

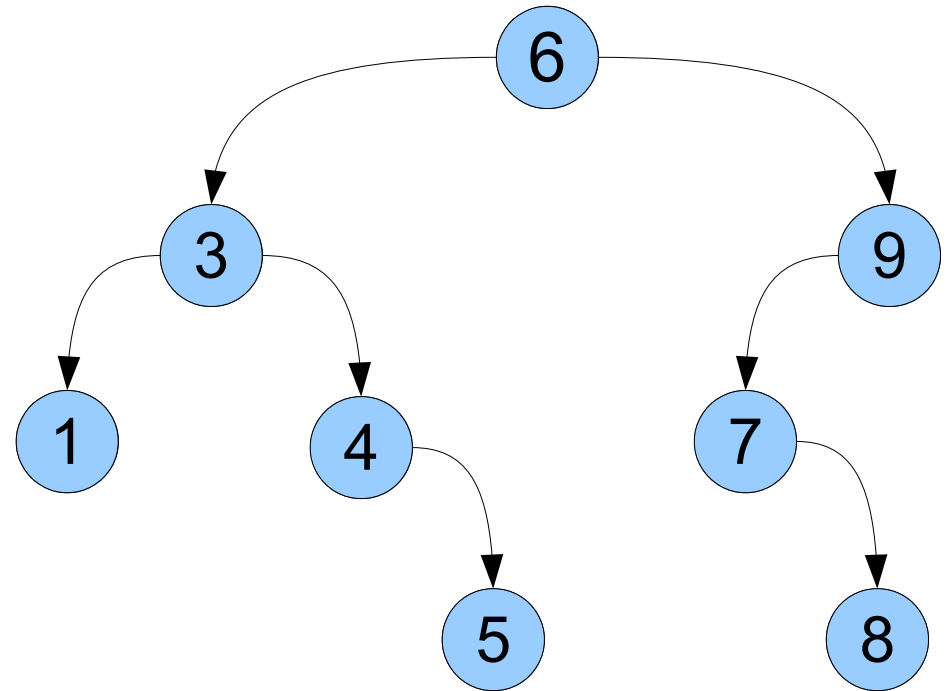
Binary Search Trees

Part Two

Recap from Last Time

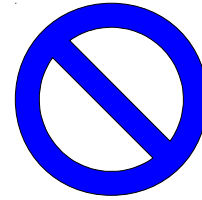
Binary Search Trees

- The data structure we have just seen is called a **binary search tree** (or **BST**).
- The tree consists of a number of **nodes**, each of which stores a value and has zero, one, or two **children**.
- All values in a node's left subtree are **smaller** than the node's value, and all values in a node's right subtree are **greater** than the node's value.

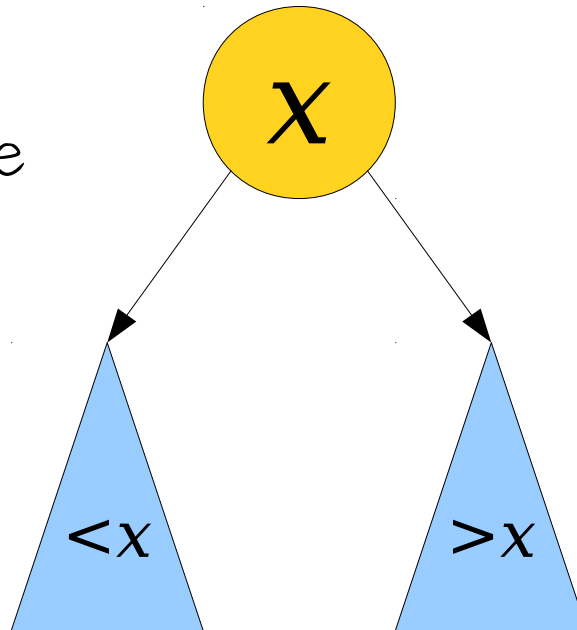


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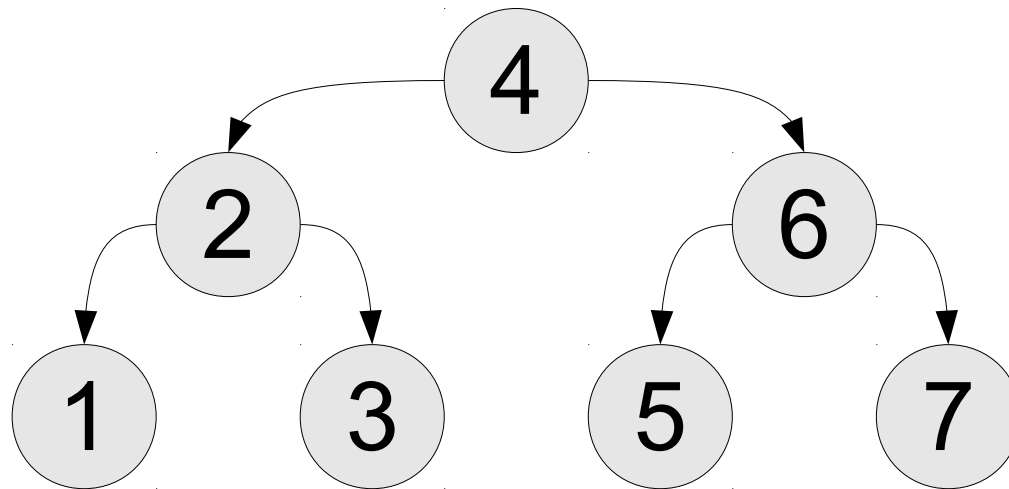
New Stuff!

Getting Rid of Trees



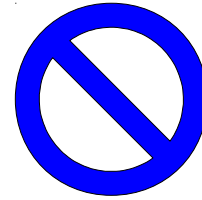
Freeing a Tree

- Once we're done with a tree, we need to free all of its nodes.
- As with a linked list, we have to be careful not to use any nodes after freeing them.

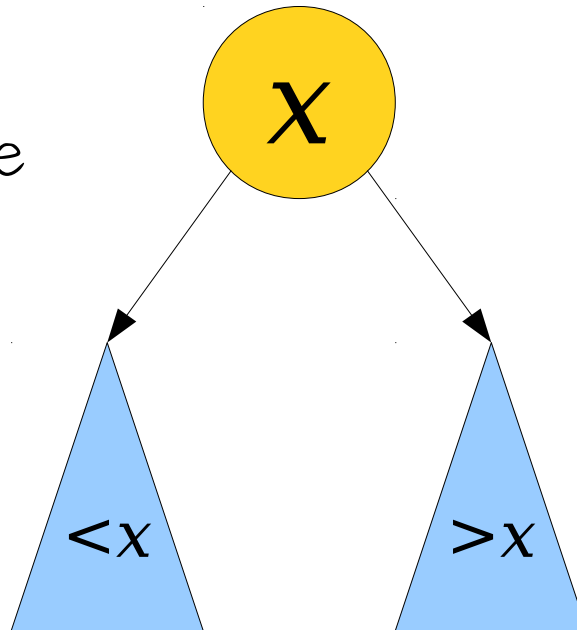


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Which Options Work?

```
void deleteTree(Node* root) {  
    if (root == nullptr) return;  
  
    delete root;  
    deleteTree(root->left);  
    deleteTree(root->right);  
}
```

