

# Lecture 13

***More dynamic programming!***

Longest Common Subsequences, Knapsack, and  
(if time) independent sets in trees.

# Announcements

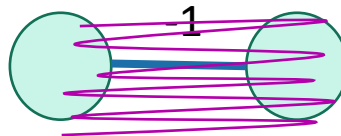
- HW6 due Wednesday!
- HW7 out Wednesday!
- FAQ: What's the best way to prepare for the final?
  - Practice problems!
    - If Section/HW aren't enough for you, there are plenty in Algorithms Illuminated and in CLRS (which is available for free via the Stanford library).
    - We'll also be posting multiple practice finals soon.
  - When you are reading the book or (re)watching lectures or section, try to guess what comes next.
    - If we state a lemma, close the book or pause the video, and try to prove the lemma.
    - If we've seen the intuition for an algorithm, try to write down pseudocode.
  - Try the HW on your own before collaborating.

# Question from last time

- Does Bellman-Ford/Floyd-Warshall work on undirected graphs?
  - Yes, just do:



- What about negative edge weights? Does that mean we just can't handle negative edge weights in undirected graphs?
  - That's right.



I can still walk back and forth forever, and shortest paths might not be defined!

Last time

# *Dynamic Programming!*

- Not coding in an action movie.



These programs dynamically  
in Mission Impossible

# Last time

## *Dynamic Programming!*

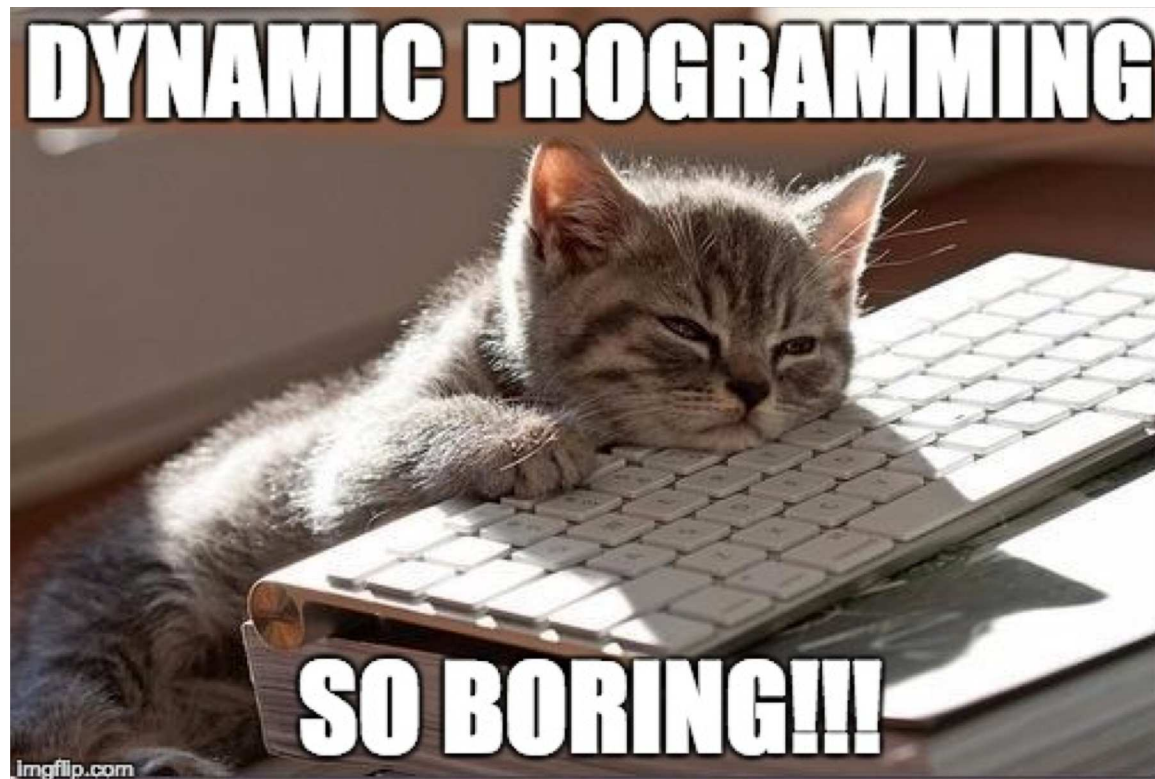
- Dynamic programming is an **algorithm design paradigm**.
- Basic idea:
  - Identify **optimal sub-structure**
    - Optimum to the big problem is built out of optima of small sub-problems
  - Take advantage of **overlapping sub-problems**
    - Only solve each sub-problem once, then use it again and again
  - Keep track of the solutions to sub-problems in a table as you build to the final solution.

