

**ATOMIC CLOCKS TECHNOLOGIES FOR GALILEO
&
RELATED APPLICATIONS**

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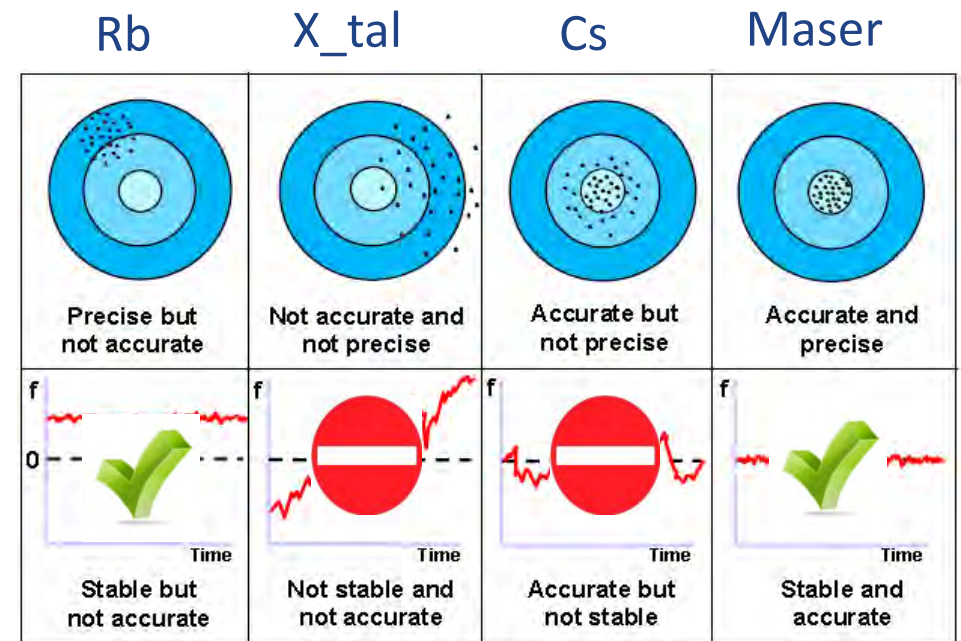
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GNSS ONBOARD ATOMIC CLOCKS REQUIREMENTS DEPENDS ON :

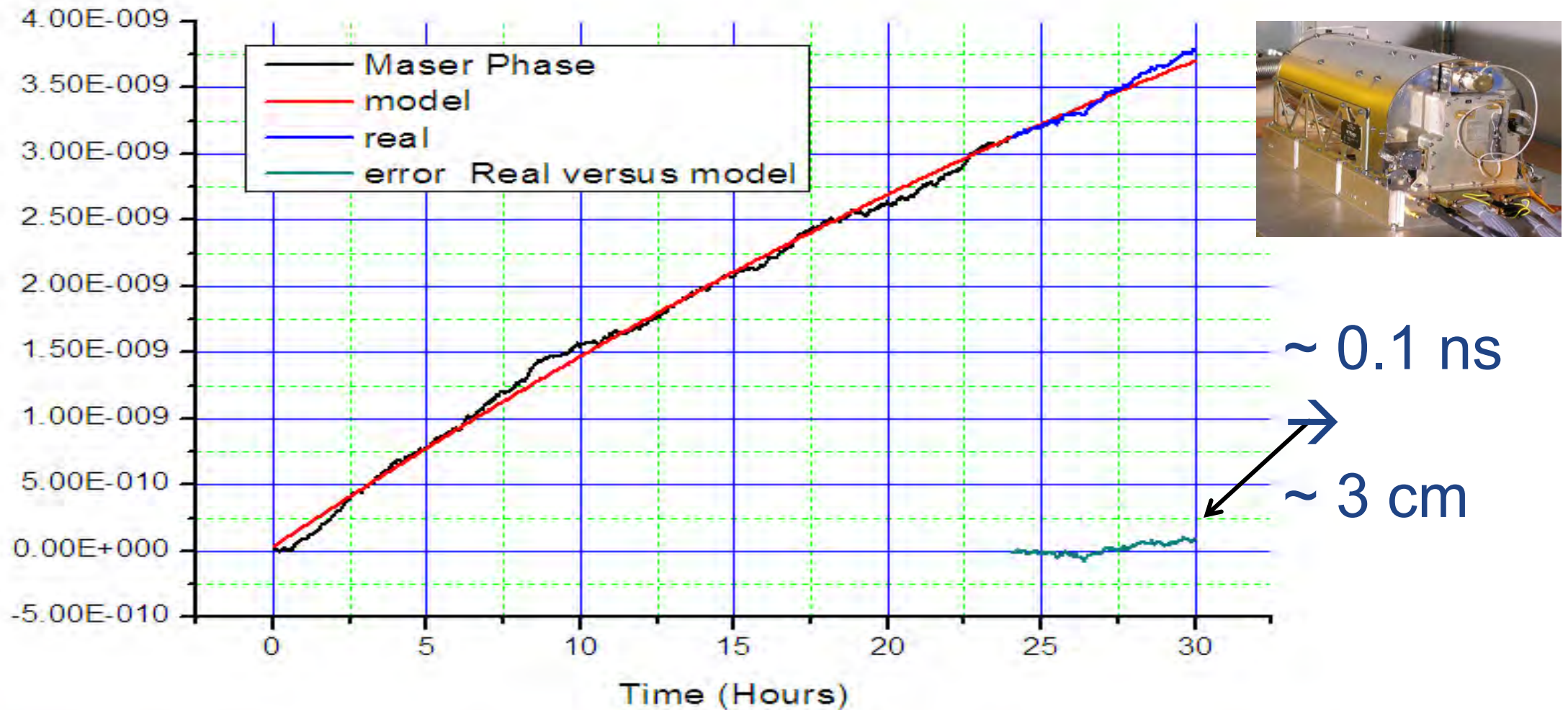
- Autonomy (clock model upload rate: tens of minutes to days)
- Navigation and positioning accuracy (meters to tens of meters)
- Satellite platform design and technical requirements
- Availability of the reference signal on board within specifications

Clocks key parameters:

- Long term drift **or** drift stability
- Short term stability
- Frequency sensitivity to environment (temperature, magnetic field, voltage, radiations)
- Reliability figure of onboard elements versus requested Availability figure



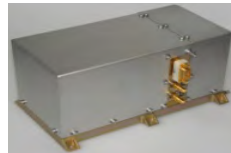
POSITION ERROR INDUCED BY THE ONBOARD PASSIVE MASER



SPACE RUBIDIUM (RAFS) AND PASSIVE HYDROGEN MASER (PHM)

Spectratime delivered more than 100 RAFS flight models and 50+ PHM flight physics packages.

3.2kg

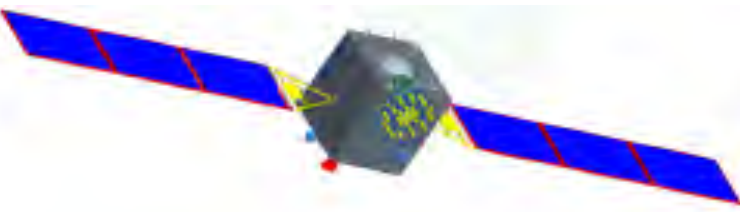
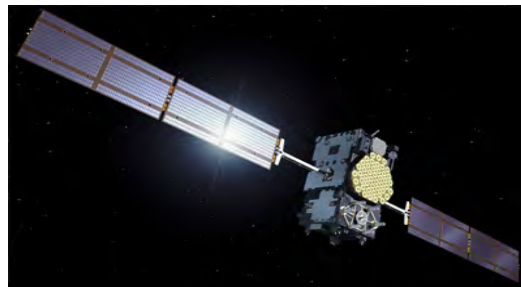


18kg

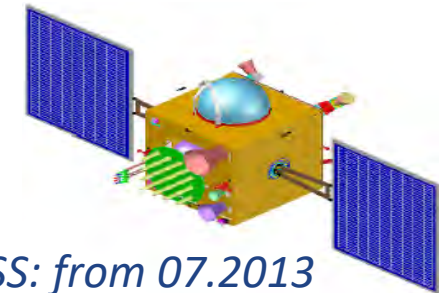
Both clock technologies have a number of years of flight experience, of which more than 100 RAFS, and 45 PHM are actually flying in various orbits.



