## WINNIE LIN

EMAIL WEBSITE	winnielin@stanford.edu web.stanford.edu/~wl1915	TEACHING	
INTERESTS SKILLS	Computer Graphics and Vision C++, Python, lua, bash, TeX, OpenCV, pbrt, PyTorch, Tensorflow, Maya, Blender, Unity	<i>04.2018- 06.2019</i>	CS231N: Neural Networks for Vision Head course assistant, Spr '19 Course assistant, Spr '18
EDUCAT		<i>01.2019- 03.2019</i>	CS205L: Math in Machine Learning Head course assistant, Win '19 '20
Stanford University 06.2021 (est) Ph.D. Computer Science (4.1)		09.2016- 12.2018	<b>CS148: Intro to Graphics</b> Course assistant, Fall '16 '18 '20
06.2017 06.2016	M.S. Computer Science (3.9) B.S. Mathematics (3.8)	01.2016- 02.2017	<b>CS109: Intro to Probability</b> Course assistant, Win Spr '15 '16
INTERNSHIPS		PROJECT	TS AND AWARDS
06.2020- 09.2020	Facebook AR/VR Deep learning for face tracking Menlo Park	Screen Credits	The Irishman (2019) Designed tools for markerless facial capture and data-driven retargeting.
06.2018- 03.2020	Industrial Light and Magic Machine learning for visual effects San Francisco	Co-author IEEE TVCG	<b>Real-time Interactive Tree Animation</b> Worked on simulation visualization and mathematical verification of the algorithm.
06.2016- 09.2016	Riot Games Hydrology System Design Mountain View	Co-author arxiv	<b>3D Reconstruction of Botanical Trees</b> Worked on semi-supervised deep learning for video-based 3D reconstruction.
06.2015- 09.2015	Radiant Entertainment Biome and Terrain Generation Los Altos	Best Project CS229	Adaptive Samplers for Raytracing [Group of 1.] Worked on using SVMs to train adaptive samplers for pbrt.
COMMUI	NITY AND OUTREACH	First Place CS248	<b>Trayl, an underwater shooting game</b> [Group of 2.] Created UI and assets, added custom acceleration structures to Unity.
06.2019	Stanford Centennial TA Award Stanford School of Engineering	Fedkiw Lab	<b>Deformable Geometry Matching</b> Experimented with deforming and aligning point clouds to high quality facial meshes.
07.2018- 06.2019	<b>CA Mentor and Department Liaison</b> Stanford CS Department	Guibas Lab	Iterative Point Cloud Superresolution Experimented with point cloud upsampling
<i>02.2015-</i> <i>04.2016</i>	<b>Girls Teaching Girls To Code '15-'16</b> Curriculum Writer, Lead Instructor	Vision Lab	methods through sequential generation.  Diffusion-based Sparse-to-Dense LIDAR
09.2015- 04.2016	Palo Alto Euler Circle Teaching Assistant	, iston hav	Designed and evaluated comparisons for sparse depth completion for sensor fusion.
09.2015- 04.2016	<b>Stanford University Math Camp</b> Residential Teaching Assistant	ME213	<b>Exploratorium Exhibition Design</b> Created prototypes and built installations at the San Francisco Exploratorium.