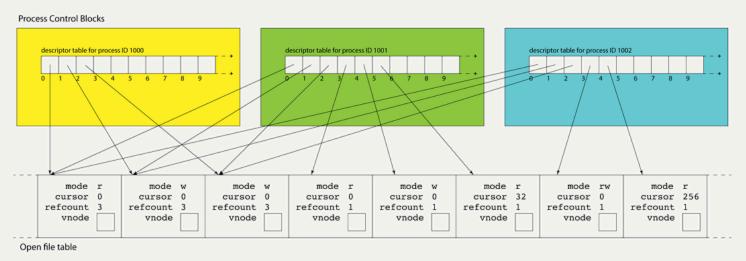
Lecture 05: Understanding execvp

Principles of Computer Systems
Spring 2019
Stanford University
Computer Science Department
Lecturer: Chris Gregg



Lecture 05: Question from yesterday: where is the cursor stored for a file?

Diagram from last lecture:



- In the last lecture, the question came up about multiple processes pointing to the open file table, and what happens to the cursor.
 - Every time there is an open () system call, a new entry is generated for the open file table.
 - If a process forks, both the parent and child share a pointer to the same open file entry, and therefore their cursors will be the same (i.e., if one reads a line, the other will read the next line). This is also true with the dup and dup2 system calls, which we will learn about (briefly) in lab and in more detail next week.

- Your second assignment of the quarter is to write a program in C (not C++) that can read from a 1970s-era Unix version 6 filesystem.
 - The test data you are reading from are literally bit-for-bit representations of a Unix v6 disk.
 - You will leverage all of the information covered in the file system lecture from Lecture 3 to write the program, and for more detailed information, see Section 2.5 of the Salzer and Kaashoek textbook.
- You will primarily be writing code in four different files (and we suggest you tackle them in this order):
 - inode.c
 - file.c
 - directory.c
 - pathname.c
- Because the program is in C, you will have to rely on arrays of structs, and low-level data manipulation, as you don't have access to any C++ standard template library classes.

• The basic idea of the assignment is to write code that will be able to locate and read files in the file system. You will, for example, be using a function we've written for you to read sectors from the disk image:

```
/**
 * Reads the specified sector (e.g. block) from the disk. Returns the number of bytes read,
 * or -1 on error.
 */
int diskimg_readsector(int fd, int sectorNum, void *buf);
```

- Sometimes, **buf** will be an array of **inode**s, sometimes it will be a buffer that holds actual file data. In any case, the function will *always* read **DISKIMG_SECTOR_SIZE** number of bytes, and it is your job to determine the relevance of those bytes.
- It is critical that you carefully read through the header files for this assignment (they are actually relatively short). There are key constants (e.g., ROOT_INUMBER, struct direntv6, etc.) that are defined for you to use, and reading them will give you an idea about where to start for parts of the assignment.

One function that can be tricky to write is the following:

```
/**
 * Gets the location of the specified file block of the specified inode.
 * Returns the disk block number on success, -1 on error.
 */
int inode_indexlookup(struct unixfilesystem *fs, struct inode *inp, int blockNum);
```

- The unixfilesystem struct is defined and initialized for you.
- The inode struct will be populated already
- The **blockNum** is the number, in linear order, of the block you are looking for in a particular file.
- For example:
 - Let's say the **inode** indicates that the file it refers to has a size of 180,000 bytes. And let's assume that **blockNum** is **302**.
 - This means that we are looking for the 302nd block of data in the file referred to by inode.
 - Recall that blocks are 512 bytes long.
 - How would you find the block index (i.e., sector index) of the 302nd block in the file?

- For example:
 - Let's say the inode indicates that the file it refers to has a size of 180,000 bytes. And let's assume that blockNum is 302.
 - This means that we are looking for the 302nd block of data in the file referred to by inode.
 - Recall that blocks are 512 bytes long
 - How would you find the block index (i.e., sector index) of the 302nd block in the file?
- 1. Determine if the file is large or not
- 2. If it isn't large, you know you only have direct addressing.
- 3. If it is large (this file is), then you have indirect addressing.
- 4. The 302nd block is going to fall into the *second* indirect block, because each block has 256 block numbers (each block number is an **unsigned short**, or a **uint16_t**).
- 5. You, therefore, need to use **diskimg_readsector** to read the sector listed in the 2nd block number (which is in the **inode** struct), then extract the (302 % 256)th short from that block, and return the value you find there.
- 6. If the block number you were looking for happened to fall into the 8th inode block, then you would have a further level of indirection for a doubly-indirect lookup.

- For the assignment, you will also have to search through directories to locate a particular file.
 - You do not have to follow symbolic links (you can ignore them completely)
 - You do need to consider directories that are longer than 32 files long (because they will take up more than two blocks on the disk), but this is not a special case! You are building generic functions to read files, so you can rely on them to do the work for you, even for directory file reading.
 - Don't forget that a filename is limited to 14 characters, and if it is exactly 14 characters, there is *not* a trailing '\0' at the end of the name (this to conserve that one byte of data!) So...you might want to be careful about using **strcmp** for files (maybe use **strncmp**, instead?)
- This is a relatively advanced assignment, with a lot of moving parts.
- Start early!
- Come to office hours or ask Piazza questions.
- Remember: CAs won't look at your code, so you must formulate your questions to be conceptual enough that they can be answered.



