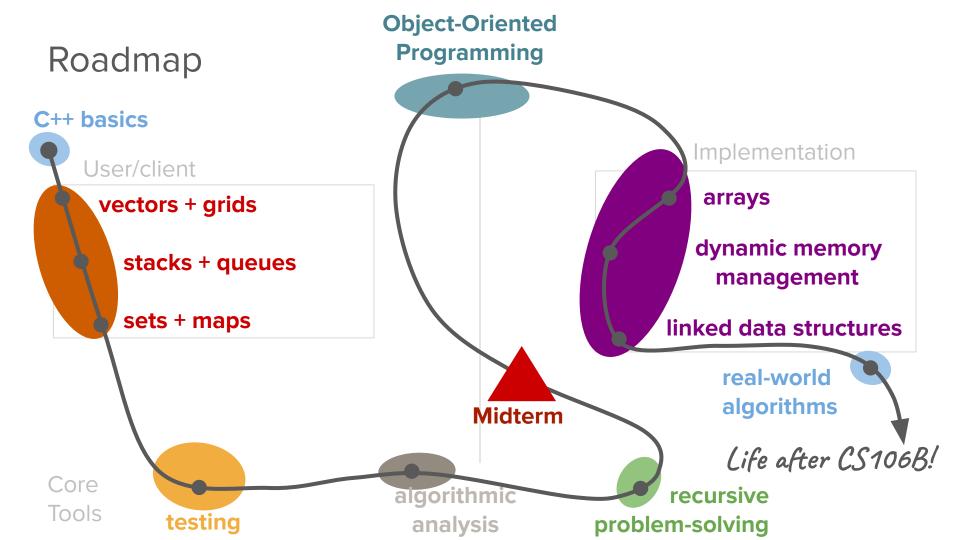
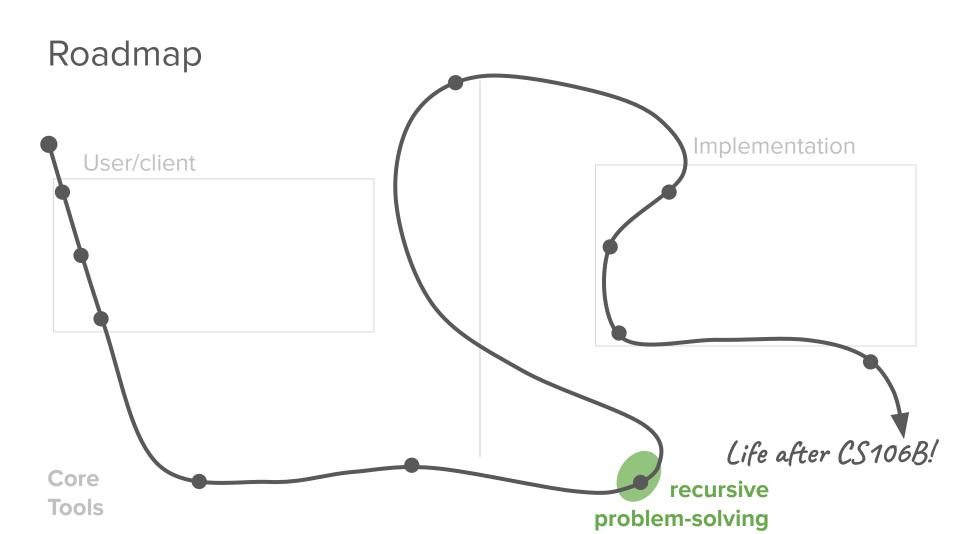
Why We Use Recursion

If you haven't played Towers of Hanoi yet (or even if you have), do that now!

mathsisfun.com/games/towerofhanoi.html







Today's question

Why is recursion such a powerful problem-solving tool?

Today's topics

1. Review

- 2. Elegance
- 3. Efficiency(the return of Big O)
- 4. Recursive Backtracking



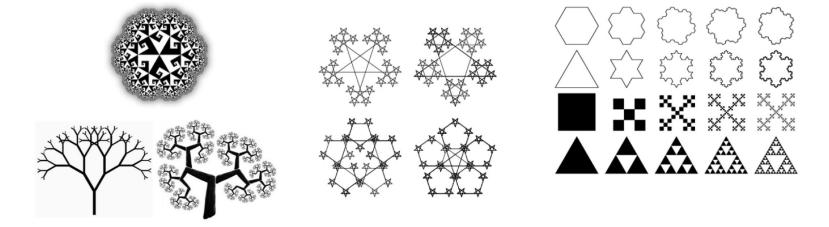
Self-Similarity

- Solving problems recursively and analyzing recursive phenomena involves identifying self-similarity
- An object is **self-similar** if it contains a smaller copy of itself.



Fractals

- A fractal is any repeated, graphical pattern.
- A fractal is composed of **repeated instances of the same shape or pattern**, arranged in a structured way.



An order-3 tree

An order-0 tree is nothing at all.

An order-**n** tree is a line with two smaller order- (**n-1**) trees starting at the end of that line.

What differentiates the smaller tree from the bigger one?

- 1. It's at a different **position**.
- 2. It has a different **size**.
- 3. It has a different orientation.
- 4. It has a different order.

Fractals and self-similar structures are often defined in terms of some parameter called the **order**, which indicates the complexity of the overall structure.

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	- Her	

Sierpinski Carpet Pseudocode (Take 2)

Sierpinski Carpet

```
void drawSierpinskiCarpet(GWindow& window, double x, double y, double size, int order) {
   // Base case: A carpet of order 0 is a filled square.
   if (order == 0) {
       drawSquare(window, x, y, size);
   } else {
       for (int row = 0; row < 3; row++) {</pre>
           for (int col = 0; col < 3; col++) {</pre>
               // The only square to skip is the very center one.
               if (row != 1 || col != 1) {
                   double newX = x + col * size / 3;
                   double newY = y + row * size / 3;
                   drawSierpinskiCarpet(window, newX, newY, size / 3, order - 1);
               }
           }
       }
```

Iteration + Recursion

- It's completely reasonable to mix iteration and recursion in the same function.
- Here, we're firing off eight recursive calls, and the easiest way to do that is with a double for loop.
- Recursion doesn't mean "the absence of iteration." It just means "solving a problem by solving smaller copies of that same problem."
- Iteration and recursion can be very powerful in combination!

Homework from yesterday

• Play Towers of Hanoi:

https://www.mathsisfun.com/games/towerofhanoi.html

- Look for and write down patterns in how to solve the problem as you increase the number of disks. Try to get to at least 5 disks!
- **Extra challenge** (optional): How would you define this problem recursively?
 - Don't worry about data structures here. Assume we have a function moveDisk(X, Y) that will handle moving a disk from the top of post X to the top of post Y.

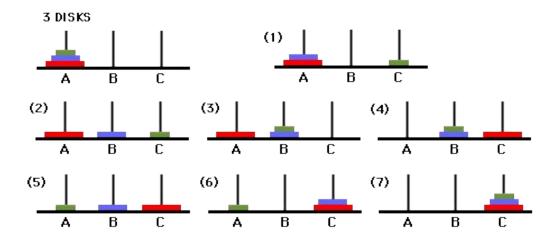
Why do we use recursion?

Why do we use recursion?

