

Programming Abstractions

CS106B

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Topics:

- **Map** implemented as a Binary Search Tree (BST)
 - › Starting with a dream: binary search in a linked list?
 - › How our dream provided the inspiration for the BST
 - › BST insert
 - › Big-O analysis of BST
 - › BST balance issues
- Traversals
 - › Pre-order, In-order, Post-order, Breadth-first
- Applications of Traversals

BST and Heap Facts (cheat sheet)

Heap (**Priority Queue**)

- **Structure:** must be “complete”
- **Order:** parent priority must be \leq both children
 - › This is for min-heap, opposite is true for max-heap
 - › No rule about whether left child is $>$ or $<$ the right child
- **Big-O:** guaranteed $\log(n)$ enqueue and dequeue
- **Operations:** always add to end of array and then “bubble up”; for dequeue do “trickle down”

BST (**Map**)

- **Structure:** any valid binary tree
- **Order:** $\text{leftchild.key} < \text{self.key} < \text{rightchild.key}$
 - › No duplicate keys
 - › Because it's a Map, values go along for the ride w/keys
- **Big-O:** $\log(n)$ if balanced, but might not be balanced, then $O(n)$
- **Operations:** recursively repeat: start at root and go left if $\text{key} < \text{root}$, and go right if $\text{key} > \text{root}$

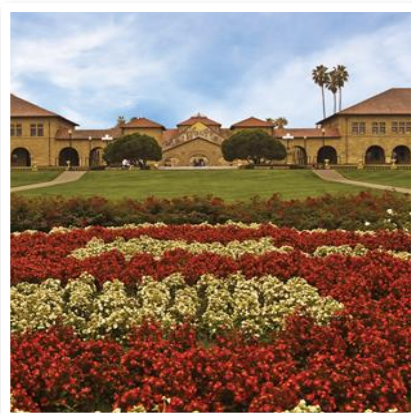
BST Balance Strategies

WE NEED TO BALANCE THE
TREE TO KEEP PERFORMANCE
 $O(\log N)$ INSTEAD OF $O(N)$



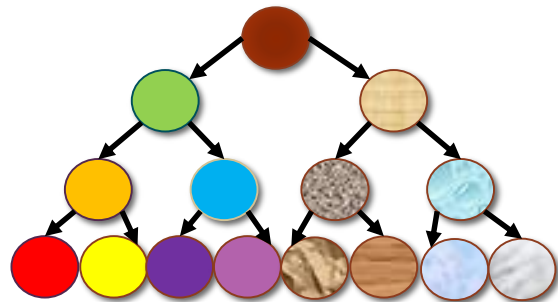
Step 1: understanding validity and equivalence in BSTs

AVL ROTATIONS: A KEY TO
OUR REBALANCING
ALGORITHMS



AVL rotations: BST-order-preserving movement of nodes

- Here is a Binary Search Tree whose keys I'm not going to show you
 - › (but the nodes have colors/textures so you can tell them apart)
- Let's pause and think about what we know must be true

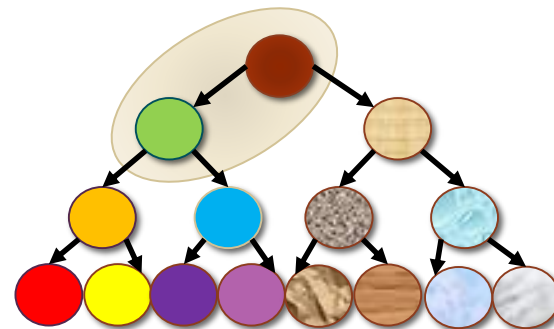


AVL rotations

put() algorithm

If key > node's key
Go right! (if doesn't exist—place here)
If key < node's key
Go left! (if doesn't exist—place here)
If key is equal, update value here.

