# CS 106B, Lecture 24 Dijkstra's and Kruskal's

### **Plan for Today**

- Real-world graph algorithms (with coding examples!)
  - Dijkstra's Algorithm for finding the least-cost path (like Google Maps)
  - Kruskal's Algorithm for finding the minimum spanning tree
    - Applications in civil engineering and biology

### **Shortest Paths**

- Recall: BFS allows us to find the shortest path
- Sometimes, you want to find the least-cost path
  - Only applies to graphs with weighted edges
- Examples:
  - cheapest flight(s) from here to New York
  - fastest driving route (Google Maps)
  - the internet: fastest path to send information through the network of routers

### **Least-Cost Paths**

- BFS uses a queue to keep track of which nodes to use next
- BFS pseudocode:

```
bfs from v_1:
  add v_1 to the queue.
  while queue is not empty:
     dequeue a node n
  enqueue n's unseen neighbors
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• How could we modify this pseudocode to dequeue the **least-cost** nodes instead of the **closest nodes**?

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- How could we modify this pseudocode to dequeue the **least-cost** nodes instead of the **closest nodes**?
  - Use a priority queue instead of a queue

### Edsger Dijkstra (1930-2002)

- famous Dutch computer scientist and prof. at UT Austin
  - Turing Award winner (1972)
- Noteworthy algorithms and software:
  - THE multiprogramming system (OS)
    - layers of abstraction
