CS111, Lecture 16
Scheduling and Dispatching

Optional reading:
Operating Systems: Principles and Practice (2nd Edition): Chapter 7 up through Section 7.2
Announcements

• Congratulations on finishing the midterm!
• Assign4 YEAH session tonight 7:30-8:30PM in Gates 403
• No section this week
Topic 3: Multithreading - How can we have concurrency within a single process? How does the operating system support this?
Multithreading - How can we have concurrency within a single process? **How does the operating system support this?**

Why is answering this question important?

- Allows us to see how threads are represented and the fairness challenges for who gets to run next / for how long (next time)
- Shows us what the mechanism looks like for switching between running threads (today and next time)
- Allows us to understand how locks and condition variables are implemented (next week)

**assign5:** implement your own version of `thread`, `mutex` and `condition_variable`!
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Learning Goals

• Learn about how the operating system keeps track of threads and processes
• Understand the general mechanisms for switching between threads and when switches occur
Plan For Today

• **Overview**: Scheduling and Dispatching
• Process and Thread State
• Running a Thread
• Switching Between Threads
• Tracking All Threads
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Scheduling And Dispatching

• So far, we have learned about how user programs can create new processes and spawn threads in those processes
• But how does the operating system manage all of this internally? When we spawn a new thread or create a new process, what happens?

Key questions we will answer:
• How does the operating system track info for threads and processes?
• How does the operating system run a thread and switch between threads?
• How does the operating system decide which thread to run next?
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- **Overview**: Scheduling and Dispatching
- **Process and Thread State**
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  - Tracking All Threads
Key question #1: How does the operating system track info about threads and processes?

The OS maintains a (private) process control block for each process - a set of relevant information about its execution. Lives as long as the process does.

- Information about memory used by this process
- File descriptor table
- Info about threads in this process
- Other misc. accounting and info
Key question #1: How does the operating system track info about threads and processes?

The OS maintains a (private) **process control block** for each process - a set of relevant information about its execution. Lives as long as the process does.

- Information about memory used by this process
- **File descriptor table**
- Info about threads in this process
- Other misc. accounting and info
The file descriptor table is an array of info about open files/resources for this process. **Key idea: a file descriptor is just an index into the file descriptor table!**

- An entry in the file descriptor table is really a *pointer* to an entry in another table, the **open file table**.
- The **open file table** is one array of information about open files/resources across all processes.
An entry in the file descriptor table is really a *pointer* to an entry in another table, the **open file table**.

- An open file table entry stores changing info like "cursor" (how far into file are we?)
- Multiple file descriptor entries (even across processes!) can point to the same open file table entry. This is how parents and children share file descriptors.
An entry in the file descriptor table is really a *pointer* to an entry in another table, the **open file table**.

- This also clarifies what **dup2** does; it copies a pointer to a new file descriptor table index.

- All of these data structures are private to the operating system. They are layered on top of the filesystem data itself.
Key question #1: How does the operating system track info about threads and processes?

The OS maintains a (private) **process control block ("PCB")** for each process - a set of relevant information about its execution. Lives as long as the process does.

- Information about memory used by this process
- File descriptor table
- *Info about threads in this process*
- Other misc. accounting and info
• Every process has 1 main thread and can spawn additional threads.
• Threads are the “unit of execution” – processes aren’t executed, threads are.

Threads share info in PCB plus also have their own private state in the PCB, e.g. thread’s stack info

• Recall: there is a register called %rsp that points to the top of the stack (“stack pointer”). Non-running threads must save their %rsp somewhere for later.
Aside: x86-64 Assembly Refresher

• A register is a 64-bit space inside a processor core.
• Each core has its own set of registers.
• Registers are like “scratch paper” for the processor. Data being calculated or manipulated is moved to registers first. Operations are performed on registers.
• Registers also hold parameters and return values for functions.
• Some registers have special responsibilities – e.g. %rsp always stores the address of the current top of the stack.
• When a thread is being kicked off, it must remember its %rsp value so it knows where its stack is the next time it runs. (we’ll see how it remembers other register values later)
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Key Question #2: How does the operating system run a thread and switch between threads?

- A processor has 1 or more “cores” - Each core contains a complete CPU capable of executing a thread
- Typically have more threads than cores, but most may not need to run at any given point in time (why? They are waiting for something)
- When the OS wants to run a thread, it loads its state (e.g. %rsp and other registers) into a core, and starts or resumes it
- **Problem:** once we run a thread, the OS is not running anymore! (e.g. 1 core) How does it regain control?
There are several ways control can switch back to the OS:

1. “Traps” (events that require OS attention):
   1. System calls (like `read` or `waitpid`)
   2. Errors (illegal instruction, address violation, etc.)
   3. Page fault (accessing memory that must be loaded in) – more later...

2. “Interrupts” (events occurring outside current thread):
   1. Character typed at keyboard
   2. Completion of disk operation
   3. Timer – to make sure OS eventually regains control

At this point, OS could then decide to run a different thread.
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- **Switching Between Threads**
- Tracking All Threads
Switching Between Threads

When the OS regains control, how does it switch to run another thread?

The **dispatcher** is OS code that runs on each core that switches between threads

- Not a thread – code that is invoked to perform the dispatching function
- Lets a thread run, then switches to another thread, etc.
- **Context switch** – changing the thread currently running to another thread. We must save the current thread state and load in the new thread state.
- Context switches are funky – like running a function that, as part of its execution, switches to a *completely different function in a completely different thread*!!
Context switch: how do we switch from thread A3 to thread B1?
Context Switching

**Step 1:** push all registers besides stack register onto the thread’s stack.
Step 2: save the stack register into the thread’s state space.


**Step 3:** load B1’s saved stack register from its thread state space.
Step 4: pop B1’s other registers from its stack space.
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How does the OS track/remember all user threads on the system?

**Key idea:** at any given time, a thread is in one of three states:

1. **Running**
2. **Blocked** – waiting for an event (disk I/O, network connection, etc.)
3. **Ready** – able to run, but waiting for CPU time
Thread States

Threads can either be **running**, **blocked** or **ready**.

- When a thread is created, it starts **ready**.
- When it is run, it goes from **ready** -> **running**
- Maybe it reaches a point where it can’t run anymore (e.g. reading a file from disk). It goes from **running** -> **blocked**
- When the event it’s waiting for has happened, it goes from **blocked** -> **ready** or **blocked** -> **running** (if it can get a core immediately)
- Sometimes we might want to interrupt a running thread to run another thread. It goes from **running** -> **ready**
Thread States

Running

Ready

Blocked
Why can’t a thread go from ready to blocked?

Because in order to become blocked, it must run code.
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**Lecture 16 takeaway:** The OS keeps a process control block for each process and uses it to context switch between threads. To switch we must freeze frame the existing register values and load in new ones.

**Next time:** more about scheduling and dispatching