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    delete root;  
}
```

Postorder Traversals

- The particular recursive pattern we just saw is called a ***postorder traversal*** of a binary tree.
- Specifically:
 - Recursively visit all the nodes in the left subtree.
 - Recursively visit all the nodes in the right subtree.
 - Visit the node itself.

Tree Efficiency



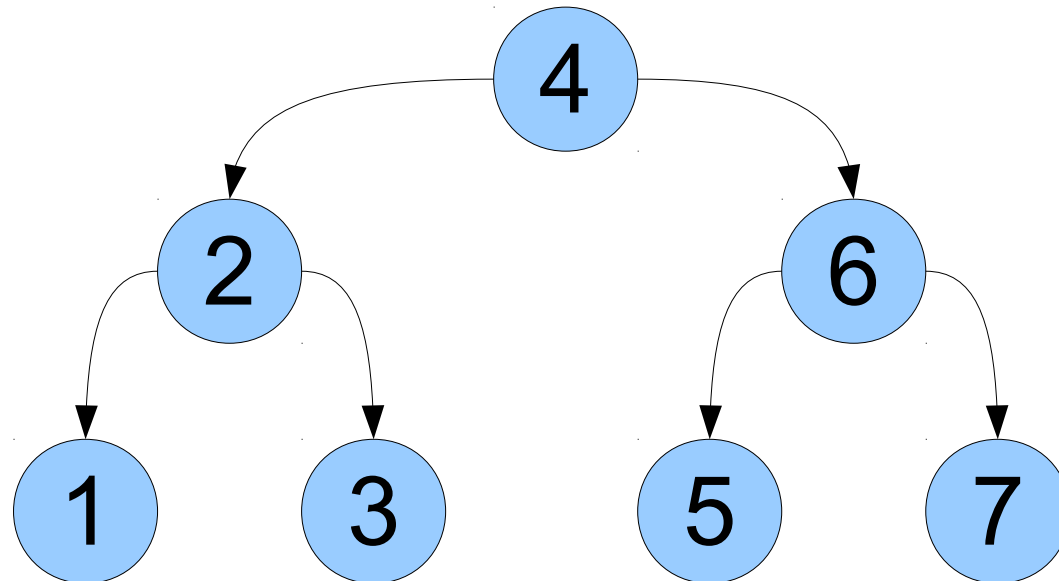
How fast are BST lookups?

How fast are BST insertions?

Insertion Order Matters

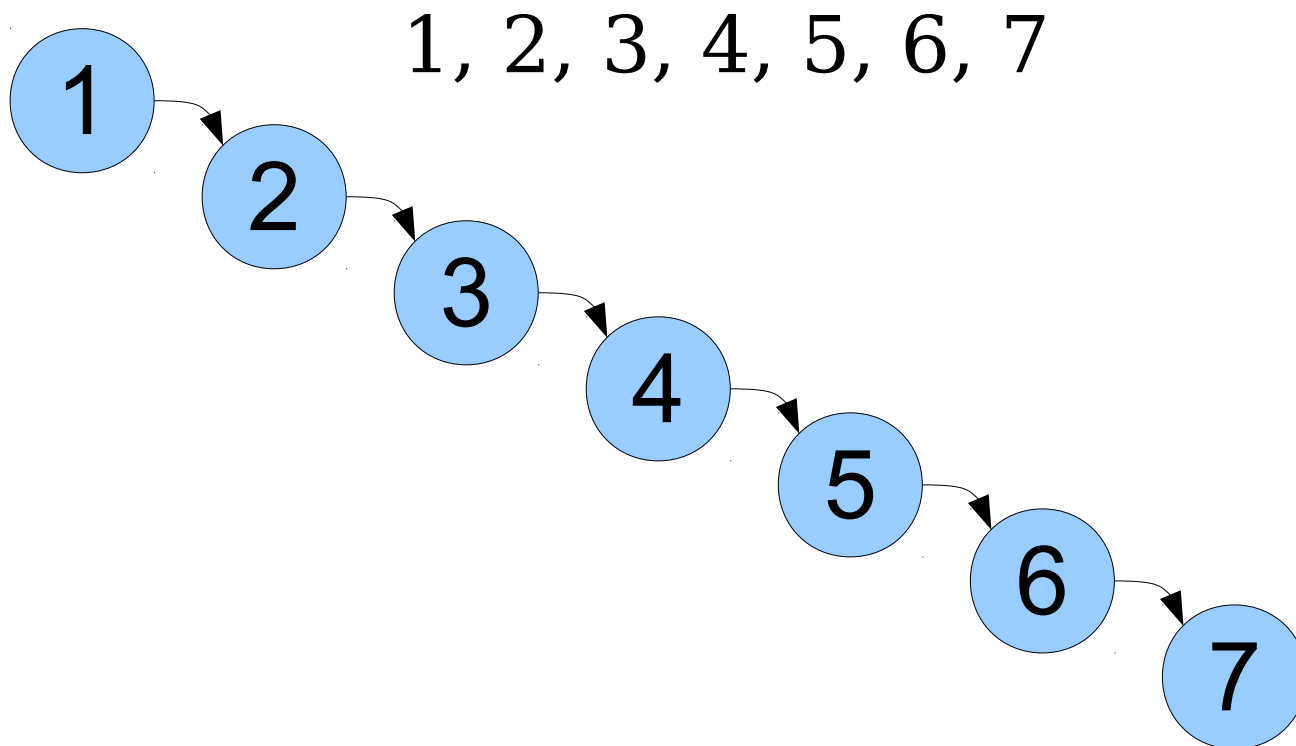
- You can have multiple BSTs holding the same elements
- Here's the BST we get by inserting these elements in this order:

4, 2, 1, 3, 6, 5, 7



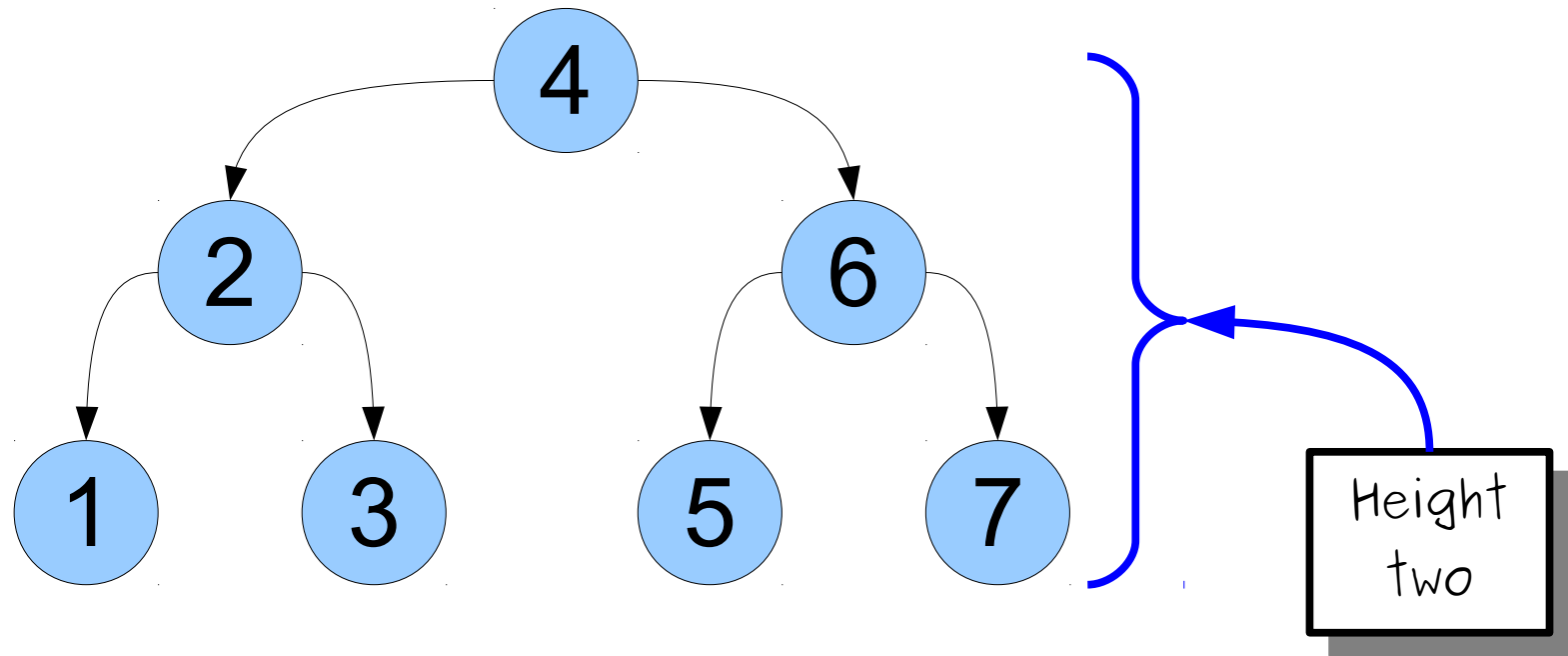
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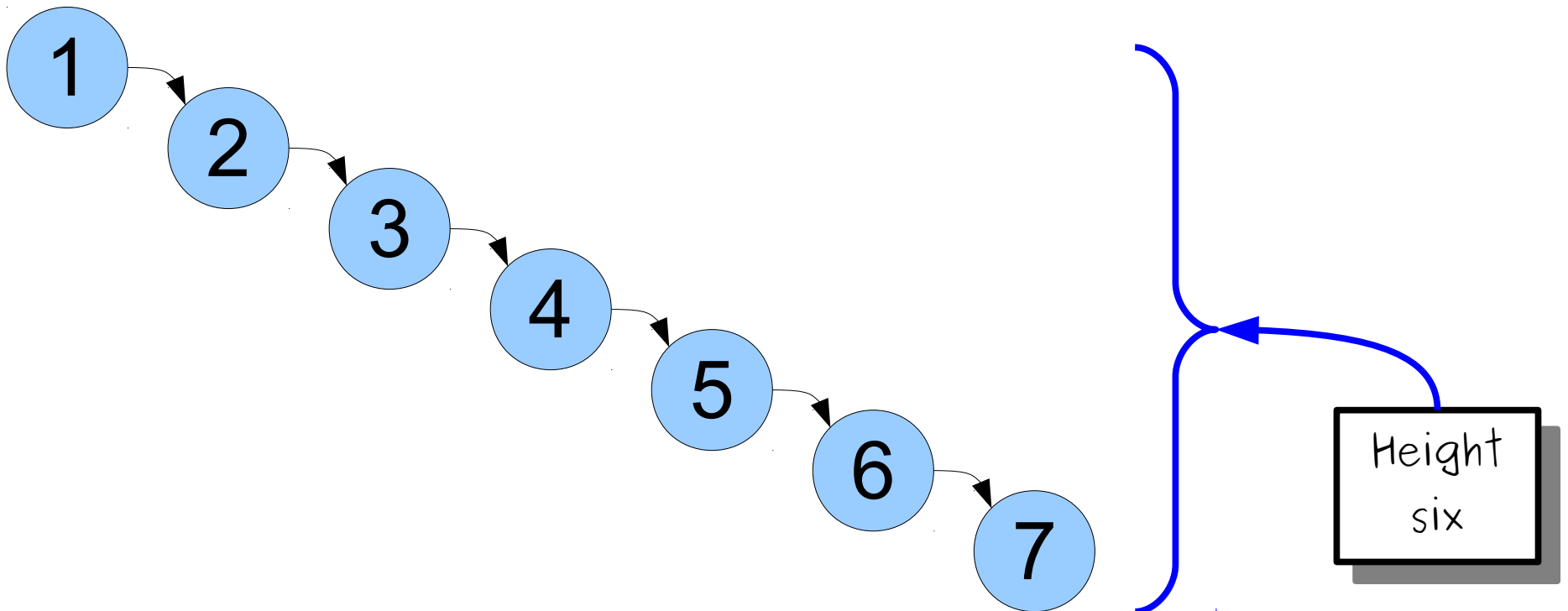
Tree Terminology

- The **height** of a tree is the number of nodes in the longest path from the root to a leaf.



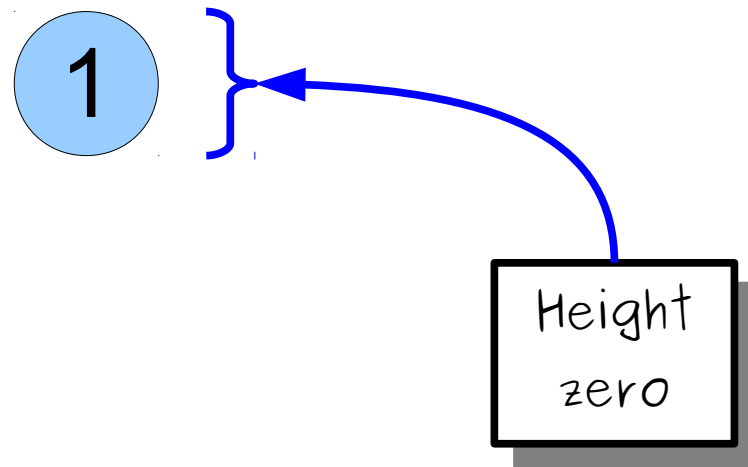
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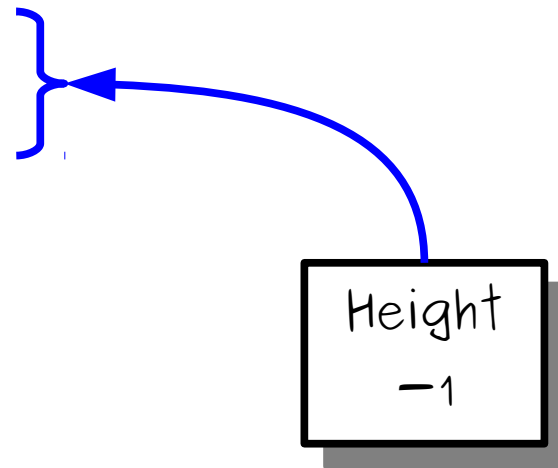
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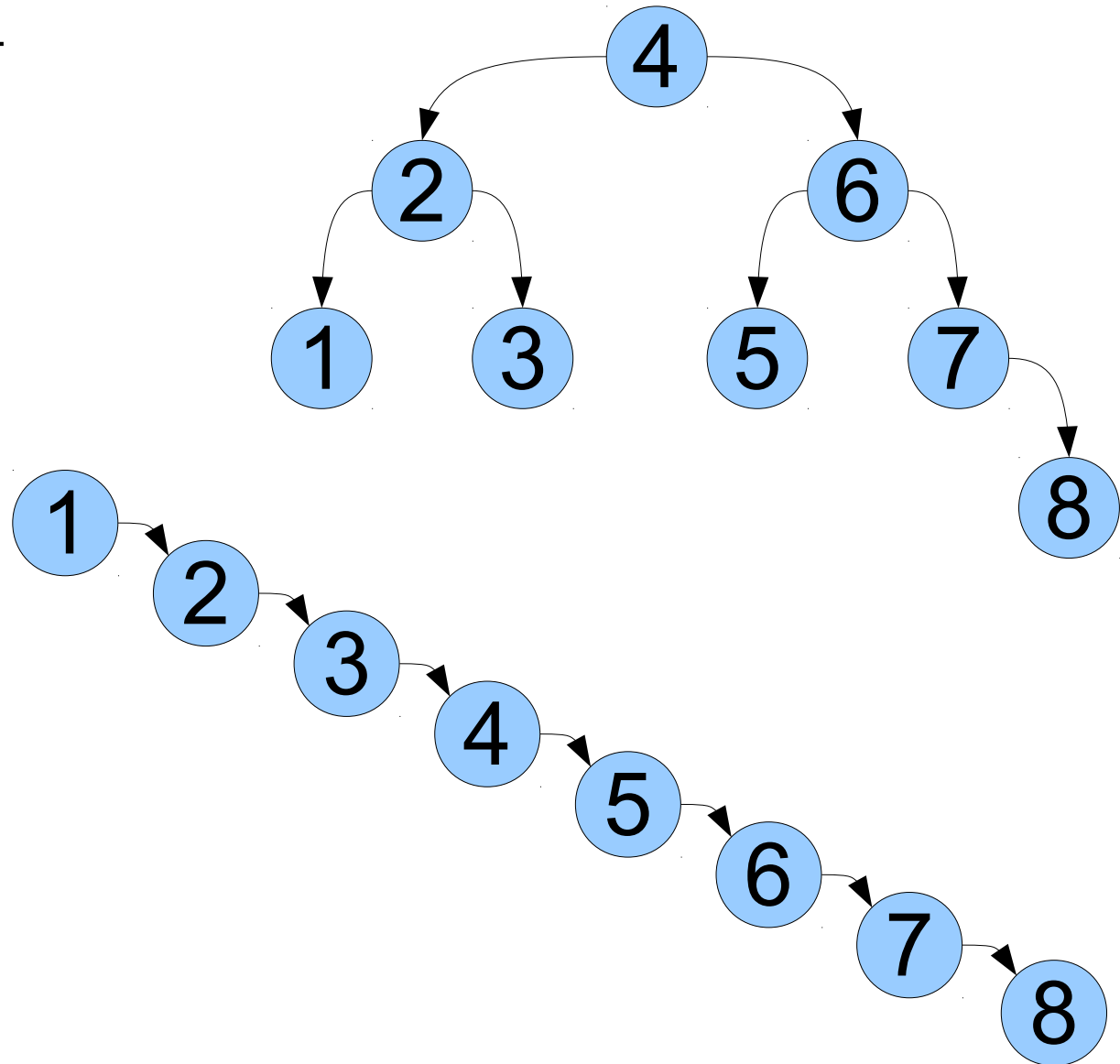