- Elegance
 - Allows us to solve problems with very clean and concise code
- Efficiency
 - Allows us to accomplish better runtimes when solving problems
- Dynamic
 - Allows us to solve problems that are hard to solve iteratively

An **elegant** example: Towers of Hanoi

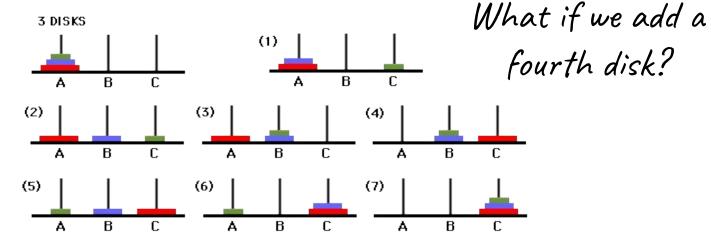
Pseudocode for 3 disks



- (1) Move disk 1 to destination
- (2) Move disk 2 to auxiliary
- (3) Move disk 1 to auxiliary
- (4) Move disk 3 to destination

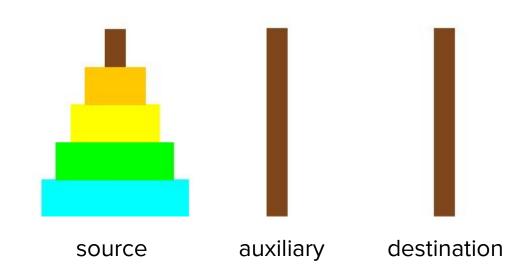
- (5) Move disk 1 to source
- (6) Move disk 2 to destination
- (7) Move disk 1 to destination

Pseudocode for 3 disks

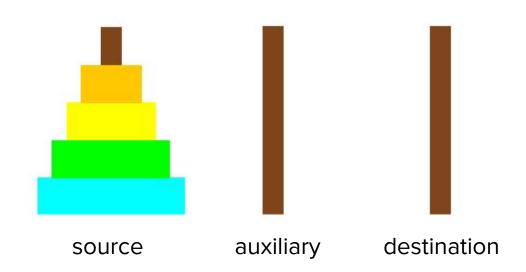


- (1) Move disk 1 to destination
- (2) Move disk 2 to auxiliary
- (3) Move disk 1 to auxiliary
- (4) Move disk 3 to destination

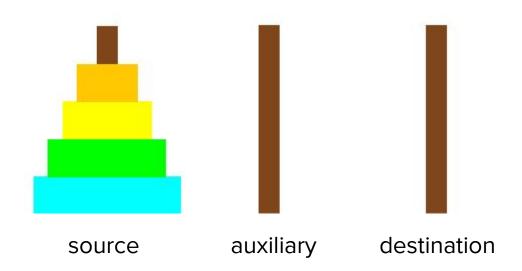
- (5) Move disk 1 to source
- (6) Move disk 2 to destination
- (7) Move disk 1 to destination



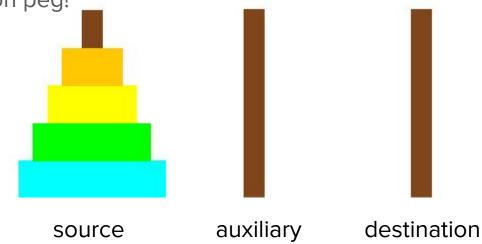
• We want to first move the biggest disk over to the destination peg.



- We want to first move the biggest disk over to the destination peg.
 - We need to get the top three disks out of the way.

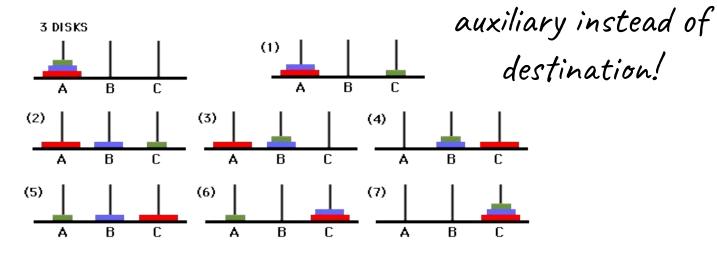


- We want to first move the biggest disk over to the destination peg.
 - We need to get the top three disks out of the way.
 - We already have an algorithm for moving three disks from a source peg to a destination peg!



Pseudocode for 3 disks

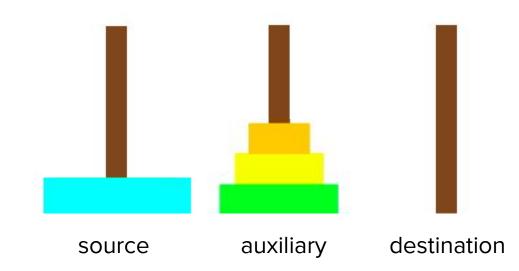
Idea: Move disks to



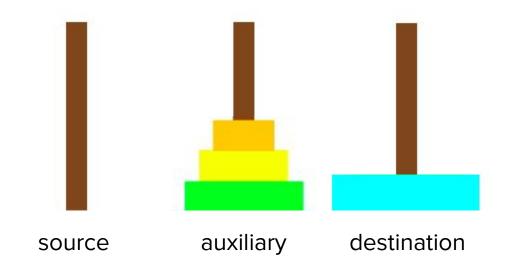
- (1) Move disk 1 to destination
- (2) Move disk 2 to auxiliary
- (3) Move disk 1 to auxiliary
- (4) Move disk 3 to destination

- (5) Move disk 1 to source
- (6) Move disk 2 to destination
- (7) Move disk 1 to destination

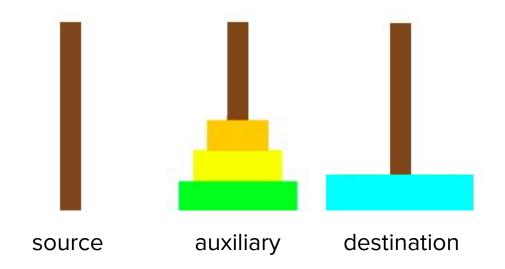
• We want to first move the biggest disk over to the destination peg.



• We want to first move the biggest disk over to the destination peg.

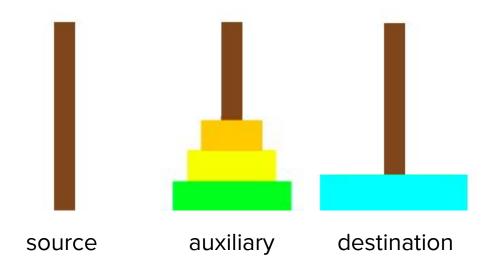


- We want to first move the biggest disk over to the destination peg.
- Now we need to move the stack of three from auxiliary to destination.



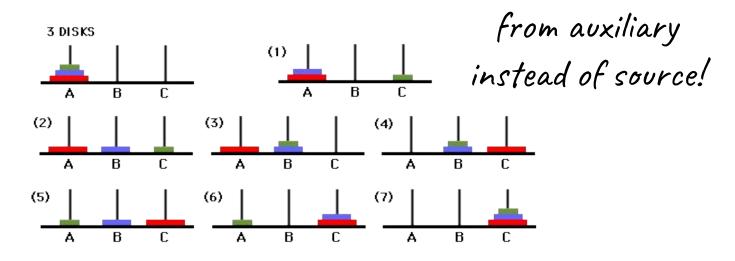
- We want to first move the biggest disk over to the destination peg.
- Now we need to move the stack of three from auxiliary to destination.