- Here is a Binary Search Tree whose keys I'm not going to show you
 - › (but the nodes have colors/textures so you can tell them apart)
- Let's pause and think about what we know must be true
 1. Cardinal's key > green's key

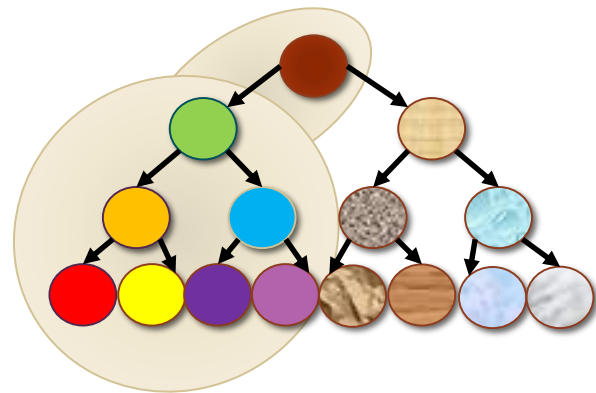


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 2. Cardinal's key > all 7 keys to its left!

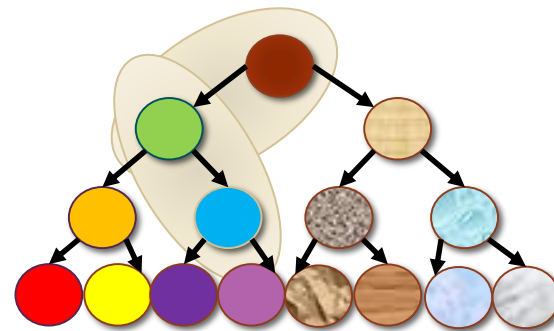


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- Let's pause and think about what we know must be true
 1. Cardinal's key > green's key
 2. Cardinal's key > all 7 keys to its left!
 3. Green's key < blue's key < cardinal's key

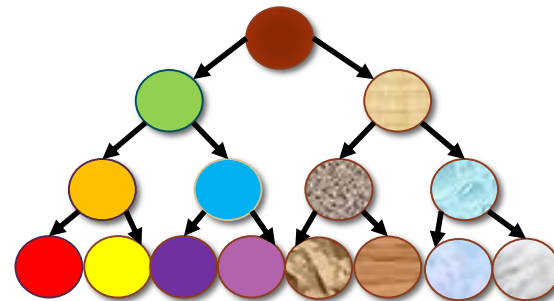


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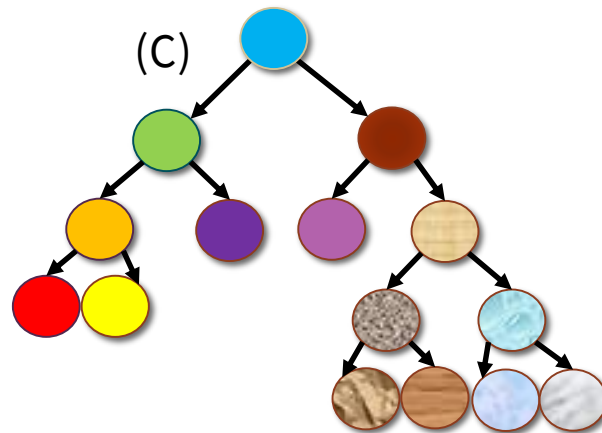
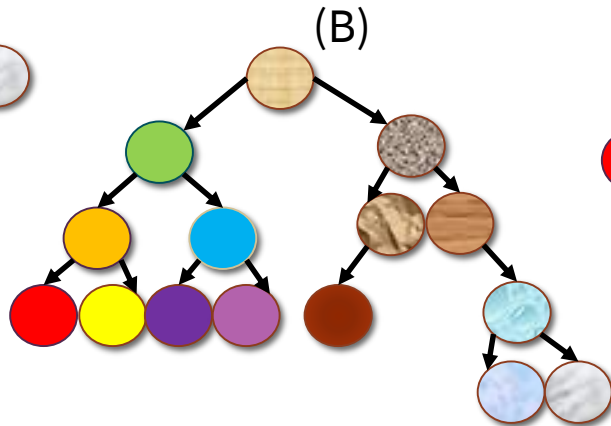
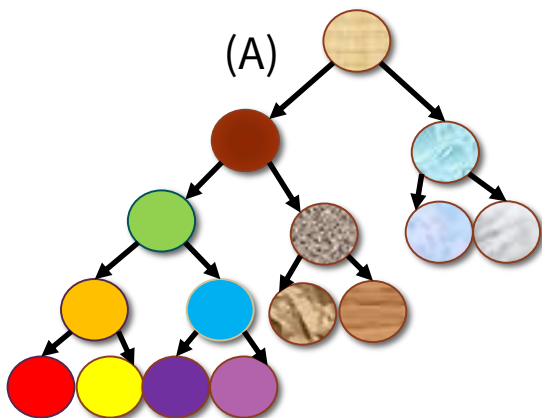
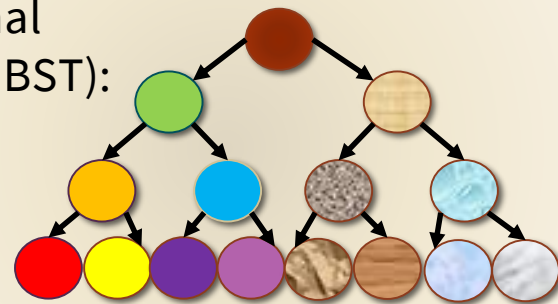
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 - (but the nodes have colors/textures so you can tell them apart)
- Let's pause and think about what we know must be true
 - Cardinal's key > green's key
 - Cardinal's key > all 7 keys to its left!
 - Green's key < blue's key < cardinal's key
- Those are just a few examples of the kind of reasoning you'll want to use for this exercise...