Galileo GIOVE –IOV : from 12.2005



BeiDou: from 04.2009

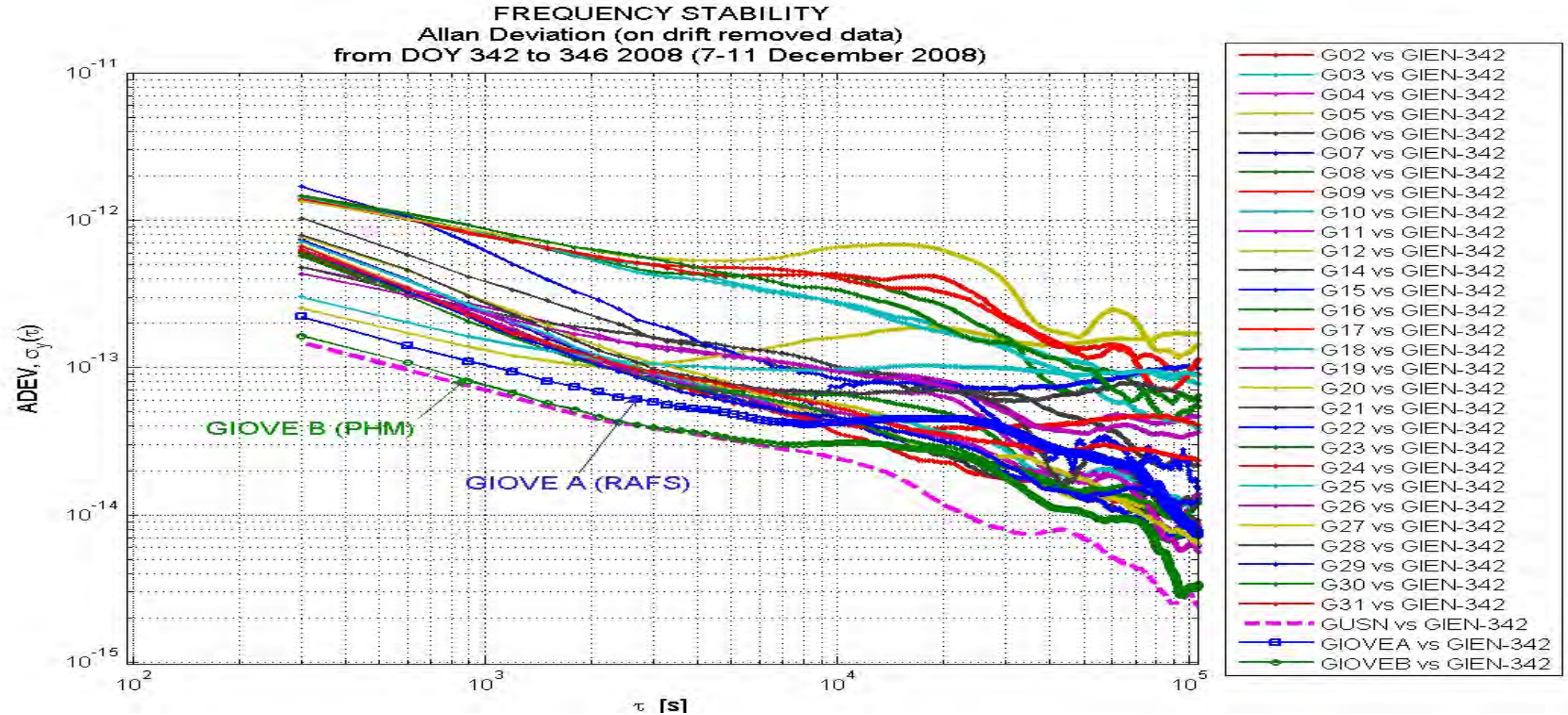


IRNSS: from 07.2013



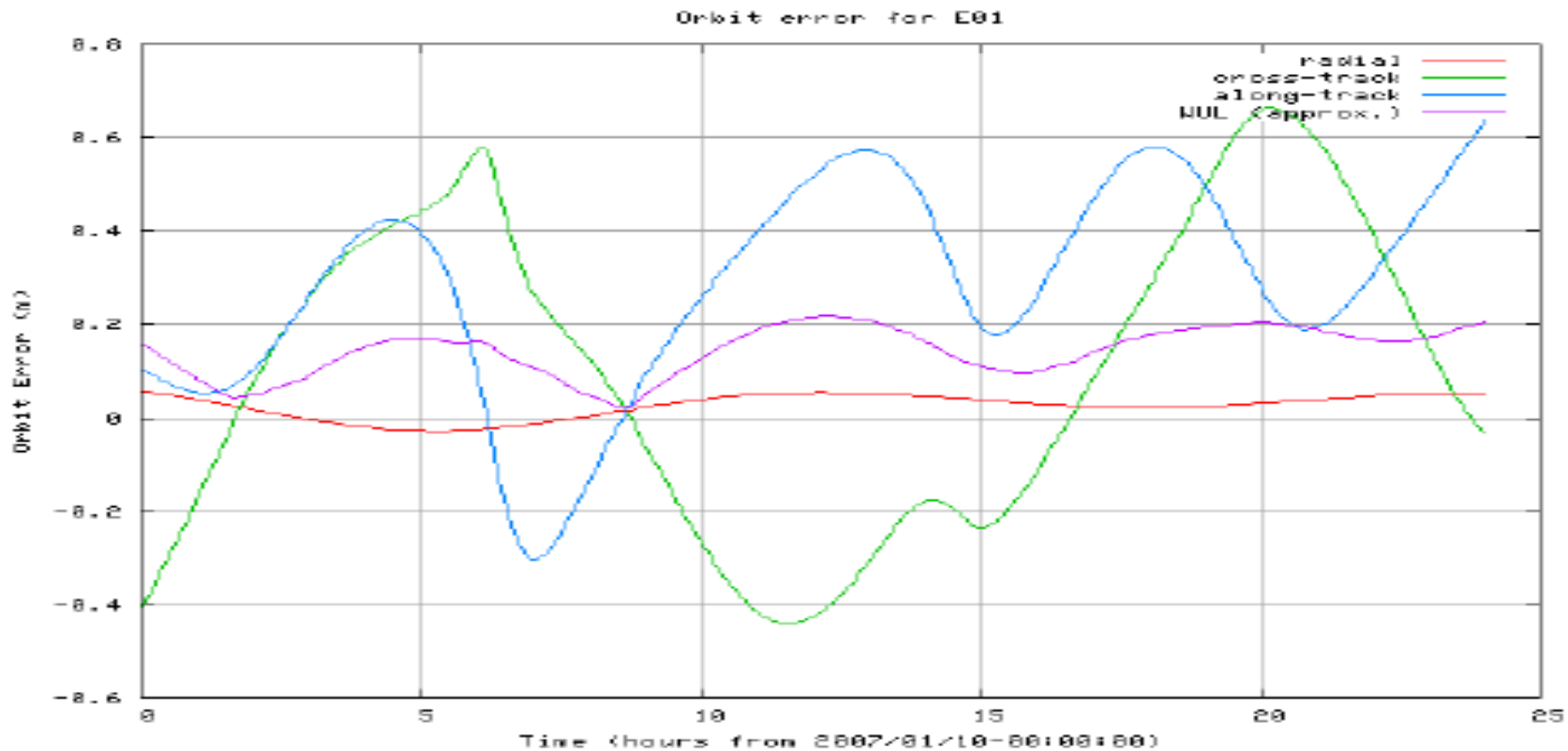
Galileo FOC: 12.2013

FREQUENCY STABILITY COMPARISON BETWEEN GALILEO AND GPS



Source: ESA/GMV, EFTF 2009

ORBIT PREDICTION ERROR LIMITING THE ON BOARD CLOCK CLOCK MODELLING



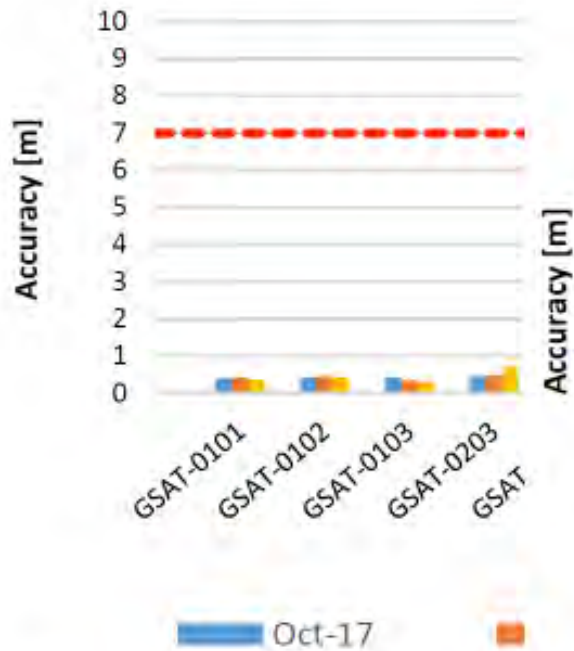
GIOVE orbit prediction error

Source: ESA/GMV , EFTF 2009

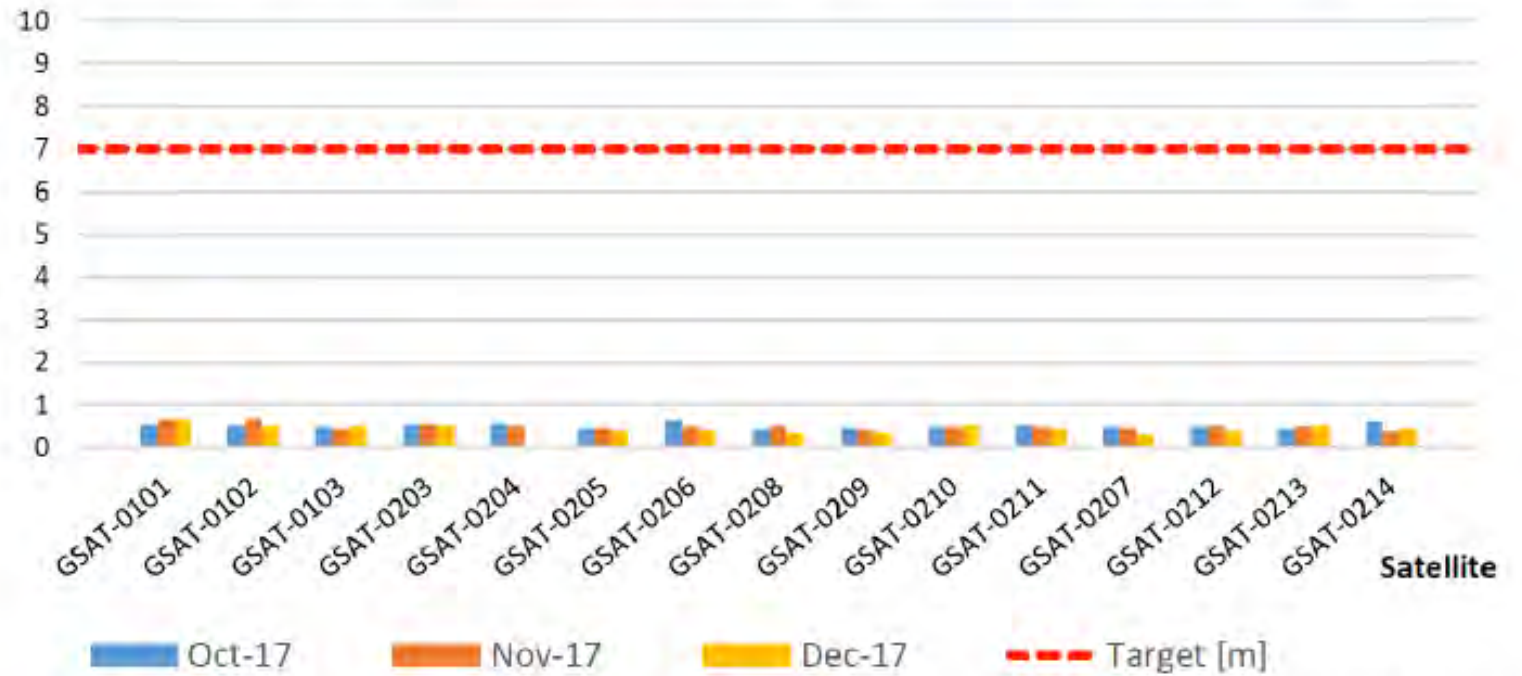
GALILEO SYSTEM PERFORMANCES

Ranging Performance

Galileo Signal in Space Ranging Accuracy - Worst case **Dual Frequency** [m]



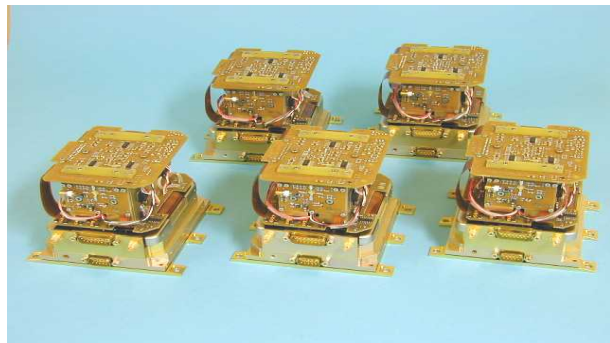
Galileo Signal in Space Ranging Accuracy - Worst case **Single Frequency** [m]



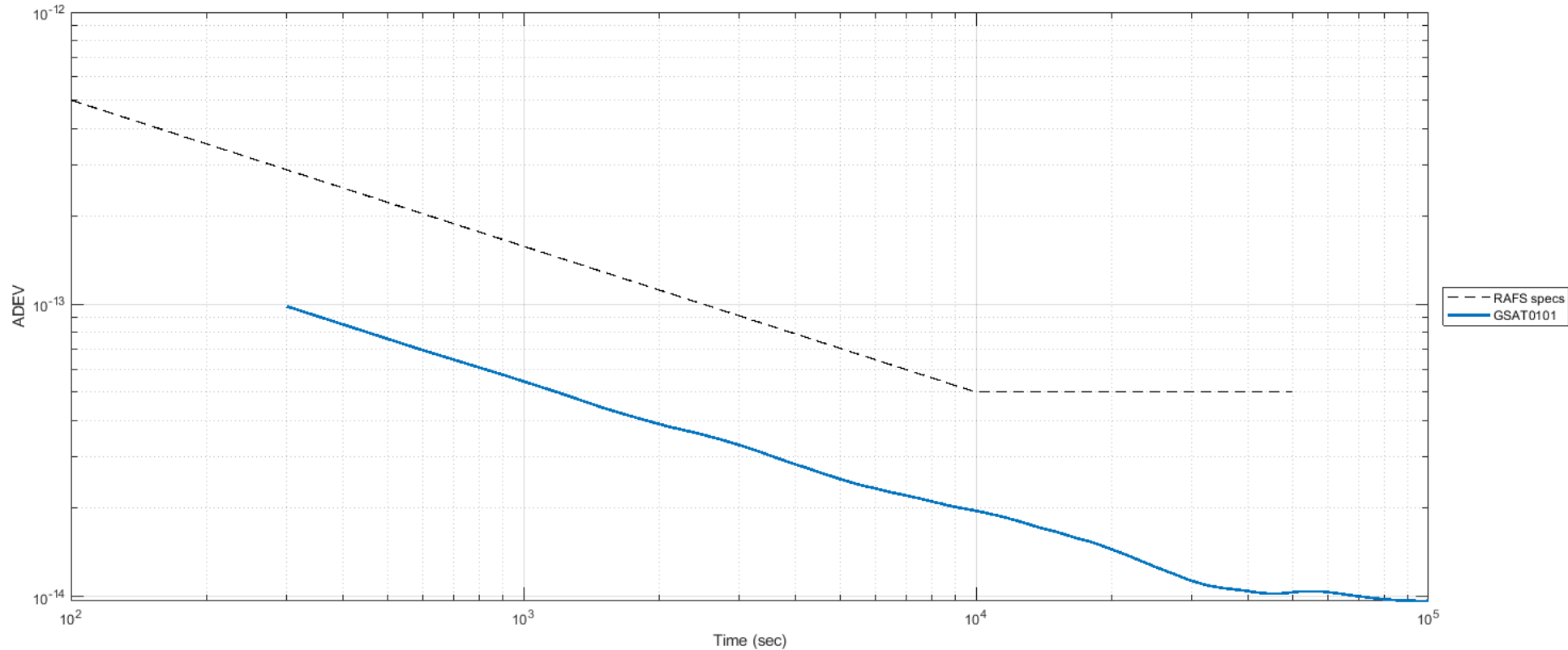
Source: ESA , EFTF 2018

SPACE RAFS DEVELOPEMENT : A 25+ YEARS STORY

- **1991** Space clock first design start for RadioAstron mission
- **1996** First ESA contract for NavSat clock design
- **2002** Life time program of 5 EQM models + QM, meeting all expectations in terms of lifetime (>12 years) along with radiations testing.
- **2005-2006** First launch & Design of 100% Swiss unit
- **2012-2017** Performances improvements under ESA GNSS evolution program



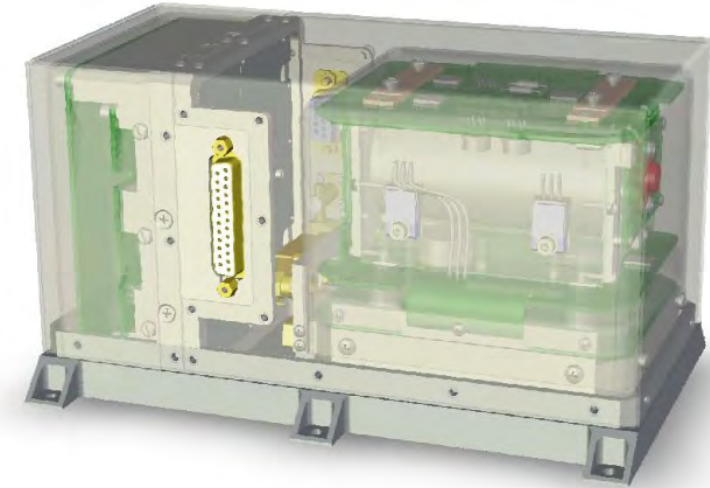
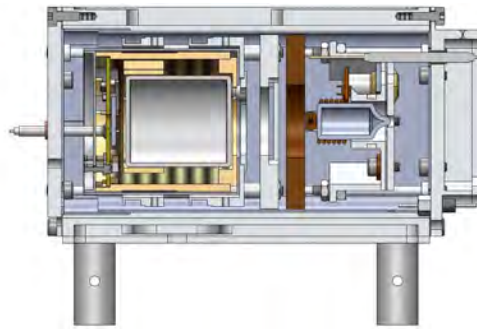
FREQUENCY STABILITY OF ON BOARD RAFS GAST101



Source: ESA , EFTF 2018

PHYSICS PARAMETERS IMPROVEMENT

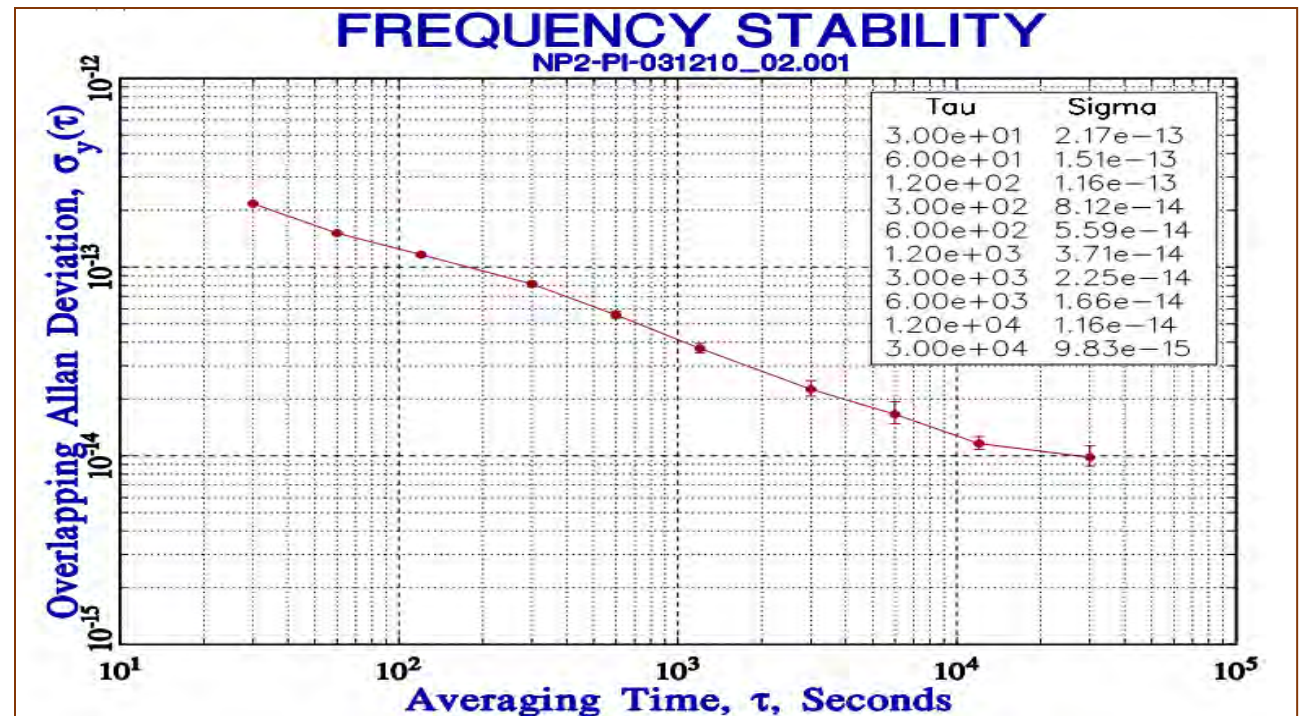
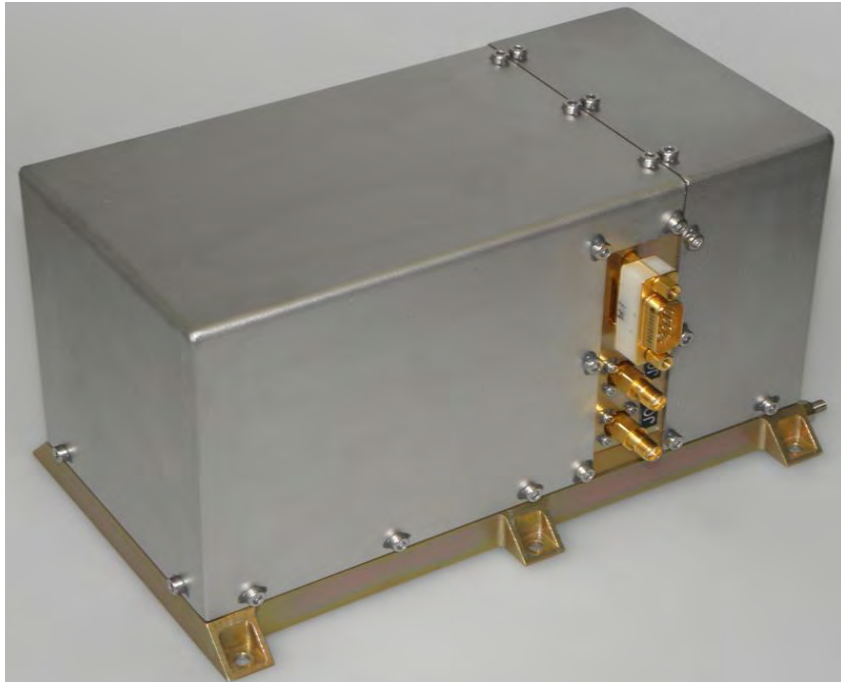
- The new RAFS design is focused to improve its robustness to external or internal perturbations/variatioins.
- The RAFS robustness is better as the various key parameters are improved.
- The key parameters are typically:
 - Light shift
 - Pressure shift & Power shift
 - Thermal sensitivity of the cell
 - Thermal sensitivity of the lamp



