

# CS111, Lecture 17

## Scheduling and Dispatching, Continued

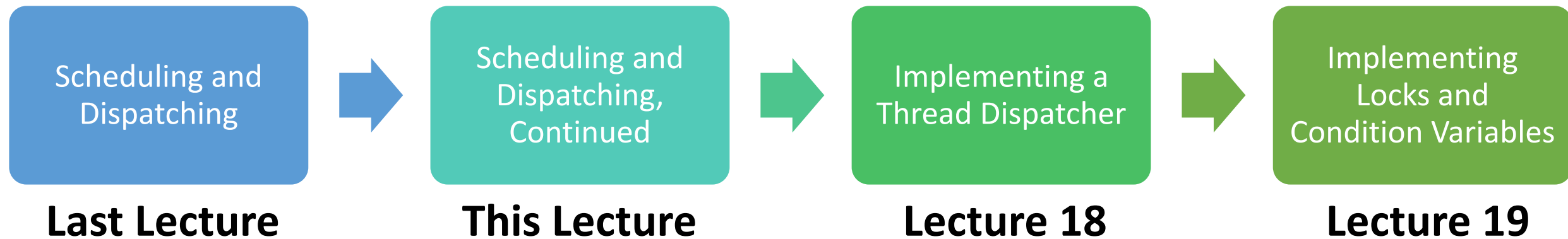


masks recommended

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Based on slides and notes created by John Ousterhout, Jerry Cain, Chris Gregg, and others.

# **Topic 3: Multithreading** - How can we have concurrency within a single process? How does the operating system support this?

# CS111 Topic 3: Multithreading, Part 2



**assign5:** implement your own version of **thread**, **mutex** and **condition\_variable**!

# Learning Goals

- Understand the general mechanisms for switching between threads
- Explore the tradeoffs in deciding which threads get to run and for how long

# Plan For Today

- **Recap:** Process Control Blocks and Threads
- **Demo:** Context Switch
- **Recap:** Thread States
- Scheduling Threads

```
cp -r /afs/ir/class/cs111/lecture-code/lect17 .
```

# Plan For Today

- **Recap: Process Control Blocks and Threads**
- Demo: Context Switch
- Recap: Thread States
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# Process and Thread State

**Key question:** How does OS track info about threads and processes?

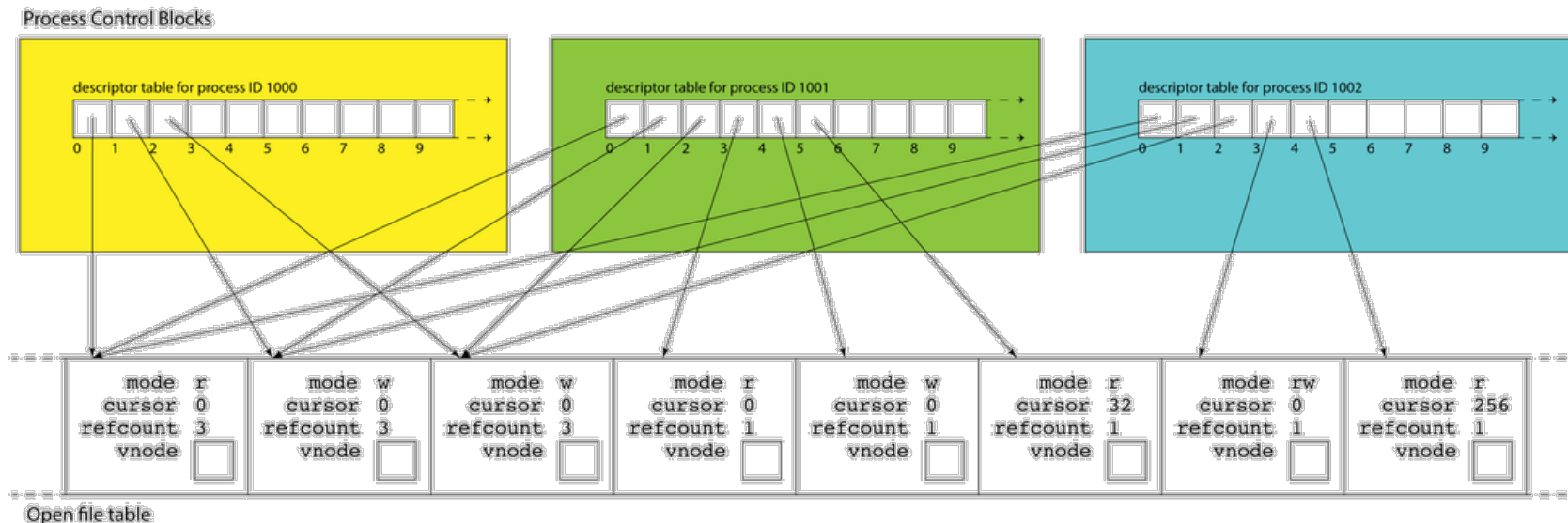
The OS maintains a **process control block** for each process - a set of relevant information about its execution. Lives as long as the process does.

- Information about memory used by this process
- File descriptor table
- Other misc. accounting and info
- State specific to each thread

# File Descriptor Table

The file descriptor table is an array of info about open files/resources for this process. **Key idea: a file descriptor is just an index into the file descriptor table!**

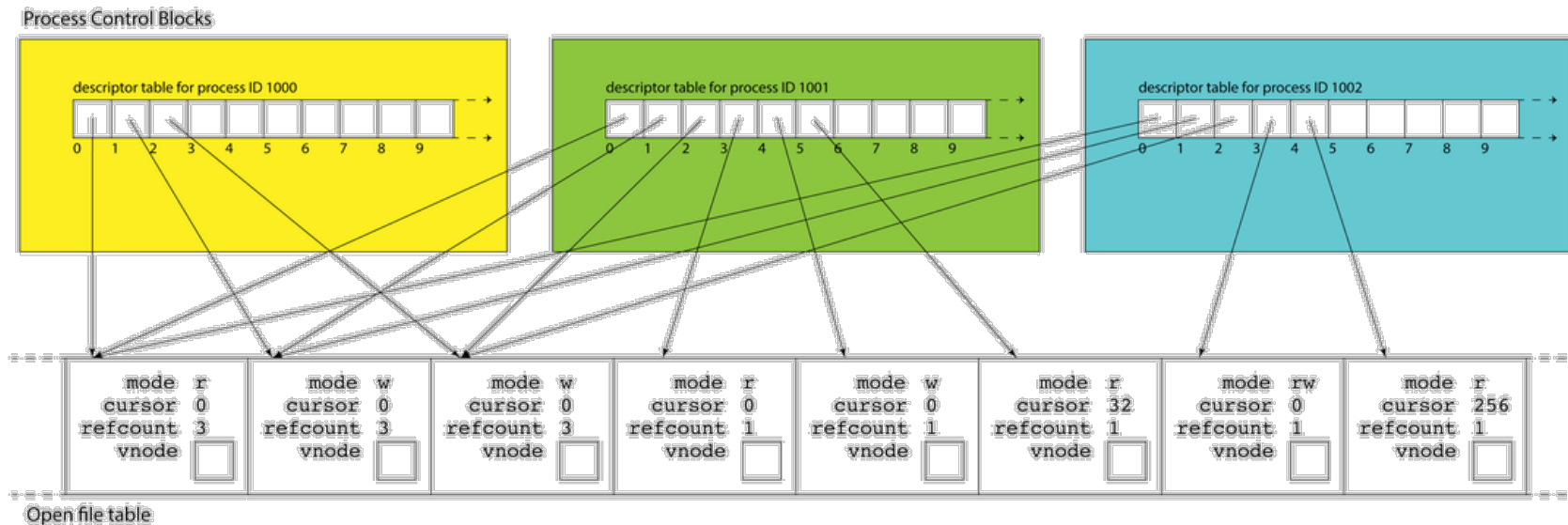
- An entry in the file descriptor table is really a *pointer* to an entry in another table, the **open file table**.
- The **open file table** is one array of information about open files/resources across all processes.





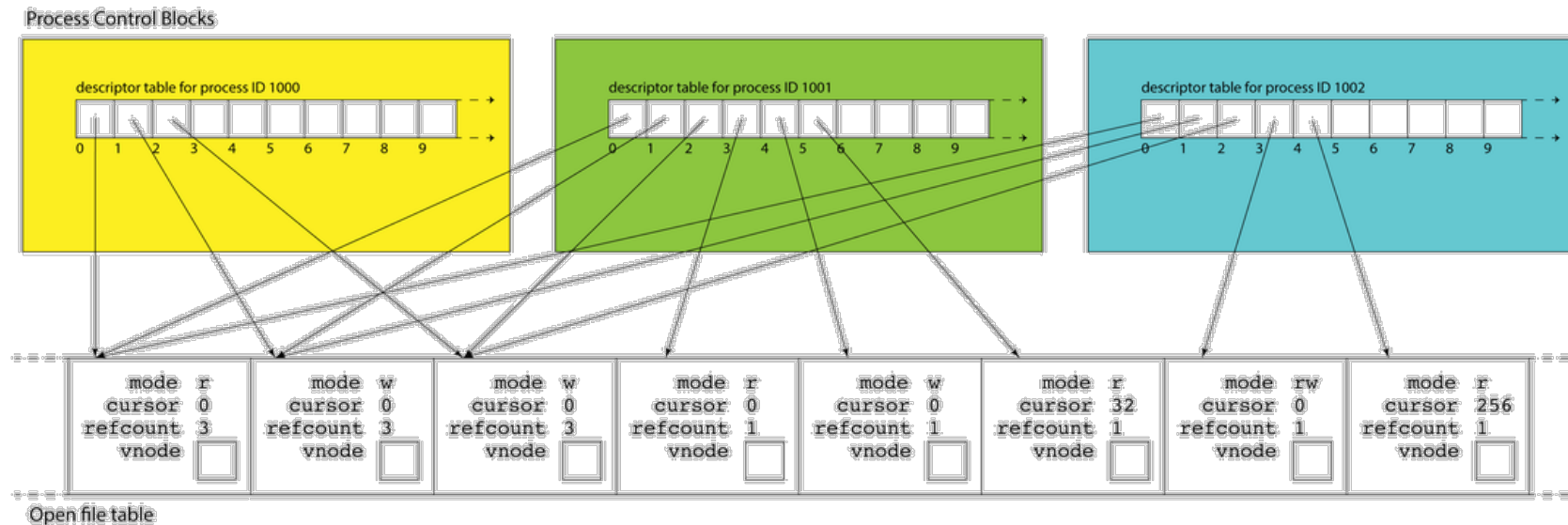
# Open File Table

- When we call **open** in our program; new open file table entry created, new file descriptor index points to it.
- When we call **pipe** in our program; 2 new open file table entries created, 2 new file descriptor indexes point to them.
- When we call **fork** in our program; new PCB, with copy of parent's FD table; so all file descriptor indexes point to the same place!