AVL rotations

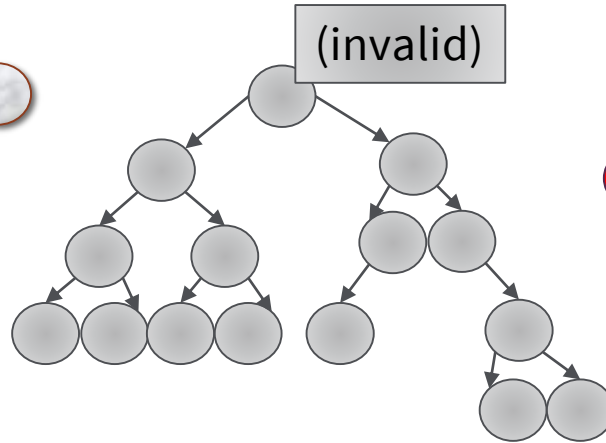
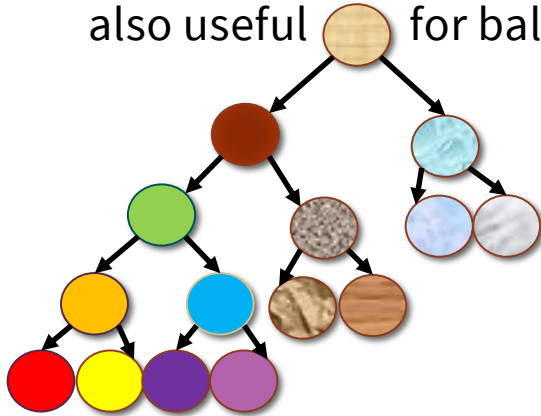
- **Your turn:** Which of the trees below are still in BST order? (*list all that apply*)

Original
(valid BST):

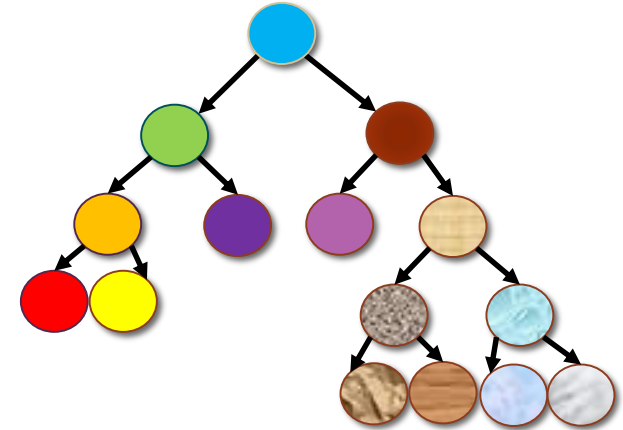
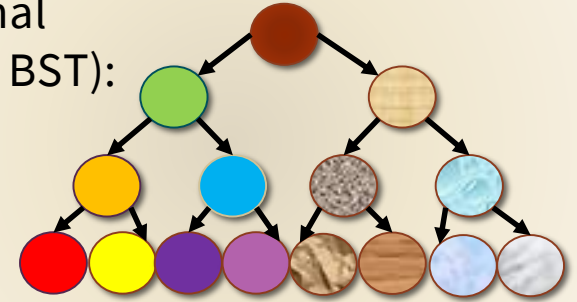