	Old design	New design	Improvement factor
Cell	Gas Mixture 1	Gas Mixture 4	
Lamp	Type A	Type C	
Light shift [/%]	7.0E-11	5.0E-12	14
Pressure shift [/ $^{\circ}$ C/mbar]	3.3E-11	2.0E-12	16
Coef. cell [/ $^{\circ}$ C]	5.0E-12	5.0E-12	Equal
Coef. lamp [/ $^{\circ}$ C]	5.0E-12	-2.0E-11	But not too critical
Short term stab @ 1sec .	3.0E-12	3.0E-12	Equal

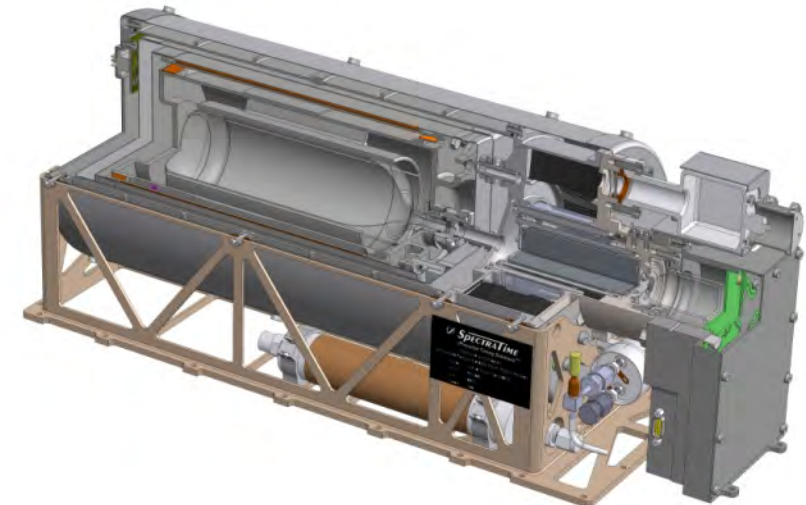
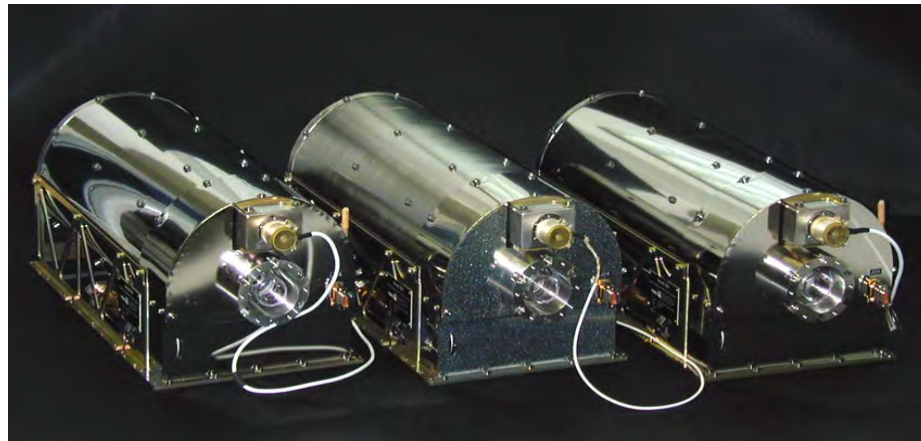
SUMMARY

- Because of its **excellent reliability**, good performances versus quality and price, the rubidium clock is **the first choice** for the GNSS satellites atomic clocks.
- With the increased batches numbers, the performances has been gradually improved, leading to **2E-14/°C** typical temp. coefficient.
- Guaranteed full performances with **+1 °C** variations on base plate.

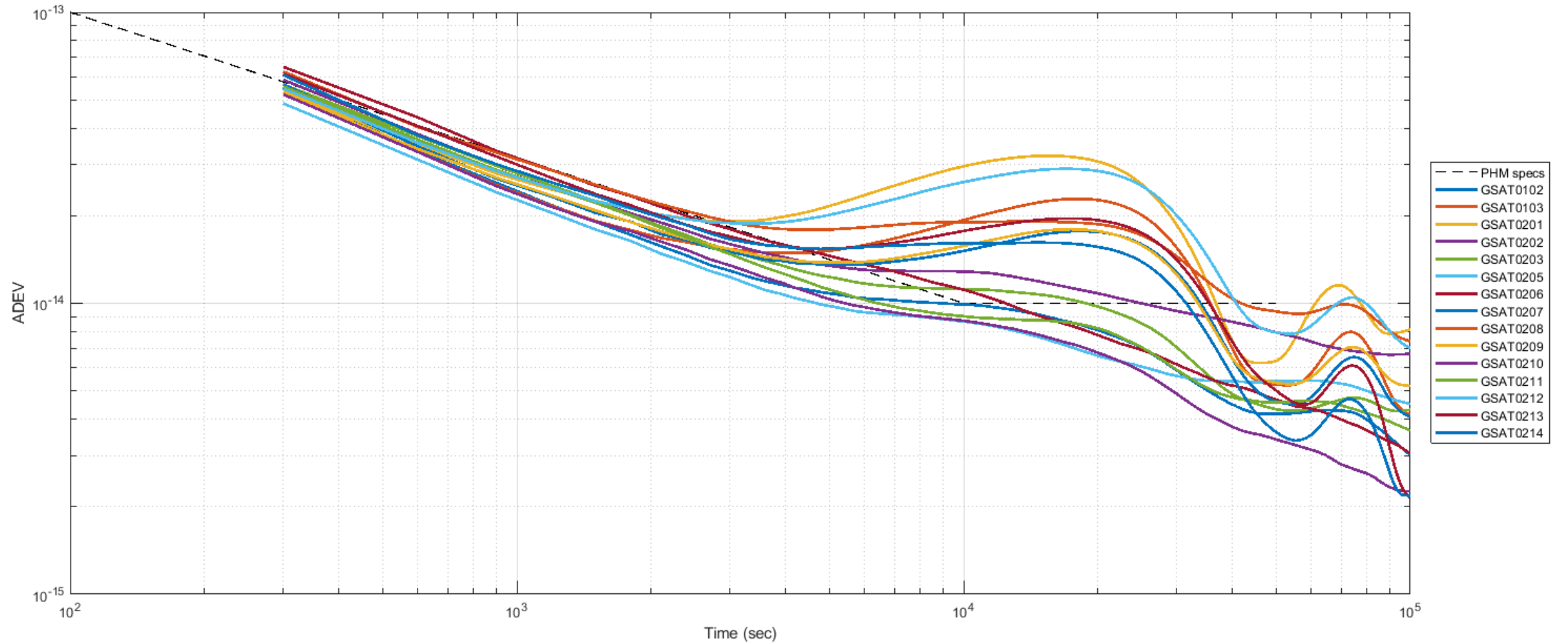


PASSIVE MASER DEVELOPEMENT HISTORY

- **2000** Set-up of consortium constituted of the Observatory of Neuchatel , Selex Galileo & Spectratime and start of SPHM development program
- **2003** Industrialisation program & lifetime verification program
- **From 2009** Set-up of production & tests capability up to 2 SPHM / month.
- **2010** Achievement of full stability on 'Mini Maser', physics package only 8Kg
- **2012-2018** Qualifications program of mini Maser & electronics package improvements



FREQUENCY STABILITY ON GALILEO SATS PHM



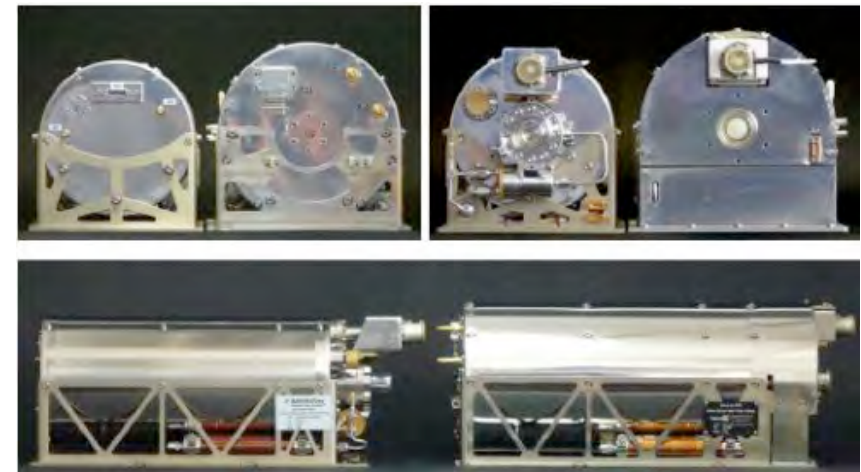
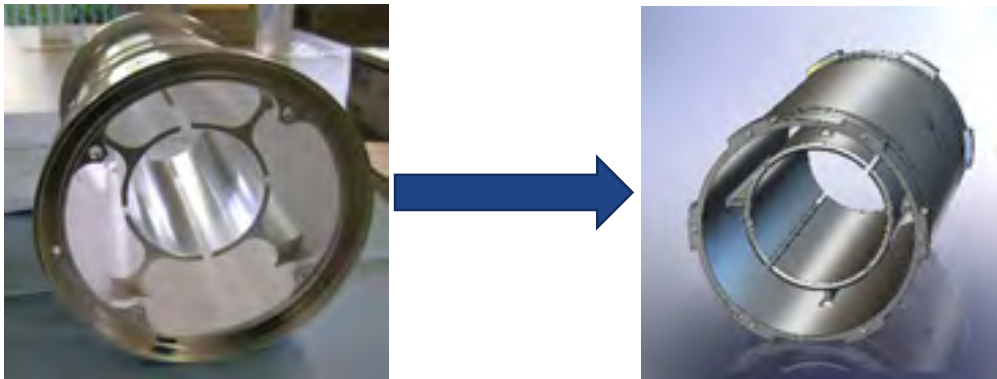
PASSIVE MASER PHYSICS PACKAGE SIZE/WEIGHT REDUCTION

Key improvements :

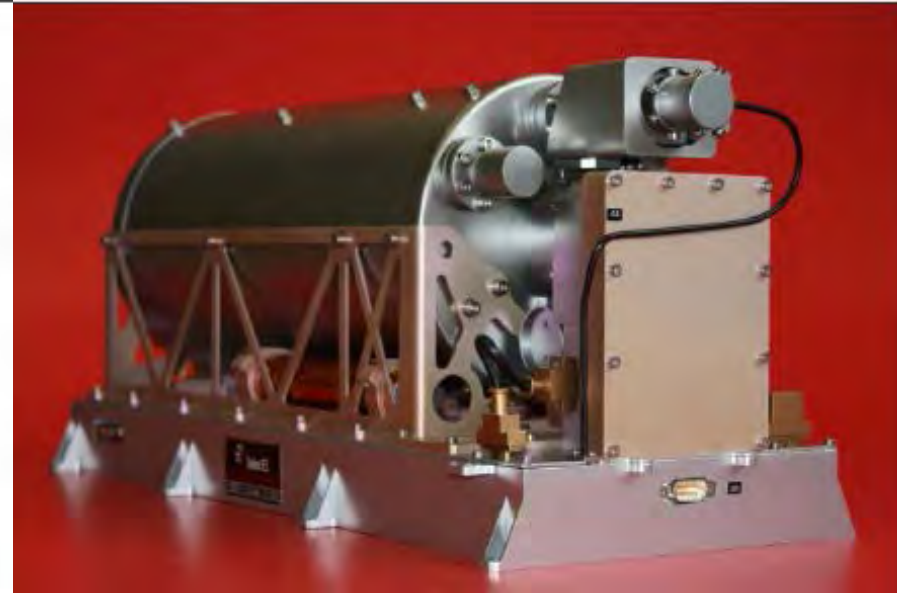
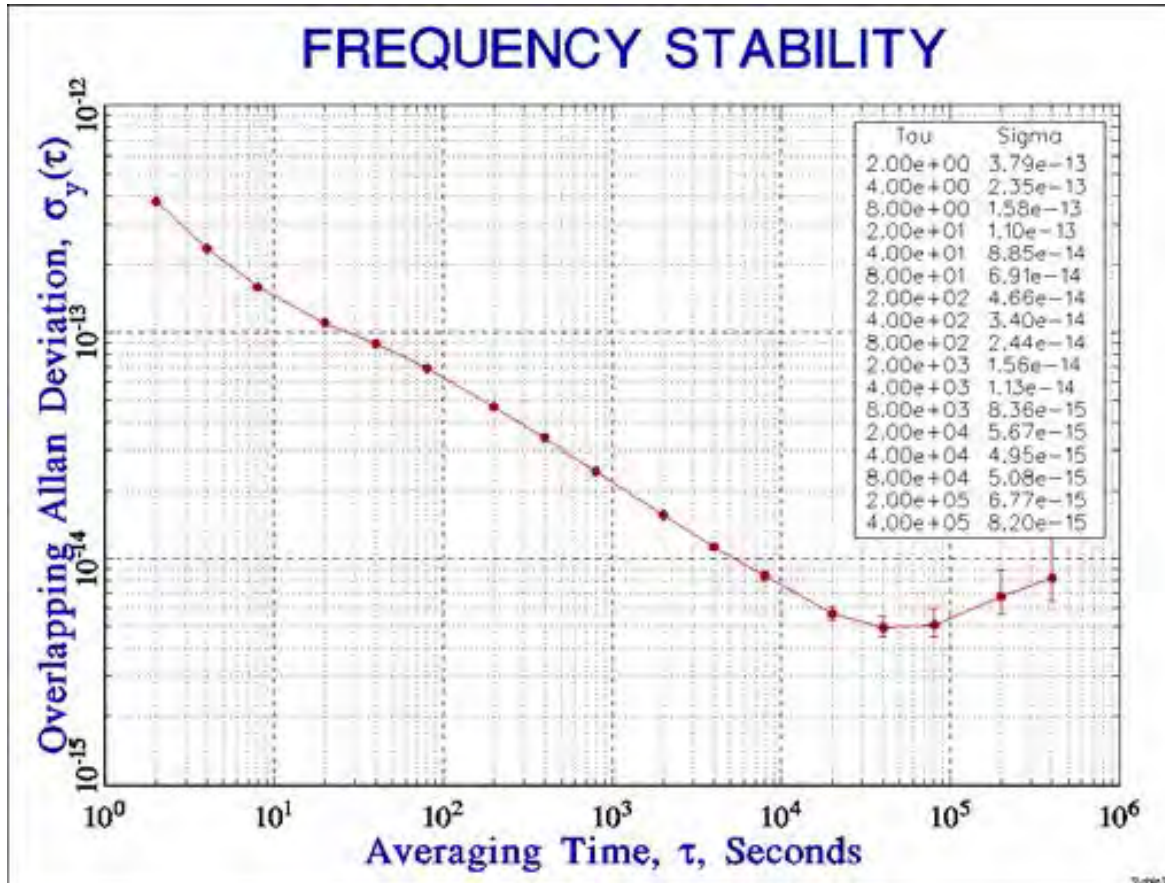
- Microwave Cavity size reduction while keeping same **quality factor Qk**
- Keeping same H storage bulb volume

$$\sigma_y(\tau) = \sqrt{\frac{k_s k T F}{2 A_c} \frac{(1 + S_0 - \alpha)^2}{Q_0 \alpha \sqrt{S_0} (1 + S_0)}} \tau^{-\frac{1}{2}}$$

$$\alpha = \frac{\mu_0 \mu_B^2 \eta' Q_k I}{\hbar V_b \gamma_1 \gamma_2} \quad \alpha \cong 0.3, S_0 \cong 0.3$$