Use our existing 3-disk algorithm!



Pseudocode for 3 disks

Idea: Move disks



- (1) Move disk 1 to destination
- (2) Move disk 2 to auxiliary
- (3) Move disk 1 to auxiliary
- (4) Move disk 3 to destination

- (5) Move disk 1 to source
- (6) Move disk 2 to destination
- (7) Move disk 1 to destination

Discuss: How could we solve Towers of Hanoi recursively?

- Assume we have a function called **moveSingleDisk(start, end)** that moves a single disk from a **start** peg to a **end** peg.
- Our function prototype that we're trying to fill in looks like this: findSolution(n, source, dest, aux)

Where **n** is the number of disks we have starting on the **source** peg. The goal is to have all disks end up on the **dest** peg, and you can use the **aux** peg to help.

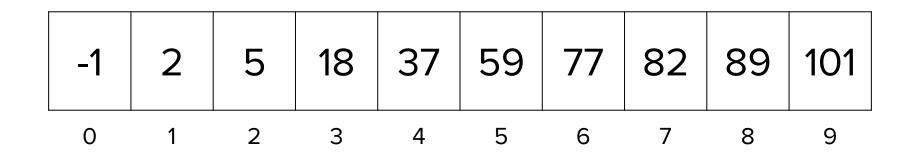
• What are our base and recursive cases for this problem?

Towers of Hanoi solution

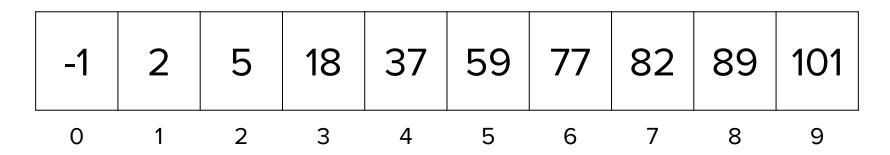
[live coding]

An **efficient** example: Binary Search

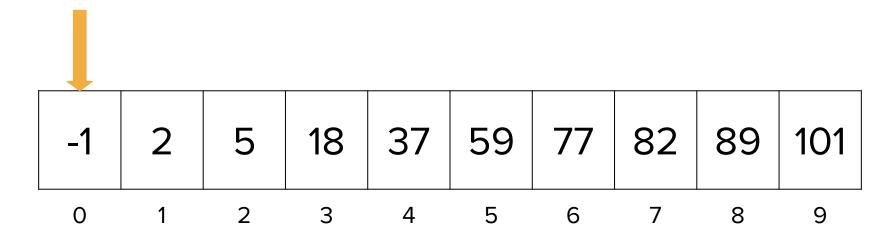
-1	2	5	18	37	59	77	82	89	101
0	1	2	3	4	5	6	7	8	9



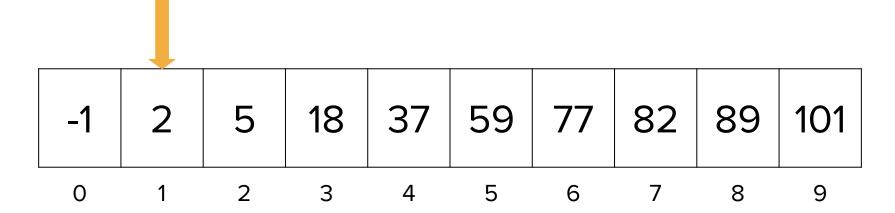
Where is 89?

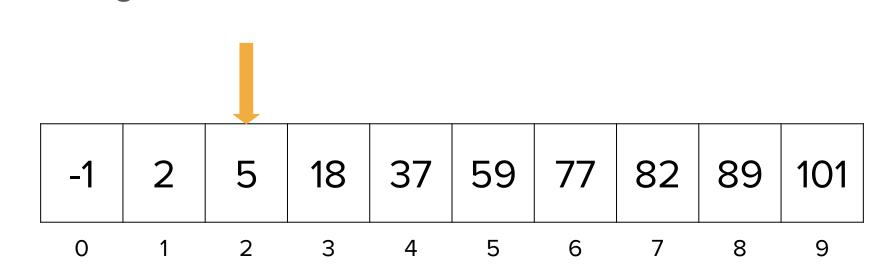


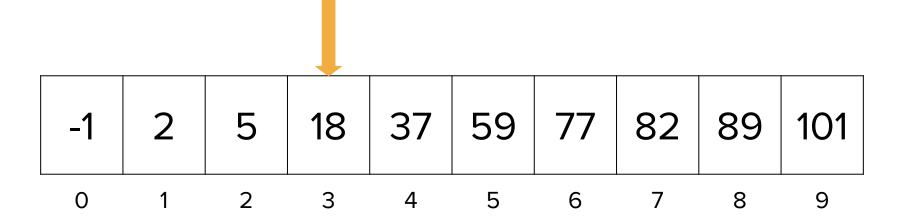
Idea #1: We could just go through each element in order and do a linear search.

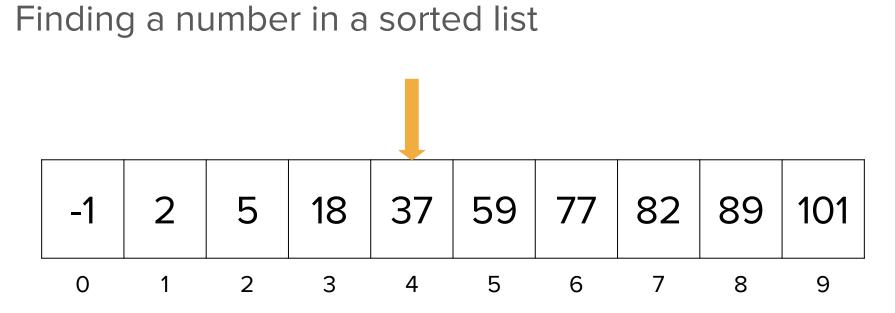


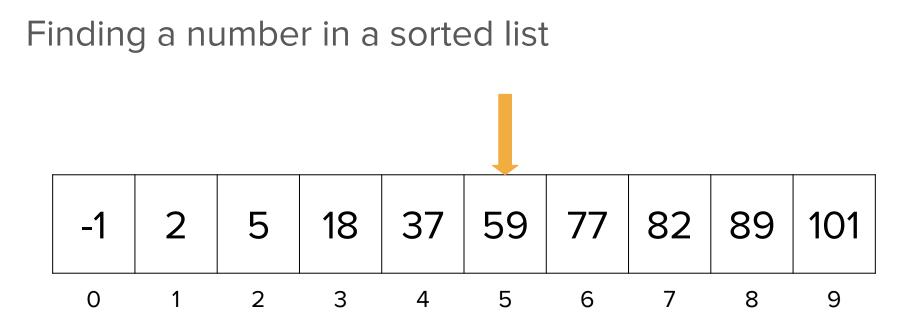
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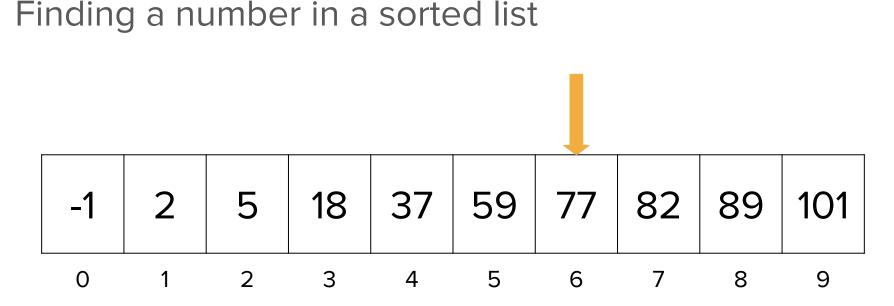