AVL rotations

- 2/3 are actual AVL rotations!
- In this case, our BST started balanced, so the rotations made the *less* balanced. But also useful for balancing.

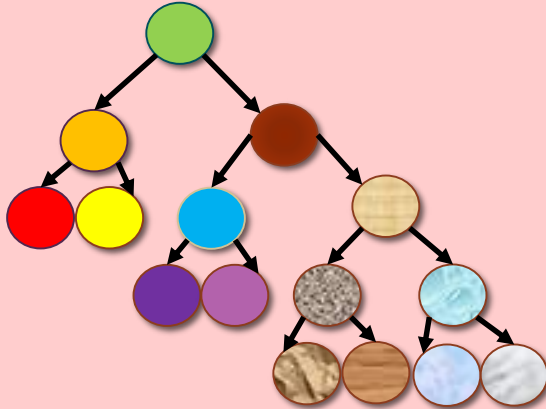


Original
(valid BST):

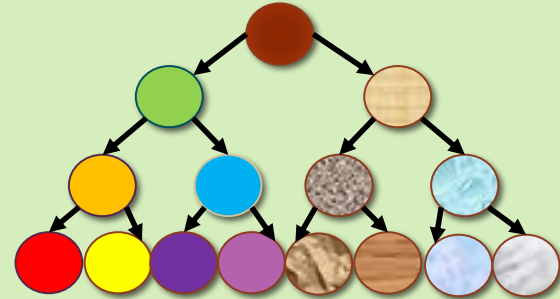


Left-Left AVL Rotation

Original (valid but unbalanced BST):



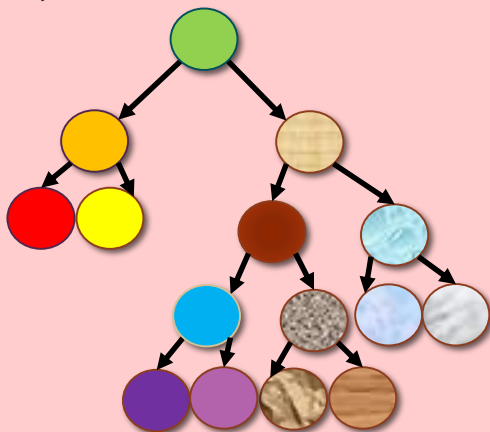
Left-Left rotation (restores balance):



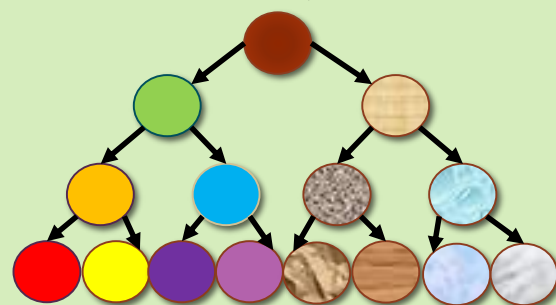
- Right-Right is just the mirror image

Right-Left AVL Rotation

Original (valid but unbalanced BST):



Right-Left rotation (restores balance):