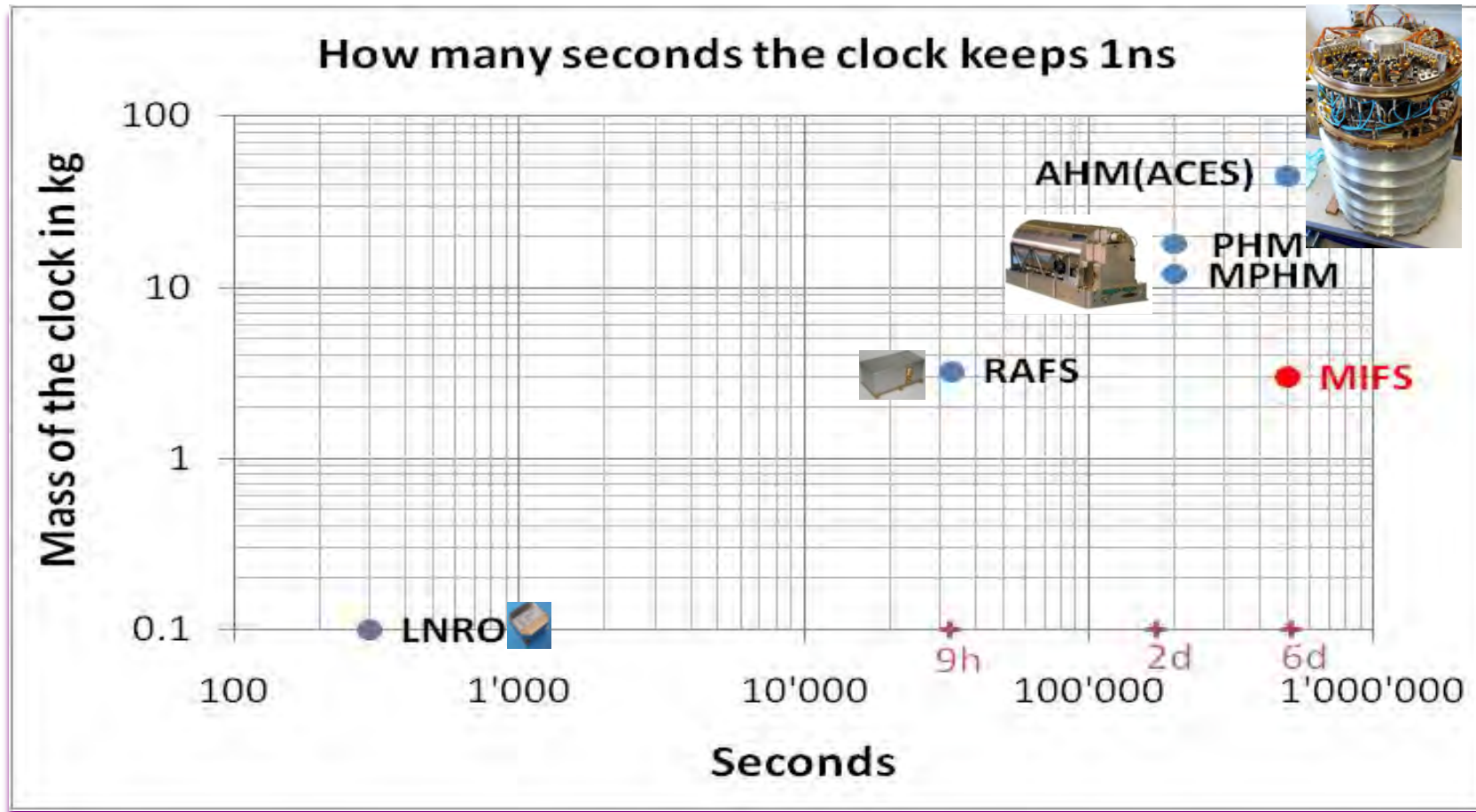
MINI-PHM EQM PP MODEL STABILITY TEST



Dimensions	179 x 465 x 175mm
Mass	8Kg
Frequency Drift (/Day)	$\leq 1 \cdot 10^{-15}$ /day

MERCURY ION FREQUENCY STANDARD (MIFS)

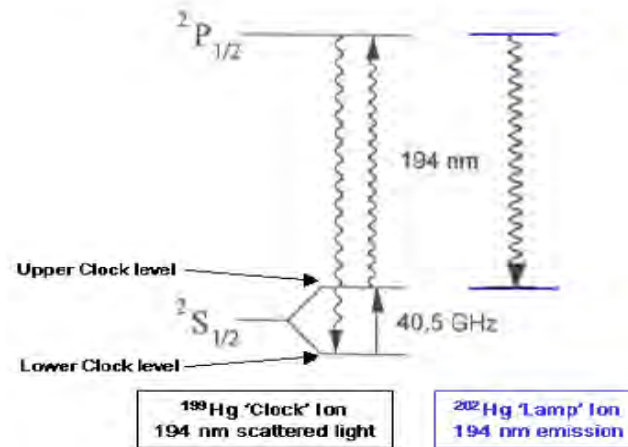
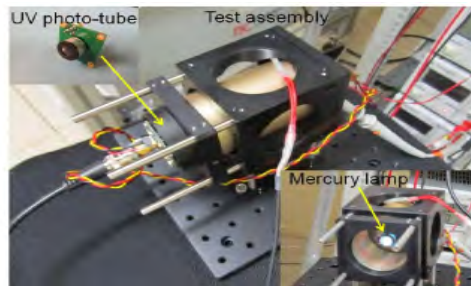
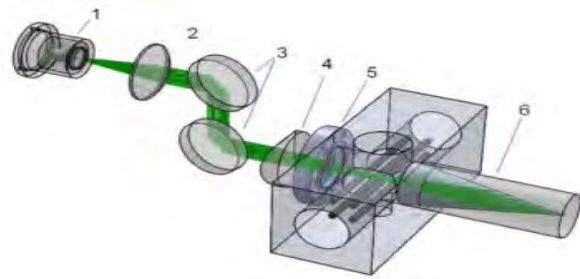
Development of Innovative Atomic Clocks for Satellites



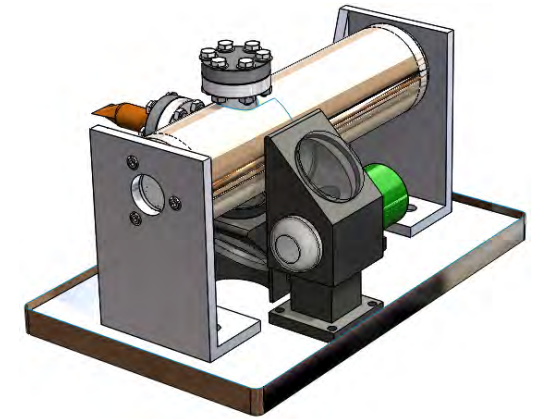
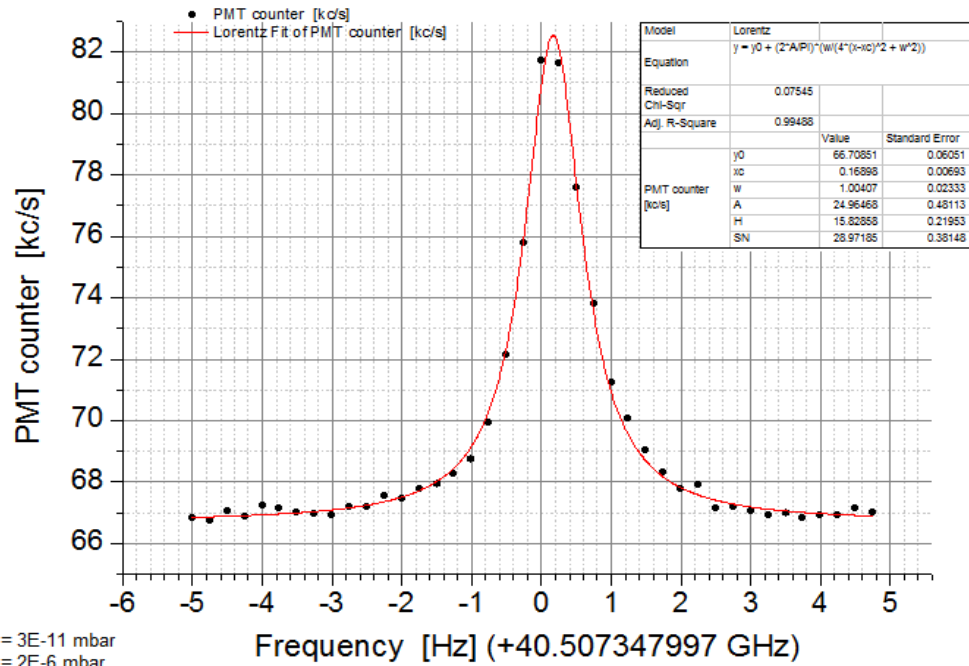
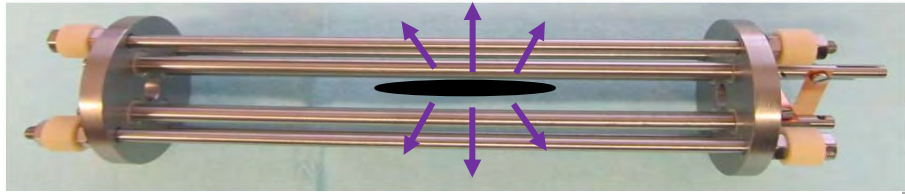
- No Laser
- No Cryogenics
- No Microwave cavities
- No wall collisions, high Q line
- No gas load, not a gas 'flow-thru' architecture, no consumables
- No Light shift!

MIFS: PRINCIPLE AND DESIGN

- Based on Mercury lamp ($^{202}\text{Hg}^+$) optical pumping/detection with a linear trap design optimized for large ion numbers ($10^6 - 10^7$ $^{199}\text{Hg}^+$).
- Clock Transition: 40,507,347,996.8 Hz

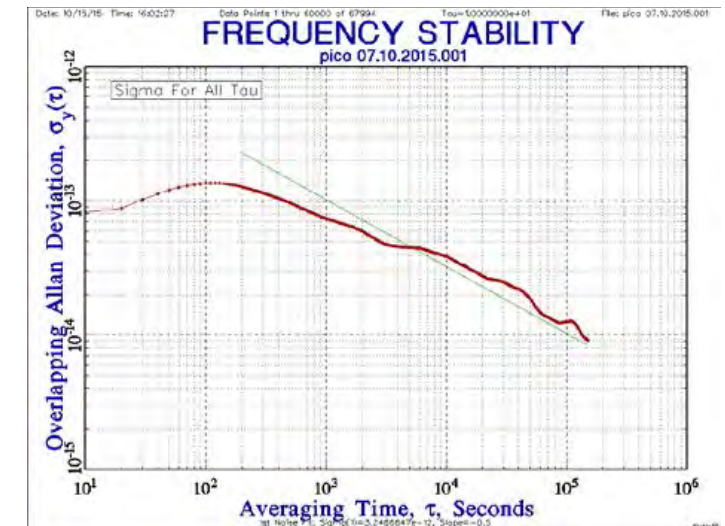
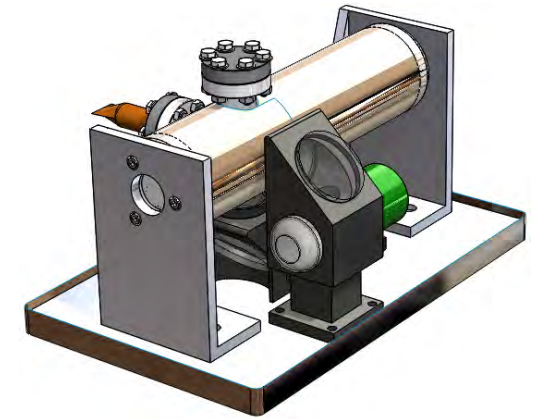


MIFS DEVELOPEMENT



MIFS DEVELOPEMENT

Parameter		Clock Technology		
	Unit	PHM	RAFS	MIFS (target)
ADEV@1s	-	< 1E-12	3E-12	< 1E-12
ADEV@1d	-	< 5E-15	1E-14	< 1E-14
Frequency drift	1/day	<1E-15	< 1E-13	< 1E-15
Magnetic sensitivity	1/G	< 3E-13	< 1E-13	< 1E-14
Thermal sensitivity	1/°C	< 3E-14	< 3E-14	< 1E-15
Volume	litre	28	2.5	< 5
Mass	kg	18	3.4	< 5
Power	W	60	< 35	< 30
Lifetime	years	12	> 15	> 15
Time to 1 ns error	days	2	0.3	10



GNSS ONBOARD CLOCKS ENSEMBLE

GNSS ONBOARD TIMING SUBSYSTEM

Critical payload of Global Navigation Satellite System, consisting of

- ❑ Ultra-stable on-board atomic clocks
- ❑ Clock Monitoring and Control Unit (CMCU)

> *Direct impact on navigation system performance through contributions of system ranging error and availability*

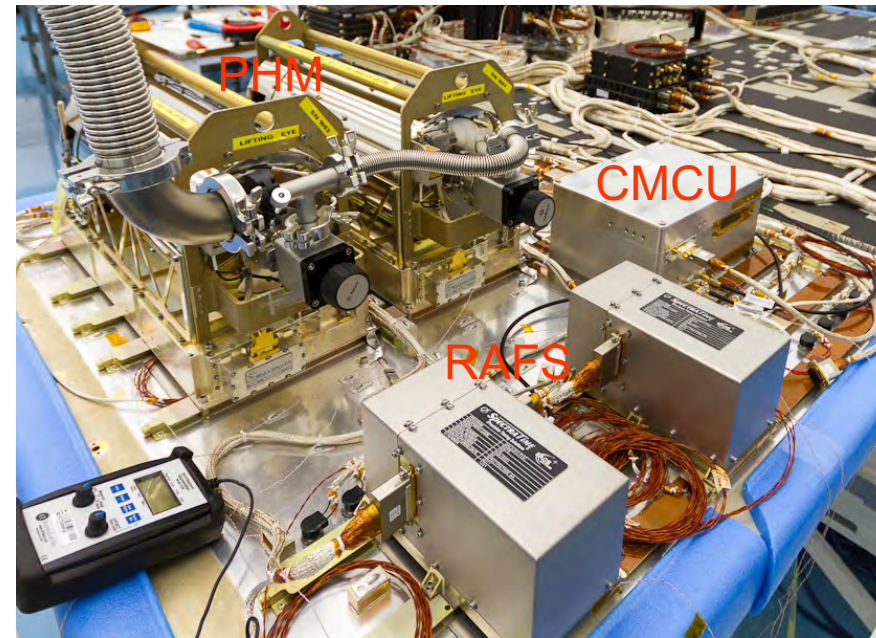
1st generation of Galileo satellites

- ❑ 1 x Master: PHM
- ❑ 1 x Hot redundancy: RAFS
- ❑ CMCU selects the clock signal to be distributed

> *Vulnerabilities and risks*

Next generation

> *Stability, robustness, reliability*



ONE CLOCK ENSEMBLE (ONCLE)

A concept of the **ONCLE** for a robust time and frequency reference system proposed by Spectratime in 2009.