Tree Terminology

- The ***height*** of a tree is the number of nodes in the longest path from the root to a leaf.
- By convention, an empty tree has height -1.



Efficiency Questions

- The time to add an element to a BST (or look up an element in a BST) depends on the height of the tree.
- The runtime is $O(h)$, where h is the height of the tree.



The cost of an insertion or lookup on a BST is $O(h)$, where h is the height of the tree.

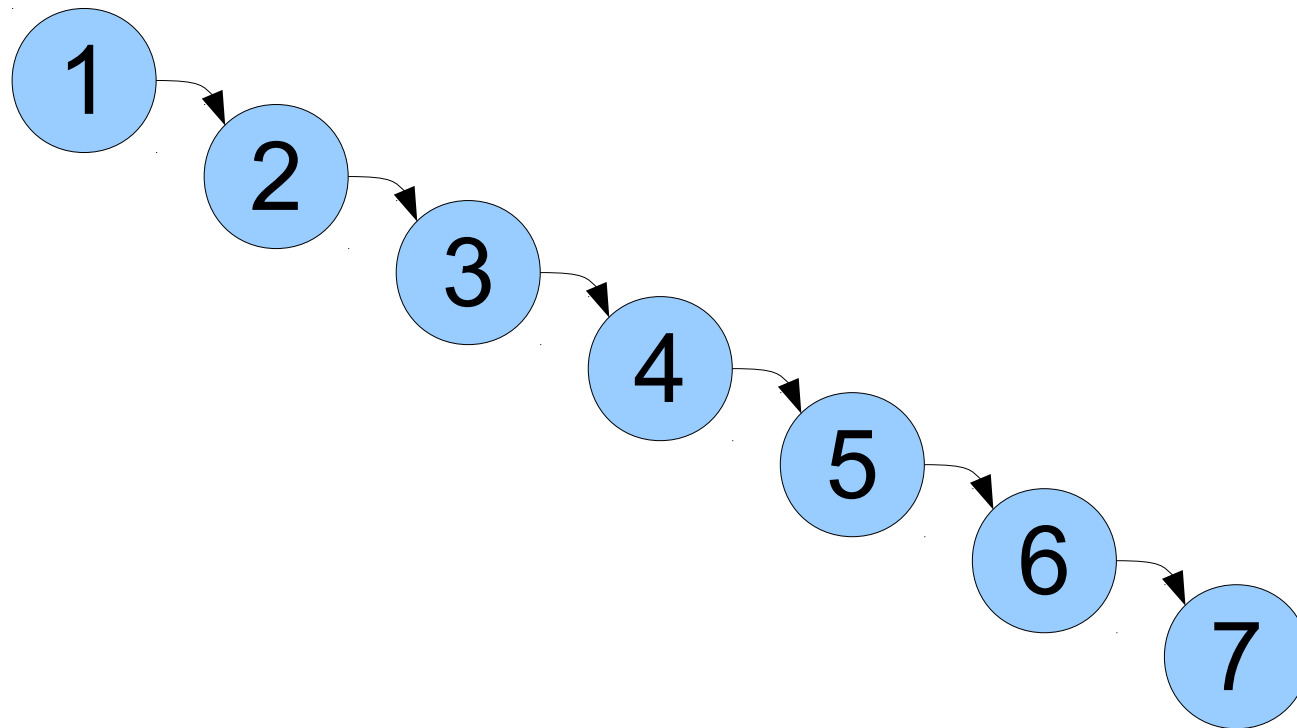
Is there a connection between h , the tree height, and n , the number of nodes?

Balanced Trees



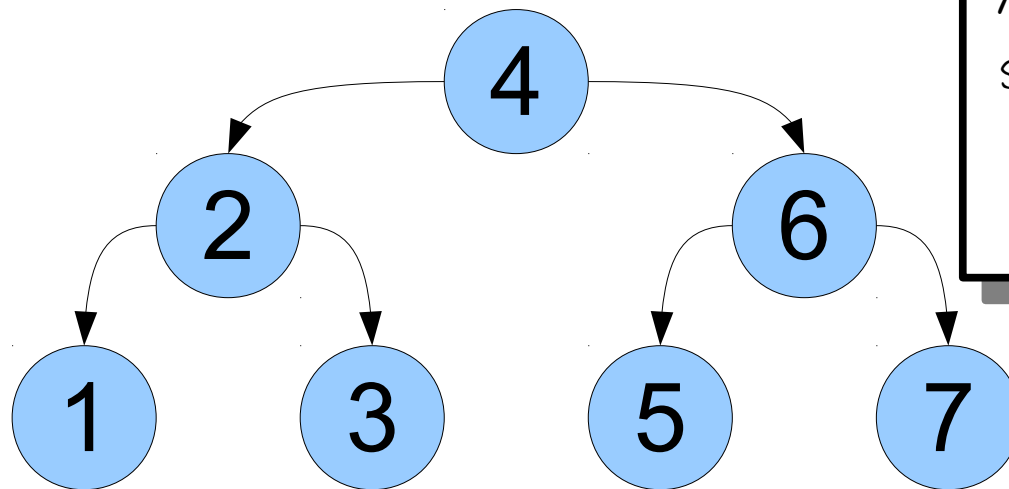
Tree Heights

- What are the maximum and minimum heights of a tree with n nodes?
- Maximum height: all nodes in a chain. Height is $O(n)$.



Tree Heights

- What are the maximum and minimum heights of a tree with n nodes?
- Maximum height: all nodes in a chain. Height is $O(n)$.
- Minimum height: tree is as complete as possible. Height is $O(\log n)$.



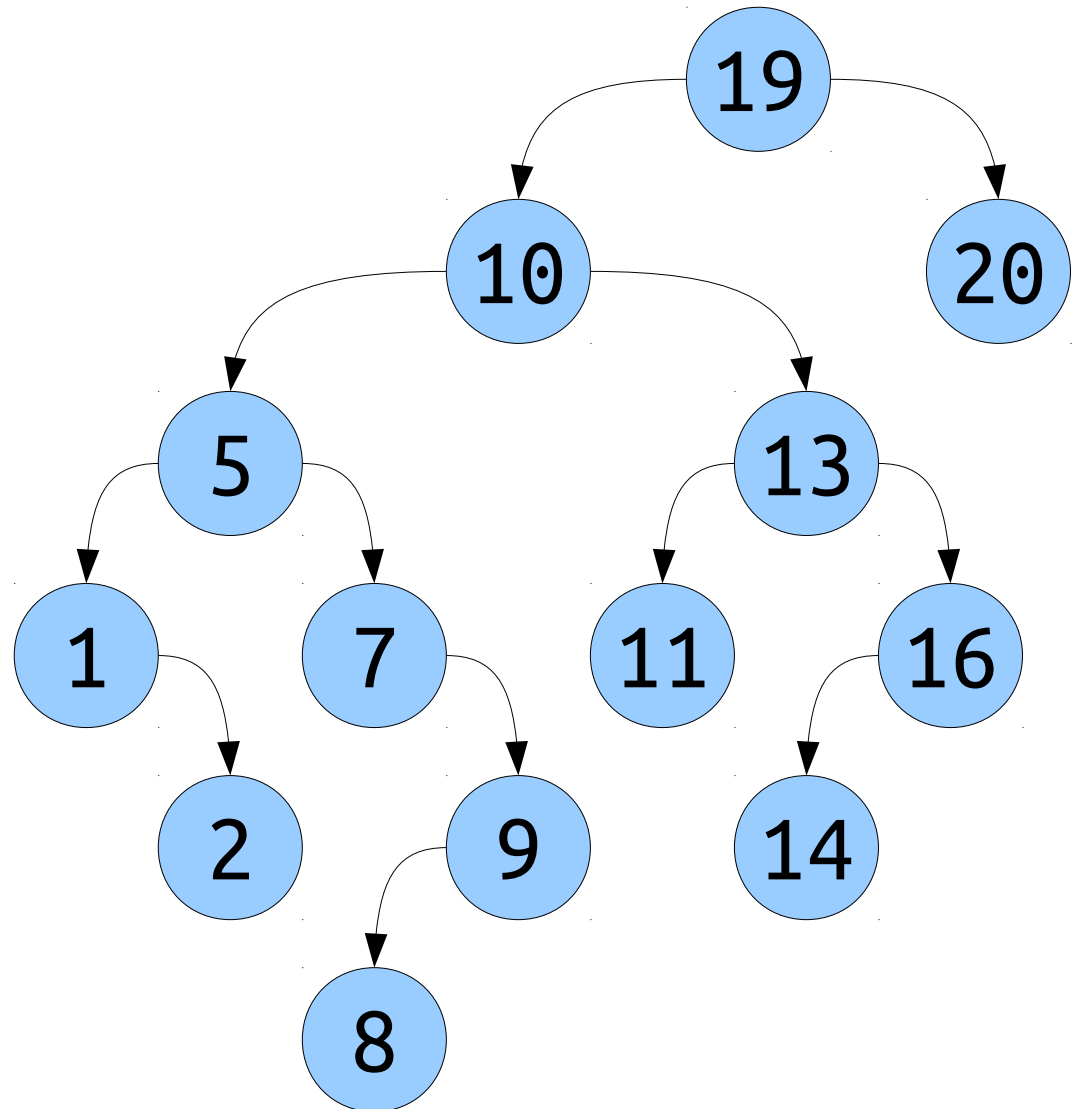
You can only double something $O(\log n)$ times before it exceeds n .

Balanced Trees