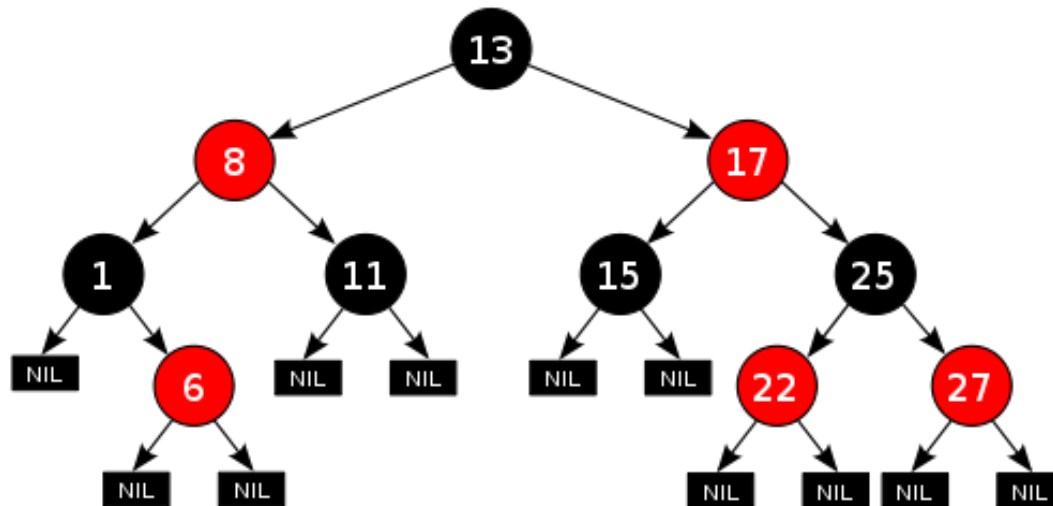


- Left-Right is just the mirror image

A few BST balance strategies

- AVL tree
 - › Uses AVL rotations to guarantee balance
- Red-Black tree
 - › Uses AVL rotations to guarantee balance is off by no more than a constant factor (longest path from root to leaf can be at most 2x the shortest path)
- Treap
 - › Each node has *two* keys and a value, one is BST key, one is a min-heap key, *both kinds of trees' order properties are maintained (!!!)*
 - › Insert nodes according to BST keys and BST order
 - › Then use AVL rotations to “bubble up” the newly inserted node as needed to restore the min-heap order property on the min-heap keys
 - › What could be cooler than that, amirite? ❤️ 😊 ❤️ 😊

Red-Black trees



Every simple path from a given node to any of its descendant leaves contains the same number of black nodes.

- (This is what guarantees “close” to balance)

Other fun types of BST

Splay tree

- Rather than only worrying about balance, Splay Tree dynamically readjusts node placement based on **how often users search for an item**. Most commonly-searched items rotate towards the root, saving time.
 - › Example: if Google did this, “Bieber” would be near the root, and “splay tree” would be further down by the leaves

B-Tree

- Like BST, but a node can have many children, not just two
- More branching means an even “flatter” (shorter height) tree
- Used for huge databases

Tree Traversals!

THESE ARE FOR ANY BINARY
TREES, BUT WE OFTEN DO
THEM ON BSTS

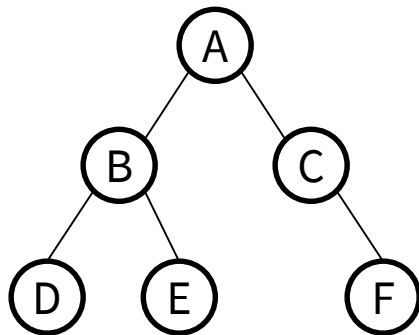


Your Turn: What does this print?

(assume we call traverse on the root node to start)

```
void traverse(Node* node) {  
    if (node != nullptr) {  
        cout << node->key << " ";  
        traverse(node->left);  
        traverse(node->right);  
    }  
}
```

- A. ABCDEF
- B. ABDECF
- C. DBEFCA
- D. DEBFCA
- E. Other/none/more

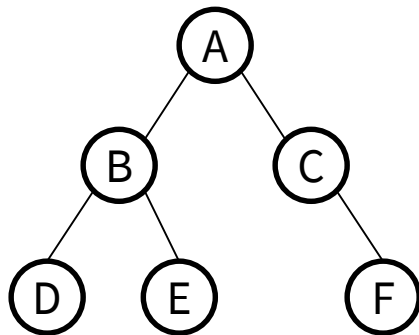


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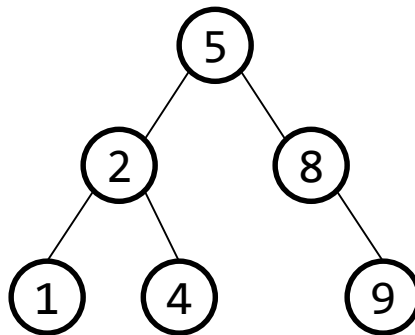