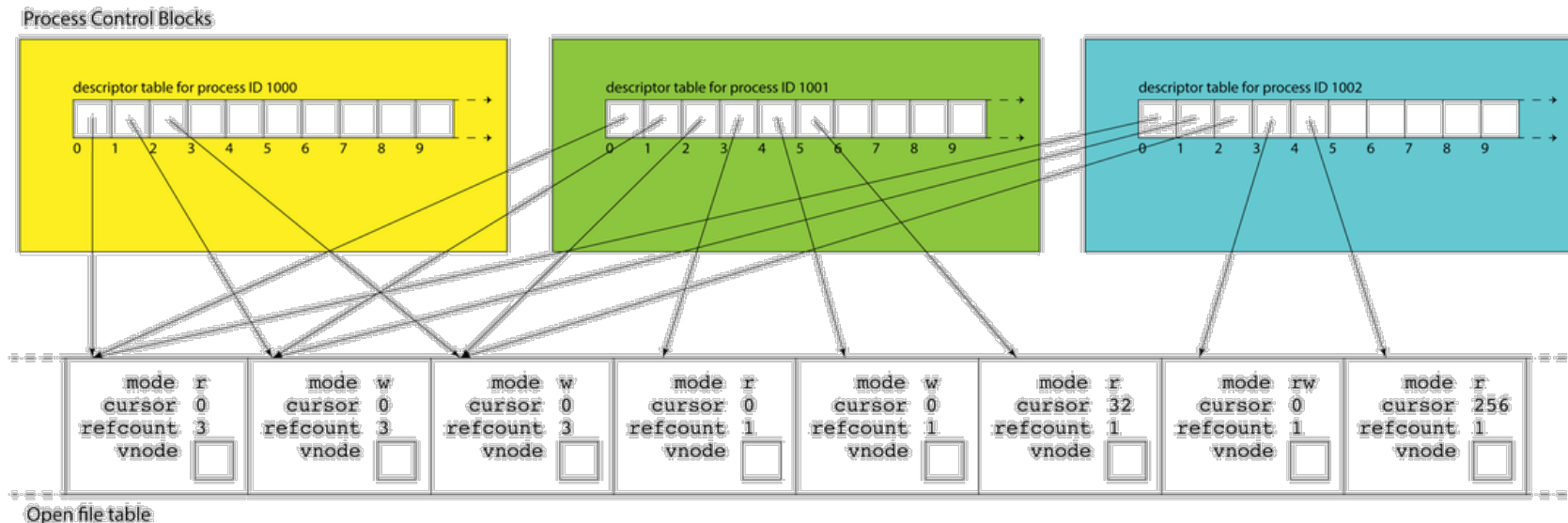
# Open File Table

- When we call **dup2** in our program, one file descriptor index is copied to another index (so both point to same open file table entry)



# Open File Table

- Each open file table entry keeps a *reference count*, a count of the number of file descriptor table entries pointing to it.
- This ref count increases whenever a new file descriptor index points to it.
- When we call **close** in our program, file descriptor index no longer points to open file table entry, open file table entry's ref count decremented.
- When open file table entry's ref count == 0, it's deleted



# Parent makes a pipe, spawns a child: what is read end's ref count?

1

2

3

4

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1

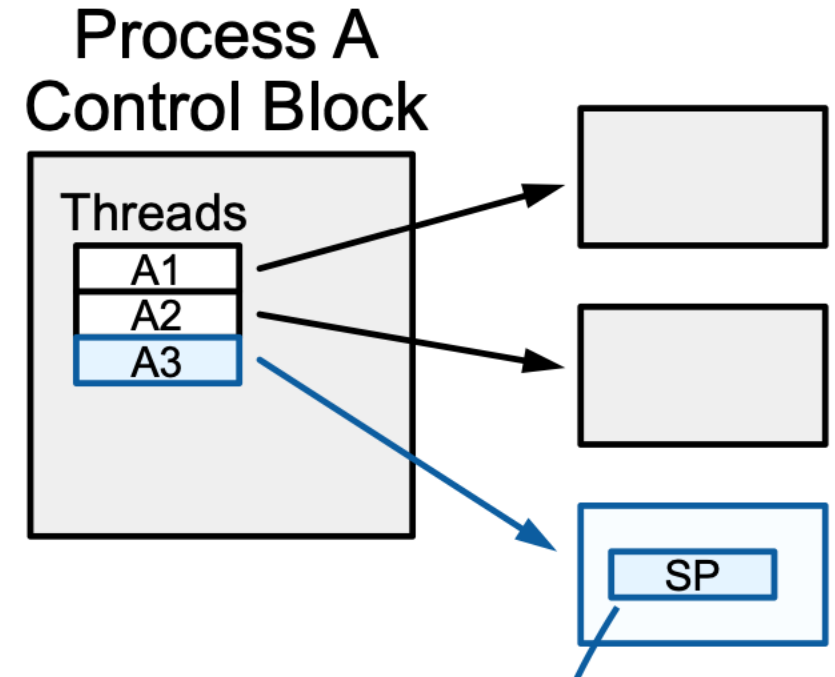
2

3

4

# Thread State

- All main info in the PCB (e.g. memory info for the entire process) is relevant to all threads
- Each thread also has some of its own private info (e.g. stack location)
- When the OS wants to run a thread, it loads its state and starts or resumes it
- How does the OS regain control?



# Regaining Control

There are several ways control can switch back to the OS:

1. “Traps” (events that require OS attention):
  1. System calls (like **read** or **waitpid**)
  2. Errors (illegal instruction, address violation, etc.)
  3. Page fault (accessing memory that must be loaded in) – more later...
2. “Interrupts” (events occurring outside current thread):
  1. Character typed at keyboard
  2. Completion of disk operation
  3. Timer – to make sure OS eventually regains control

At this point, OS could then decide to run a different thread.



# Switching Between Threads

When the OS regains control, how does it switch to run another thread?

- **Key idea:** we must load the thread's state onto a processor core and run it
- State = **registers**
  - Registers store data being manipulated by the core
  - %rsp stores current top of stack
  - Stack remembers what function to continue executing
- If we can load this thread's %rsp + other saved registers, then it can resume right where it left off
- *Context switch* – changing the thread currently running to another thread. We must save the current thread state and load in the new thread state.

# Switching Between Threads

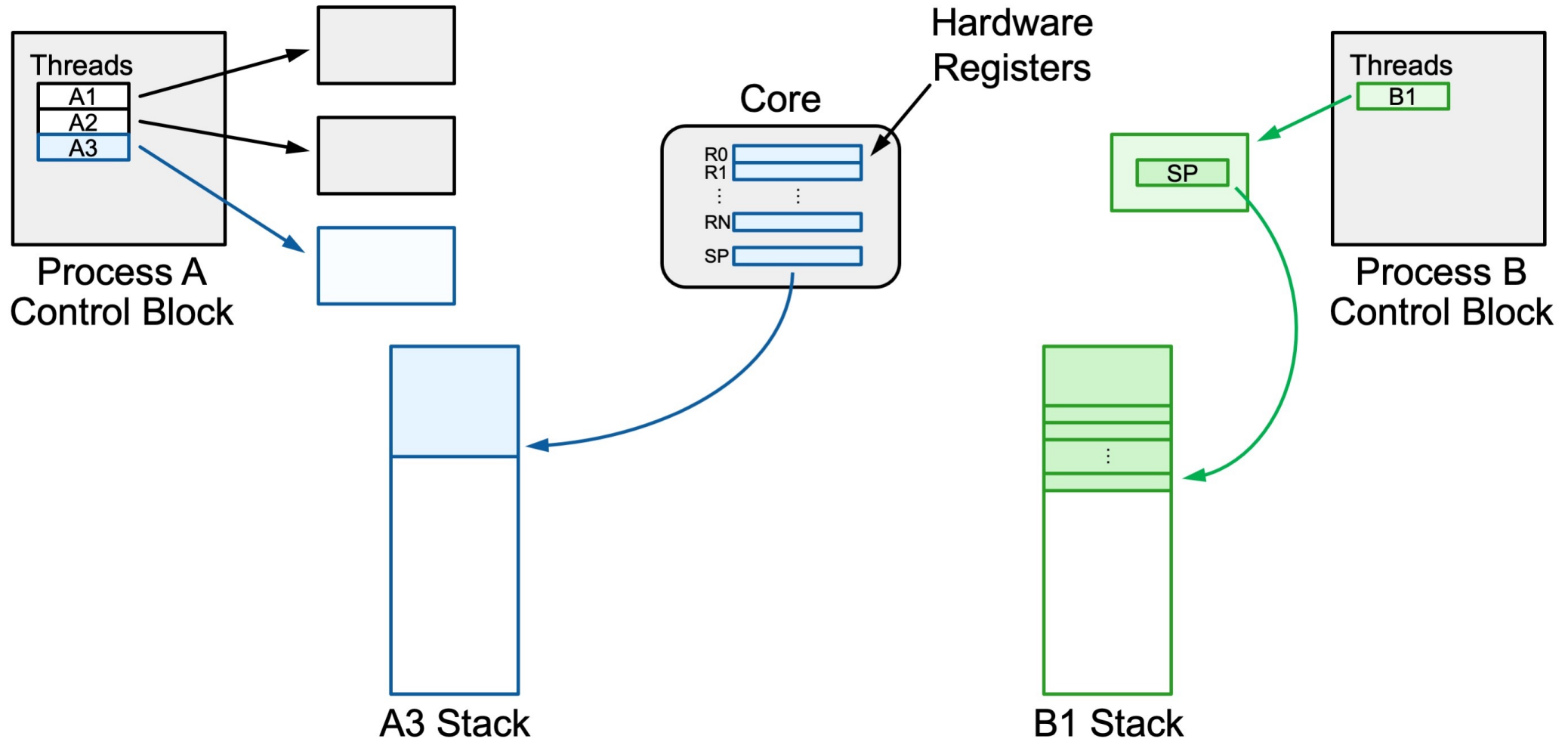
When the OS regains control, how does it switch to run another thread?