- A binary search tree is called ***balanced*** if its height is $O(\log n)$, where n is the number of nodes in the tree.
- Balanced trees are extremely efficient:
 - Lookups take time $O(\log n)$.
 - Insertions take time $O(\log n)$.
 - Deletions take time $O(\log n)$.
- ***Question:*** How do you balance a tree?

Balanced Trees

- **Theorem:** If you start with an empty tree and add in random values, then, with high probability, the tree is balanced.
- **Proof:** Take CS161!
- **Takeaway:** If you're adding elements to a BST and their values are actually random, then your tree is likely to be balanced.



Balanced Trees

- A ***self-balancing tree*** is a BST that reshapes itself on insertions and deletions to stay balanced.
- There are many strategies for doing this. They're beautiful. They're clever. And they're beyond the scope of CS106B.
- Some suggested topics to read up on, if you're curious:
 - Red/black trees (take CS161 or CS166!)
 - AVL trees (covered in the textbook)
 - Splay trees (trees that reshape on lookups)
 - Scapegoat trees (yes, that's what they're called)
 - Treaps (half binary heap, half binary search tree!)

Balanced Trees

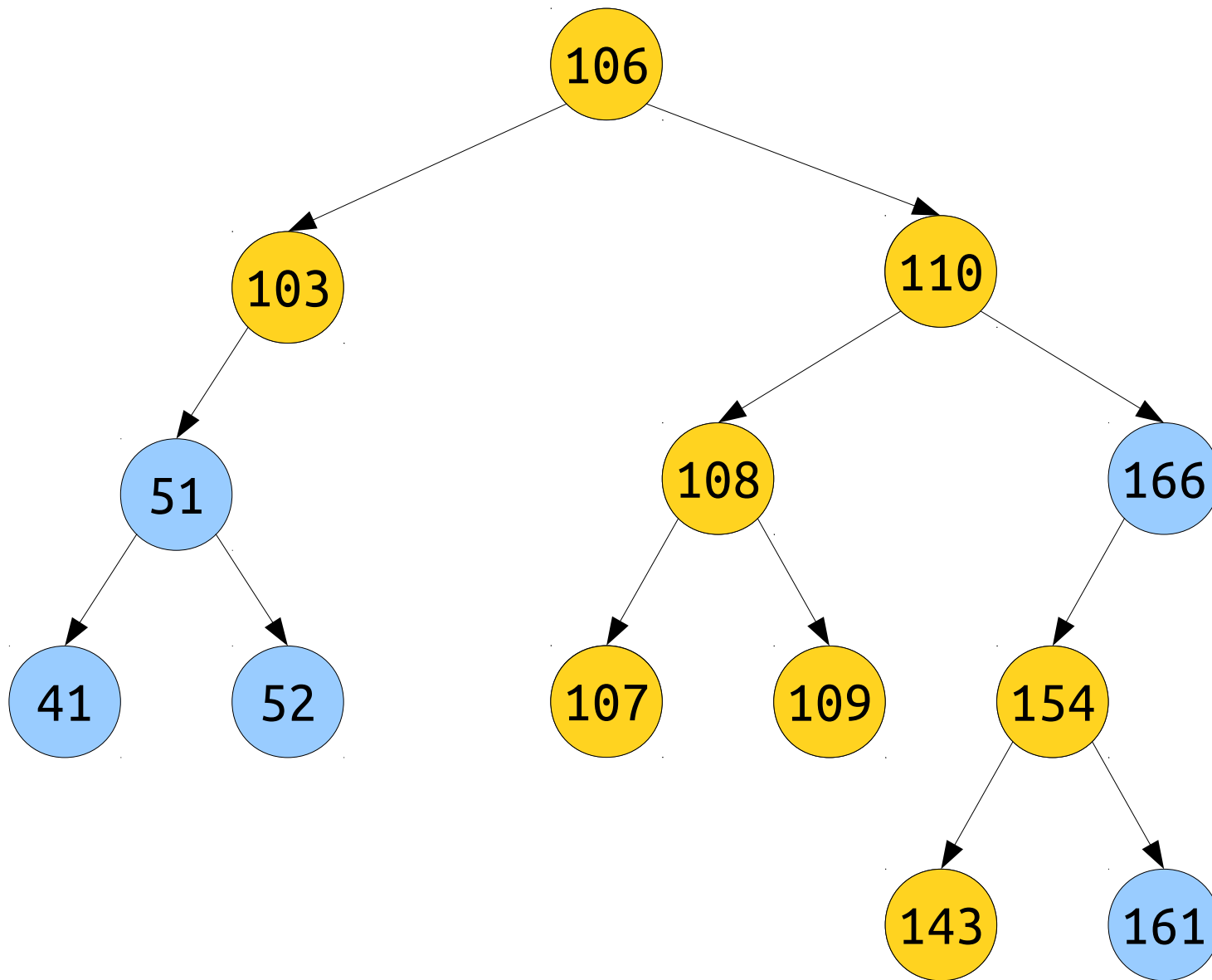
- If you're given a collection of values to put in a BST, and they're already sorted, you can construct a perfectly-balanced tree from them.
- Things to think about:
 - Which element would you put up at the root?
 - What would the children of that element be?
- These are great questions to think through.

Range Searches

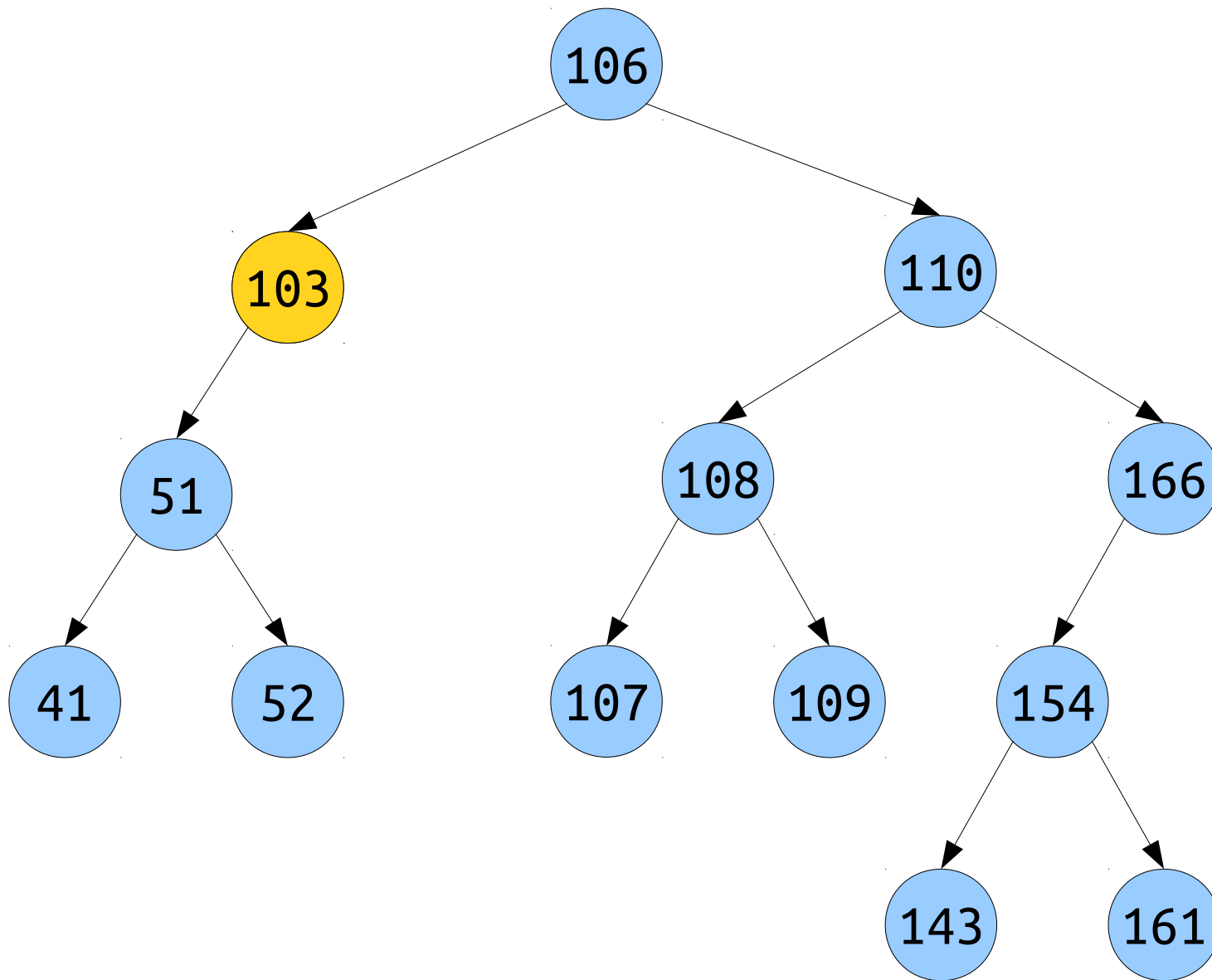


Range Searches

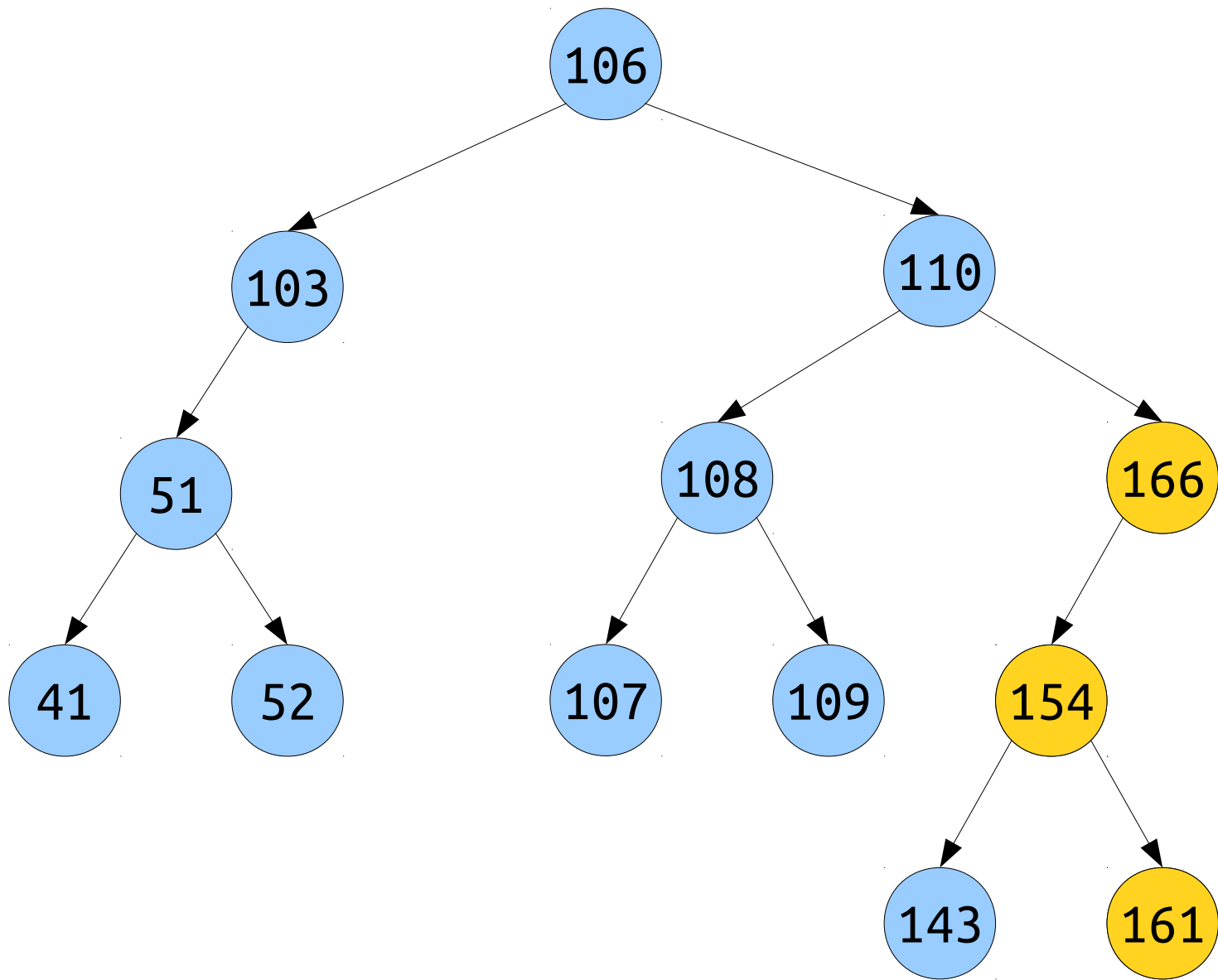
- We can use BSTs to do *range searches*, in which we find all values in the BST within some range.
- For example:
 - If the values in the BST are dates, we can find all events that occurred within some time window.
 - If the values in the BST are number of diagnostic scans ordered, we can find all doctors who order a disproportionate number of scans.



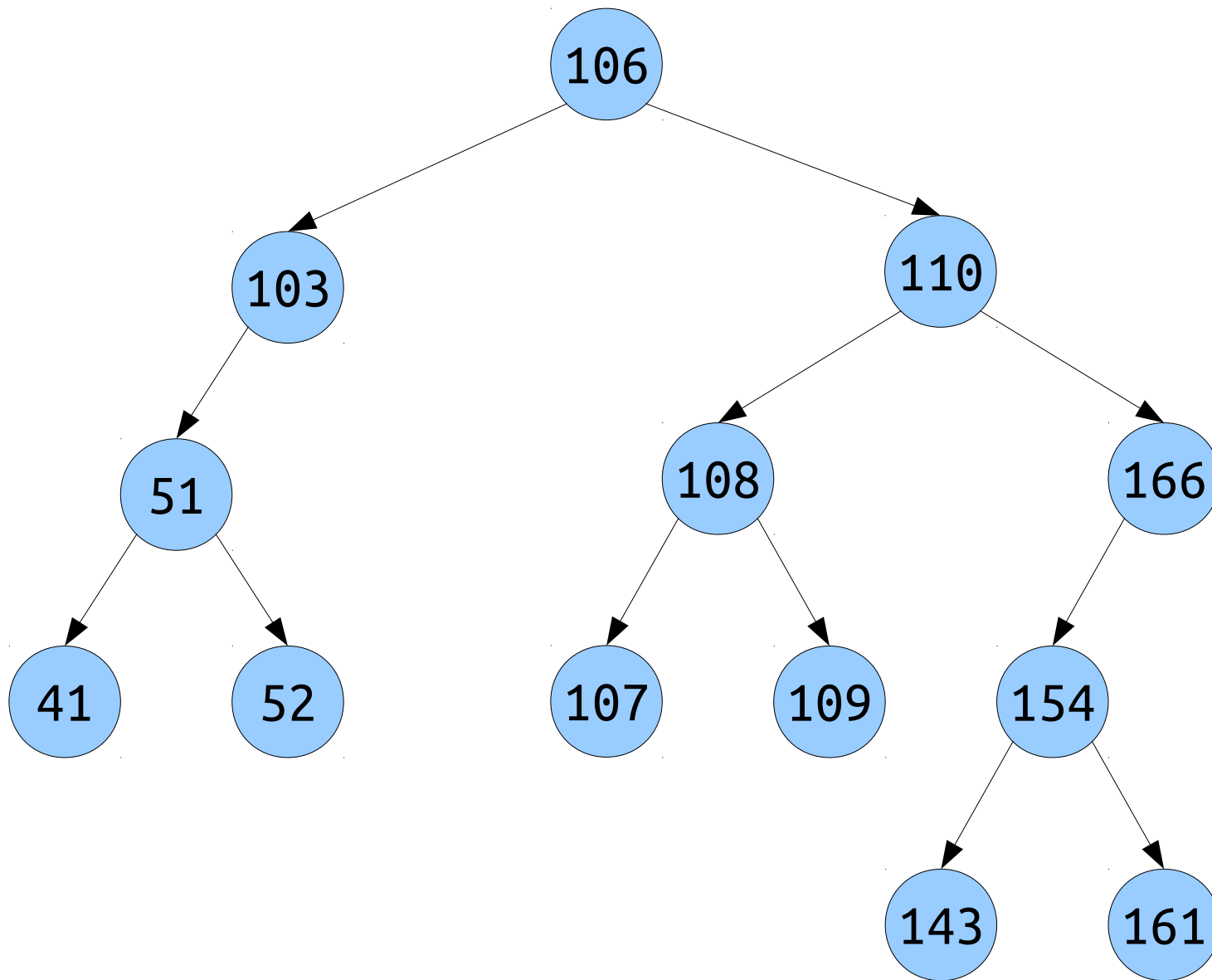
Find all elements in this tree in the range **[103, 154]**.



Find all elements in this tree in the range **[99, 105]**.



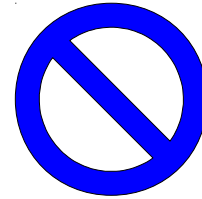
Find all elements in this tree in the range **[150, 170]**.



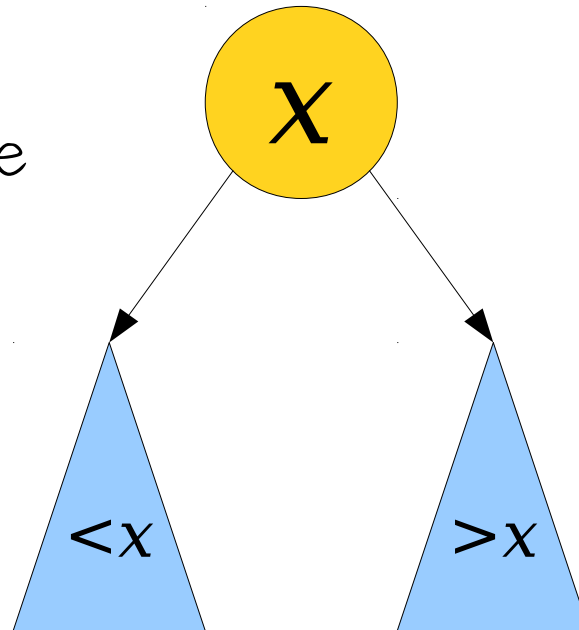
Find all elements in this tree in the range **[137, 138]**.