  - Compiler for a language that can do recursion
  - Dijkstra's algorithm
  - Dining Philosophers Problem: resource contention, deadlock
- famous papers:
  - "Go To considered harmful"
  - "On the cruelty of really teaching computer science"



# Dijkstra pseudocode

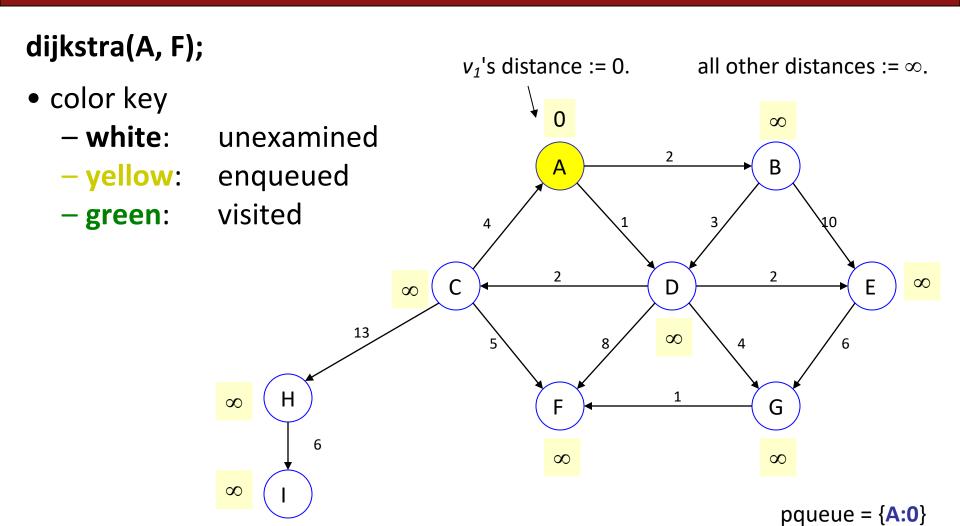
#### dijkstra( $v_1$ , $v_2$ ):

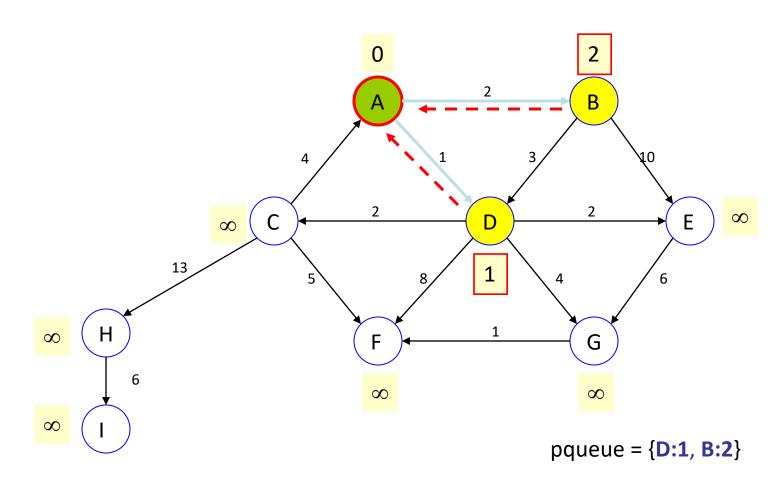
consider every vertex to have a cost of infinity, except  $v_1$  which has a cost of 0. create a *priority queue* of vertexes, ordered by cost, storing only  $v_1$ .

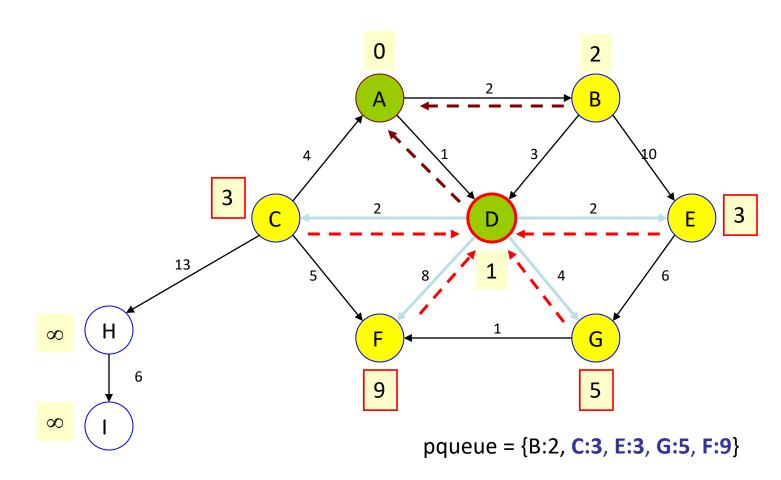
while the *pqueue* is not empty:

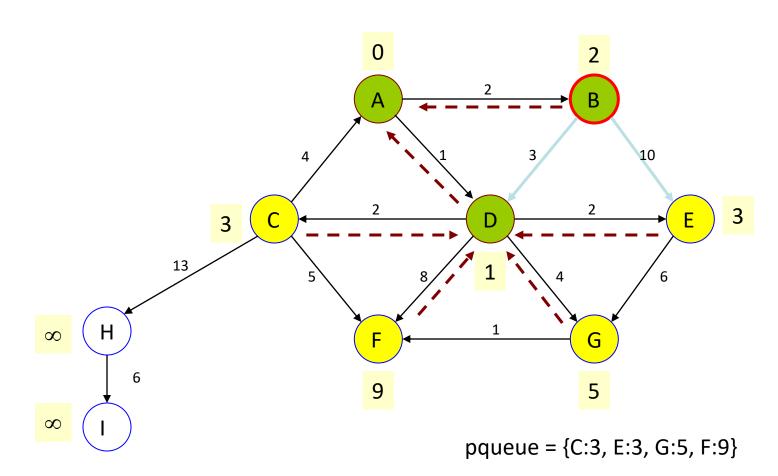
dequeue a vertex v from the pqueue, and mark it as visited. for each unvisited neighbor, n, of v, we can reach n with a total cost of (v's cost + the weight of the edge from v to n). if this cost is cheaper than n's current cost, we should enqueue the neighbor n to the pqueue with this new cost, and remember v was its previous vertex.

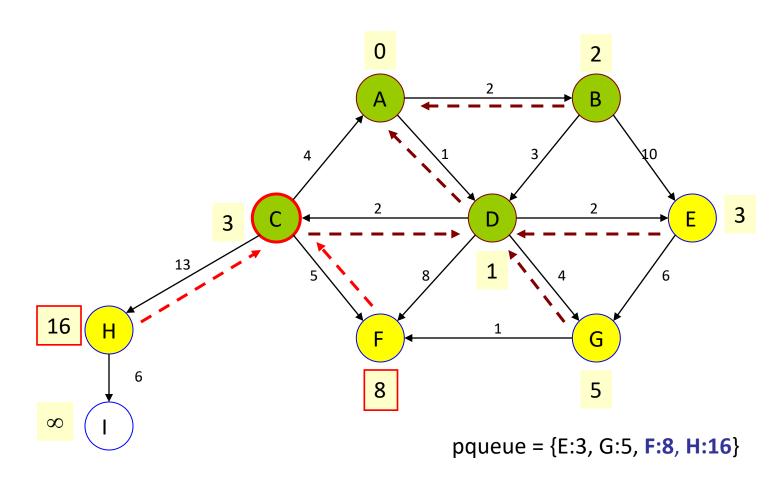
when we are done, we can **reconstruct the path** from  $v_2$  back to  $v_1$  by following the path of previous vertices.

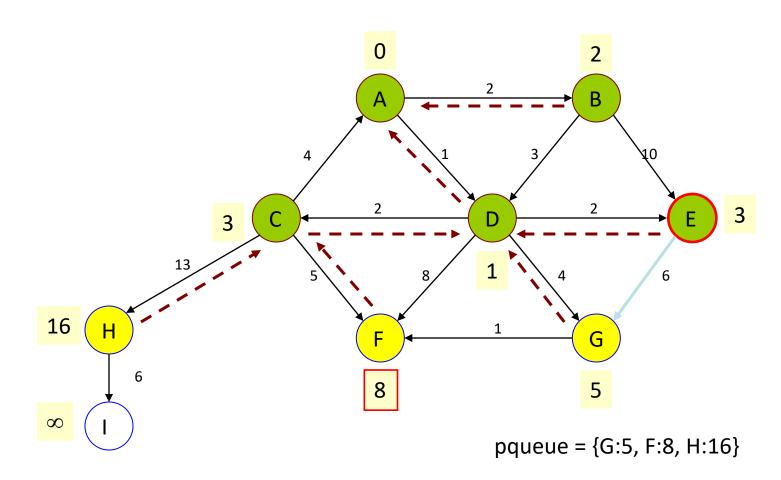


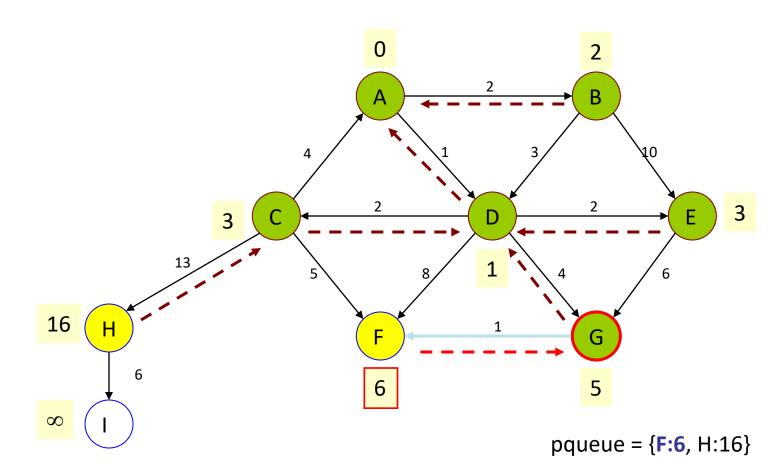


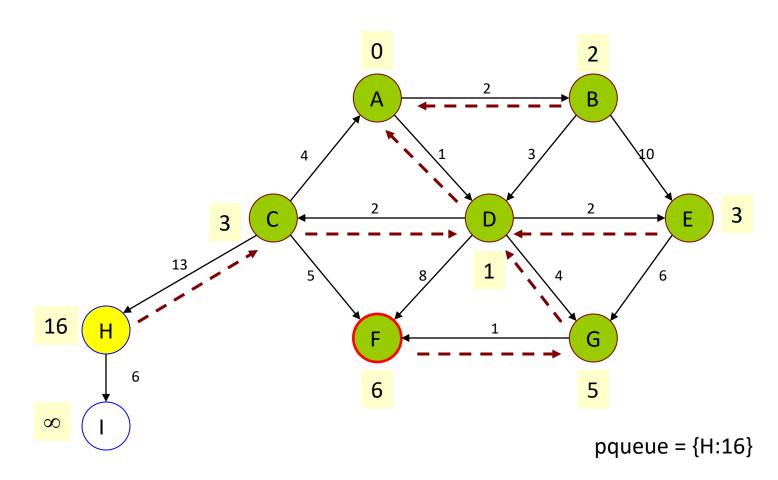


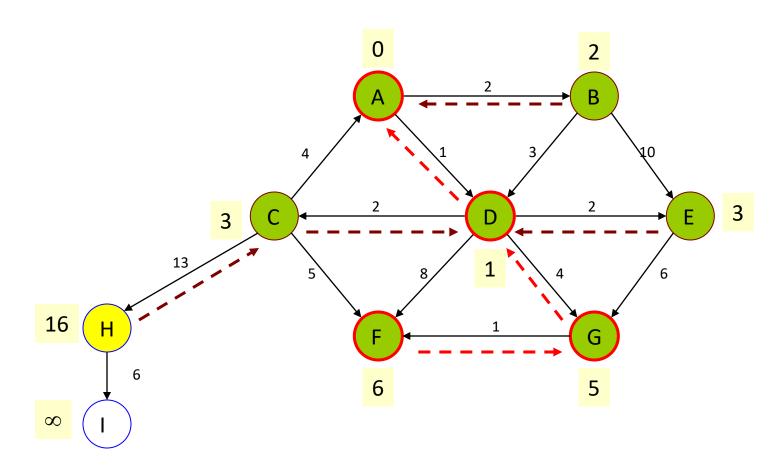












### **Algorithm properties**

- Dijkstra's algorithm is a *greedy algorithm*:
  - Make choices that currently seem best