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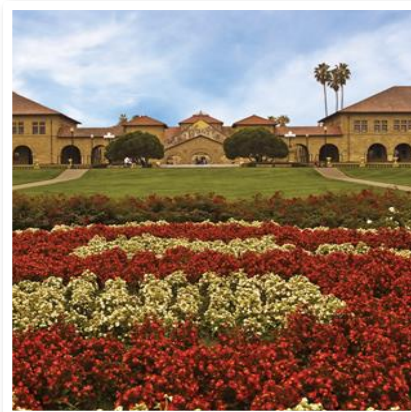
```
void traverse(Node* node) {  
    if (node != nullptr) {  
        traverse(node->left);  
        cout << node->key << " ";  
        traverse(node->right);  
    }  
}
```

- A. 1 2 4 5 8 9
- B. 1 4 2 9 8 5
- C. 5 2 1 4 8 9
- D. 5 2 8 1 4 9
- E. Other/none/more



Applications of Tree Traversals

BEAUTIFUL LITTLE THINGS
FROM AN
ALGORITHMS/THEORY
STANDPOINT, BUT THEY HAVE
A PRACTICAL SIDE TOO!



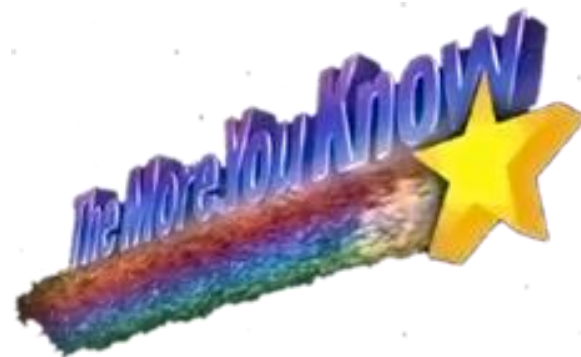
Traversals a very commonly-used tool in your CS toolkit

```
void traverse(Node* node) {  
    if (node != NULL) {  
        traverse(node->left);  
        // "do something"  
        traverse(node->right);  
    }  
}
```

- Customize and move around the “do something,” and that’s the basis for dozens of algorithms and applications

Stanford Library Map

- Remember how when you iterate over the Stanford library Map you get the keys in sorted order?
 - › (we used this for the word occurrence counting code example in class)
- Now you know why it can do that in $O(N)$ time!
 - › **Stanford library Map is a BST**
 - › **In-order traversal on BST!**

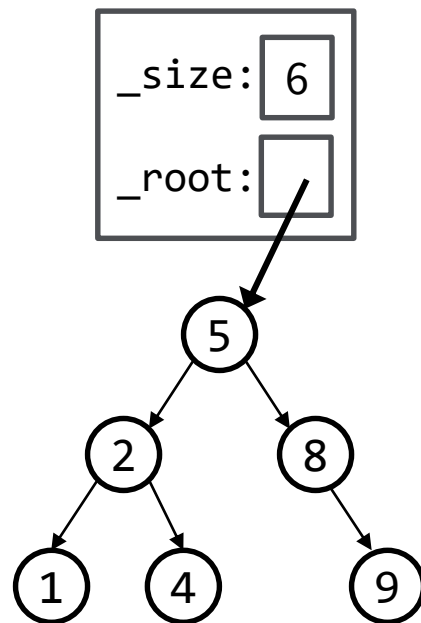


Your Turn: Applications of the traversals

- You are writing the **destructor** for a BST class. Given a pointer to the root, it needs to free each node. Which traversal would form the foundation of your destructor algorithm?

