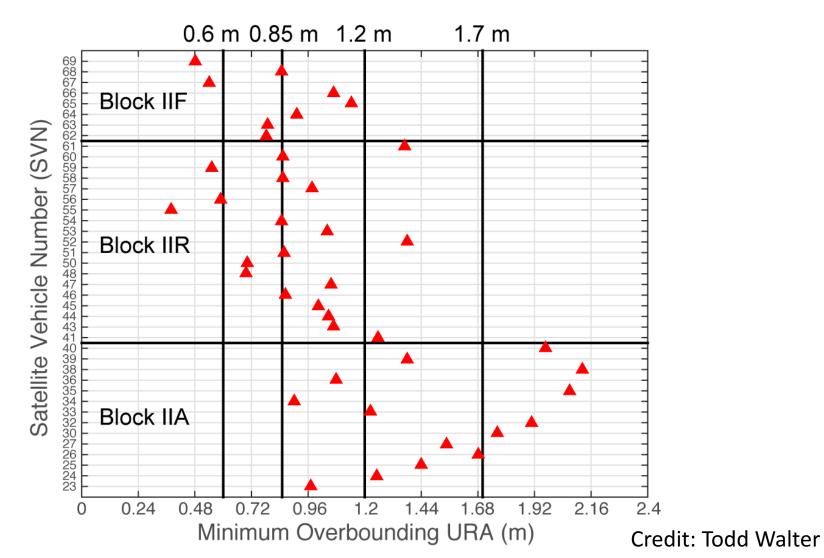
#### Threat model

	Nominal	Narrow fault	Wide fault
Clock and Ephemeris	Orbit/clock estimation and prediction and broadcast limits	Includes clock runoffs, bad ephemeris, unflagged manoeuvres	Erroneous EOPP, inadequate manned ops, ground-inherent failures
Signal Deformation	Nominal differences in signals due to RF components, filters, and antennas waveform distortion	Failures in satellite payload signal generation components. Faulted signal model as described in ICAO	N/A
Code-Carrier Incoherence	e.g. incoherence observed in IIF L5 signal or GEO L1 signals	e.g. incoherence observed in IIF L5 signal or GEO L1 signals	N/A
Interfrequency Biases	Delay differences in satellite payload signal paths	Delay differences in satellite payload signal paths TBC	N/A
Satellite Antenna Bias	Look-angle dependent biases caused at satellite antennas	Look-angle dependent biases caused at satellite antennas	N/A
Ionosphere	N/A	Scintillation	Multiple scintillations at solar storms
Troposphere	Nominal troposphere error (after applying SBAS MOPS model for tropo correction)	N/A	N/A
Receiver Noise and Multipath	Nominal noise and multipath terms in airborne model (TBC Gailleo BOC(1,1) and L5/E5a))	e.g.: receiver tracking failure or multipath from onboard reflector. TBC	e.g.: receiver tracking multiple failure or multipath from onboard reflector. TBC

#### GLONASS constellation wide fault



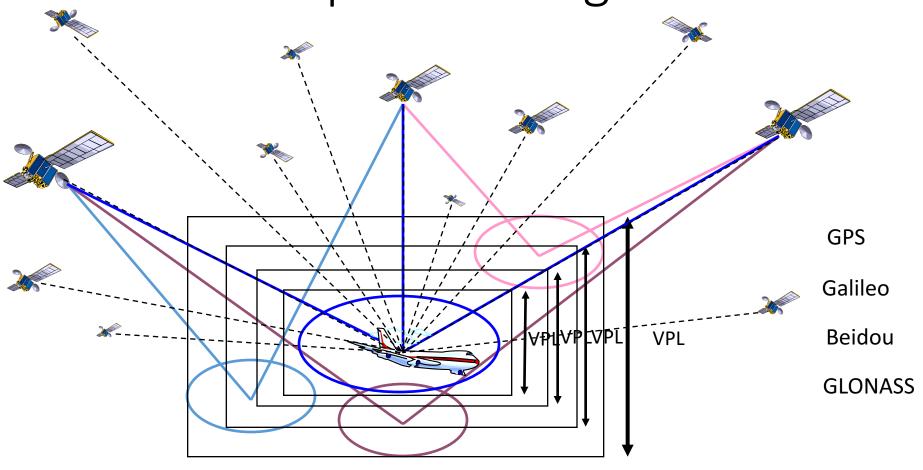
## GPS Service history: Nominal clock and ephemeris errors (2009-2014)