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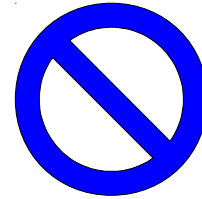
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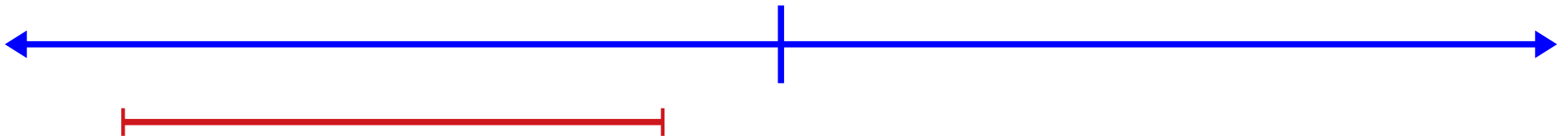
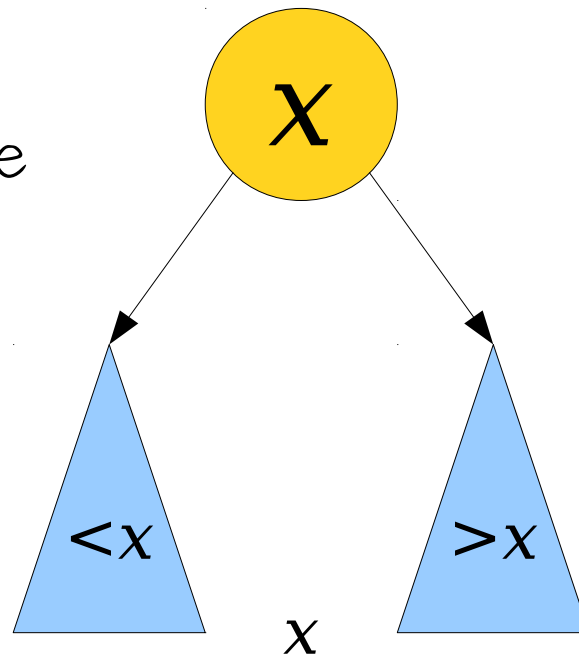
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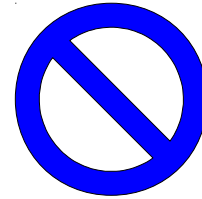
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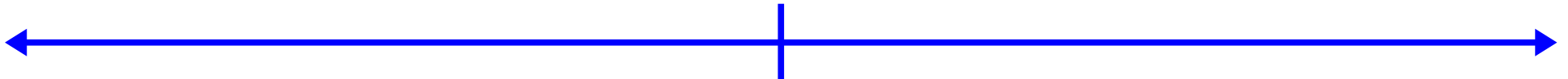
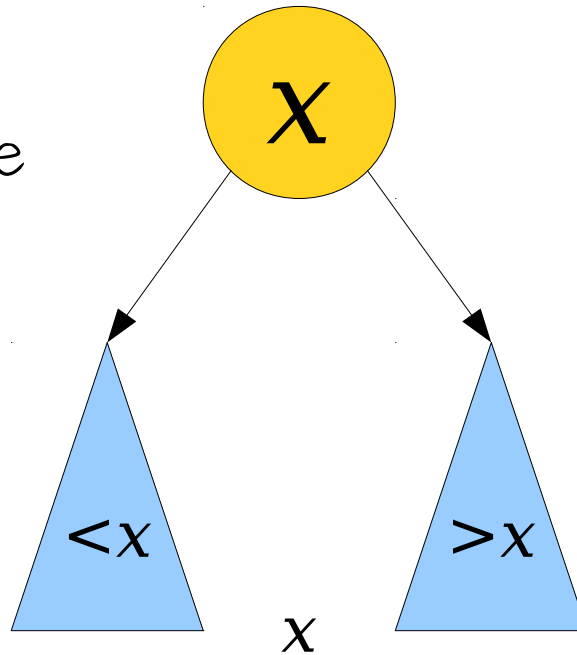
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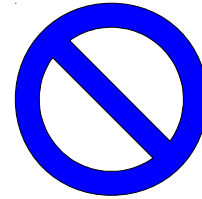
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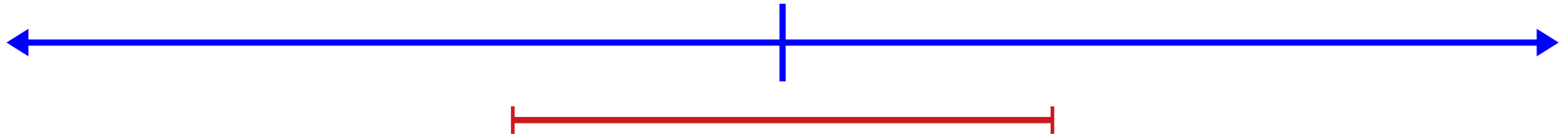
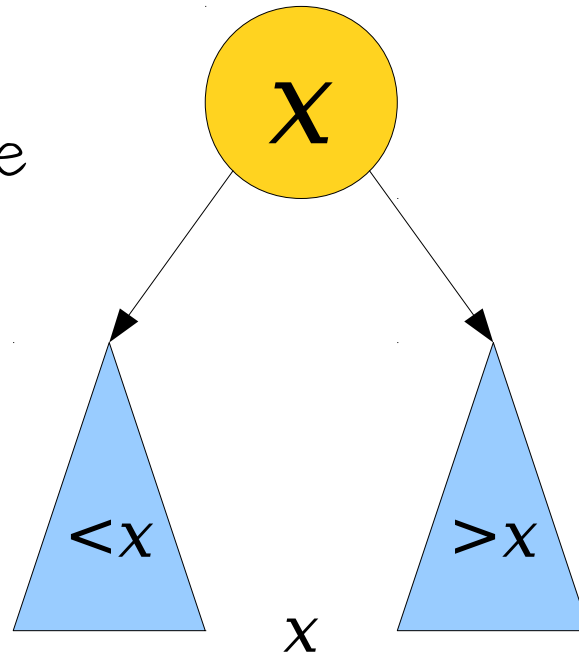
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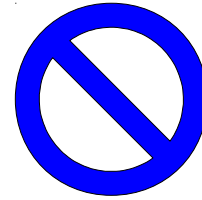
Range Searches

- A hybrid between an inorder traversal and a regular BST lookup!
- The idea:
 - If the node is in the range being searched, add it to the result.
 - Recursively explore each subtree that could potentially overlap with the range.
- ***Fun fact:*** The runtime of a range search is $O(h + z)$, where h is the height of the tree and z is the number of items in the range. Come chat with me after class if you're curious why this is!