- **Improved robustness and performances**

Advanced processing in real time with min. 3 input clocks

- ❑ Clock Ensemble based on weighted averaging
- ❑ Clock Fault Detection & Correction based on a cascade of low-pass recursive filters & associated logic
- ❑ Steering loop to keep all clocks in phase and frequency

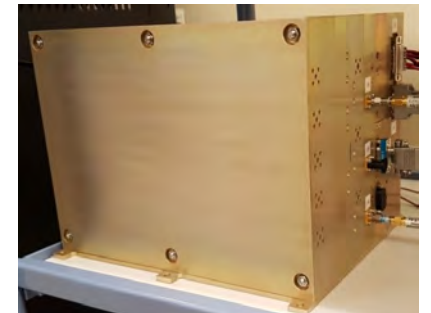
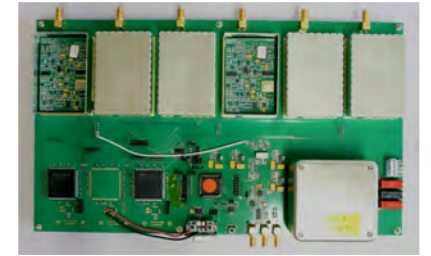
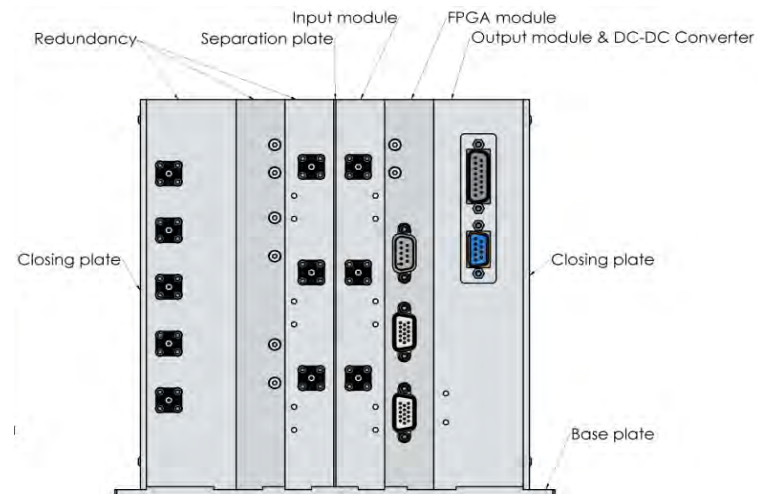
- **Simple and reliable**

- ❑ Possibly implemented into single RAD-HARD FPGA

DEVELOPMENTS UNDER EGEP

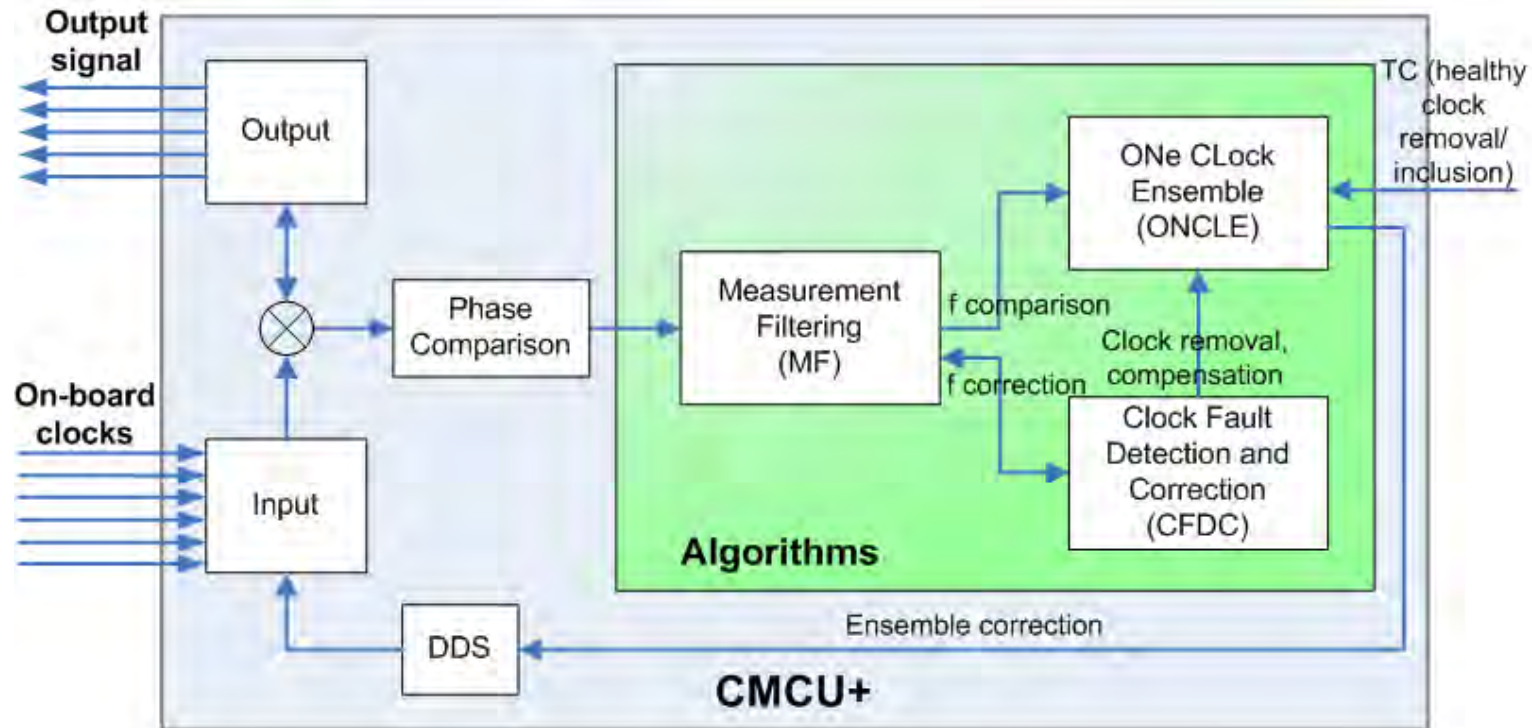
European GNSS Evolution Programme (EGEP)

- ❑ 2012 – 2014: Robust On-board Frequency Reference Subsystem (**FRS**), Elegant Breadboard
 - > Feasibilities of HW & Algorithms approaches demonstrated
- ❑ 2015 – 2019: On-board Clock Ensemble CMCU (**CMCU+**), Engineering Model
 - > 50% contributions from Orolia (Spectratime)
 - ✓ HW: Output module (inc. LNMO), DC-DC Converter, Box mechanics
 - ✓ Algorithms: design, development, high-level verification tests



ALGORITHMS DESIGN

CMCU+ architectures and algorithms functions



Algorithm architecture based on FRS development, adapted with CMCU HW architecture

VERIFICATION METHOD

Algorithms design verified successfully by simulation under various test cases with 3 clock sets including clock events on master and secondary clocks

High-level performance verification conducted at CMCU+ EM level

- ❑ Real-time operation
- ❑ 2 sets of clock configurations (atomic clock technology diversity)
 - ✓ Set A: 1 x PHM + 3 x RAFS
 - ✓ Set B: 3 x PHM + 1 x RAFS
- ❑ Test results verified by
 - ✓ Clock handling capability
 - ✓ ADEV
 - ✓ Maximum Accumulated Phase Offset (MAPO)

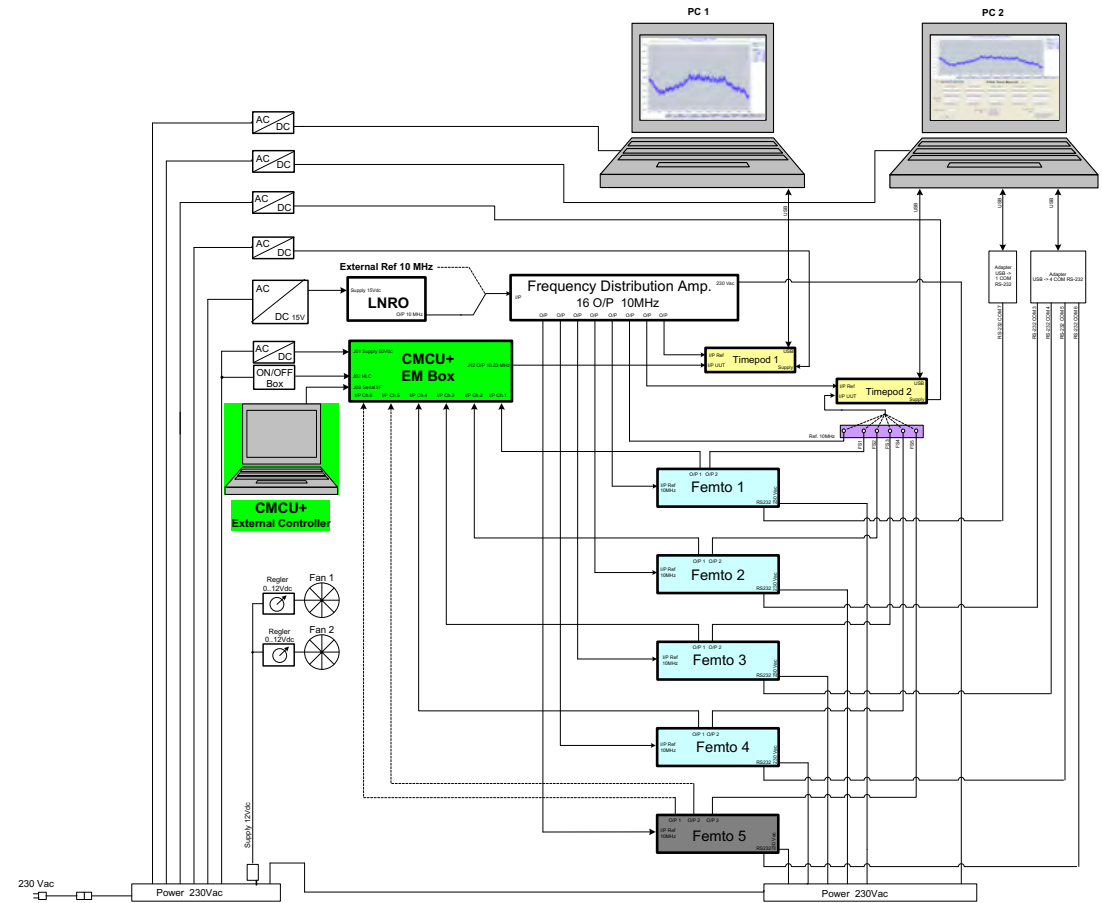
CMCU+ TEST SETUP



Testing and validation tool

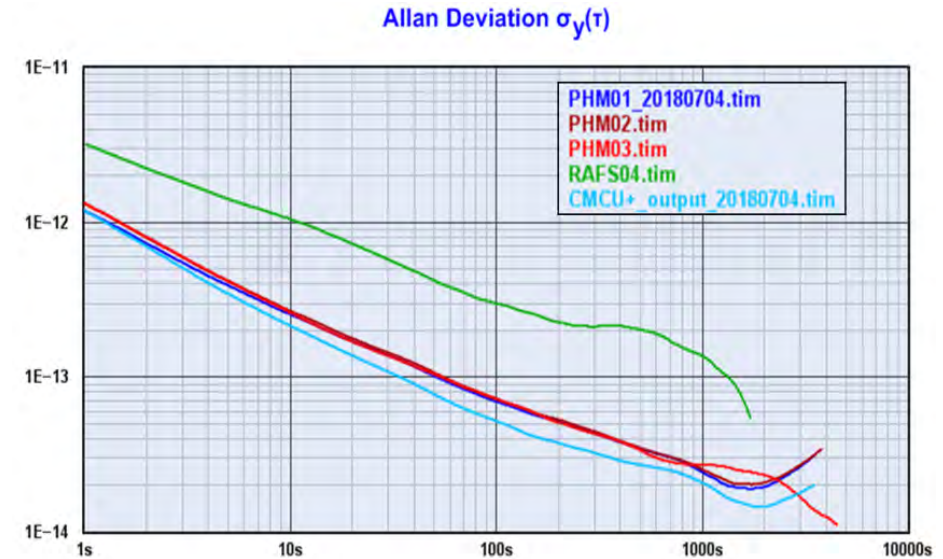
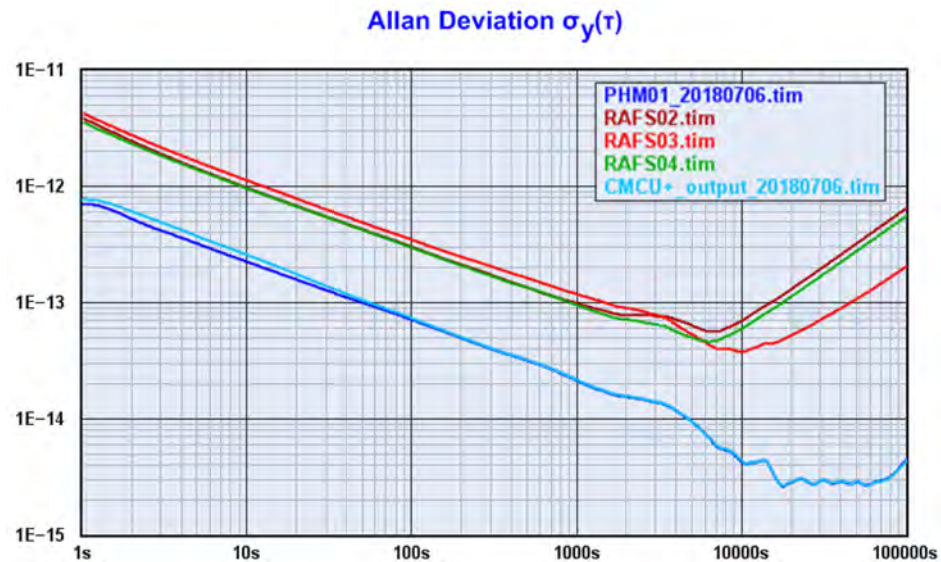
iTest® FemtoStepper