# Today

- Examples of dynamic programming:
  1. Longest common subsequence
  2. Knapsack problem
    - Two versions!
  3. Independent sets in trees
    - If we have time...
    - (If not the slides will be there as a reference)
- Yet more examples of DP in Algorithms Illuminated!
  - Weighted Independent Set in Paths
  - Sequence Alignment
  - Optimal Binary Search Trees

# The goal of this lecture

- For you to get **really bored** of dynamic programming



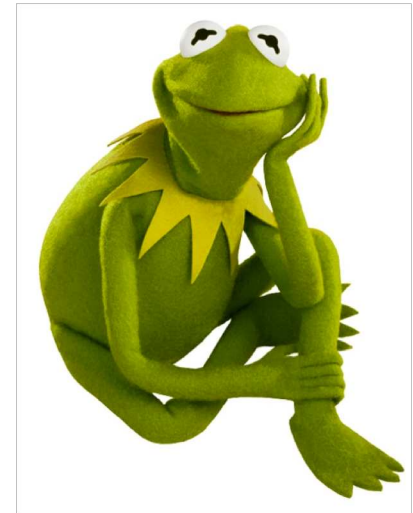
# Longest Common Subsequence

- How similar are these two species?



DNA:

AGCCCTAAGGGCTACCTAGCTT



DNA:

GACAGCCTACAAGCGTTAGCTTG

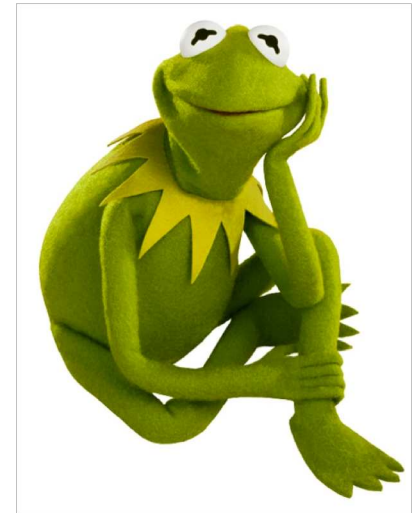
# Longest Common Subsequence

- How similar are these two species?



DNA:

AGCCCTAAGGGCTACCTAGCTT



DNA:

GACAGCCTACAAGCGTTAGCTTG

- Pretty similar, their DNA has a long common subsequence:

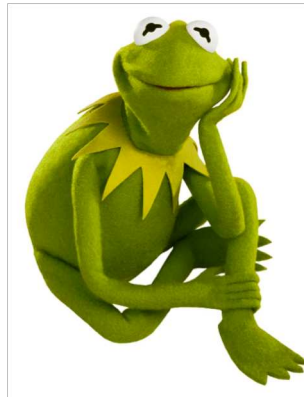
AGCCTAAGCTTAGCTT

# Longest Common Subsequence

- Subsequence:
  - **BDFH** is a **subsequence** of **ABCDEF<sub>G</sub>H**
- If X and Y are sequences, a **common subsequence** is a sequence which is a subsequence of both.
  - **BDFH** is a **common subsequence** of **ABCDEF<sub>G</sub>H** and of **ABDF<sub>G</sub>H<sub>I</sub>**
- A **longest common subsequence**...
  - ...is a common subsequence that is longest.
  - The **longest common subsequence** of **ABCDEF<sub>G</sub>H** and **ABDF<sub>G</sub>H<sub>I</sub>** is **ABDF<sub>G</sub>H**.

# We sometimes want to find these


- Applications in **bioinformatics**



- The unix command **diff**
- Merging in version control
  - **svn**, **git**, etc...