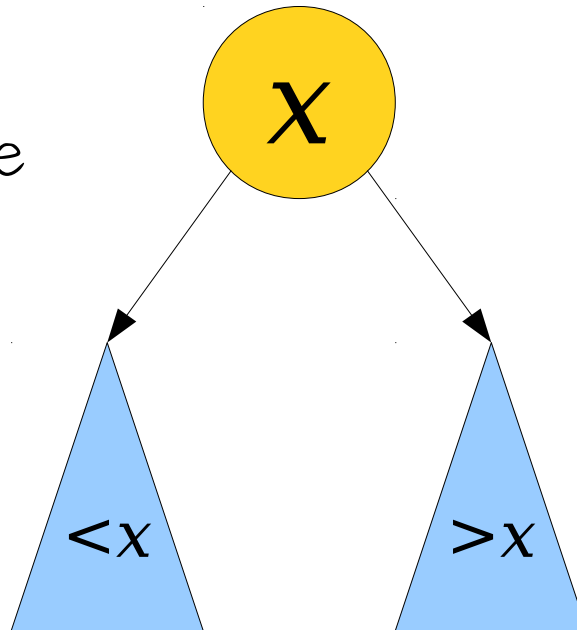
To Summarize:

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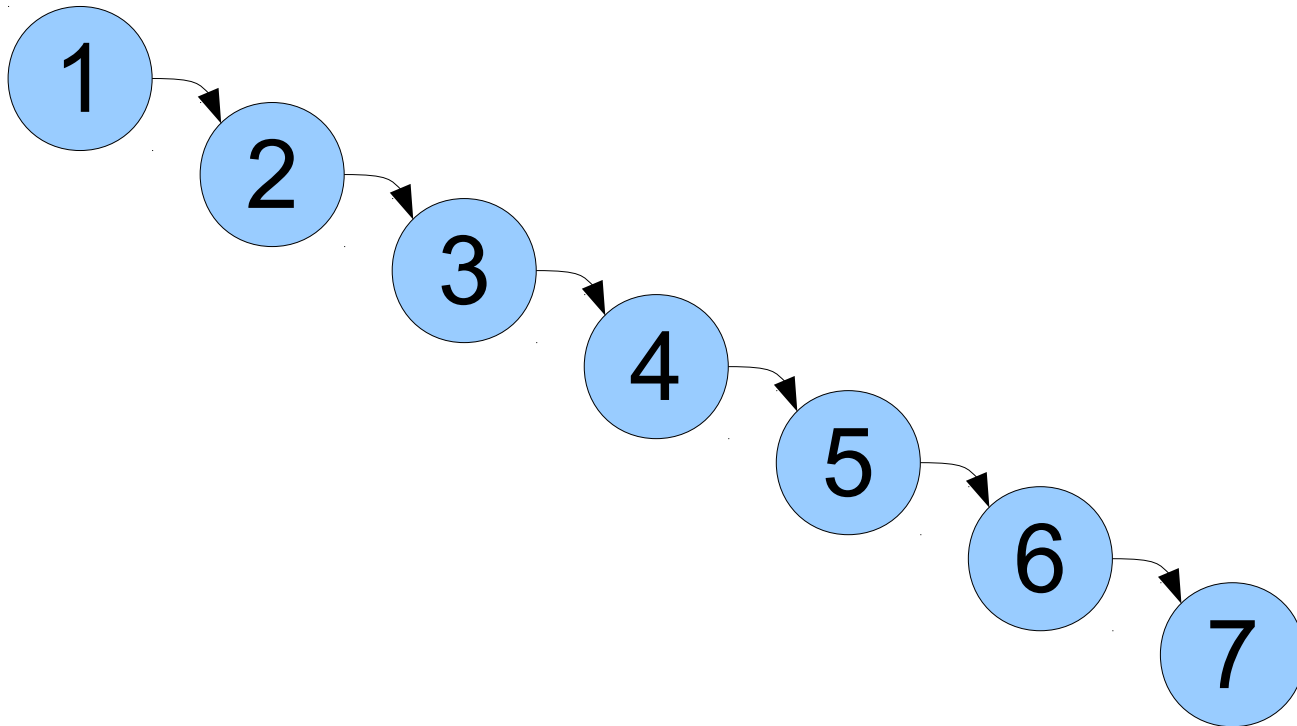
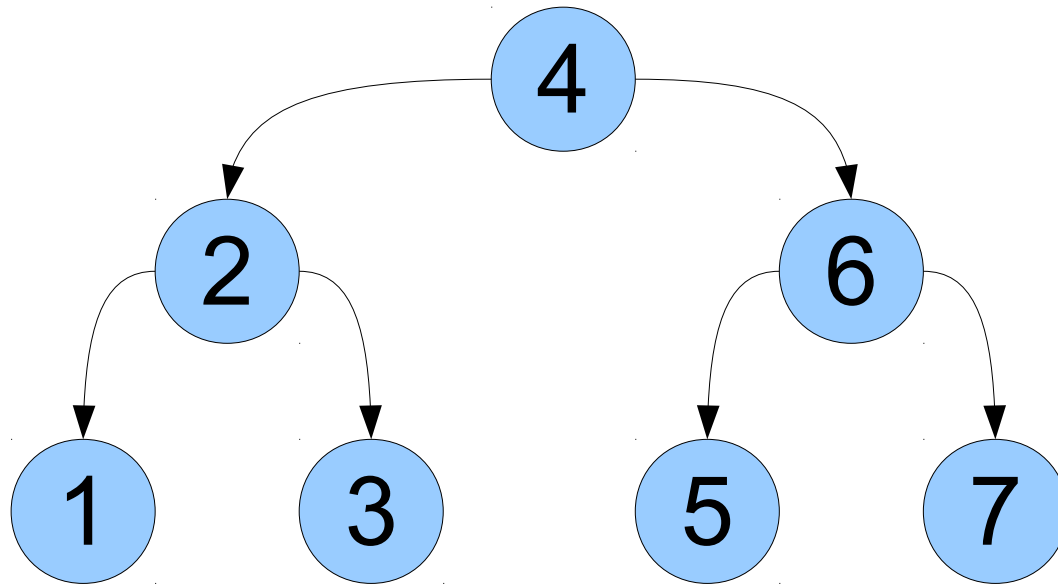


... and whose right
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```
struct Node {  
    Type value;  
    Node* left; // Smaller values  
    Node* right; // Bigger values  
};
```

```
bool contains(Node* root, const string& key) {  
    if (root == nullptr) return false;  
    else if (key == root->value) return true;  
    else if (key < root->value) return contains(root->left, key);  
    else return contains(root->right, key);  
}
```

```
void insert(Node*& root, const string& key) {  
    if (root == nullptr) {  
        root = new Node;  
        node->value = key;  
        node->left = node->right = nullptr;  
    } else if (key < root->value) {  
        insert(root->left, key);  
    } else if (key > root->value) {  
        insert(root->right, key);  
    } else {  
        // Already here!  
    }  
}
```



```
void printTree(Node* root) {  
    if (root == nullptr) return;  
  
    printTree(root->left);  
    cout << root->value << endl;  
    printTree(root->right);  
}
```

```
void deleteTree(Node* root) {  
    if (root == nullptr) return;  
  
    deleteTree(root->left);  
    deleteTree(root->right);  
    delete root;  
}
```

```
void printInRange(Node* tree, const string& low, const string& high) {  
    if (tree == nullptr) return;  
  
    if (high < tree->value) {  
        printInRange(tree->left, low, high);  
    } else if (low > tree->value) {  
        printInRange(tree->right, low, high);  
    } else {  
        printInRange(tree->left, low, high);  
        cout << tree->value << endl;  
        printInRange(tree->right, low, high);  
    }  
}
```

Your Action Items

- ***Read Chapter 16.1 - 16.2.***
 - All about BSTs!
- ***Finish Assignment 7.***
 - You can use late periods here if you'd like, but be careful about doing so since you can't use them on the next assignment.

Next Time

- ***Other Binary Trees***
 - BSTs are wonderful, but other tree structures with similar shapes exist.
- ***Huffman Coding***
 - Using fewer bits to send a message.