- ✓ Ability to 'REPLAY' clock data
- ✓ Generate clock anomalies
- ✓ High resolution : 100 fs, 1e-17



TEST CASE: ENSEMBLE STATIONARY PERFORMANCE

> Two AFS Sets, two data sets: 2-day per 1s; 4-hour per 0.1s



> Output ADEV:

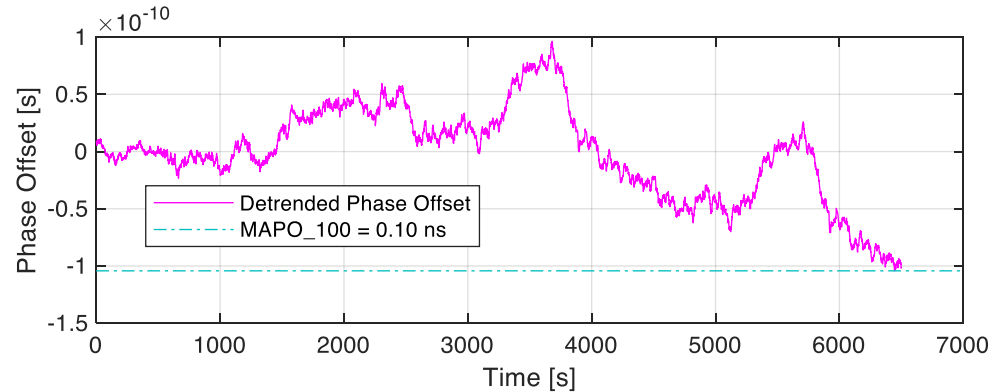
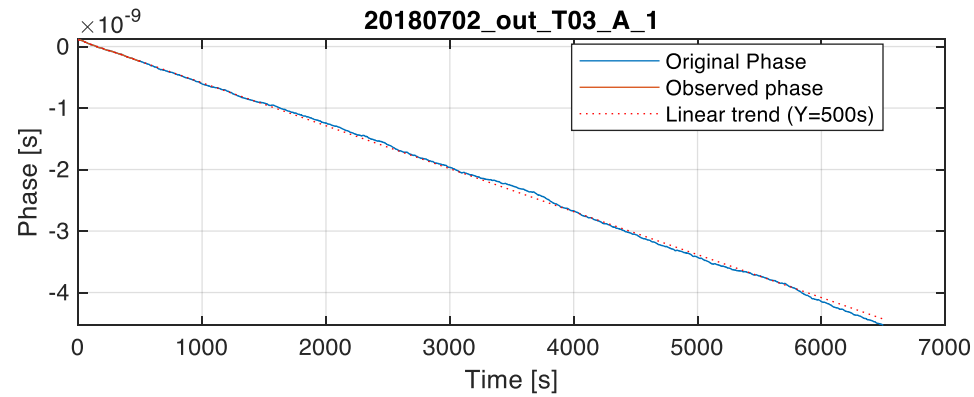
Set A Equivalent as Master PHM

Set B At 1s, equivalent as PHM, impacted by PLL

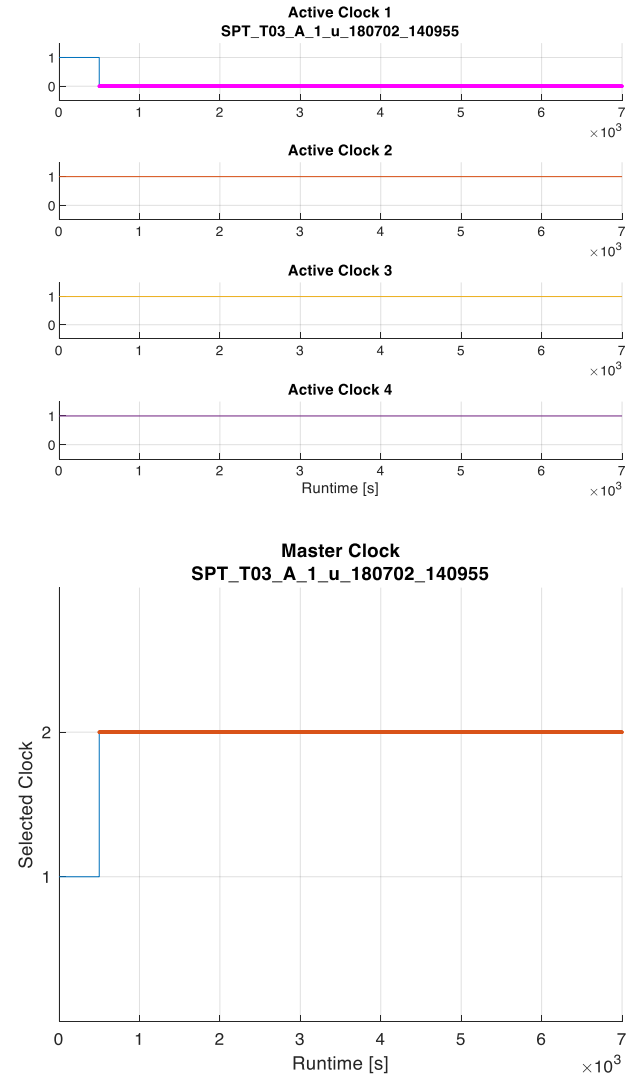
At $\geq 10s$: $1/\sqrt{3}$ of ADEV of PHM

TEST CASE: HEALTHY AFS REMOVAL BY COMMAND_A (MASTER)

> PHM01: Removal at 500s

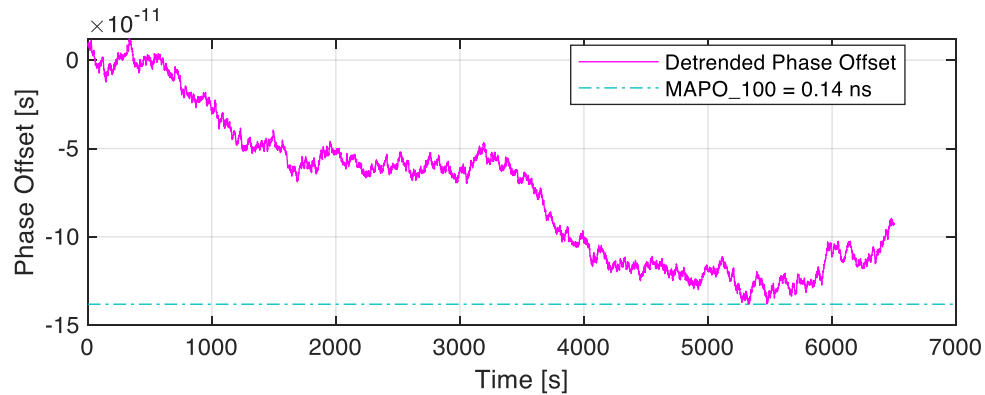
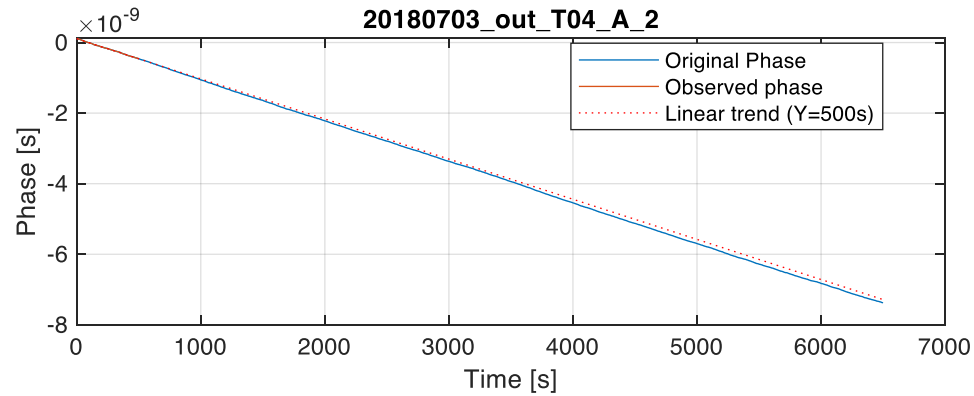


> PHM01 removed and smoothly switched over

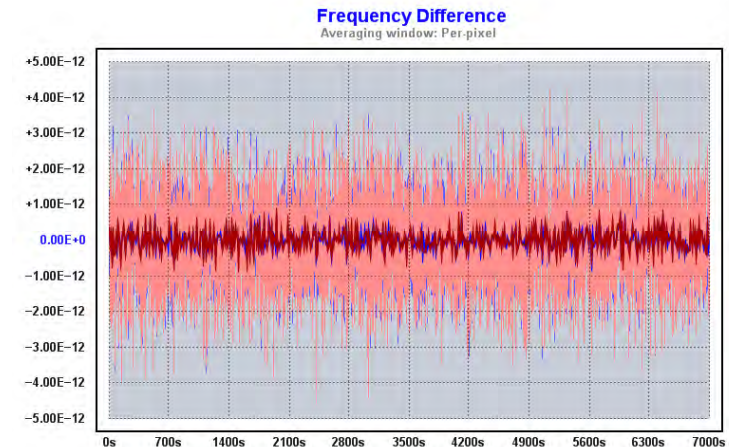
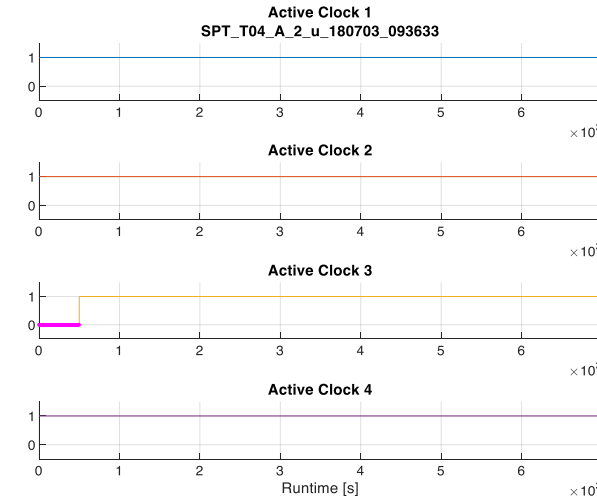


TEST CASE: HEALTHY AFS INCLUSION BY COMMAND_A (SECONDARY)

> RAFS03: Included at 500s



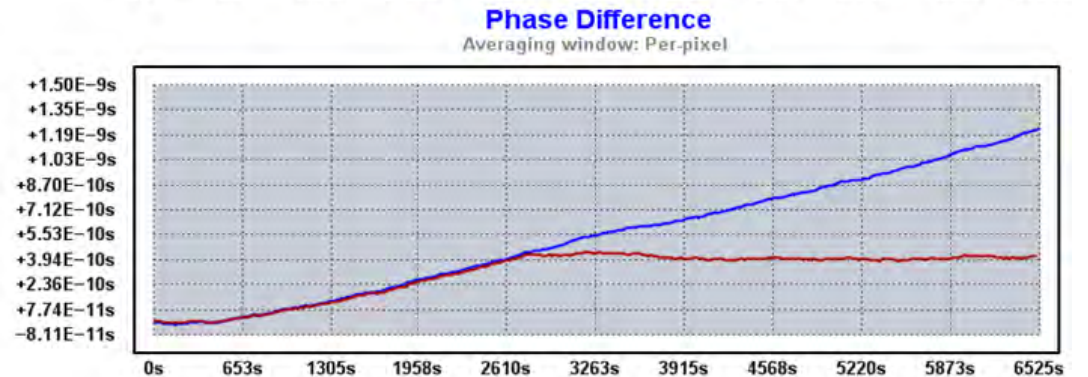
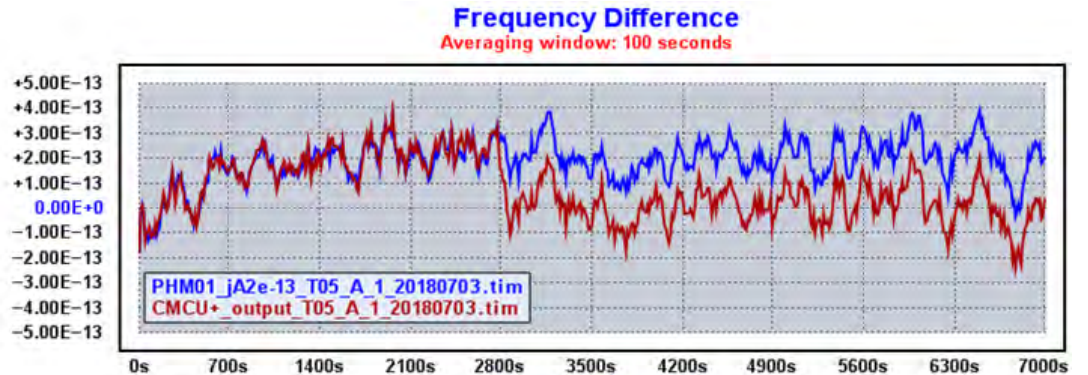
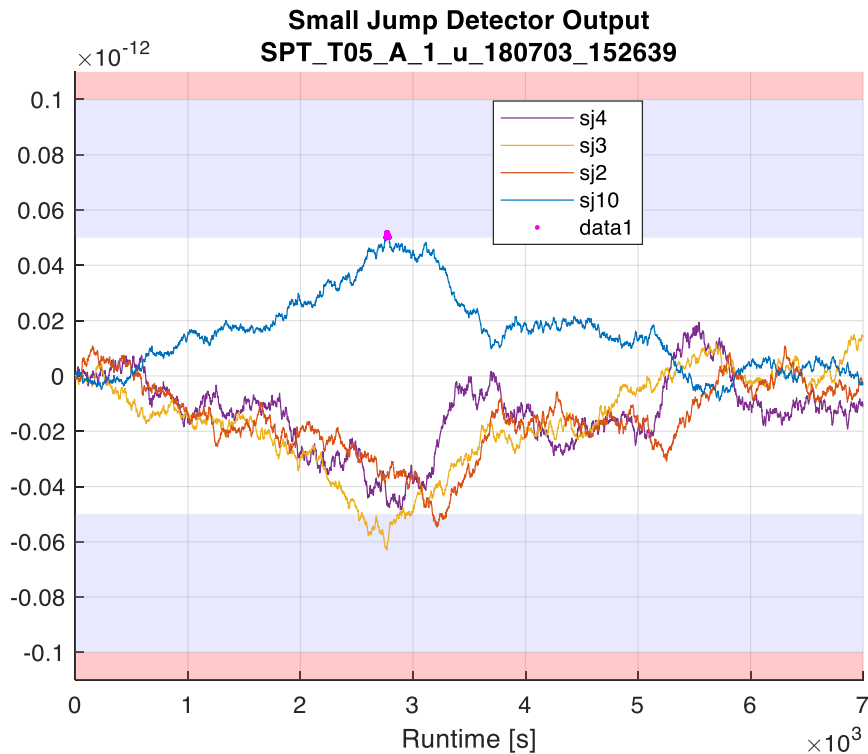
> RAFS included w/o impact on output