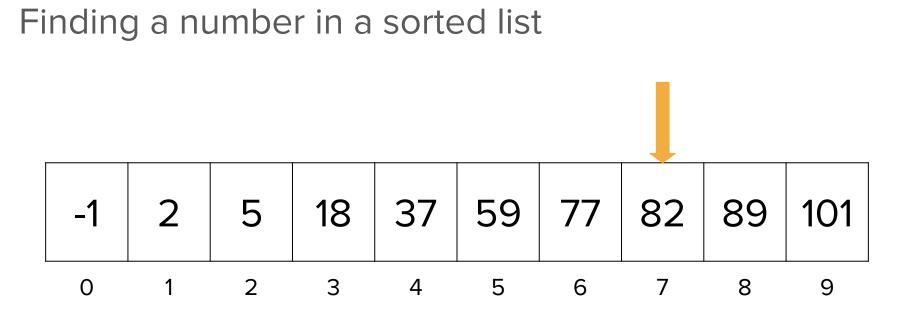


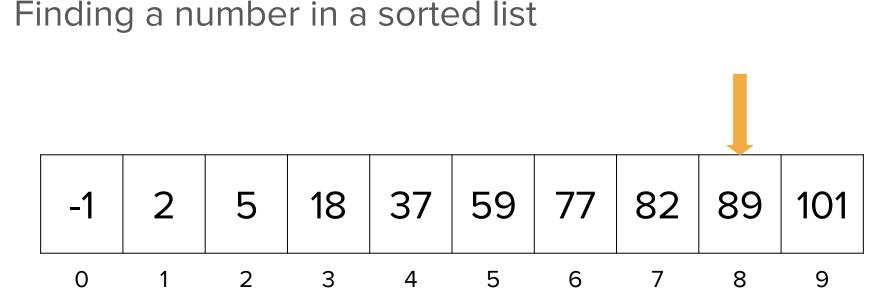


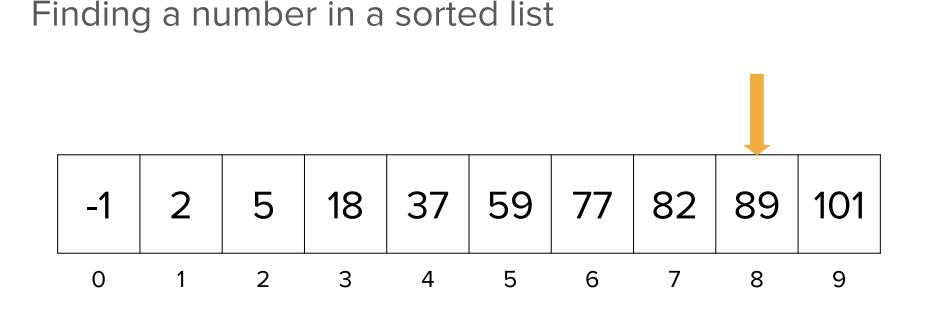




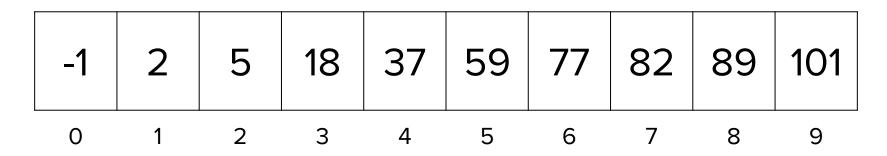








(inear search is **O(n)**



Can we do better? Can we take advantage of the structure of the data?

ADT Big-O Matrix

- Vectors
- .size() 0(1)
- .add() 0(1)
- v[i] O(1)
- o .insert() O(n)
- \circ .remove() O(n)
- \circ .clear() O(n)
- o traversal O(n)
- Grids
- \circ .numRows()/.numCols()
 - 0(1)
- ○g[i][j] O(1)
- \circ .inBounds() O(1)
- \circ traversal O(n²)

- Queues
- .size() O(1)
- 0 .peek() O(1)
- \circ .enqueue() O(1)
- \circ .dequeue() O(1)
- \circ .isEmpty() O(1)
- \circ traversal O(n)
- Stacks
 .size() O(1)
 .peek() O(1)
 .push() O(1)
 .pop() O(1)
 .isEmpty() O(1)
 - \circ traversal O(n)

• Sets

- o .size() O(1)
- o .isEmpty() O(1)
- .add() ???
- .remove() ???
- .contains() ???
- \circ traversal O(n)
- Maps
- .size() 0(1)
- \circ .isEmpty() O(1)
- m[key] ???
- o .contains() ???
- \circ traversal O(n)

ADT Big-O Matrix

- Vectors
- .size() 0(1)
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 - 0(1)
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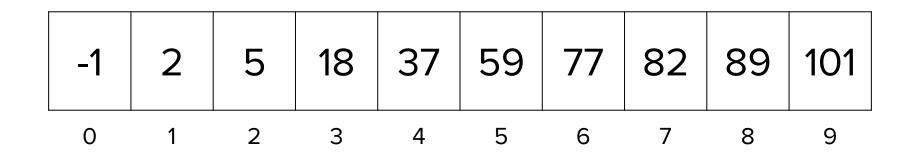
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- \circ traversal O(n)
- Maps
- \circ .size() O(1)
- \circ .isEmpty() O(1)
- o m[key] ???
- o .contains() ???
- \circ traversal O(n)

Note: Sets and Maps don't actually use a sorted list to store information, but the general idea of searching sorted data is similar. Remember how their elements/keys always printed out in alphabetical order?

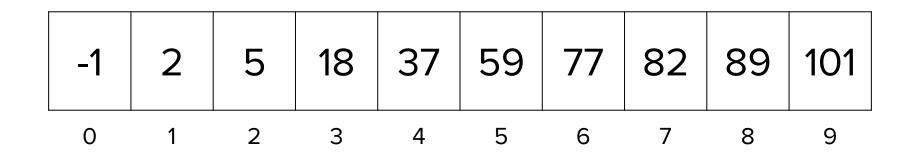
Note: Sets and Maps don't actually use a sorted list to store information, but the general idea of searching sorted data is similar.



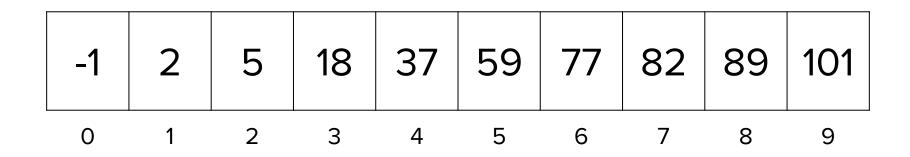
Where is 89?