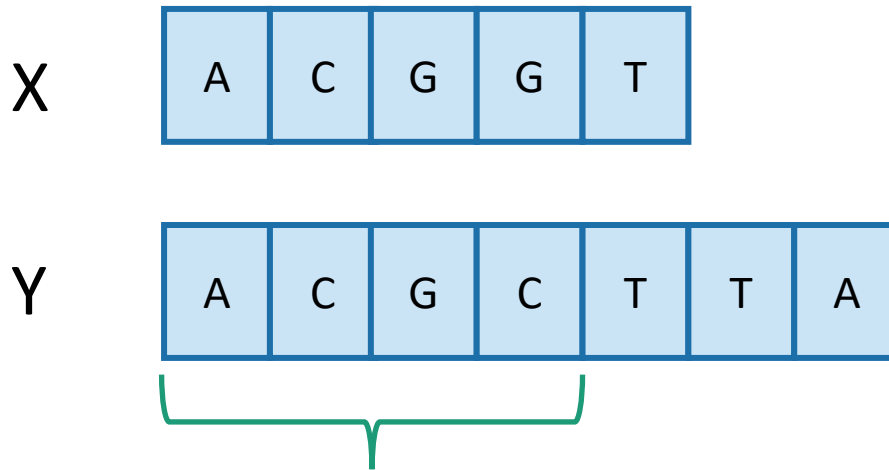
```
[DN0a22a660:~ mary$ cat file1
A
B
C
D
E
F
G
H
[DN0a22a660:~ mary$ cat file2
A
B
D
F
G
H
I
[DN0a22a660:~ mary$ diff file1 file2
3d2
< C
5d3
< E
8a7
> I
DN0a22a660:~ mary$
```

# Recipe for applying Dynamic Programming

- **Step 1:** Identify optimal substructure. 
- **Step 2:** Find a recursive formulation for the length of the longest common subsequence.
- **Step 3:** Use dynamic programming to find the length of the longest common subsequence.
- **Step 4:** If needed, keep track of some additional info so that the algorithm from Step 3 can find the actual LCS.
- **Step 5:** If needed, code this up like a reasonable person.

# Step 1: Optimal substructure

Prefixes:



**Notation:** denote this prefix **ACGC** by  $Y_4$

- Our sub-problems will be finding LCS's of prefixes to X and Y.
- Let  $C[i,j] = \text{length\_of\_LCS}(X_i, Y_j)$

Examples:  $C[2,3] = 2$   
 $C[4,4] = 3$

# Optimal substructure ctd.

- Subproblem:
  - finding LCS's of prefixes of X and Y.
- Why is this a good choice?
  - As we will see, there's some relationship between LCS's of prefixes and LCS's of the whole things.
  - These subproblems overlap a lot.

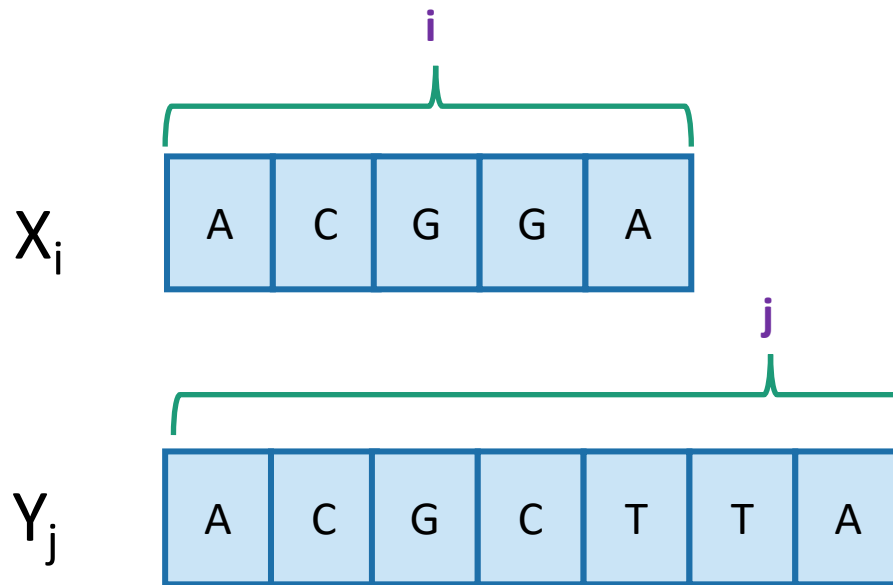
# Recipe for applying Dynamic Programming