The **dispatcher** is OS code that runs on each core that switches between threads and does context switches

- You're going to write parts of one on assign5!
- Context switches are funky – like running a function that, as part of its execution, switches to a *completely different function in a completely different thread!!*

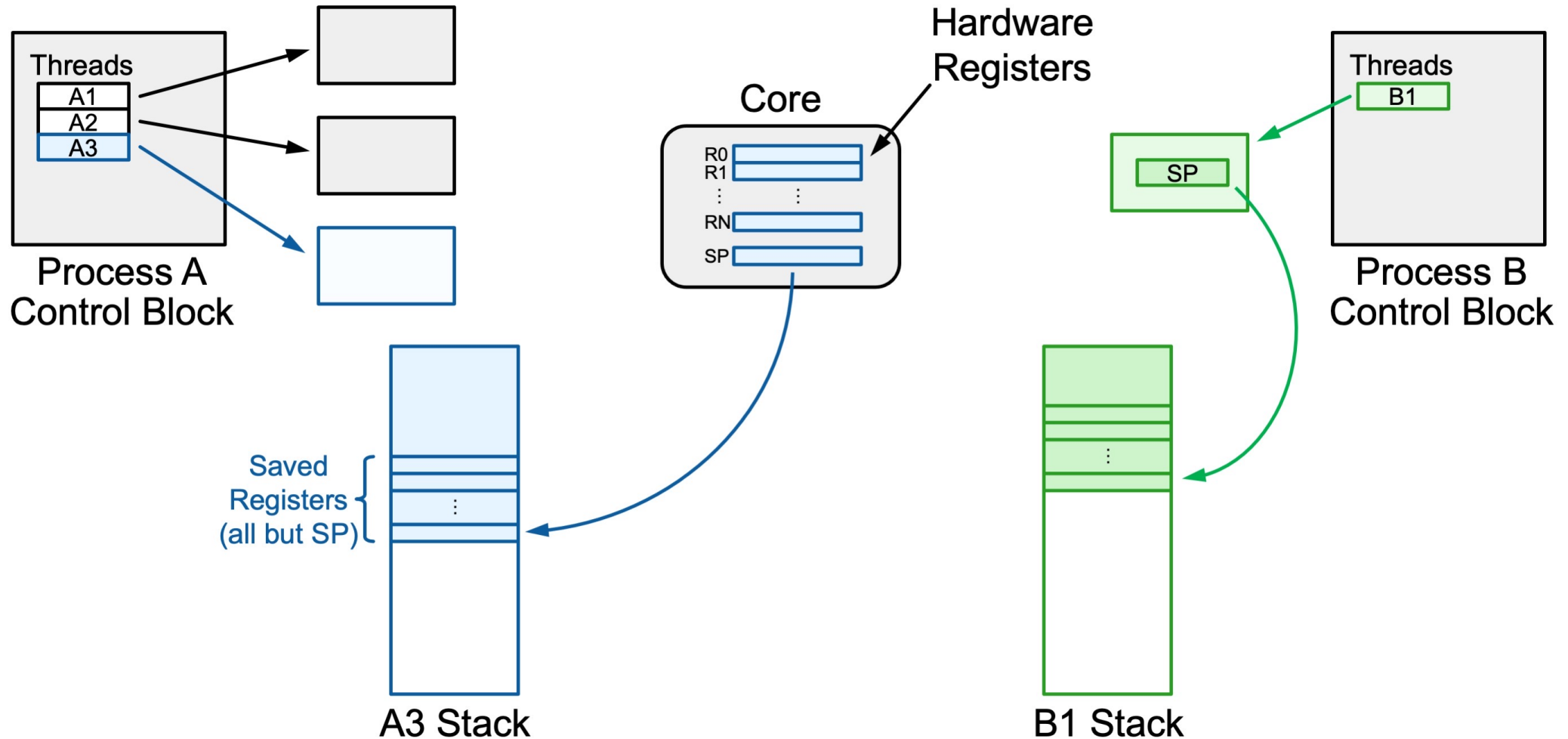
# Context Switching

*Context switch: how do we switch from thread A3 to thread B1?*



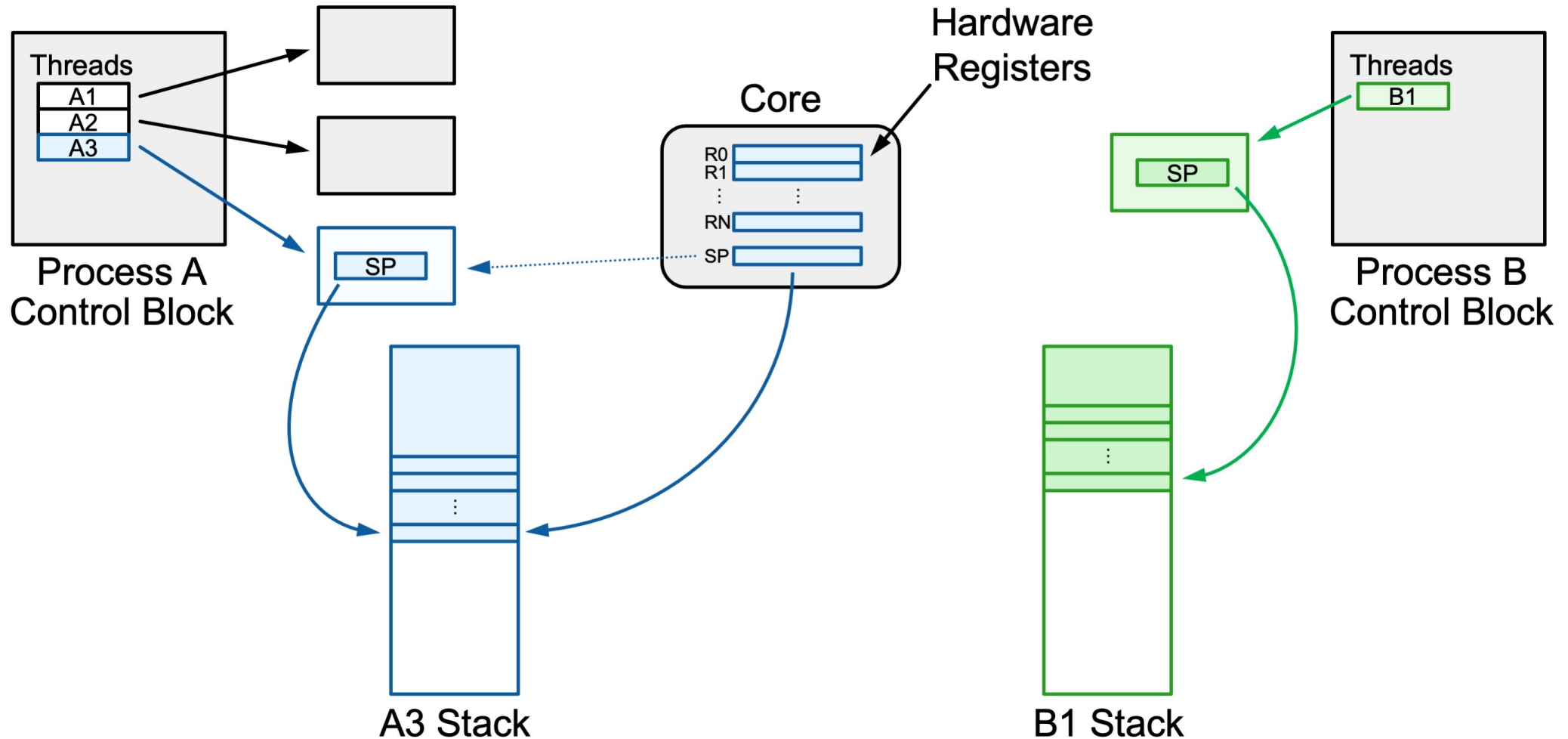
# Context Switching

**Step 1:** *push all registers besides stack register onto the thread's stack.*



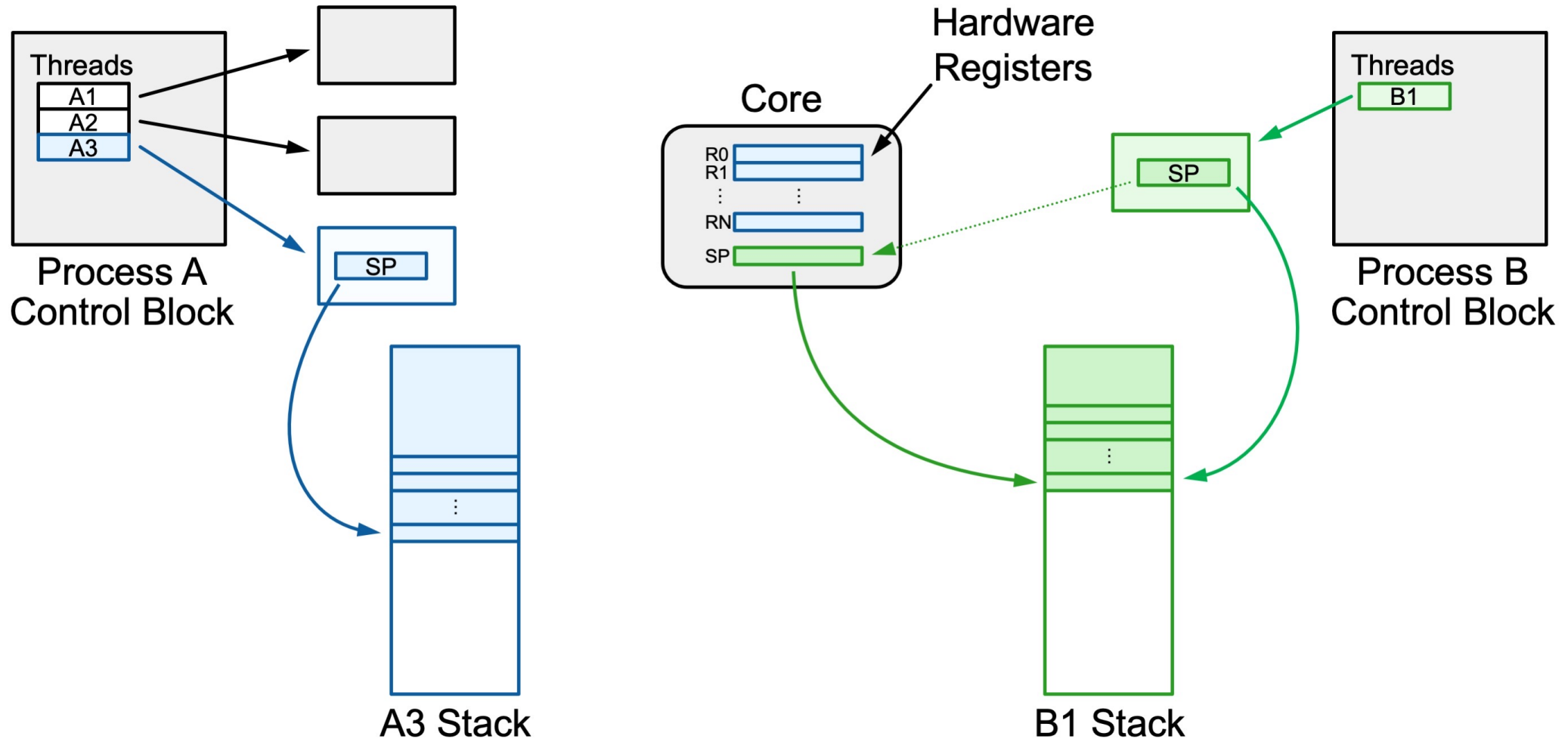