- Third example: Synchronizing between parent and child using waitpid
 - waitpid can be used to temporarily block one process until a child process exits.

```
pid_t waitpid(pid_t pid, int *status, int options);
```

- The first argument specifies the wait set, which for the moment is just the id of the child process that needs to complete before waitpid can return.
- The second argument supplies the address of an integer where termination information can be placed (or we can pass in **NULL** if we don't care for the information).
- The third argument is a collection of bitwise-or'ed flags we'll study later. For the time being, we'll just go with 0 as the required parameter value, which means that waitpid should only return when a process in the supplied wait set exits.
- The return value is the pid of the child that exited, or -1 if waitpid was called and there were no child processes in the supplied wait set.

- Third example: Synchronizing between parent and child using waitpid
 - Consider the following program, which is more representative of how fork really gets used in practice (full program, with error checking, is right here):

```
int main(int argc, char *argv[]) {
  printf("Before.\n");
  pid_t pid = fork();
  printf("After.\n");
  if (pid == 0) {
    printf("I am the child, and the parent will wait up for me.\n");
    return 110; // contrived exit status
} else {
    int status;
    waitpid(pid, &status, 0)
    if (WIFEXITED(status)) {
        printf("Child exited with status %d.\n", WEXITSTATUS(status));
    } else {
        printf("Child terminated abnormally.\n");
    }
    return 0;
}
```



- Third example: Synchronizing between parent and child using waitpid
 - The output is the same every single time the above program is executed.

```
myth60$ ./separate
Before.
After.
After.
I am the child, and the parent will wait up for me.
Child exited with status 110.
myth60$
```

- The implementation directs the child process one way, the parent another.
- The parent process correctly waits for the child to complete using waitpid.
- The parent lifts child exit information out of the waitpid call, and uses the WIFEXITED macro to examine some high-order bits of its argument to confirm the process exited normally, and it uses the WEXITSTATUS macro to extract the lower eight bits of its argument to produce the child return value (which we can see is, and should be, 110)
- The waitpid call also donates child process-oriented resources back to the system

- Synchronizing between parent and child using waitpid
 - This next example is more of a brain teaser, but it illustrates just how deep a clone the process created by **fork** really is (full program, with more error checking, is right here).

- The code emulates a coin flip to seduce exactly one of the two processes to sleep for a second, which is more than enough time for the child process to finish.
- The parent waits for the child to exit before it allows itself to exit. It's akin to the parent not being able to fall asleep until he/she knows the child has, and it's emblematic of the types of synchronization directives we'll be seeing a lot of this quarter.
- The final printf gets executed twice. The child is always the first to execute it, because the parent is blocked in its waitpid call until the child executes everything.

- Spawning and synchronizing with multiple child processes
 - A parent can call fork multiple times, provided it reaps the child processes (via waitpid) once they exit. If we want to reap processes as they exit without concern for the order they were spawned, then this does the trick (full program checking right here):

```
int main(int argc, char *argv[]) {
  for (size_t i = 0; i < 8; i++) {
    if (fork() == 0) exit(110 + i);
  }
  while (true) {
    int status;
    pid_t pid = waitpid(-1, &status, 0);
    if (pid == -1) { assert(errno == ECHILD); break; }
    if (WIFEXITED(status)) {
        printf("Child %d exited: status %d\n", pid, WEXITSTATUS(status));
    } else {
        printf("Child %d exited abnormally.\n", pid);
    }
    return 0;
}</pre>
```



- Spawning and synchronizing with multiple child processes
 - Note we feed a -1 as the first argument to waitpid. That -1 states we want to hear about any child as it exits, and pids are returned in the order their processes finish.
 - Eventually, all children exit and waitpid correctly returns -1 to signal there are no more processes under the parent's jurisdiction.
 - When waitpid returns -1, it sets a global variable called errno to the constant ECHILD to signal waitpid returned -1 because all child processes have terminated. That's the "error" we want.

```
myth60$ ./reap-as-they-exit
Child 1209 exited: status 110
Child 1210 exited: status 111
Child 1211 exited: status 112
Child 1216 exited: status 117
Child 1212 exited: status 113
Child 1213 exited: status 114
Child 1214 exited: status 115
Child 1215 exited: status 116
myth60$
```

```
myth60$ ./reap-as-they-exit
Child 1453 exited: status 115
Child 1449 exited: status 111
Child 1448 exited: status 110
Child 1450 exited: status 112
Child 1451 exited: status 113
Child 1452 exited: status 114
Child 1455 exited: status 117
Child 1454 exited: status 116
myth60$
```



- Spawning and synchronizing with multiple child processes
 - We can do the same thing we did in the first program, but monitor and reap the child processes in the order they are forked.
 - Check out the abbreviated program below (full program with error checking right here):