Filename	Sample Interval	Duration
20180703_PHM01_1s_I60_T04_A_2.tim	0.500 s	1h 56m 40s
20180703_out_T04_A_2.tim	0.500 s	1h 56m 40s

TEST CASE: HIGH-DYNAMICS FREQUENCY JUMP_A (MASTER)

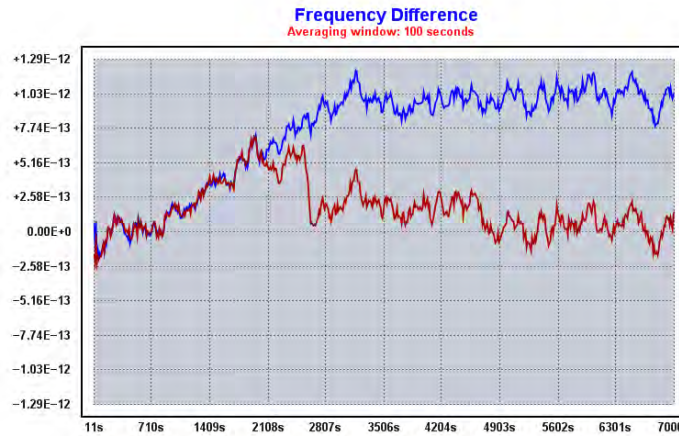
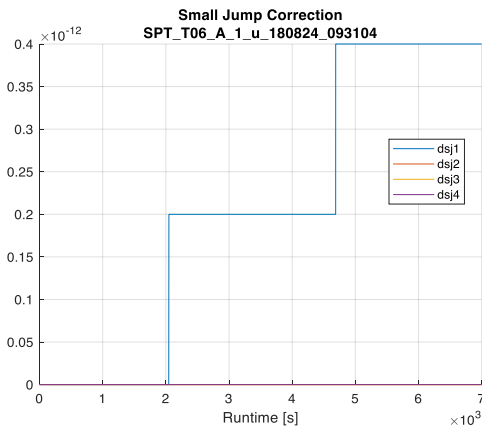
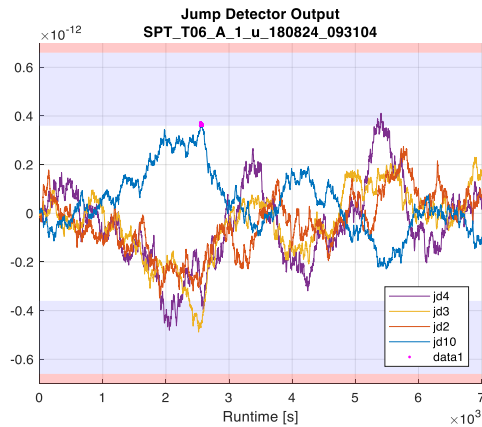
> Input PHM01: $f_{\text{jump}}=2e-13 \sim \text{MAPO}_{100}=1.22\text{ns}$



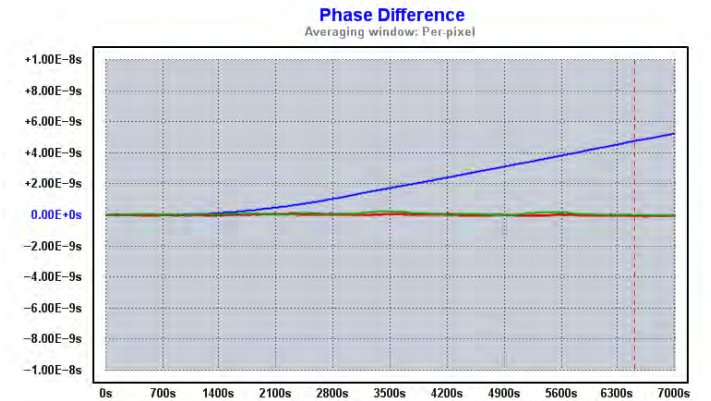
> CMCU+ output: f_{jump} corrected by SJ $\sim \text{MAPO}_{100}=0.45\text{ns}$

TEST CASE: MEDIUM-DYNAMICS FREQUENCY JUMP_A (MASTER)

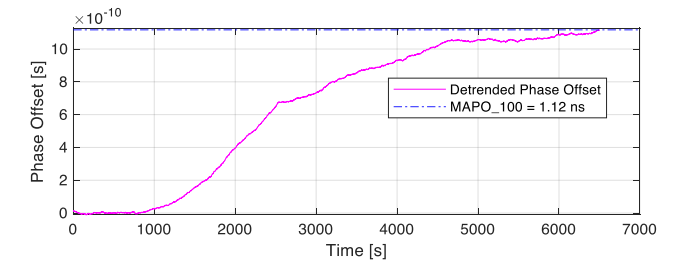
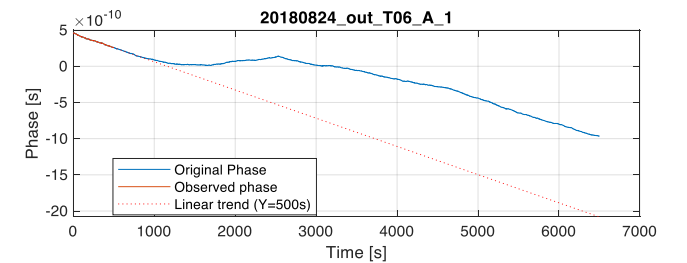
> Input PHM01: $f_{\text{jump}}=1\text{e-}12$ during 2500s ~ $\text{MAPO}_{100}=4.8\text{ns}$



Filename	Sample Interval	Duration
20180824_PHM01_jB1e-12y_T06_A_1.tim	0.500 s	1h 56m 40s
20180824_out_T06_A_1.tim	0.500 s	1h 56m 40s



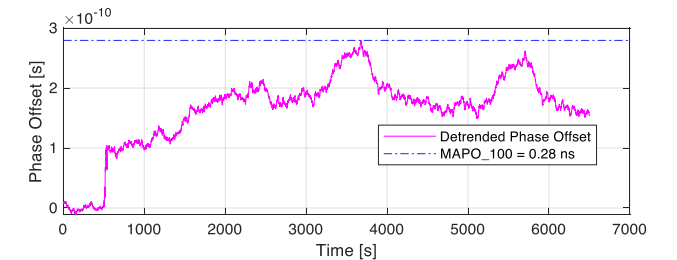
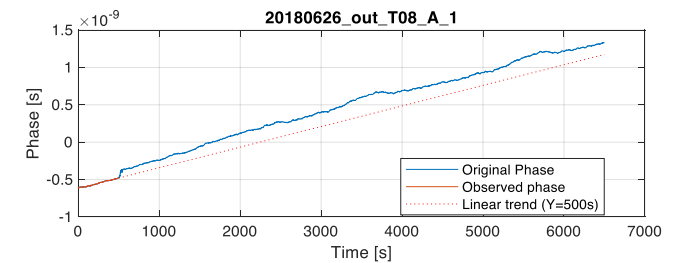
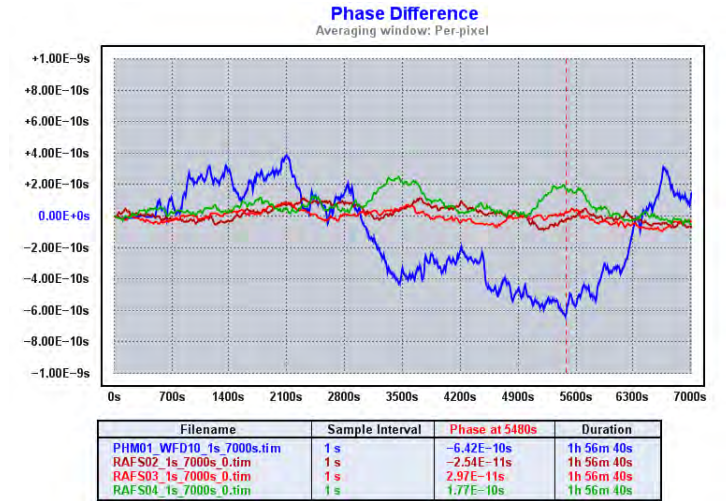
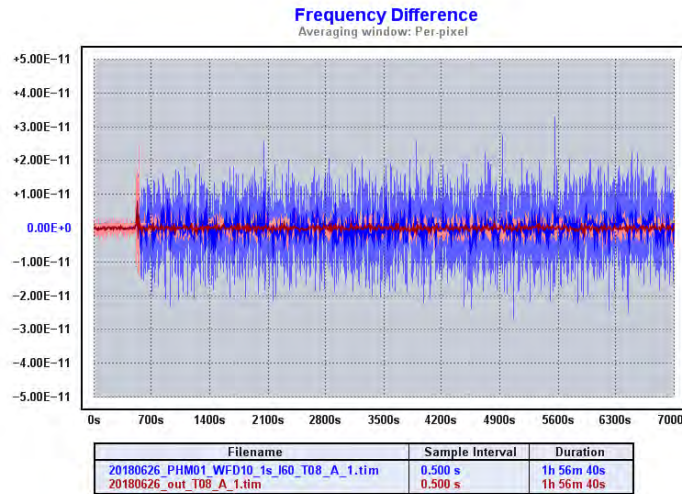
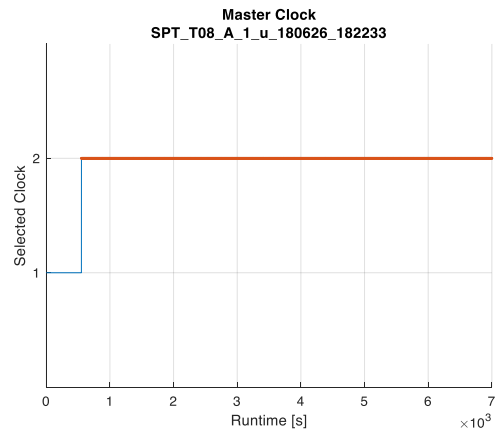
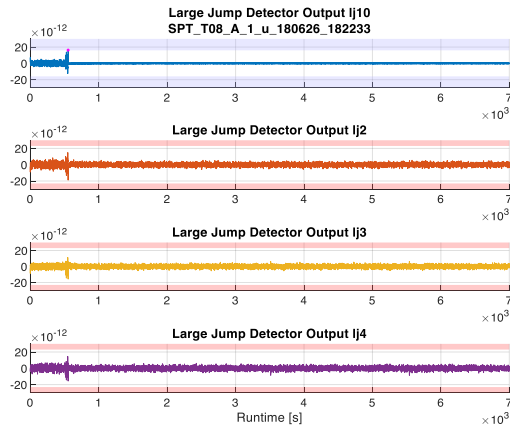
Filename	Sample Interval	Phase at 6501s	Duration
PHM01_jB1e-12y_1s_7000s.tim	1 s	4.77E-9s	1h 56m 40s
RAF502_1s_7000s_0.tim	1 s	-6.21E-11s	1h 56m 40s
RAF503_1s_7000s_0.tim	1 s	-8.30E-11s	1h 56m 40s
RAF504_1s_7000s_0.tim	1 s	-8.38E-12s	1h 56m 40s



> CMCU+ output: f_{jump} corrected by JD&SJ ~ $\text{MAPO}_{100}=1.12\text{ns}$

TEST CASE: WFN LEVEL INCREASE_A (MASTER)

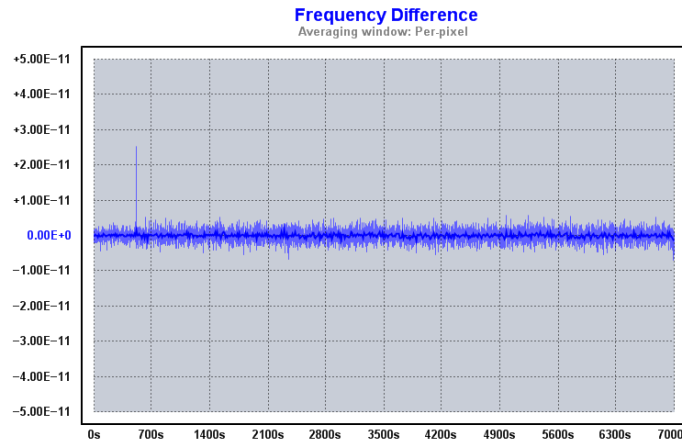
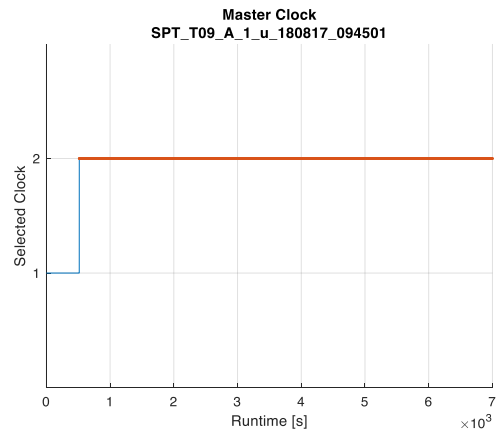
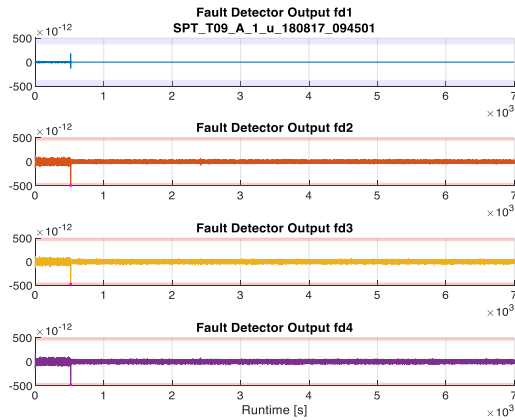
> Input PHM01: 10xWFN



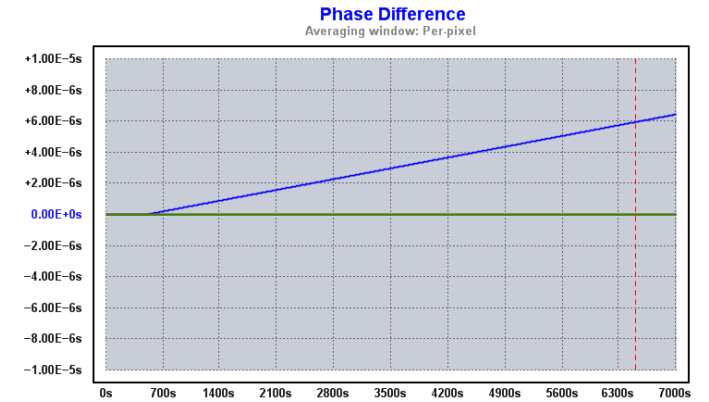
> CMCU+ output: fjump corrected by JD&SJ ~ MAPO_100=0.28ns

TEST CASE: FAILURE JUMP_A (MASTER)