Idea #2: Binary search

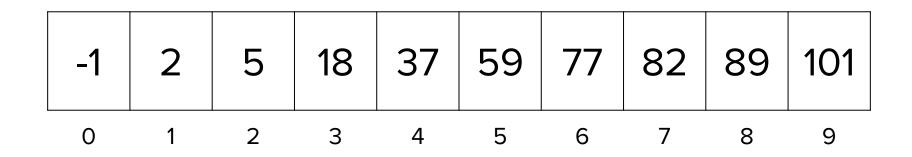
- Eliminate half of the data at each step.
- Algorithm: Check the middle element at (startIndex + endIndex) / 2
 - If the middle element is bigger than your desired value, eliminate the right half of the data and repeat.
 - If the middle element is smaller than your desired value, eliminate the left half of the data and repeat.
 - Otherwise, you've found your element!



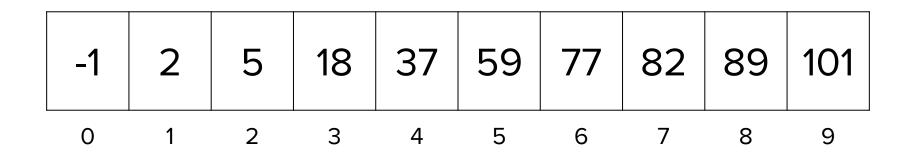
Where is 89?



Start by looking at index: (startIndex + endIndex) / 2

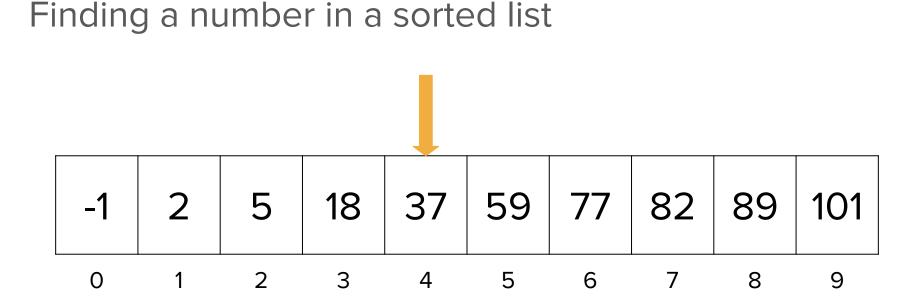


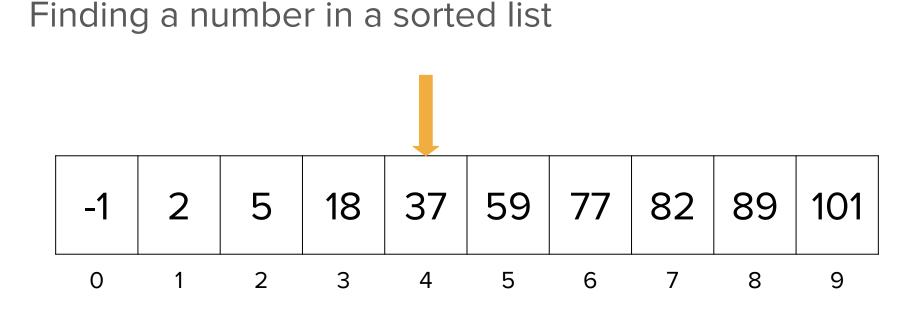
Start by looking at index: (0 + 9) / 2



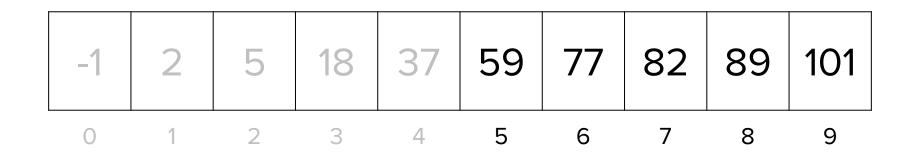
Start by looking at index:

4

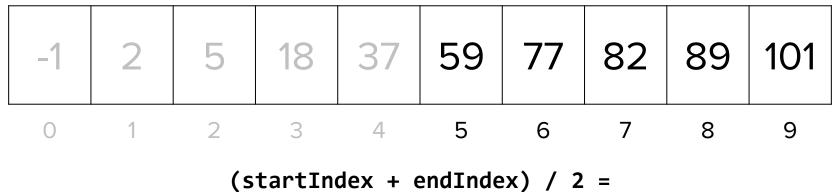


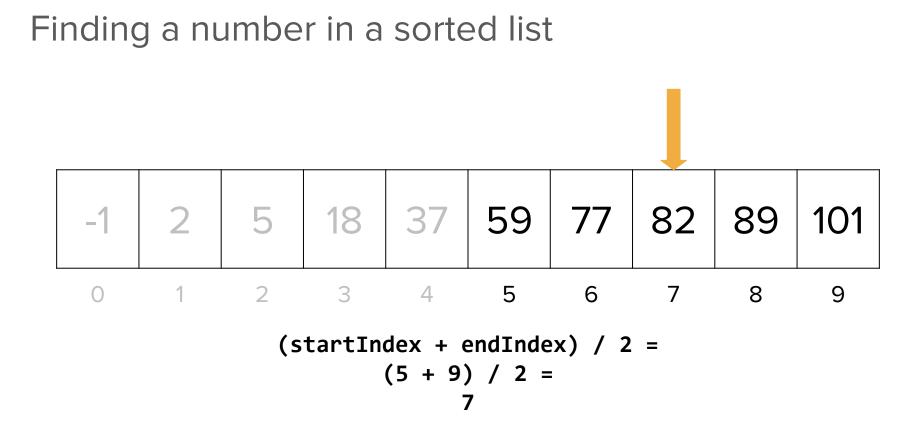


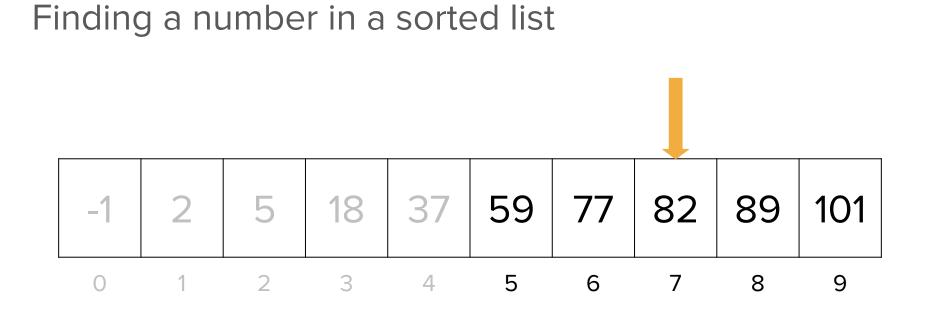
Too small



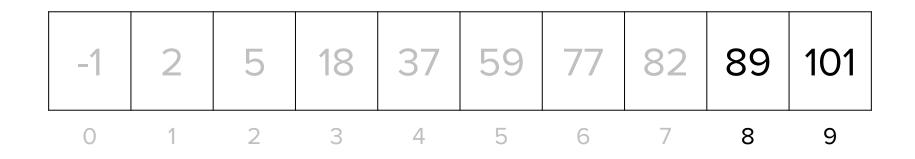
Eliminate left half





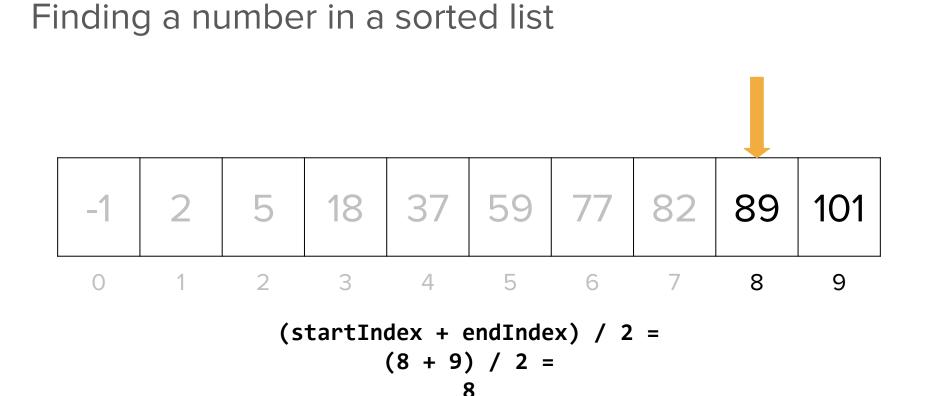


Too small



Eliminate left half







Success!