# Context Switching

**Step 2:** *save the stack register into the thread's state space.*



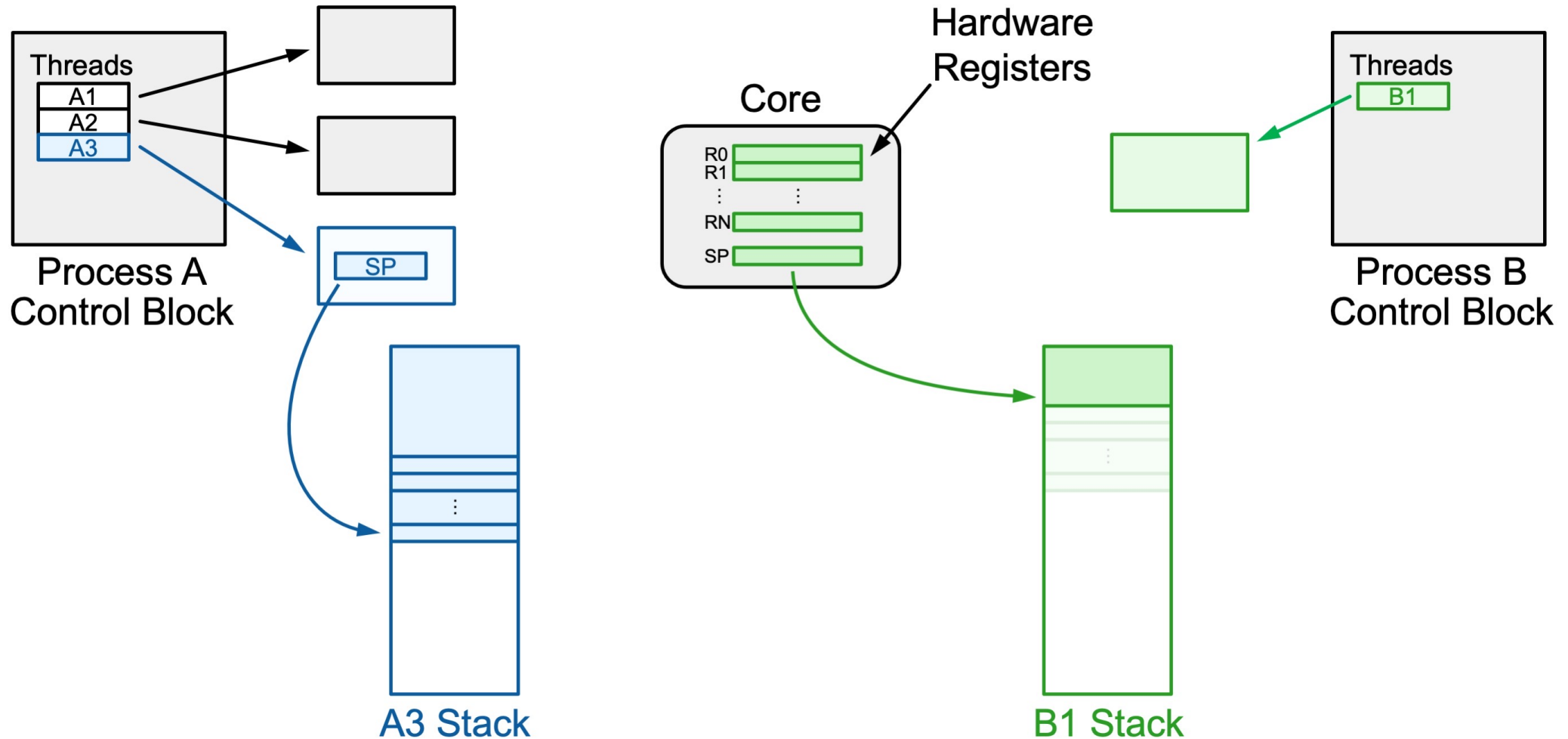
# Context Switching

**Step 3:** load B1's saved stack register from its thread state space.



# Context Switching

**Step 4:** *pop B1's other registers from its stack space.*



**Demo: context-switch.cc**



# Plan For Today

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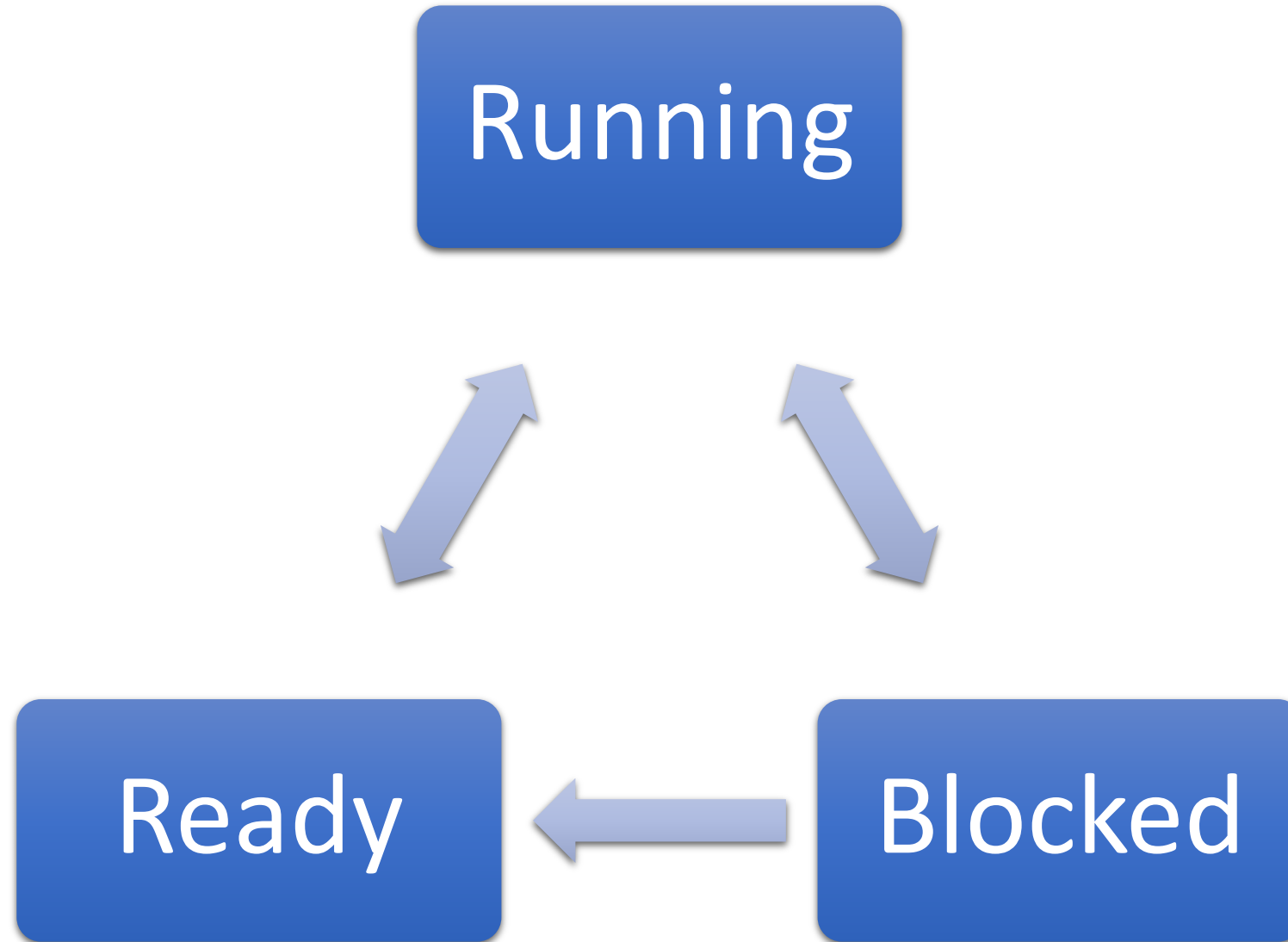
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# Tracking All Threads