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# Goal

- Write  $C[i,j]$  in terms of the solutions to smaller sub-problems

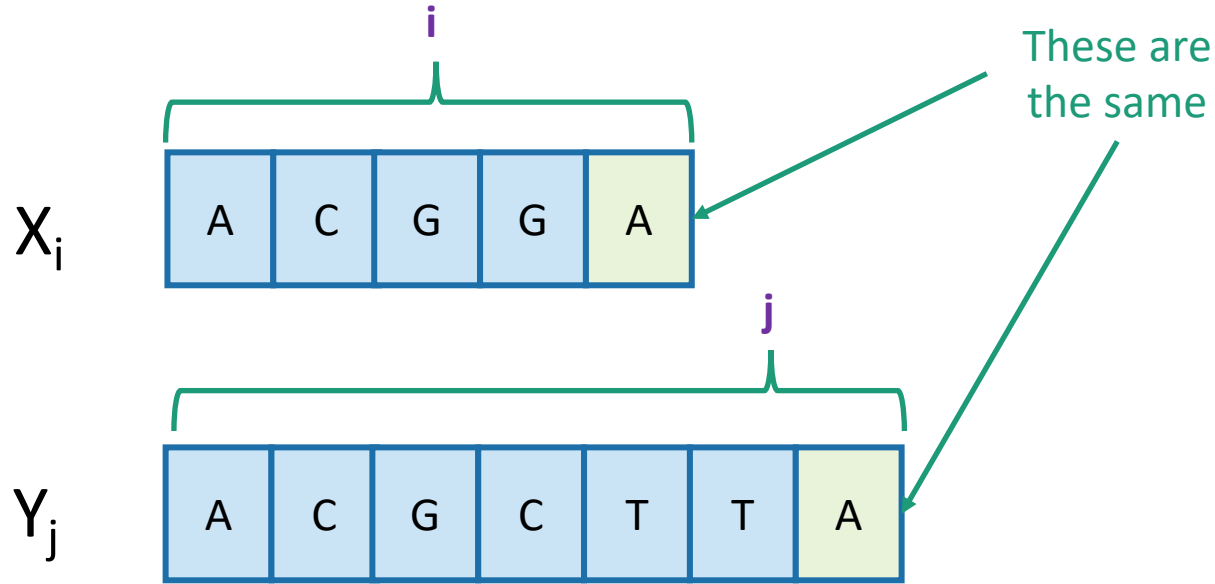


$$C[i,j] = \text{length\_of\_LCS}(X_i, Y_j)$$

# Two cases

Case 1:  $X[i] = Y[j]$

- Our sub-problems will be finding LCS's of prefixes to X and Y.
- Let  $C[i,j] = \text{length\_of\_LCS}(X_i, Y_j)$