Defining binary search recursively

- Algorithm: Check the middle element at (startIndex + endIndex) / 2
 - If the middle element is bigger than your desired value, eliminate the right half of the data and repeat.
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Defining binary search recursively

- Algorithm: Check the middle element at (startIndex + endIndex) / 2
 - If the middle element is bigger than your desired value, eliminate the right half of the data and repeat.
 - If the middle element is smaller than your desired value, eliminate the left half of the data and repeat.
 - Otherwise, you've found your element!
- Recursive cases
 - Element at middle is too small + binarySearch(right half of data)
 - Element at middle is too large → binarySearch(left half of data)

Defining binary search recursively

- Algorithm: Check the middle element at (startIndex + endIndex) / 2
 - If the middle element is bigger than your desired value, eliminate the right half of the data and repeat.
 - If the middle element is smaller than your desired value, eliminate the left half of the data and repeat.
 - Otherwise, you've found your element!
- Recursive cases
 - Element at middle is too small + binarySearch(right half of data)
 - Element at middle is too large → binarySearch(left half of data)
- Base cases
 - Element at middle == desired element
 - Desired element is not in your data

Discuss: Read the code for

binarySearch() and identify the base/recursive cases.

Attendance ticket:

https://tinyurl.com/binarySearchCases

Please don't send this link to students who are not here. It's on your honor!