**Key idea:** at any given time, a thread is in one of three states:

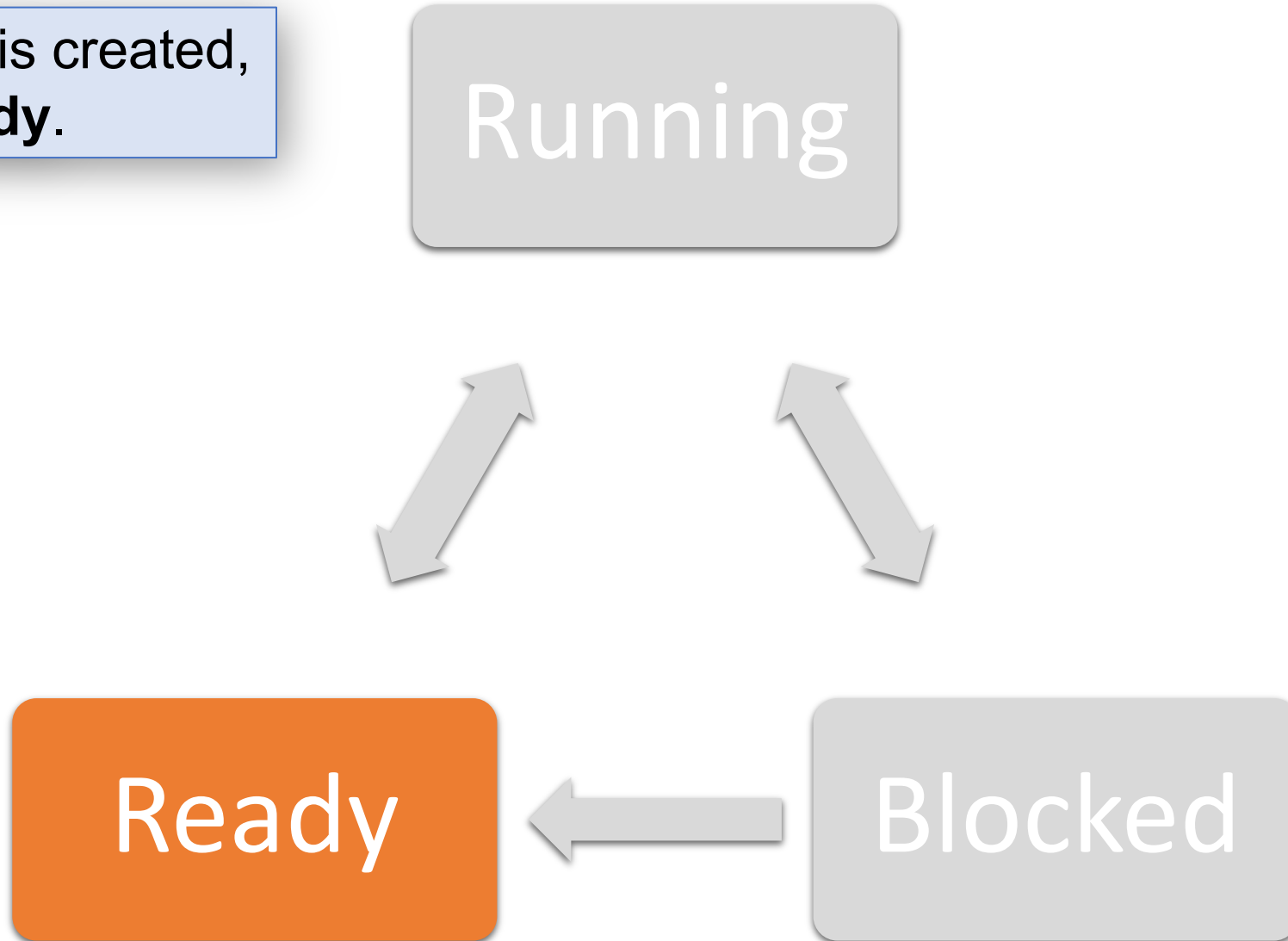
1. **Running**
2. **Blocked** – waiting for an event (disk I/O, network connection, etc.)
3. **Ready** – able to run, but waiting for CPU time

# Thread States



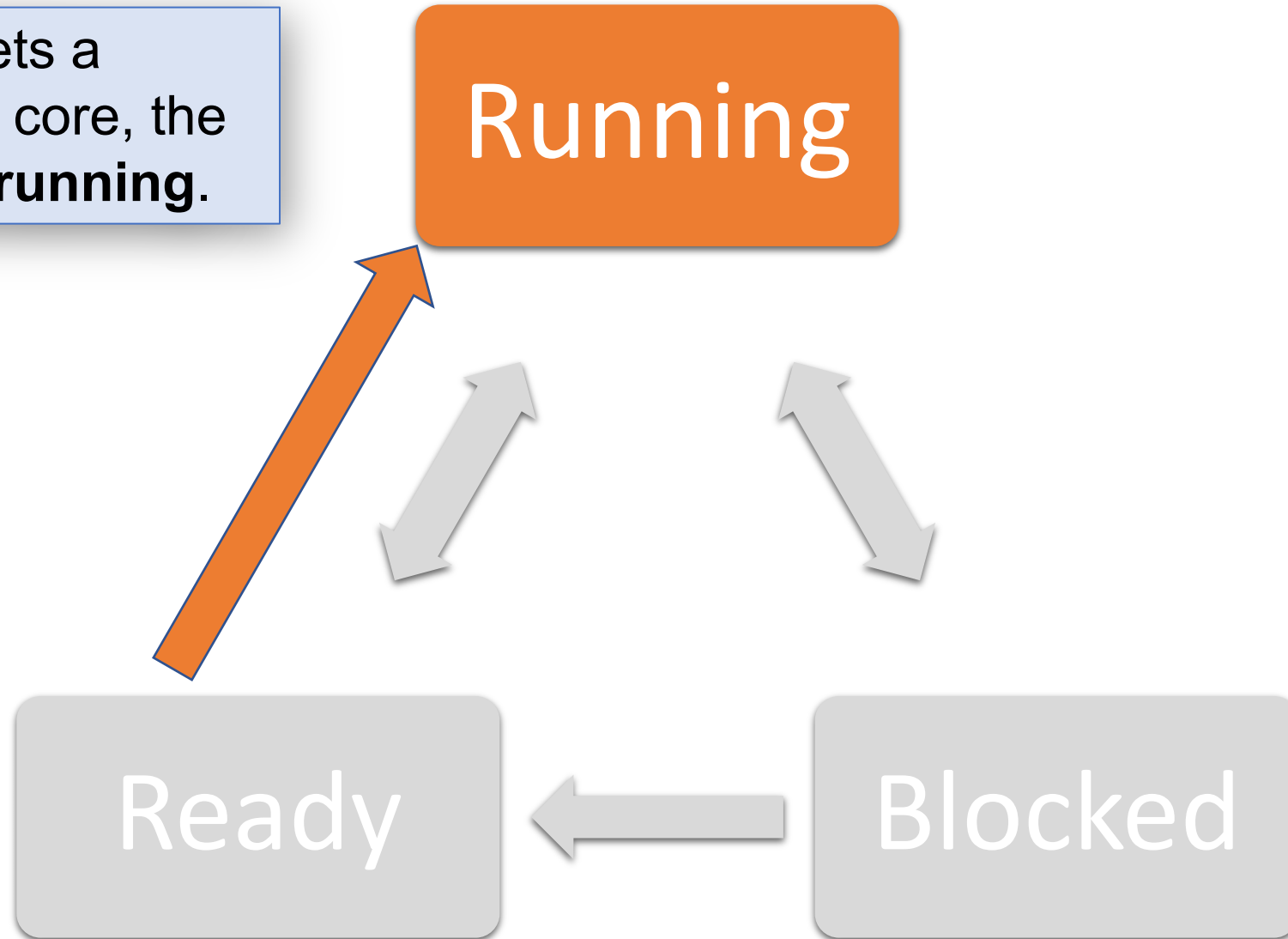
# Thread States

When a thread is created, it starts out **ready**.