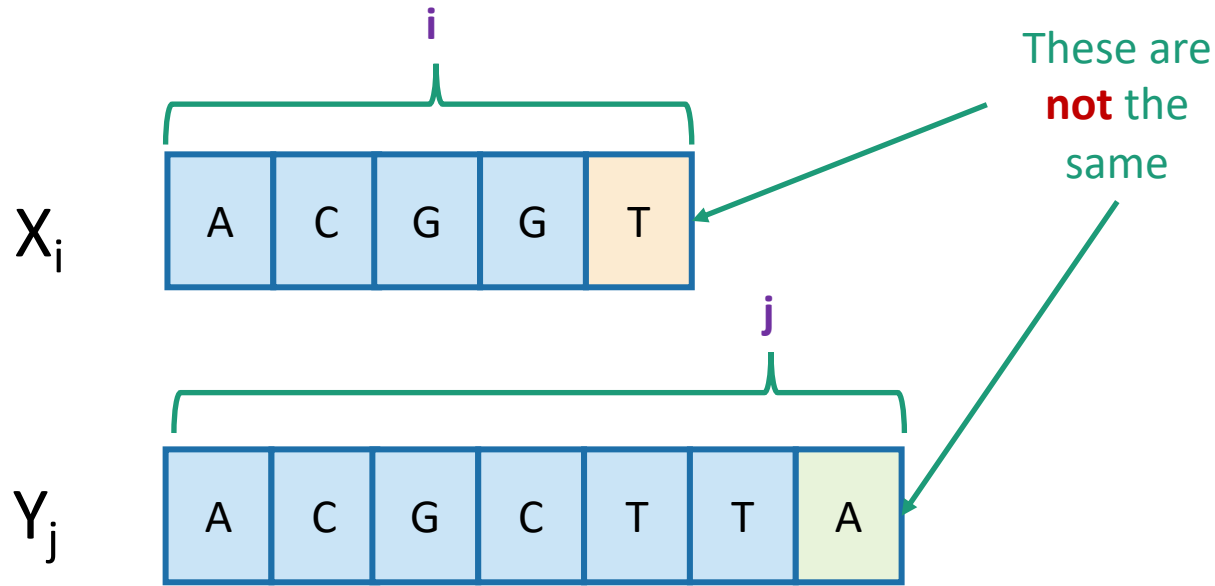


- Then  $C[i,j] = 1 + C[i-1,j-1]$ .
  - because  $\text{LCS}(X_i, Y_j) = \text{LCS}(X_{i-1}, Y_{j-1})$  followed by A

# Two cases

Case 2:  $X[i] \neq Y[j]$

- Our sub-problems will be finding LCS's of prefixes to X and Y.
- Let  $C[i,j] = \text{length\_of\_LCS}(X_i, Y_j)$



- Then  $C[i,j] = \max\{ C[i-1,j], C[i,j-1] \}$ .
  - either  $\text{LCS}(X_i, Y_j) = \text{LCS}(X_{i-1}, Y_j)$  and T is not involved,
  - or  $\text{LCS}(X_i, Y_j) = \text{LCS}(X_i, Y_{j-1})$  and A is not involved,
  - (maybe both are not involved, that's covered by the “or”).

# Recursive formulation of the optimal solution

$X_0$ 

--

  
 $Y_j$ 

A	C	G	C	T	T	A
---	---	---	---	---	---	---

$$\bullet C[i, j] = \begin{cases} 0 & \text{if } i = 0 \text{ or } j = 0 \\ C[i - 1, j - 1] + 1 & \text{if } X[i] = Y[j] \text{ and } i, j > 0 \\ \max\{C[i, j - 1], C[i - 1, j]\} & \text{if } X[i] \neq Y[j] \text{ and } i, j > 0 \end{cases}$$

Case 0

Case 1

$X_i$ 

A	C	G	G	A
---	---	---	---	---

$Y_j$ 

A	C	G	C	T	T	A
---	---	---	---	---	---	---

Case 2

$X_i$ 

A	C	G	G	T
---	---	---	---	---

$Y_j$ 

A	C	G	C	T	T	A
---	---	---	---	---	---	---

# Recipe for applying Dynamic Programming

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# LCS DP

- **LCS(X, Y):**

- $C[i,0] = C[0,j] = 0$  for all  $i = 0, \dots, m, j = 0, \dots, n$ .
- **For**  $i = 1, \dots, m$  and  $j = 1, \dots, n$ :
  - **If**  $X[i] = Y[j]$ :
    - $C[i,j] = C[i-1,j-1] + 1$
  - **Else:**
    - $C[i,j] = \max\{ C[i,j-1], C[i-1,j] \}$
- Return  $C[m,n]$

**Running time:**  
 **$O(nm)$**

$$C[i,j] = \begin{cases} 0 & \text{if } i = 0 \text{ or } j = 0 \\ C[i-1,j-1] + 1 & \text{if } X[i] = Y[j] \text{ and } i, j > 0 \\ \max\{ C[i,j-1], C[i-1,j] \} & \text{if } X[i] \neq Y[j] \text{ and } i, j > 0 \end{cases}$$

# Example

X    A   C   G   G   A

Y    A   C   T   G

Y

A   C   T   G

X

A

C

G

G

A

0	0	0	0	0
0				
0				
0				
0				
0				

$$C[i, j] = \begin{cases} 0 & \text{if } i = 0 \text{ or } j = 0 \\ C[i - 1, j - 1] + 1 & \text{if } X[i] = Y[j] \text{ and } i, j > 0 \\ \max\{C[i, j - 1], C[i - 1, j]\} & \text{if } X[i] \neq Y[j] \text{ and } i, j > 0 \end{cases}$$

# Example

X    A   C   G   G   A

Y    A   C   T   G

Y

A   C   T   G

X

A

C

G

G


A

0	0	0	0	0
0	1	1	1	1
0	1	2	2	2
0	1	2	2	3
0	1	2	2	3
0	1	2	2	3

So the LCM of X  
and Y has length 3.