# Mapping the threat model into the Integrity Support Message

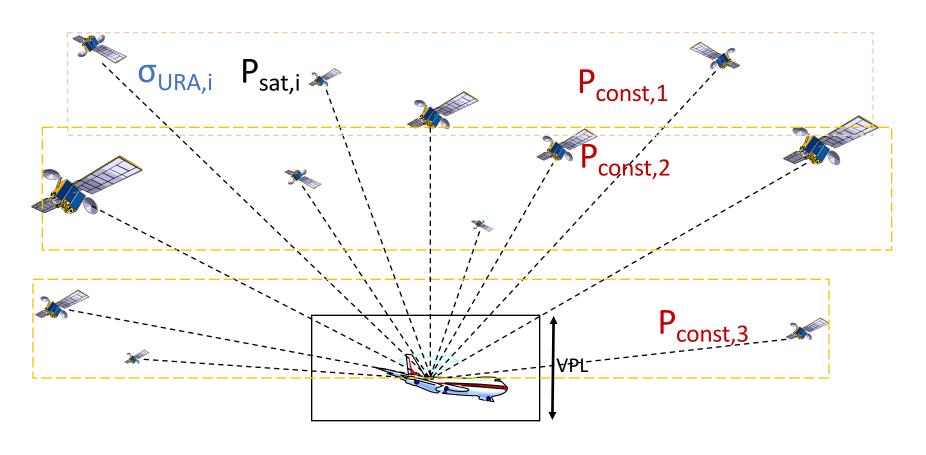
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#### Solution Separation Algorithm



Blanch et al "Advanced RAIM user Algorithm Description: Integrity Support Message Processing, Fault Detection, Exclusion, and Protection Level Calculation," *Proceedings of the 25th International Technical Meeting of The Satellite Division of the Institute of Navigation (ION GNSS 2012)*, Nashville, TN, September 2012

### Advanced RAIM concept



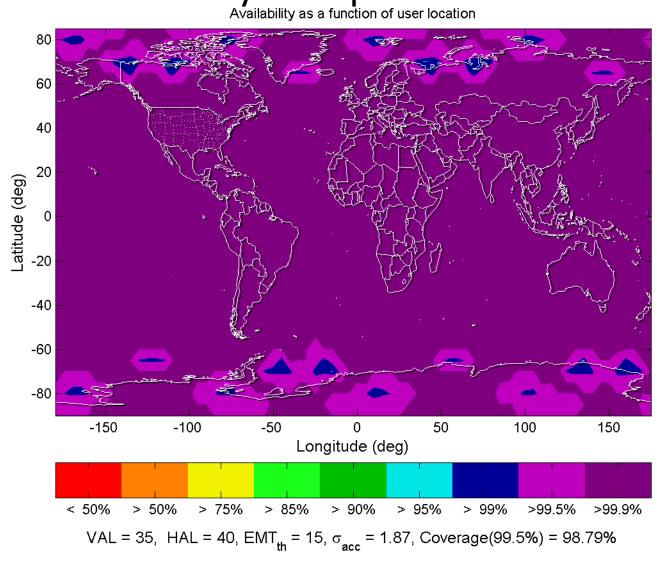
Integrity Support Message :  $\sigma_{URA,i}$   $P_{sat,i}$   $P_{const,j}$ 

#### Integrity Support Message

	Parameter	Description	Value	Size (bits)			
	ISM_WN	ISM Week Number	[0, 1, 1023]	10			
ader	ISM_TOW	ISM Time of Week (hours)	[0, 1, 167]	8			
Data Header	ANSP ID	Service Provider Identification	[0, 1, 255]	8			
Dat	Criticality	Usable for Precise/Vertical?	[0, 1]	1			
	Total Header = 27 bits						
Per Constellation Parameters	$Mask_i$	32 bits indicating whether an SV is valid for ARAIM (1) or not (0)	$[m_1, m_2, \ldots m_{32}]$	32			
Para	$P_{const,i}$	Probability of constellation fault at a given time	[10-8, 10-5, 10-4, 10-3]	2			
ion	$P_{sat,j}$	Probability of satellite fault at a given time	[10-6, 10-5, 10-4, 10-3]	2			
tellat	$a_{\mathit{URA},j}$	Multiplier of the URA for integrity	[1, 1.25, 1.5, 2, 2.5, 3, 5, 10]	3			
Cons	$a_{\mathit{URE},j}$	Multiplier of the URA for continuity & accuracy	[0.25, 0.5, 0.75, 1, 1.25, 1.5, 2, 4]	3			
Per (	$b_{nom,j}$	Nominal bias term in meters	[0.0:0.25: 2.5,, 3, 4, 5, 7.5, 10]	4			
	Total Core = 4	46 bits x 4 Constellations = 184 bits					

Would fit in one SBAS message (250 bits), or in one GPS CNAV message (300 bits)