- It is correct because it maintains the following two properties:
  - 1) for every marked vertex, the current recorded cost is the lowest cost to that vertex from the source vertex.
  - 2) for every unmarked vertex v, its recorded distance is shortest path distance to v from source vertex, considering only currently known vertices and v.

### Dijkstra's runtime

- For sparse graphs, (i.e. graphs with much less than  $V^2$  edges) Dijkstra's is implemented most efficiently with a priority queue.
  - initialization: O(V)
  - while loop: O(V) times
    - remove min-cost vertex from pq: O(log V)
    - potentially perform *E* updates on cost/previous
    - update costs in pq: O(log V)
  - reconstruct path: O(E)
  - Total runtime:  $O(V \log V + E \log V)$ 
    - For more in depth calculation: <a href="http://www-inst.eecs.berkeley.edu/~cs61bl/r//cur/graphs/dijkstra-algorithm-runtime.html?topic=lab24.topic&step=4&course="http://www-runtime.html?topic=lab24.topic&step=4&course="http://www-runtime.html?topic=lab24.topic&step=4&course="http://www-runtime.html?topic=lab24.topic&step=4&course="http://www-runtime.html?topic=lab24.topic&step=4&course="http://www-runtime.html?topic=lab24.topic&step=4&course="http://www-runtime.html?topic=lab24.topic&step=4&course="http://www-runtime.html?topic=lab24.topic&step=4&course="https://www-runtime.html?topic=lab24.topic&step=4&course="https://www-runtime.html?topic=lab24.topic&step=4&course="https://www-runtime.html?topic=lab24.topic&step=