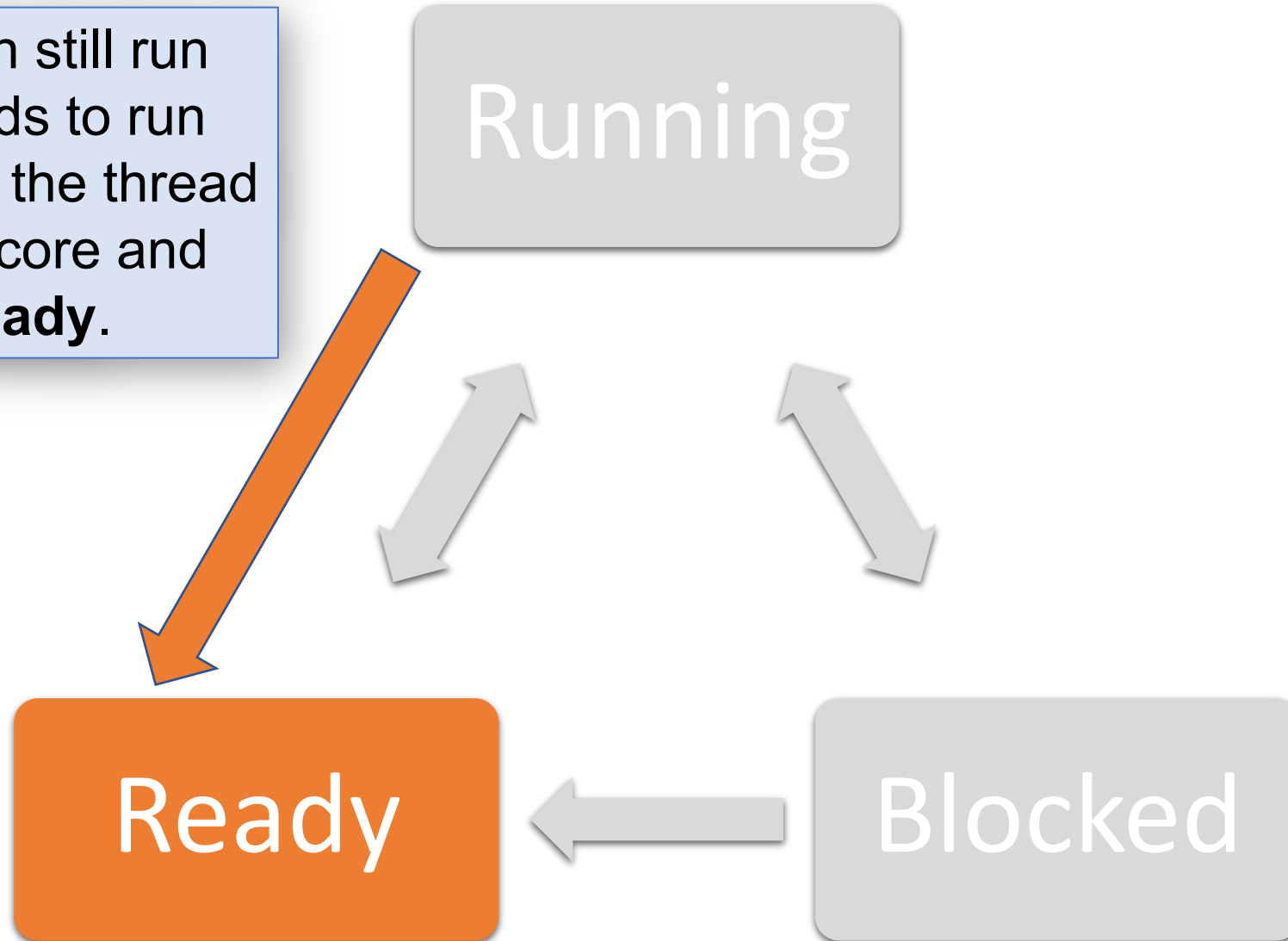
# Thread States

When the OS lets a thread run on a core, the thread goes to **running**.



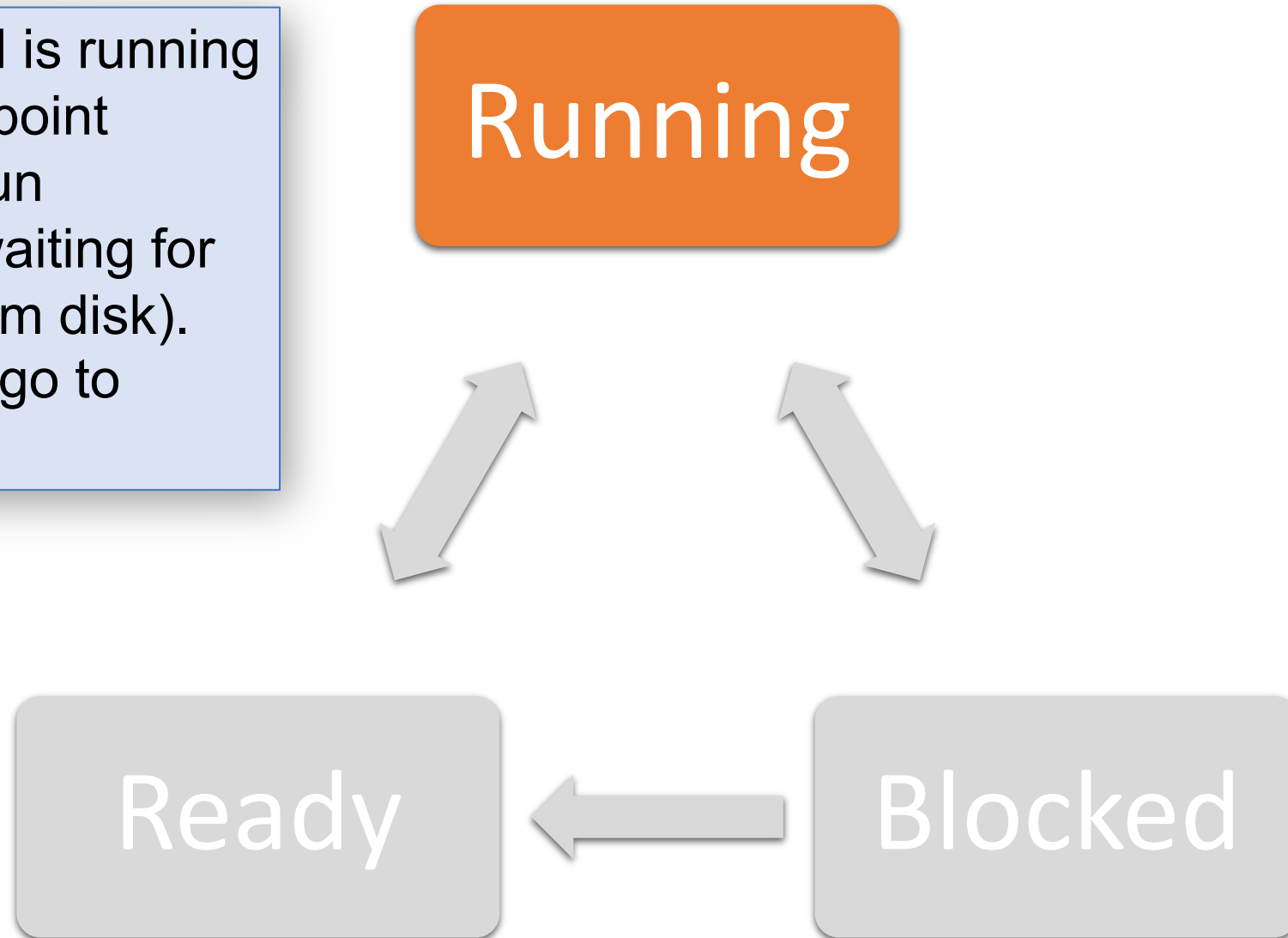
# Thread States

If the thread can still run but the OS needs to run another thread, the thread is taken off the core and goes back to **ready**.