Binary search code

```
int binarySearch(Vector<int>& v, int targetVal, int startIndex, int endIndex) {
   if (startIndex > endIndex) {
       return -1;
   }
   int middleIndex = (startIndex + endIndex) / 2;
   int currentVal = v[middleIndex];
   if (targetVal == currentVal) {
       return middleIndex;
   } else if (targetVal < currentVal) {</pre>
       return binarySearch(v, targetVal, startIndex, middleIndex - 1);
  } else {
       return binarySearch(v, targetVal, middleIndex + 1, endIndex);
```

```
int binarySearch(Vector<int>& v, int targetVal, int startIndex, int endIndex) {
  if (startIndex > endIndex) {
       return -1;
   int middleIndex = (startIndex + endIndex) / 2;
                                                                 Kase cases
   int currentVal = v[middleIndex];
  if (targetVal == currentVal) {
       return middleIndex;
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```

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int binarySearch(Vector<int>& v, int targetVal, int startIndex, int endIndex) {
   if (startIndex > endIndex) {
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   }
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                                                               Recursive cases
   int currentVal = v[middleIndex];
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```

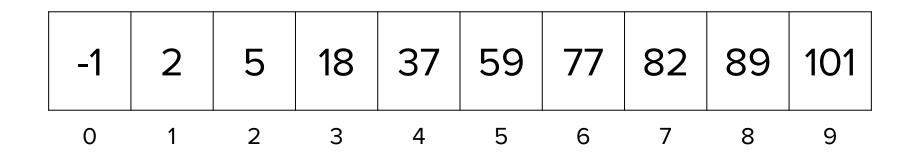
```
int binarySearch(Vector<int>& v, int targetVal, int startIndex, int endIndex) {
   if (startIndex > endIndex) {
      return -1;
                                                     We don't want the user to have
   }
                                                    to pass these in, but we need
  int middleIndex = (startIndex + endIndex) / 2;
  int currentVal = v[middleIndex];
                                                     them to update our search range
  if (targetVal == currentVal) {
      return middleIndex;
  } else if (targetVal < currentVal) {</pre>
       return binarySearch(v, targetVal, startIndex, middleIndex - 1);
  } else {
      return binarySearch(v, targetVal, middleIndex + 1, endIndex);
```

int binarySearch(Vector<int>& v, int targetVal) {
 return binarySearchHelper(v, targetVal, 0, v.size() - 1);
}

int binarySearchHelper(Vector<int>& v, int targetVal, int startIndex, int endIndex) {
 ...
}

Use a **recursive helper function** for the extra parameters! (binarySearchHelper would have the same code as the previous slide)

Finding a number in a sorted list



What's the runtime?

Binary search runtime

• For data of size **N**, it eliminates half until 1 element remains:

• How many divisions does it take?

Binary search runtime

- For data of size **N**, it eliminates half until 1 element remains.
- Think of it from the other direction:
 - How many times do I have to multiply by 2 to reach N?

• Call this number of multiplications **x**:

 $2^{\times} = N$ x = $\log_2 N$

Binary search runtime

- For data of size **N**, it eliminates half until 1 element remains.
- Think of it from the other direction:
 - How many times do I have to multiply by 2 to reach N?

• Call this number of multiplications **x**:

 $2^{\times} = N$ x = $\log_2 N$

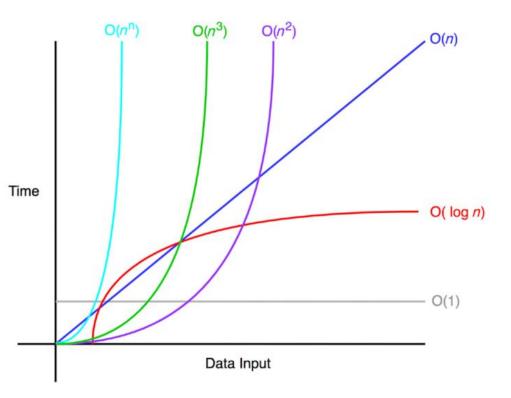
• Binary search has logarithmic Big-O: **O(log N)**

binarysearch.cpp

[demo]

Logarithmic runtime

- Better than linear
- A common runtime when you're able to "divide and conquer" in your algorithm, like with binary search



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- \circ .isEmpty() O(1)
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- Stacks
- .size() O(1)
- .peek() 0(1)
- \circ .push() O(1)
- \circ .pop() O(1)
- \circ .isEmpty() O(1)
- \circ traversal O(n)

• Sets

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- o .add() ???
 o .remove() ???
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- \circ .size() O(1)
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ADT Big-O Matrix

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 .pop() O(1)
 .isEmpty() O(1)
 - \circ traversal O(n)

- Sets
- .size() O(1)
- \circ .isEmpty() O(1)
- \circ .add() O(log(n))
- \circ .remove() O(log(n))
- \circ .contains() O(log(n))
- \circ traversal O(n)
- Maps
- \circ .size() O(1)
- \circ .isEmpty() O(1)
- \circ m[key] O(log(n))
- \circ .contains() O(log(n))
- o traversal O(n)

Announcements

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- Assignment 2 is due **tonight at 11:59pm**, and Assignment 1 revisions are due **Sunday, July 10, at 11:59pm PDT**.
- The midterm will be next Monday, July 11 during lecture.
 - There will be a midterm review session tomorrow around noon. Watch Ed for a finalized location and time!
 - Today's content will only show up in the form of extra credit.
- Assignment 3, which is all about recursion, will be released after the midterm.
- Jenny will be rescheduling her individual OH next week.

A **dynamic** example: Exploring many possibilities

- So far, we've seen problems that could be solved iteratively or recursively.
 - Depending on the problem, you could make the argument that one of the approaches was stylistically preferable or easier to understand.
 - But both got the job done!

- So far, we've seen problems that could be solved iteratively or recursively.
- However, there is a whole class of problems that are very difficult, or nearly impossible, to solve with an iterative approach.
 - These problems have the goal of exploring many different possibilities or solutions.
 - Because iteration is inherently linear (and not dynamic), it is usually used to build up a single solution without exploring many possible alternatives.