4&course="https://www-runtime.html?topic=lab24.topic&step=4&course="https://www-runtime.html?topic=lab24.topic&step=4&course="https://www-runtime.html?topic=lab24.topic&step=4&course="https://www-runtime.html?topic=lab24.topic&step=4&course="https://www-runtime.html?topic=lab24.topic&step=4&course="https://www-runtime.html?topic=lab24.topic&step=4&course="https://www-runtime.html?topic=lab24.topic&step=4&course="https://www-runtime.html?topic=lab24.topic&step=4&course="https://www-runtime.html">https://www-runtime.html</a>

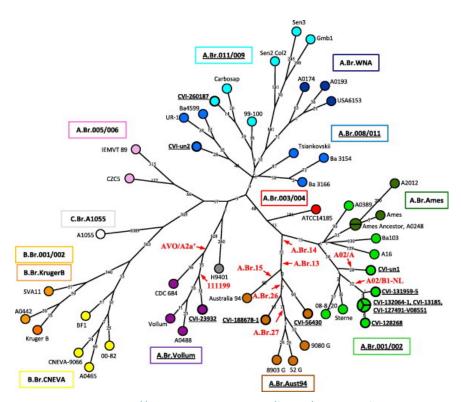
### Announcements

• Assn. 6 due today

• Assn. 7 (the last one!) comes out today

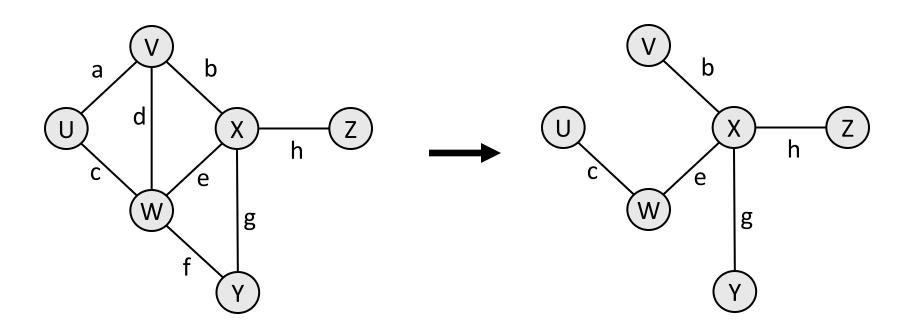
### **Minimum Spanning Trees**

- Sometimes, you want to find a way to connect every node in a graph in the least-cost way possible
  - Utility (road, water, or power) connectivity
  - Tracing virus evolution



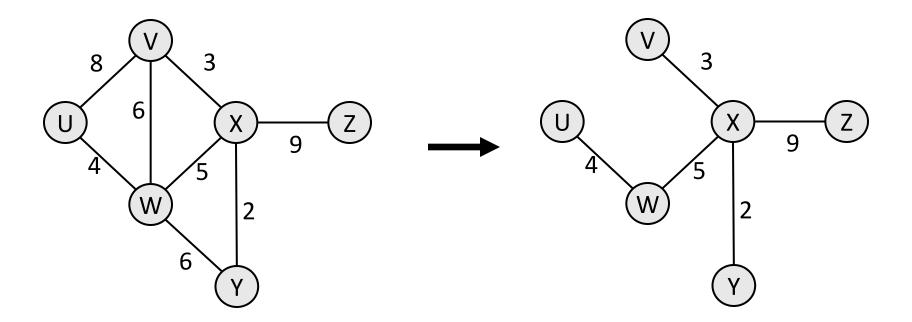
## **Spanning trees**

- A spanning tree of a graph is a set of edges that connects all vertices in the graph with no cycles.
  - What is a spanning tree for the graph below?



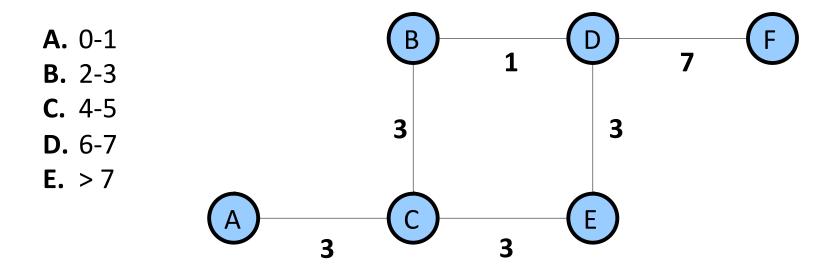
## Minimum spanning tree

• minimum spanning tree (MST): A spanning tree that has the lowest combined edge weight (cost).



# MST examples

• Q: How many minimum spanning trees does this graph have?



### Kruskal's algorithm

• Kruskal's algorithm: Finds a MST in a given graph.