- A. Pre-order
- B. In-order
- C. Post-order
- D. Something else

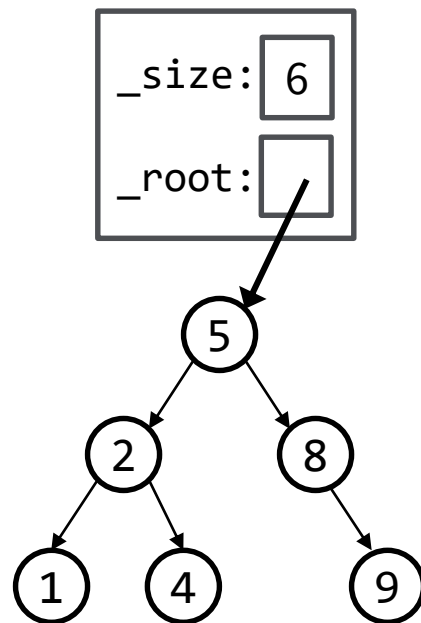
```
void bstDestructorRecursiveHelper(Node *node) {  
    if (node != nullptr) {  
        delete node; // pre-order  
        bstDestructorRecursiveHelper(node->left);  
        delete node; // in-order  
        bstDestructorRecursiveHelper(node->right);  
        delete node; // post-order  
    }  
}
```



Applications of the traversals

- You are writing the **destructor** for a BST class. Given a pointer to the root, it needs to free each node. Which traversal would form the foundation of your destructor algorithm?
 - › If we do pre-order, we dereference the node pointer after delete—bad!!
 - › Same problem if we do in-order
 - › Post-order avoids this problem

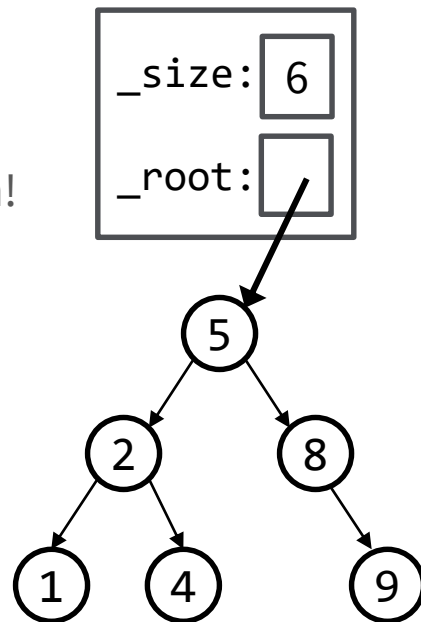
```
void bstDestructorRecursiveHelper(Node *node) {  
    if (node != nullptr) {  
        delete node; // pre-order  
        bstDestructorRecursiveHelper(node->left);  
        bstDestructorRecursiveHelper(node->right);  
    }  
}
```



Applications of the traversals

- You are writing the **destructor** for a BST class. Given a pointer to the root, it needs to free each node. Which traversal would form the foundation of your destructor algorithm?
 - › **Post-order is a good choice**, because we need to use the node's fields to recurse
 - › Don't want to delete fields before we use them!

```
void bstDestructorRecursiveHelper(Node *node) {  
    if (node != nullptr) {  
        bstDestructorRecursiveHelper(node->left);  
        bstDestructorRecursiveHelper(node->right);  
        delete node; // post-order  
    }  
}
```

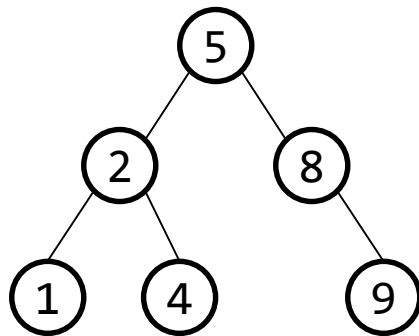


Breadth-First Tree Traversal

A somewhat different kind of traversal

How can we get code to print top-to-bottom, left-to-right order?

```
void traverse(Node* node) {  
    if (node != nullptr) {  
        ?? cout << node->key << " ";  
        traverse(node->left);  
        traverse(node->right);  
    }  
}
```



You can't do it by using this code and moving around the cout—we already tried moving the cout to all 3 possible places and it didn't print breadth-first order

- You can but you use a **queue** instead of recursion
- **“Breadth-first”** search you've seen on previous assignments
- *Again we see this key theme of BFS (queue) vs DFS (stack/recursion)!*