 - Recursion allows us to explore many potential possibilities at once via the power of branching that comes when we have multiple recursive calls.

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- However, there is a whole class of problems that are very difficult, or nearly impossible, to solve with an iterative approach.
- To solve these problems and generate many possible solutions, we will have to learn a new problem-solving technique called **recursive backtracking**.
 - The key steps in recursive backtracking are that you make a choice about how to generate a solution, you use recursion to explore that choice, and then you might make a different choice and repeat the process.
 - This paradigm is called "choose-explore-unchoose."

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Let's do an example!



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HH HT

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- Let's say that you're playing a game that involves flipping a coin a certain number of times in a row. Your success in the game depends on the exact sequence of "heads" and "tails" that you get.
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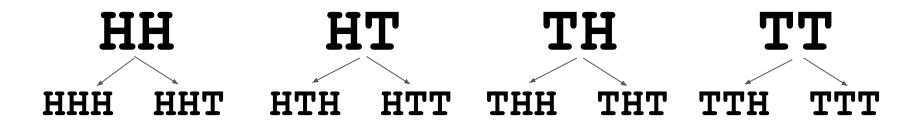
How do we know that we got all the possibilities? How do we avoid repeats?



- Let's say that you're playing a game that involves flipping a coin a certain number of times in a row. Your success in the game depends on the exact sequence of "heads" and "tails" that you get.
- Can we observe any patterns between the outcomes in the game with 2 flips and the outcomes in the game with 3 flips?



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- Can we observe any patterns between the outcomes in the game with 2 flips and the outcomes in the game with 3 flips?
 - There is a self-similar tree-like relationship between the possible outcomes of 2 flips and the possible outcomes of 3 flips.
 - The branching in the tree comes from deciding whether or not to add an H or a T to the existing sequence.
 - Together these branching sequences of decisions define a **decision tree.**

Why decision trees?

• We've seen trees in the context of fractals (drawing pretty shapes), but now we're going to apply meaningful context to these trees.

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- In problems where we care about many possible outcomes, decision trees can help illustrate the recursive backtracking strategy for generating outcomes. They model the options we can choose from and the "decisions" we make along the way.

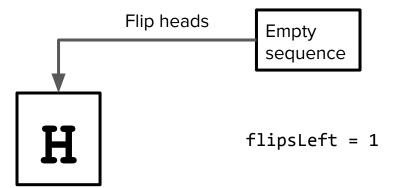
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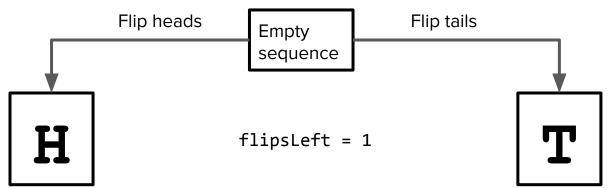
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- In problems where we care about many possible outcomes, decision trees can help illustrate the recursive backtracking strategy for generating outcomes. They model the options we can choose from and the "decisions" we make along the way.
- Let's create a visualization of the possible space of outcomes that could result from N coin flips. Each decision is one flip, and the options for a single flip are either heads or tails.

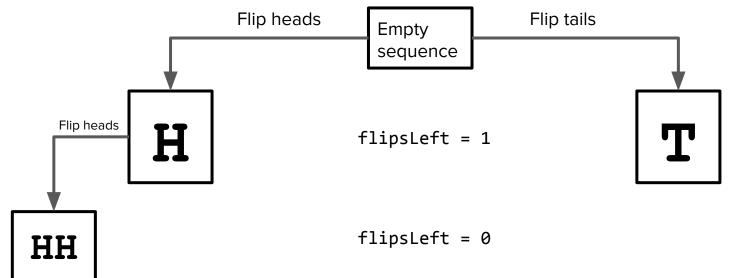
Example decision tree for N=2

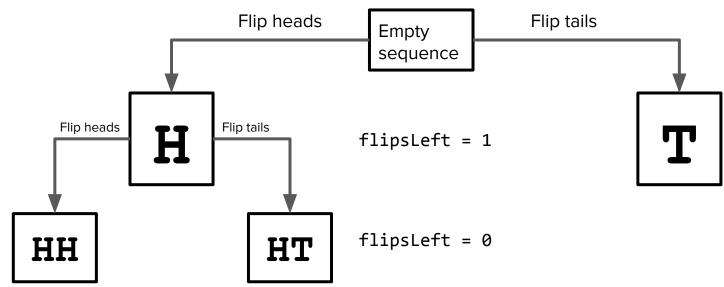
Empty sequence

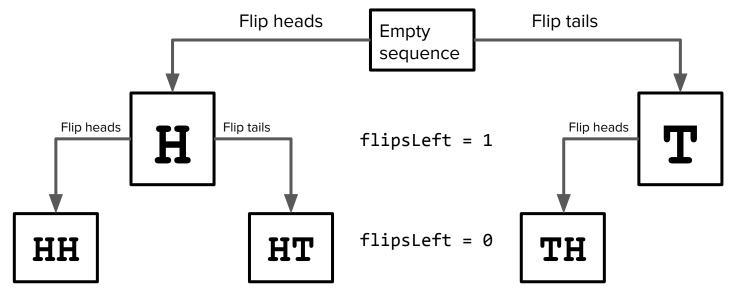
Example decision tree for N=2

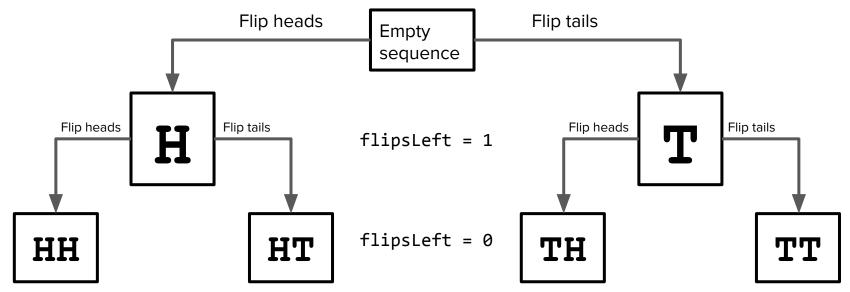


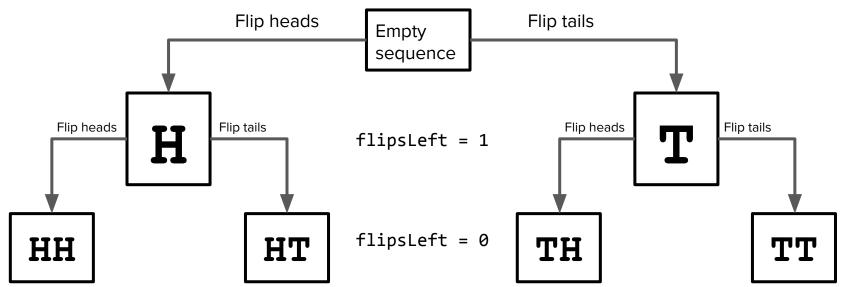




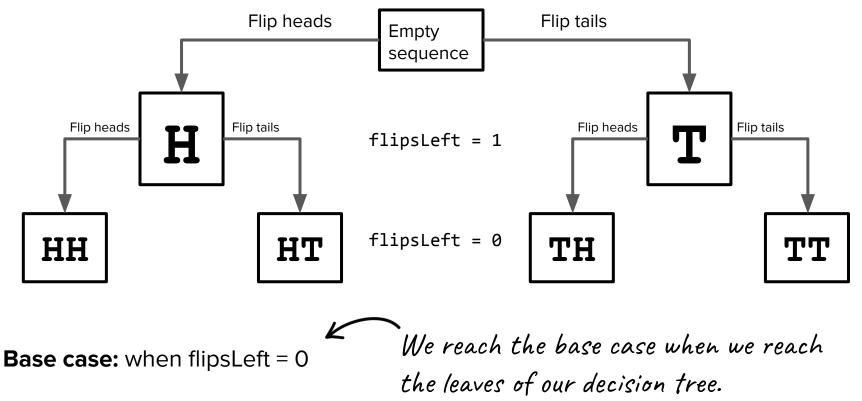


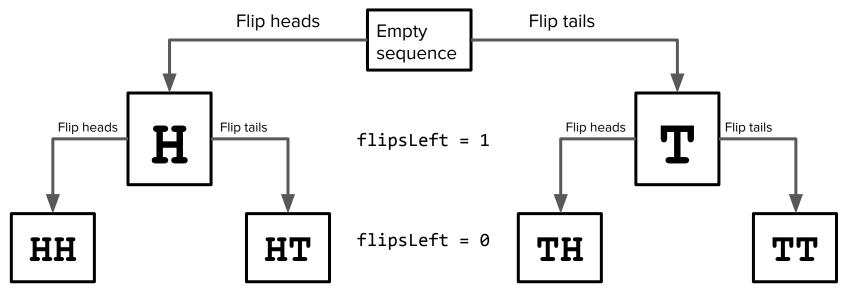






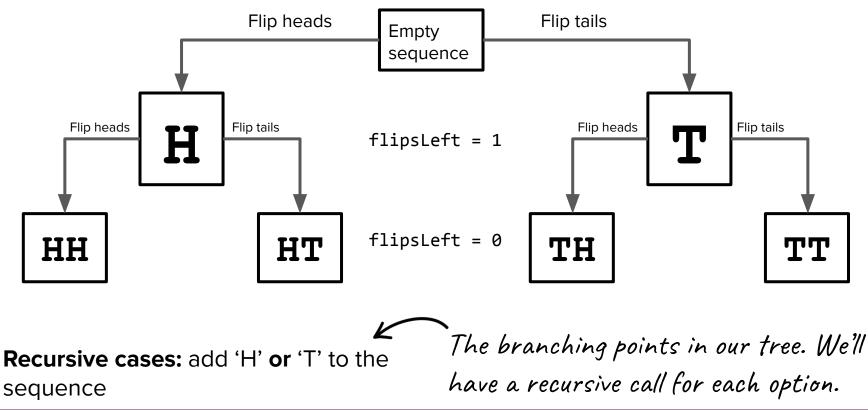
Base case: when flipsLeft = 0





Recursive cases: add 'H' or 'T' to the

sequence



Let's code it!

void generateSequences(int length);

Takeaways: recursive backtracking + decision trees

• Unlike our previous recursion paradigm in which a solution gets built up as recursive calls return, in backtracking our final outputs occur at our base cases (leaves) and get built up as we go down the decision tree.

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Takeaways: recursive backtracking + decision trees

- Unlike our previous recursion paradigm in which a solution gets built up as recursive calls return, in backtracking our final outputs occur at our base cases (leaves) and get built up as we go down the decision tree.
- The height of the tree corresponds to the number of decisions we have to make. The width at each decision point corresponds to the number of options.
- To exhaustively explore the entire search space, we must **try every possible** option for every possible decision. That can be a lot of paths to walk!
 - For the previous example, we have to make N decisions, with 2 choices for each decision. This means 2^N total possible outcomes!



Why do we use recursion?

- Elegance
 - Allows us to solve problems with very clean and concise code
- Efficiency
 - Allows us to accomplish better runtimes when solving problems
- Dynamic
 - Allows us to solve problems that are hard to solve iteratively

Two types of recursion

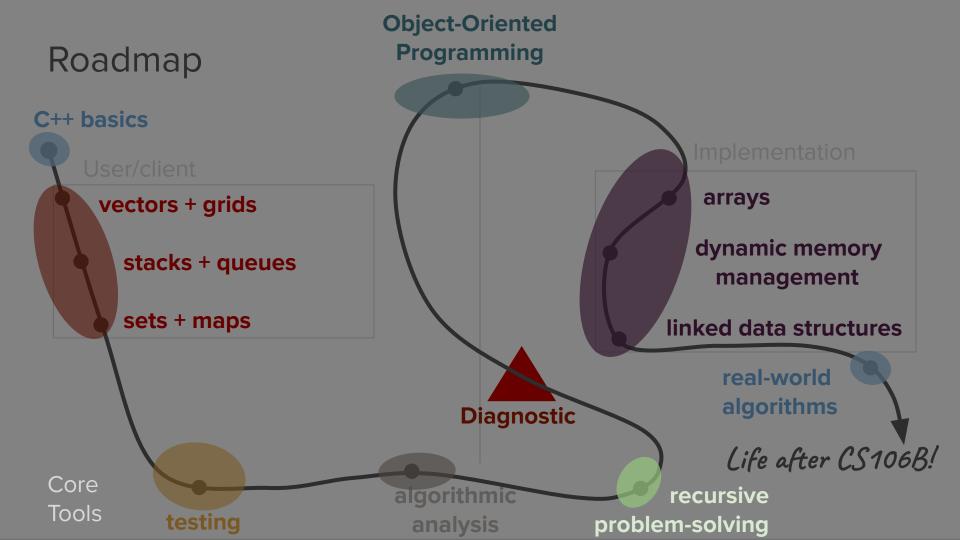
Basic recursion

- One repeated task that builds up a solution as you come back up the call stack
- The final base case defines the initial seed of the solution and each call contributes a little bit to the solution
- Initial call to recursive function produces final solution

Backtracking recursion

- Build up many possible solutions through multiple recursive calls at each step
- Seed the initial recursive call with an "empty" solution
- At each base case, you have a potential solution

What's next?



Recursive Backtracking