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function kruskal(graph):
 Start with an empty structure for the MST
 Place all edges into a priority queue
     based on their weight (cost).
 While the priority queue is not empty:
     Dequeue an edge e from the priority queue.
     If e's endpoints aren't already connected,
           add that edge into the MST.
     Otherwise, skip the edge.
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• **Runtime:** O(E log E) = O(E log V)

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<sup>-</sup> pq = {n:14, o:15, p:16, q:17, r:18}

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function kruskal(graph):
Start with an empty structure for the MST
                                                              k:11
Place all edges into a priority queue
     based on their weight (cost).
While the priority queue is not empty:
                                                 i:9
   Dequeue an edge e from the priority queue.
   If e's endpoints aren't already connected,
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• In what order would Kruskal's algorithm visit the edges in the graph below? What MST would it produce?

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$$- pq = \{r:18\}$$

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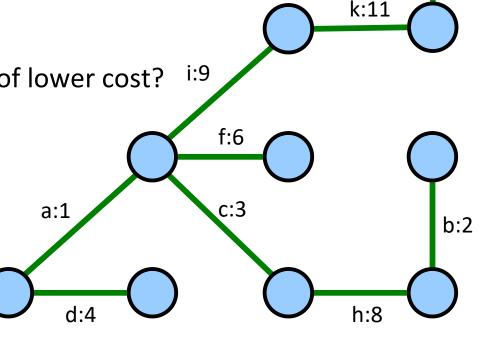
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                                                           f:6
    Otherwise, skip the edge.
```