# Multi-constellation L1-L5 ARAIM availability map



GPS 24 – Galileo 24

URA = 1 m

 $P_{const} = 10^{-4}$ 

# Vertical ARAIM: L1-L5 performance

LPV-200

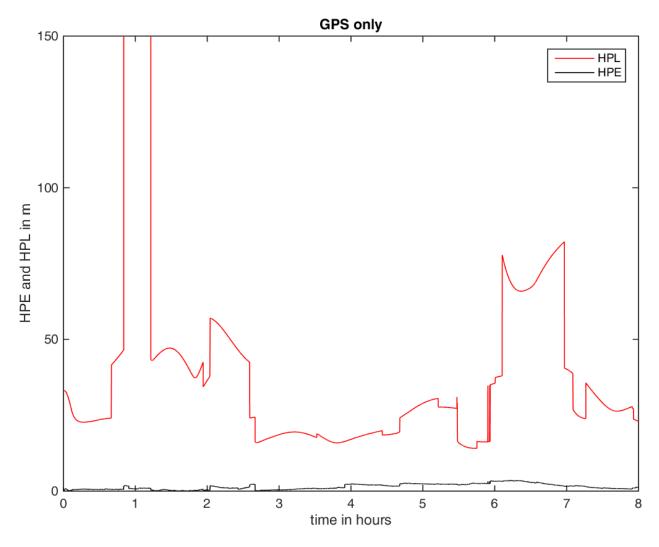
Constellation/URA	.5 m	.75 m	1 m	1.5 m	2 m
Depleted (GPS 23 – GAL 23)	88.1	86.1	81.3	38.1	0
Baseline (GPS 24 – GAL 24)	100	100	98.8	88.2	3
Optimistic (GPS 27 – GAL 27)	100	100	99.8	94.9	21.8

#### LPV-250

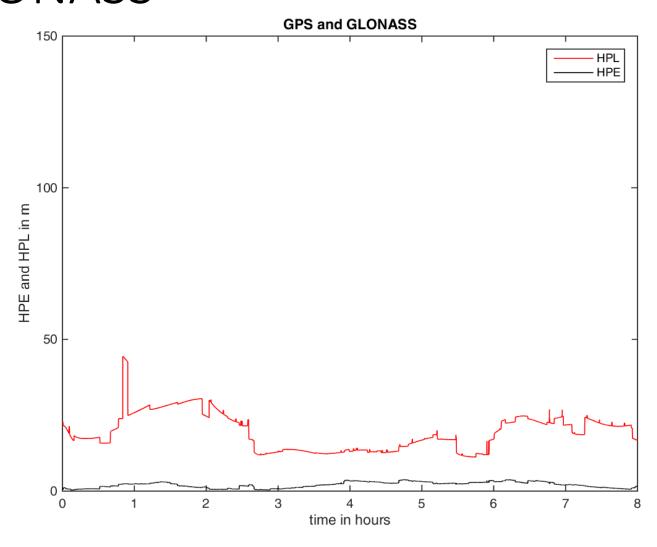
Constellation/URA	.5 m	.75 m	1 m	1.5 m	2 m
Depleted (GPS 23 – GAL 23)	94.0	91.8	87.7	75.0	35.4
Baseline (GPS 24 – GAL 24)	100	100	100	99.0	89.5
Optimistic (GPS 27 – GAL 27)	100	100	100	100	93.85

Constellation wide fault is mitigated by the residuals check:  $P_{const} = 10^{-4}$ 

### Horizontal ARAIM with GPS only (matches current RAIM performance)



## Horizontal ARAIM with GPS and GLONASS



#### Summary

- Advanced RAIM is a natural and very promising method to exploit multi-constellation GNSS.
- It will improve dramatically horizontal performance and may provide vertical guidance
- Advanced RAIM is conceptually simple (at the user level)
- Challenges remain for the determination of the Integrity Support Message

#### Reports and publications

Working Group C, ARAIM Technical Subgroup, Interim Report, Issue 1.0, December 19, 2012.
 Available at:

http://ec.europa.eu/enterprise/newsroom/cf/\_getdocument.cfm?doc\_id=7793 http://www.gps.gov/policy/cooperation/europe/2013/working-groupc/ARAIM-report-1.0.pdf

 GPS-Galileo Working Group C ARAIM Technical Subgroup Milestone 2 Report, February 11, 2015. Available at:

http://www.gps.gov/policy/cooperation/europe/2015/working-group-c/ http://ec.europa.eu/growth/tools-databases/newsroom/cf/itemdetail.cfm?item\_id=8191

#### Other publications:

- Walter, Todd, Blanch, Juan, "Characterization of GNSS Clock and Ephemeris Errors to Support ARAIM," *Proceedings of the ION 2015 Pacific PNT Meeting*, Honolulu, Hawaii, April 2015, pp. 920-931.
- Blanch, J., Walter, T., Enge, P., Kropp, V.,"A Simple Position Estimator that Improves Advanced RAIM Performance," IEEE Transactions on Aerospace and Electronic Systems Vol. 51, No. 3, July 2015.
- Blanch, J., Walter, T., Enge, P., Lee, Y., Pervan, B., Rippl, M., Spletter, A., Kropp, V., "Baseline Advanced RAIM User Algorithm and Possible Improvements," *IEEE Transactions on Aerospace and Electronic Systems*, Volume 51, No. 1, January 2015.
- Blanch, J., Walter, T., and Enge, P., "Results on the Optimal Detection Statistic for Integrity Monitoring," Proceedings of the Institute of Navigation International Technical Meeting 2013, San Diego, January 2013. Submitted to NAVIGATION.
- Phelts, R.E., Blanch, J., Walter, T., Enge, P., "The Effect of Nominal Signal Deformation Biases on ARAIM Users," Proceedings of the 2014 International Technical Meeting of The Institute of Navigation, San Diego, California, January 2014, pp. 56-67.