- Spawning and synchronizing with multiple child processes
 - This version spawns and reaps processes in some first-spawned-first-reaped manner.
 - The child processes aren't required to exit in FSFR order.
 - In theory, the first child thread could finish last, and the reap loop could be held up on its very first iteration until the first child really is done. But the process zombies—yes, that's what they're called—are reaped in the order they were forked.
 - Below is a sample run of the **reap-in-fork-order** executable. The pids change between runs, but even those are guaranteed to be published in increasing order.

```
myth60$ ./reap-as-they-exit
Child with pid 4689 accounted for (return status of 110).
Child with pid 4690 accounted for (return status of 111).
Child with pid 4691 accounted for (return status of 112).
Child with pid 4692 accounted for (return status of 113).
Child with pid 4693 accounted for (return status of 114).
Child with pid 4694 accounted for (return status of 115).
Child with pid 4695 accounted for (return status of 116).
Child with pid 4696 accounted for (return status of 117).
myth60$
```



- It is possible to have a **fork**ed process simply do other work that you program. In other words, you have two processes, each doing work concurrently, and you've programmed the code for both processes. These are the examples we've seen so far.
- However, this is actually *not* the most common use for **fork**. Most often, a programmer wants to run a *completely separate program*, but wants to maintain control over the program, and may also (quite frequently) want to send data to the program through **stdin** and capture the output of the program through its **stdout**.
- This is what your shell does whenever you launch a program. The shell is a program, and when you type a command, it executes that program, and waits for it to end.

```
2. cgregg@myth61: ~/cs110/spring-2019 (ssh)

cgregg@myth61:~/cs110/spring-2019$ ls

assignments lecture-examples live-lecture tmp

cgregg@myth61:~/cs110/spring-2019$ which ls

/bin/ls

cgregg@myth61:~/cs110/spring-2019$
```

- In the screenshot to the left, the terminal shell is a program, and after you type Is, the shell runs the ls program, located at /bin/ls.
- The shell waits for **1s** to finish, and then reprompts for another command.



- Enter the execvp system call!
 - **execvp** effectively reboots a process to run a different program from scratch. Here is the prototype:

```
int execvp(const char *path, char *argv[]);
```

- path identifies the name of the executable to be invoked.
- **argv** is the argument vector that should be funneled through to the new executable's **main** function.
- For the purposes of CS110, path and argv[0] end up being the same exact string.
- If **execvp** fails to cannibalize the process and install a new executable image within it, it returns -1 to express failure.
- If execvp succeeds, it never returns in the calling process. #deep
- execvp has many variants (execle, execlp, and so forth. Type man execvp to see all of them). We generally rely on execvp in this course.

- First example using **execup**? An implementation **mysystem** to emulate the behavior of the libc function called **system**.
 - Here we present our own implementation of the mysystem function, which executes the supplied command as if we typed it out in the terminal ourselves, ultimately returning once the surrogate command has finished.
 - If the execution of command exits normally (either via an exit system call, or via a normal return statement from main), then our mysystem implementation should return that exact same exit value.
 - If the execution exits abnormally (e.g. it segfaults), then we'll assume it aborted because some signal was ignored, and we'll return that negative of that signal number (e.g. -11 for SIGSEGV).



• Here's the implementation, with minimal error checking (the full version is right here):

```
1 static int mysystem(const char *command) {
2    pid_t pid = fork();
3    if (pid == 0) {
4        char *arguments[] = {"/bin/sh", "-c", (char *) command, NULL};
5        execvp(arguments[0], arguments);
6        printf("Failed to invoke /bin/sh to execute the supplied command.");
7        exit(0);
8    }
9    int status;
10    waitpid(pid, &status, 0);
11    return WIFEXITED(status) ? WEXITSTATUS(status) : -WTERMSIG(status);
12 }
```

- Instead of calling a subroutine to perform some task and waiting for it to complete,
 mysystem spawns a child process to perform some task and waits for it to complete.
- We don't bother checking the return value of **execvp**, because we know that if it returns at all, it returns a -1. If that happens, we need to handle the error and make sure the child process terminates, via an exposed **exit(0)** call.
- Why not call **execvp** inside parent and forgo the child process altogether? Because **execvp** would consume the calling process, and that's not what we want.

• Here's a test harness that we can run to confirm our mysystem implementation is working as

expected:

```
1 static const size_t kMaxLine = 2048;
2 int main(int argc, char *argv[]) {
3    char command[kMaxLine];
4    while (true) {
5        printf("> ");
6        fgets(command, kMaxLine, stdin);
7        if (feof(stdin)) break;
8        command[strlen(command) - 1] = '\0'; // overwrite '\n'
9        printf("retcode = %d\n", mysystem(command));
10    }
11
12    printf("\n");
13    return 0;
14 }
```

- **fgets** is a somewhat overflow-safe variant on **scanf** that knows to read everything up through and including the newline character.
 - The newline character is retained, so we need to chomp that newline off before calling mysystem.