• Kruskal's algorithm would output the following MST:

The MST's total cost is:

$$1+2+3+4+6+8+9+11+16 = 60$$

Can you find any spanning trees of lower cost?
 Of equal cost?



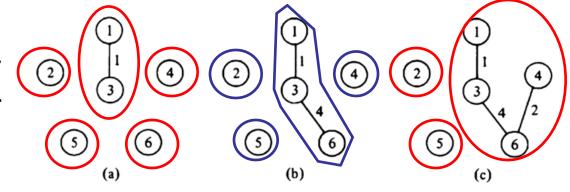
# Implementing Kruskal

What data structures should we use to implement this algorithm?

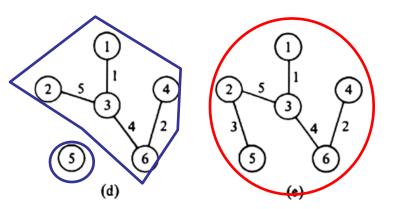
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```

#### **Vertex clusters**

- Need some way to identify which vertexes are "connected" to which other ones
  - we call these "clusters" of vertices
- Also need an efficient way to figure out which cluster a given vertex is in.



 Also need to merge clusters when adding an edge.



#### Kruskal's Code

- How would we code Kruskal's algorithm to find a minimum spanning tree?
- What type of graph (adjacency list, adjacency matrix, or edge list) should we use?