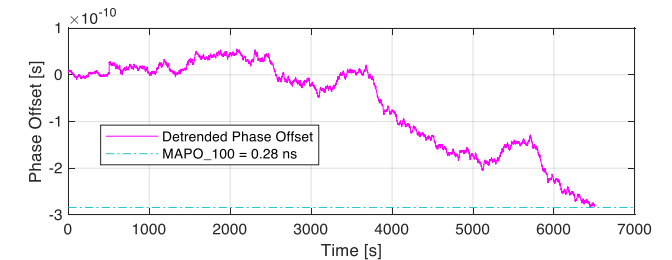
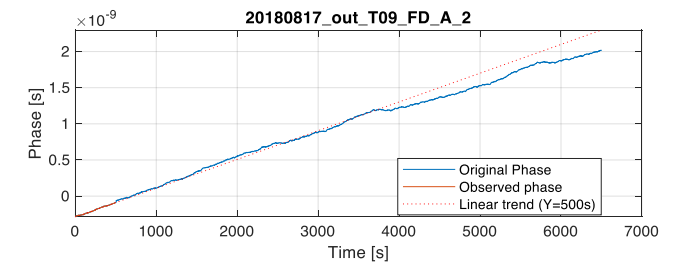
> Input PHM01 failure jump $1e-10 \sim \text{MAPO}_{100}=6\mu\text{s}$



Filename	Sample Interval	Duration
20180817_out_T09_FD_A_1.tim	0.500 s	1h 56m 40s



Filename	Sample Interval	Phase at 6501s	Duration
PHM01_jA1e-9_1s_7000s.tim	1 s	5.94E-6s	1h 56m 40s
RAFSD2_1s_7000s_0.tim	1 s	-6.21E-11s	1h 56m 40s
RAFSD3_1s_7000s_0.tim	1 s	-8.30E-11s	1h 56m 40s
RAFSD4_1s_7000s_0.tim	1 s	-8.38E-12s	1h 56m 40s



> Failed Master PHM detected by FD, removed and switched over $\sim \text{MAPO}_{100}=0.28\text{ns}$

CONCLUSIONS

Direct Results

- Algorithms designed, developed, and verified by an extended test and validation campaign
- Functionalities and performances verified successfully with improved robustness and timing accuracy
- A smart, robust and feasible solution for a spaceborne implementation
- Benefits for on-board timing sub-system for 2nd Generation of Galileo satellites (G2G)

Next

- Further tuning of parameters
- To be implemented into fully flight hardware
- Configurability and flexibility of operation

MINIATURE CLOCKS FOR FUTURE LEO –PNT SATELLITES



MINI RUBIDIUM: PROJECT GOAL & APPLICATIONS



- High stability frequency source
- Telecom & mobile network synchronization (TDM, PTP)
- Military airborne, ground, mobile & unmanned radio communications
- Oil & gas sensor-based exploration
- Instrumentation
- Portable & battery-sensitive applications
- **GPS-based applications**

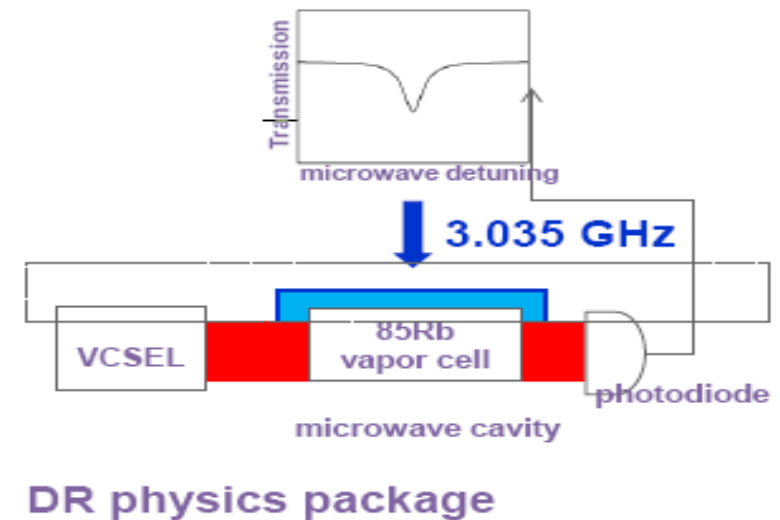
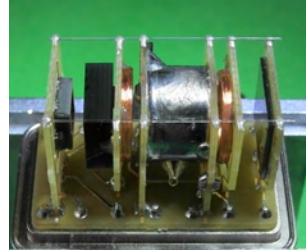
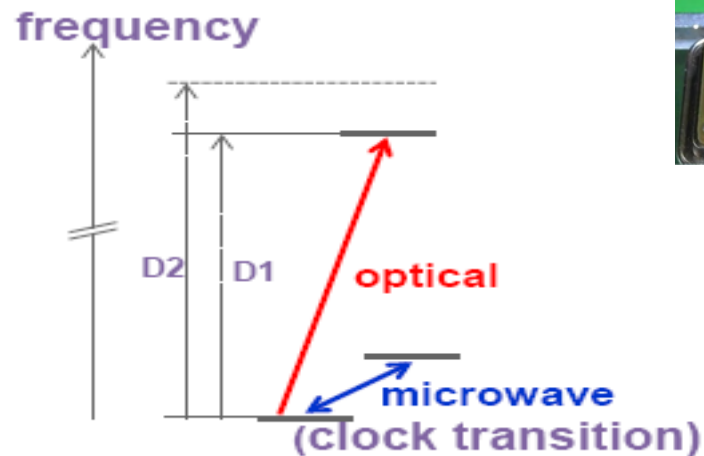
Frequency	10 MHz
Temperature range	-5°C to 55°C
Frequency change over Temp. range	$\leq 2E-10$
Short term stability	$1.5E-10 @ 1s$
Aging (after 3 month)	$< 2E-12 / \text{day}$

Size	$52.2 \times 52.2 \times 19.5\text{mm.}$
Weight	90 g max.
Volume	$< 50 \text{ cc}$
Power	0.4 W

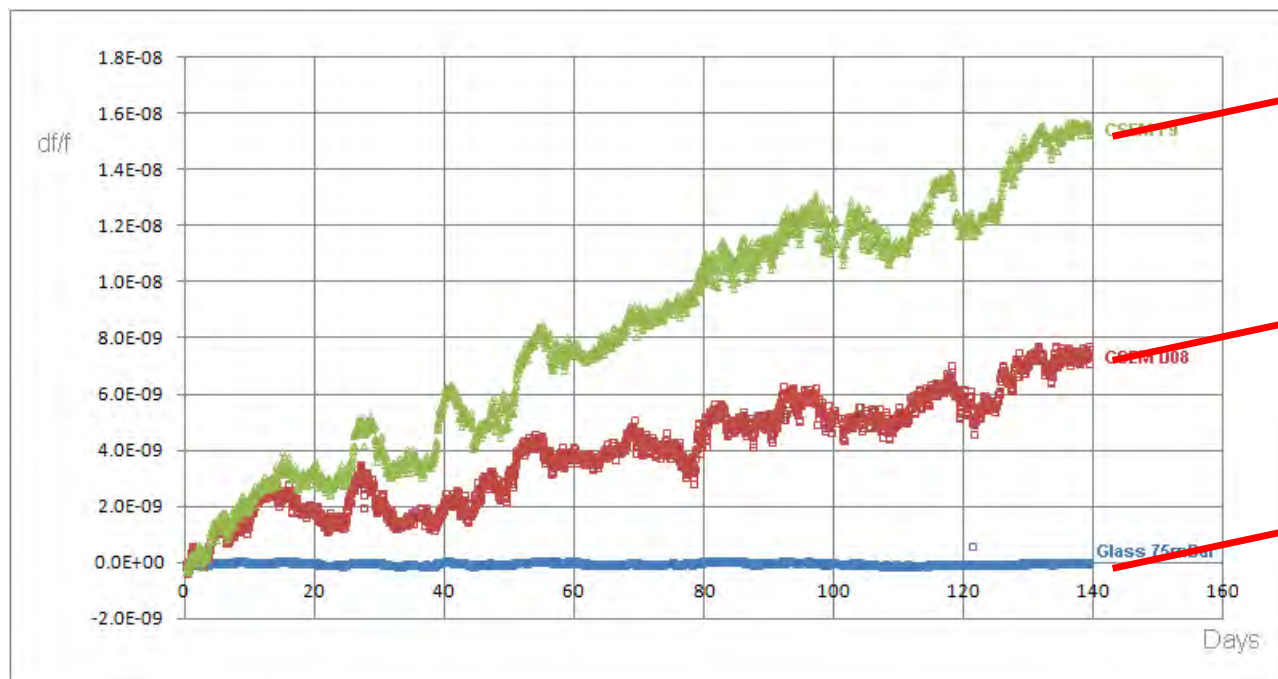
DOUBLE-RESONANCE PHYSICS PACKAGE

Schematic of the laser pumped double resonance (D1) physics package

- (+) Less constraints on laser (No RF modulation)
- (+) No need taking care of light polarization
- (+) Laser amplitude & frequency drift can be compensated
- (+) With new patented technique , less RF power is necessary and no size limitation



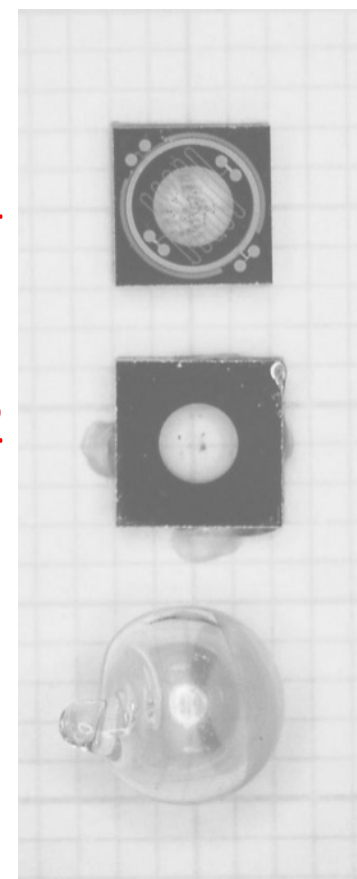
NEW MINIATURE RUBIDIUM CLOCK : DRIFT RATES



MEM1

MEM2

Glass



MINI RUBIDIUM: PRODUCTION STATUS

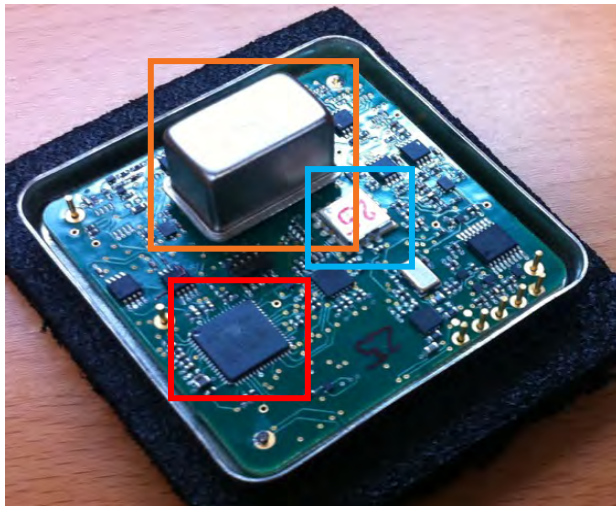
2016 - 2017




Preparation of 50 mTS units for test-campaign

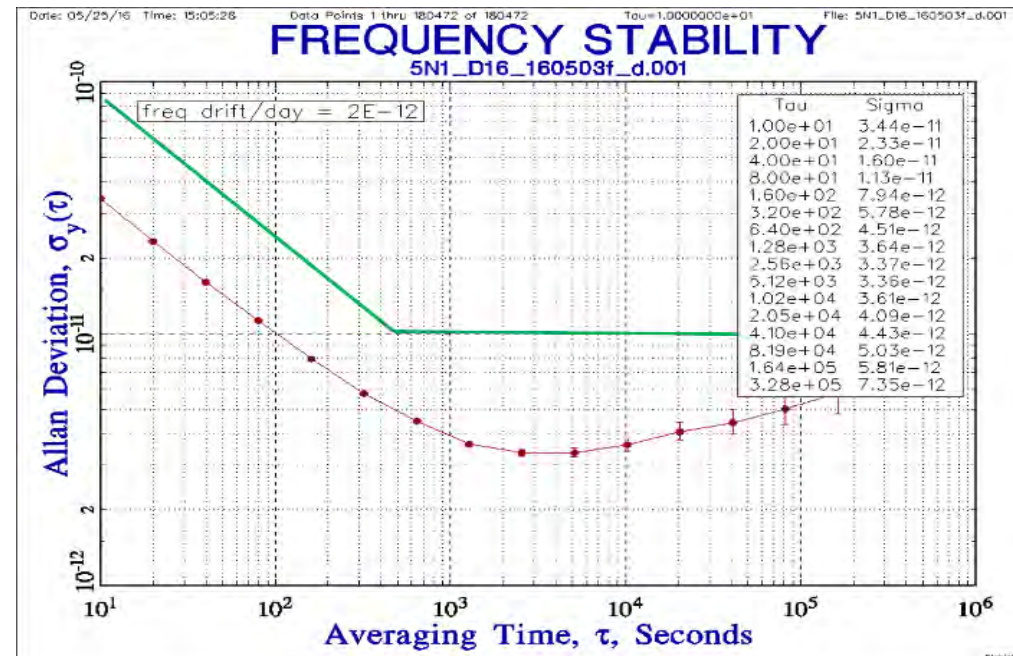
2018 -

Pre-production units to be shipped to selected clients

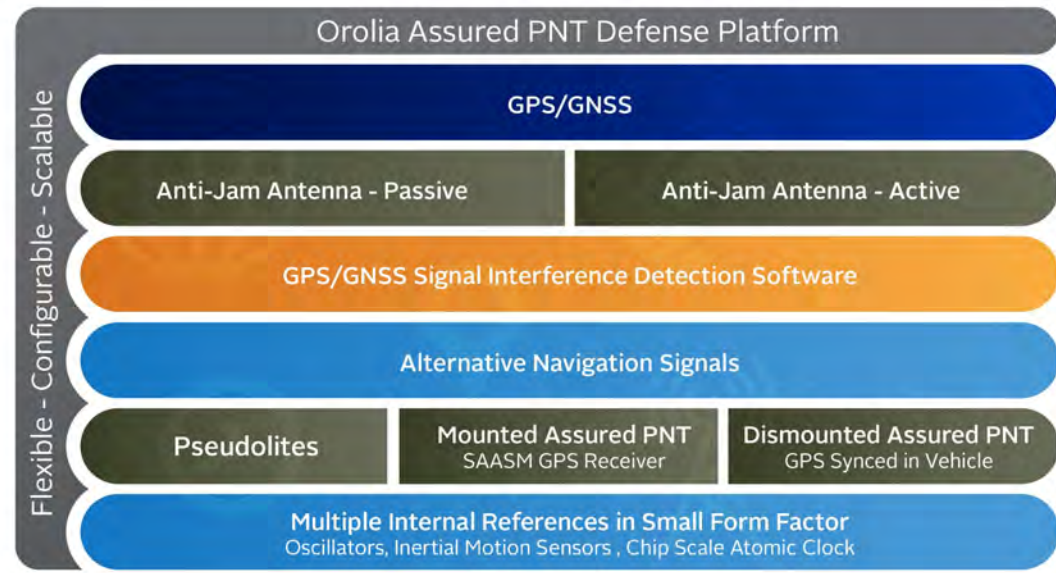
Successful passing radiations testing fully suitable for LEO satellites applications (LEO PNT)



-  Physics Package (DIL-14)
-  VCO @3GHz
-  DSP micro-processor



MOBILE PNT – MRO50 APPLICATIONS



VersaSync



Next Generation Resilient Time and Frequency Source

VersaPNT



Rugged Position, Navigation and Timing



THANK YOU
FOR YOUR ATTENTION



 spectratime
an Orolia brand