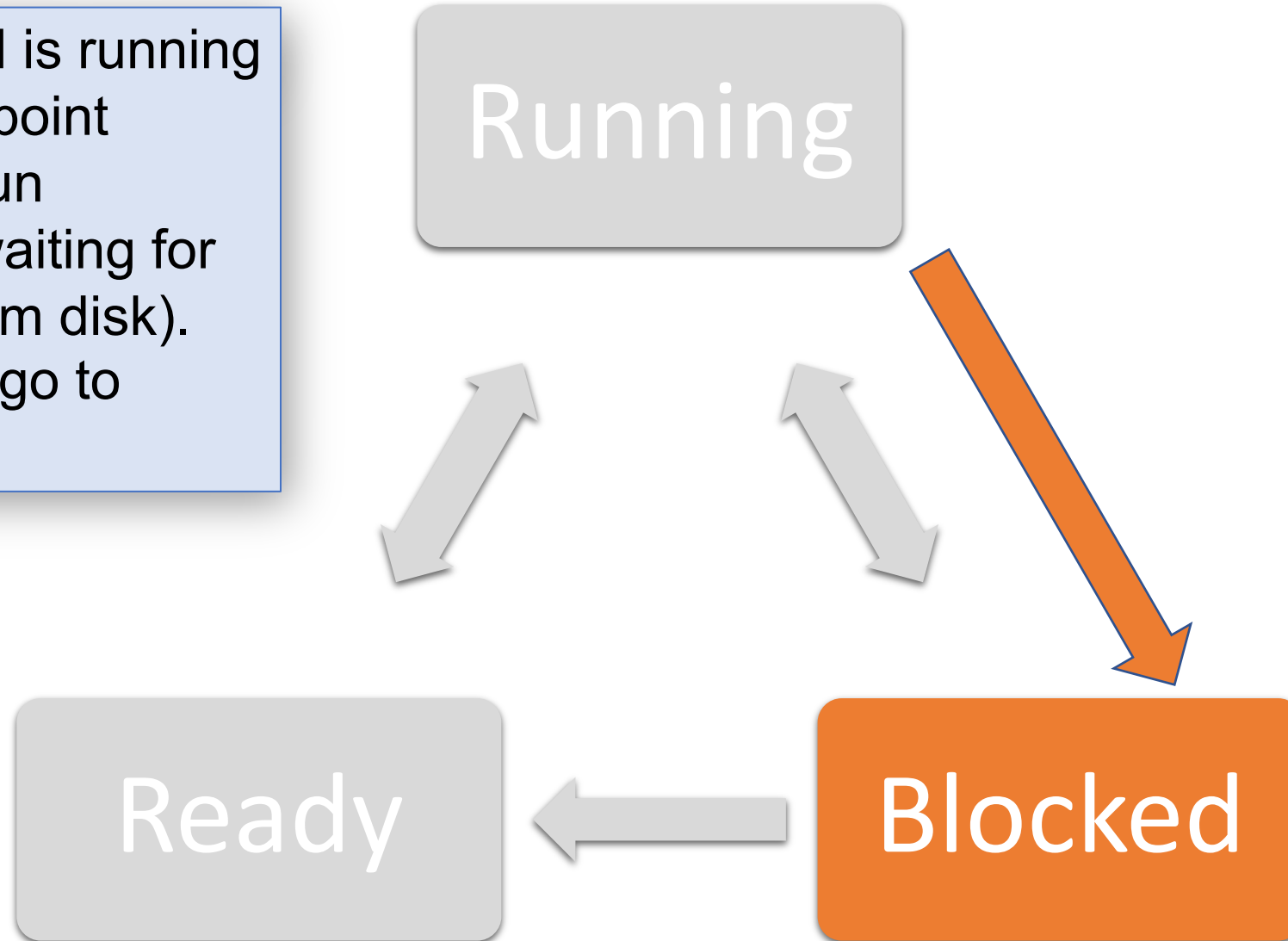
# Thread States

Maybe a thread is running and reaches a point where it can't run anymore (eg. waiting for file contents from disk). The thread will go to **blocked**.



# Thread States

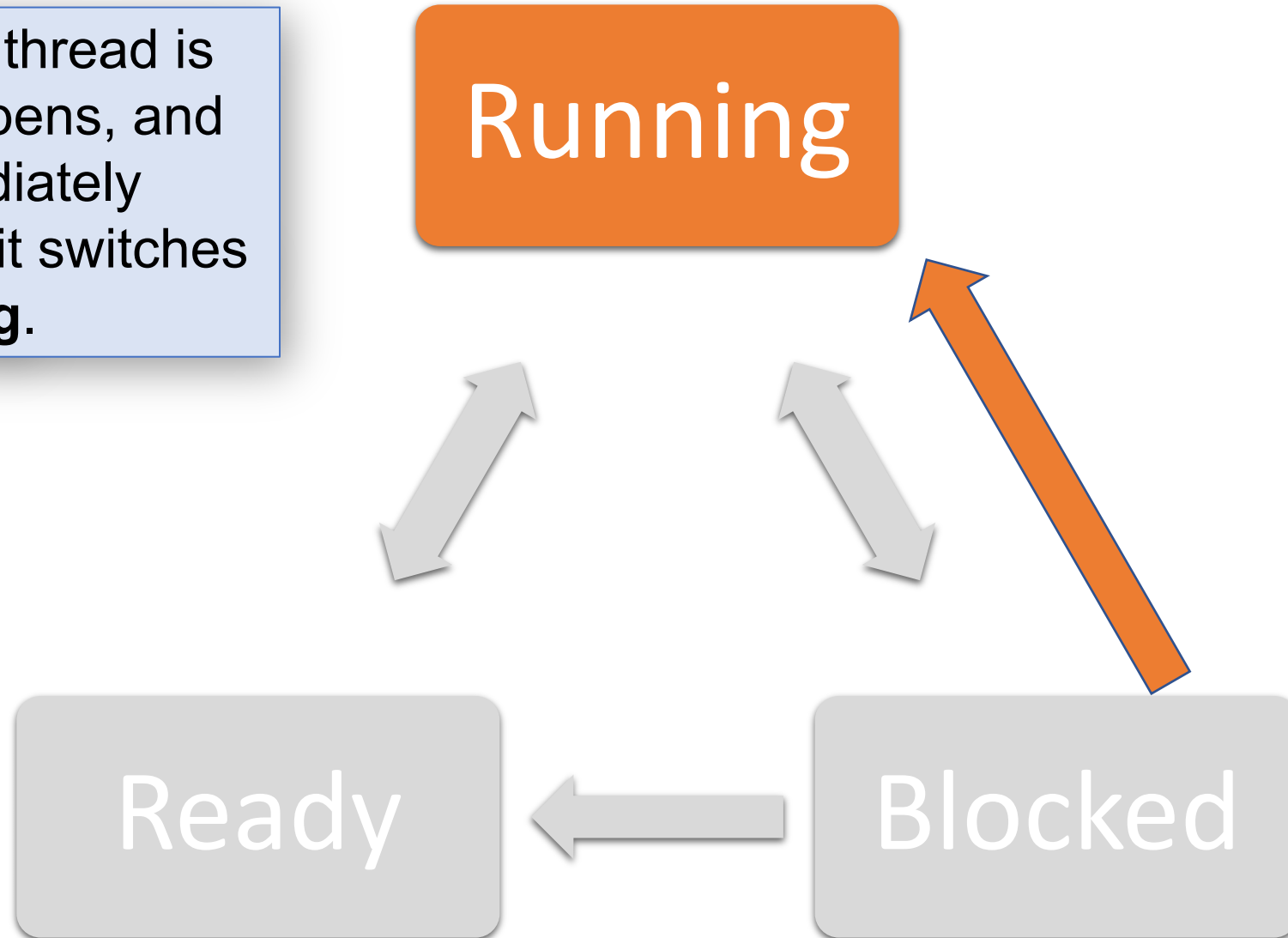
Maybe a thread is running and reaches a point where it can't run anymore (eg. waiting for file contents from disk). The thread will go to **blocked**.





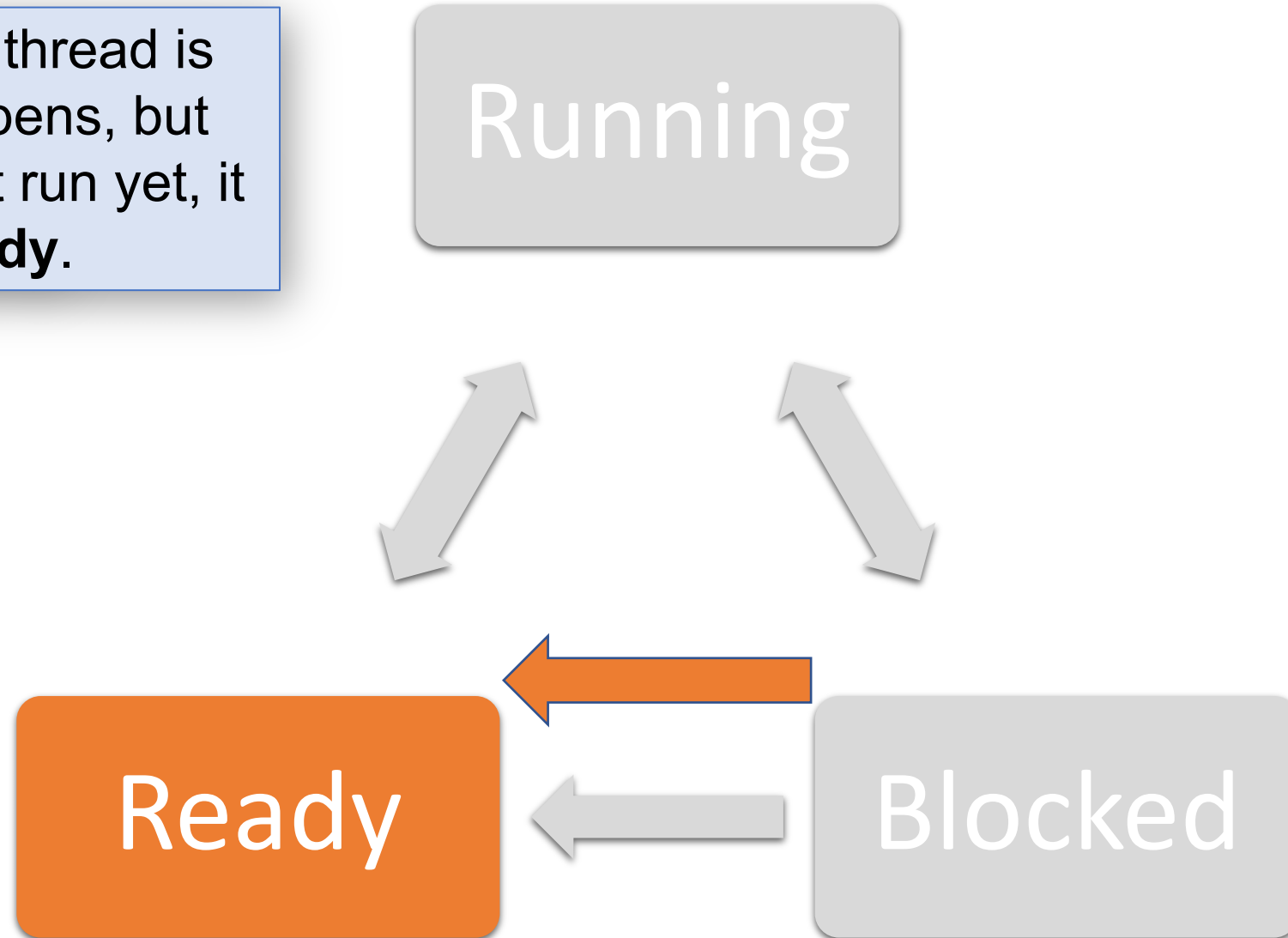
# Thread States

If the event the thread is waiting for happens, and a core is immediately available for it, it switches back to **running**.