$$C[i,j] = \begin{cases} 0 & \text{if } i = 0 \text{ or } j = 0 \\ C[i-1,j-1] + 1 & \text{if } X[i] = Y[j] \text{ and } i,j > 0 \\ \max\{C[i,j-1], C[i-1,j]\} & \text{if } X[i] \neq Y[j] \text{ and } i,j > 0 \end{cases}$$

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# Example

X    A   C   G   G   A

Y    A   C   T   G

Y

A   C   T   G

X

A	0	0	0	0	0
C	0				
G	0				
G	0				
A	0				

$$C[i, j] = \begin{cases} 0 & \text{if } i = 0 \text{ or } j = 0 \\ C[i - 1, j - 1] + 1 & \text{if } X[i] = Y[j] \text{ and } i, j > 0 \\ \max\{C[i, j - 1], C[i - 1, j]\} & \text{if } X[i] \neq Y[j] \text{ and } i, j > 0 \end{cases}$$

# Example

X    A   C   G   G   A

Y    A   C   T   G

Y

A   C   T   G

X  
A  
C  
G  
G  
A

0	0	0	0	0
0	1	1	1	1
0	1	2	2	2
0	1	2	2	3
0	1	2	2	3
0	1	2	2	3

$$C[i,j] = \begin{cases} 0 & \text{if } i = 0 \text{ or } j = 0 \\ C[i-1,j-1] + 1 & \text{if } X[i] = Y[j] \text{ and } i, j > 0 \\ \max\{C[i,j-1], C[i-1,j]\} & \text{if } X[i] \neq Y[j] \text{ and } i, j > 0 \end{cases}$$

# Example

X    A   C   G   G   A

Y    A   C   T   G

Y

A   C   T   G

X  
A  
C  
G  
G  
A

0	0	0	0	0
0	1	1	1	1
0	1	2	2	2
0	1	2	2	3
0	1	2	2	3
0	1	2	2	3

- Once we've filled this in, we can work backwards.

$$C[i,j] = \begin{cases} 0 & \text{if } i = 0 \text{ or } j = 0 \\ C[i-1,j-1] + 1 & \text{if } X[i] = Y[j] \text{ and } i, j > 0 \\ \max\{C[i,j-1], C[i-1,j]\} & \text{if } X[i] \neq Y[j] \text{ and } i, j > 0 \end{cases}$$

# Example

X    A   C   G   G   A

Y    A   C   T   G

Y

A   C   T   G

X  
A  
C  
G  
G  
A

0	0	0	0	0
0	1	1	1	1
0	1	2	2	2
0	1	2	2	3
0	1	2	2	3
0	1	2	2	3

- Once we've filled this in, we can work backwards.

That 3 must have come from the 3 above it.

$$C[i,j] = \begin{cases} 0 & \text{if } i = 0 \text{ or } j = 0 \\ C[i-1,j-1] + 1 & \text{if } X[i] = Y[j] \text{ and } i,j > 0 \\ \max\{C[i,j-1], C[i-1,j]\} & \text{if } X[i] \neq Y[j] \text{ and } i,j > 0 \end{cases}$$

# Example

X    A   C   G   G   A

Y    A   C   T   G

Y

A   C   T   G

X  
A  
C  
G  
G  
A

0	0	0	0	0
0	1	1	1	1
0	1	2	2	2
0	1	2	2	3
0	1	2	2	3
0	1	2	2	3

- Once we've filled this in, we can work backwards.
- A diagonal jump means that we found an element of the LCS!

This 3 came from that 2 – we found a match!

$$C[i,j] = \begin{cases} 0 & \text{if } i = 0 \text{ or } j = 0 \\ C[i-1,j-1] + 1 & \text{if } X[i] = Y[j] \text{ and } i,j > 0 \\ \max\{C[i,j-1], C[i-1,j]\} & \text{if } X[i] \neq Y[j] \text{ and } i,j > 0 \end{cases}$$