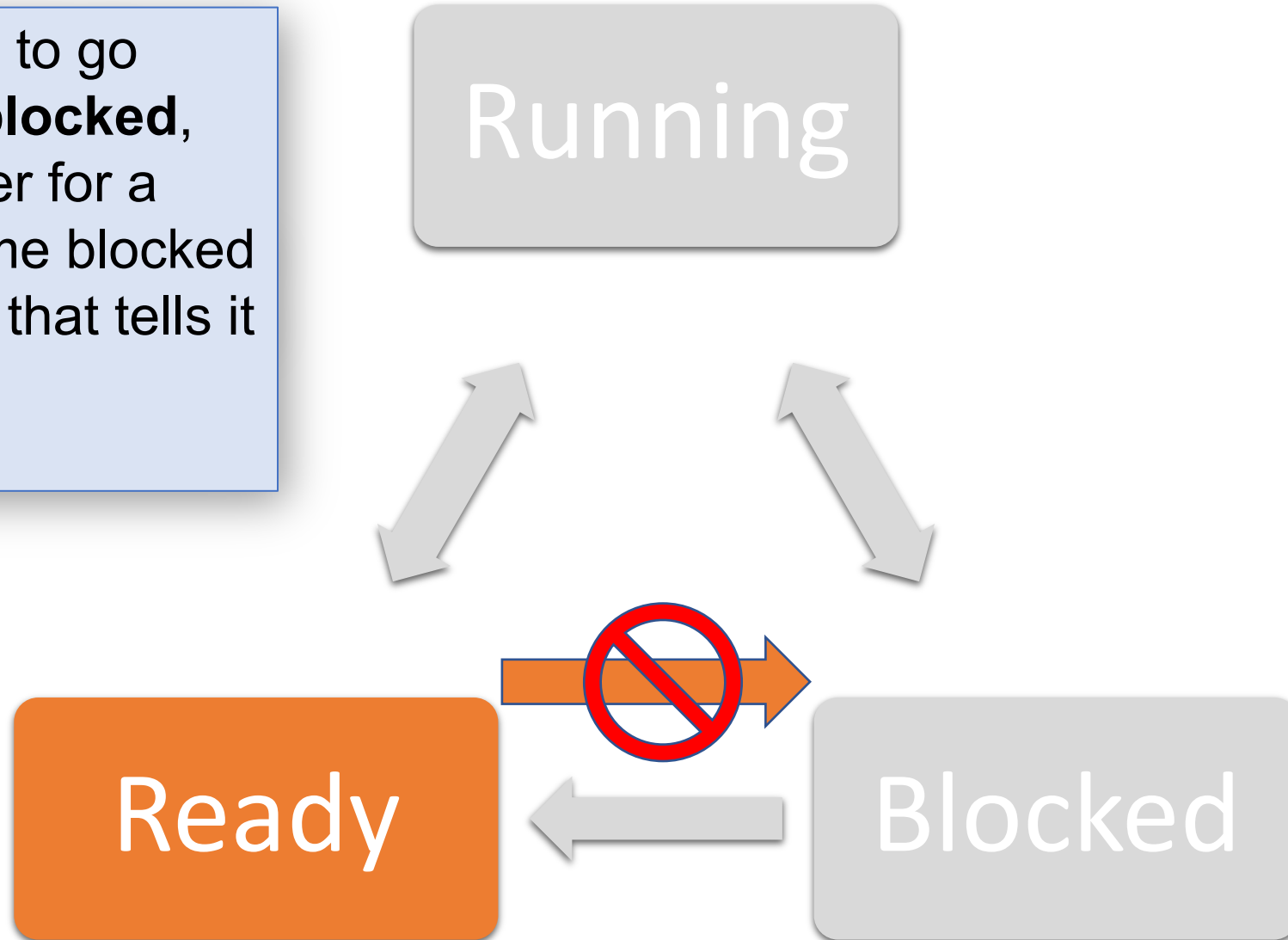
# Thread States

If the event the thread is waiting for happens, but the thread can't run yet, it switches to **ready**.



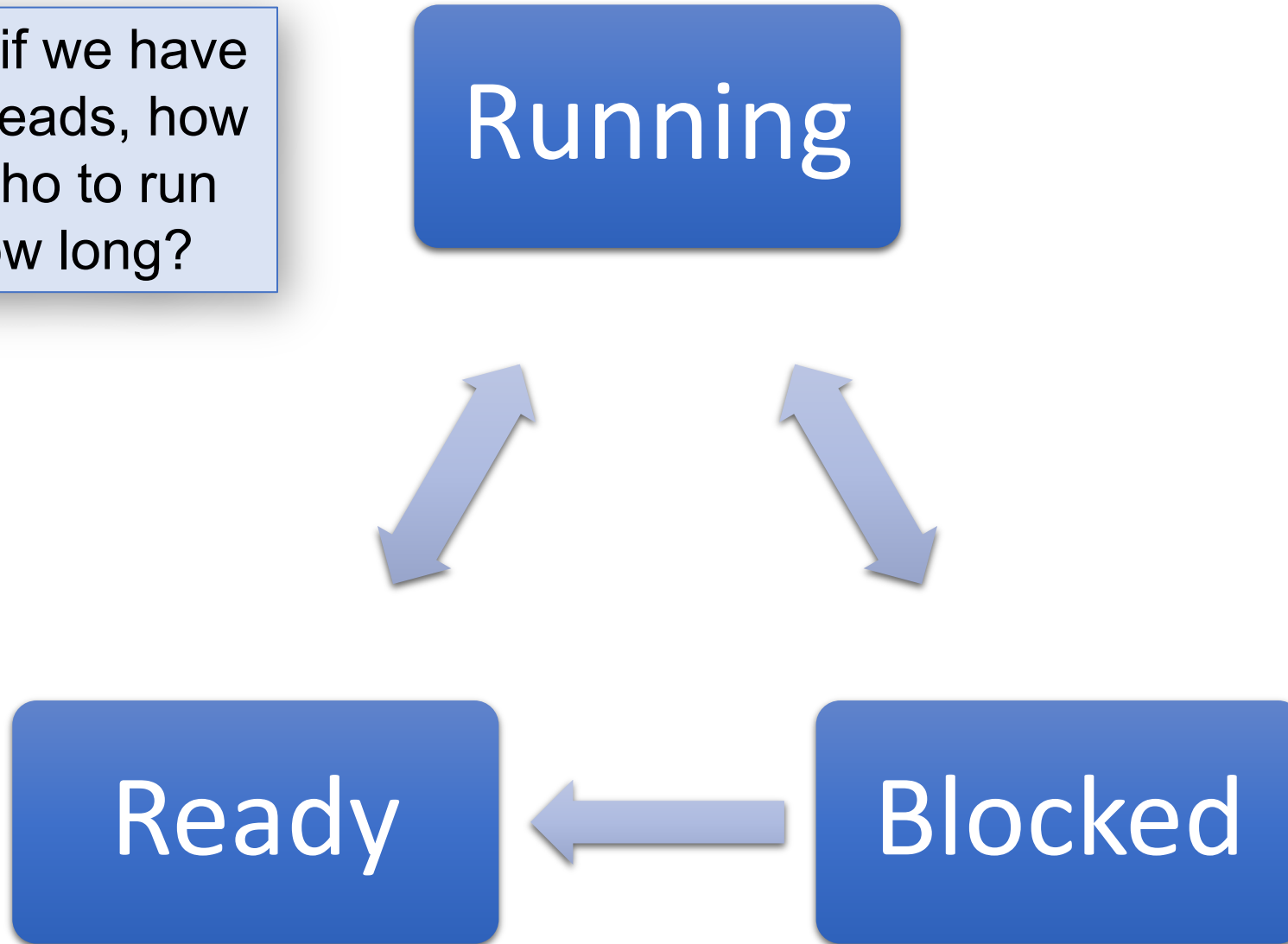
# Thread States

It's not possible to go from **ready** to **blocked**, because in order for a thread to become blocked it must do work that tells it it must wait for something.



# Thread States

**Key question:** if we have many **ready** threads, how do we decide who to run next, and for how long?



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# First-come-first-serve

**Key Question:** How does the operating system decide which thread to run next? (e.g. many **ready** threads). Assume just 1 core.

**One idea - “first-come-first-serve”:** keep all ready threads in a *ready queue*. Add threads to the back. Run the first thread on the queue until it exits or blocks.

**Problem:** thread could run away with core and run forever!

# Round Robin

**Problem:** thread could run away with core and run forever!

**Solution:** define a *time slice*, the max run time without a context switch (e.g. 10ms).

**Idea:** round robin scheduling – run thread for one time slice, then put at back of ready queue. (you'll use this on assign5)

**Question:** what's a good time slice?

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## **Lecture 17 takeaway:**

Context switching saves the current thread state and switches to a completely different stack frame! When we have many ready threads, how do we decide which gets to run, and for how long?

**Next time:** more discussions about scheduling, and implementing dispatchers.