# Example

X    A   C   G   G   A

Y    A   C   T   G

Y

A   C   T   G

X  
A  
C  
G  
G  
A

0	0	0	0	0
0	1	1	1	1
0	1	2	2	2
0	1	2	2	3
0	1	2	2	3
0	1	2	2	3

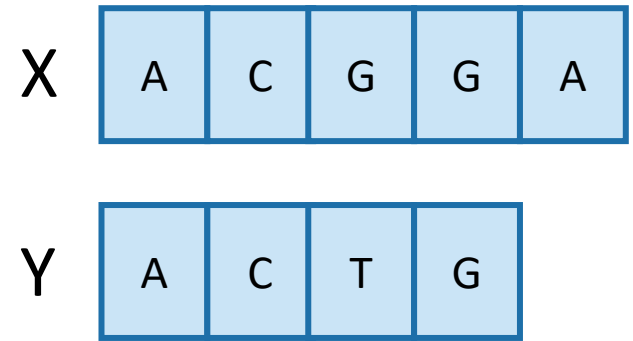
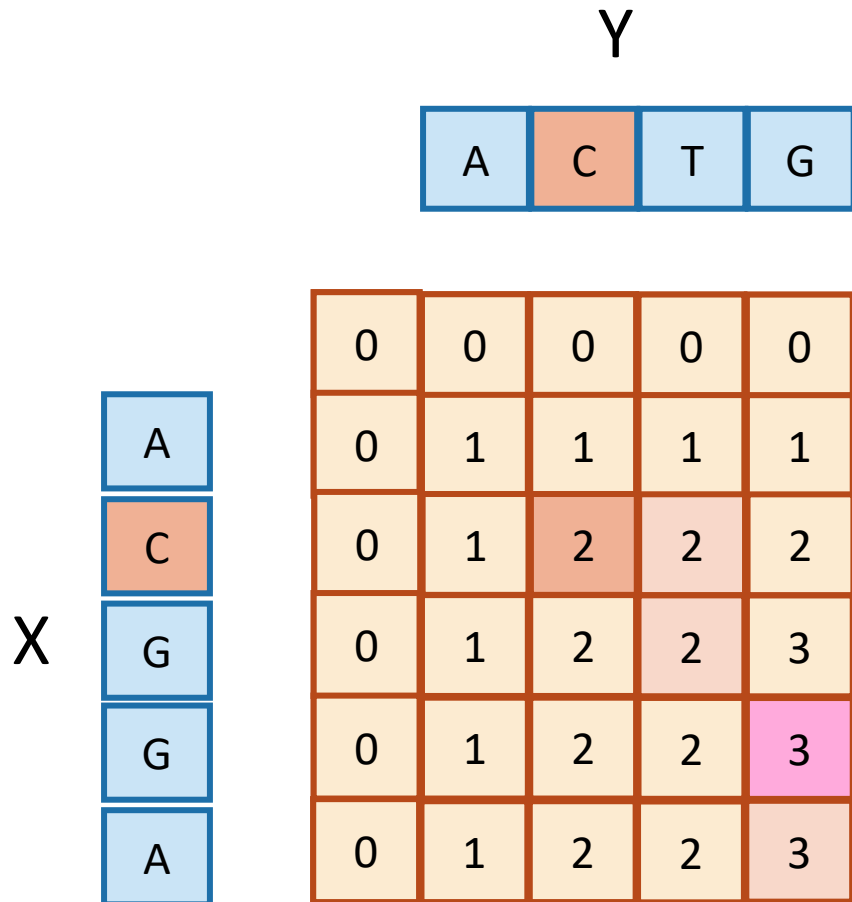
- Once we've filled this in, we can work backwards.
- A diagonal jump means that we found an element of the LCS!

That 2 may as well have come from this other 2.

G

$$C[i, j] = \begin{cases} 0 & \text{if } i = 0 \text{ or } j = 0 \\ C[i - 1, j - 1] + 1 & \text{if } X[i] = Y[j] \text{ and } i, j > 0 \\ \max\{C[i, j - 1], C[i - 1, j]\} & \text{if } X[i] \neq Y[j] \text{ and } i, j > 0 \end{cases}$$

# Example

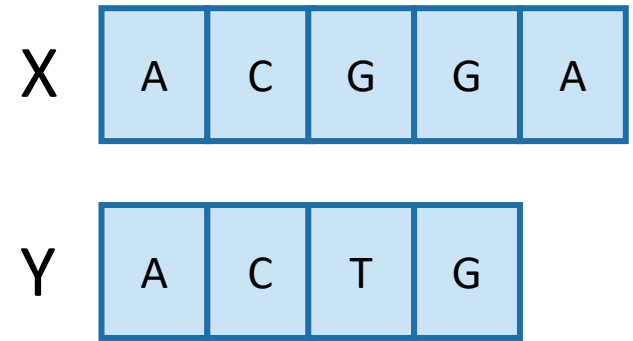
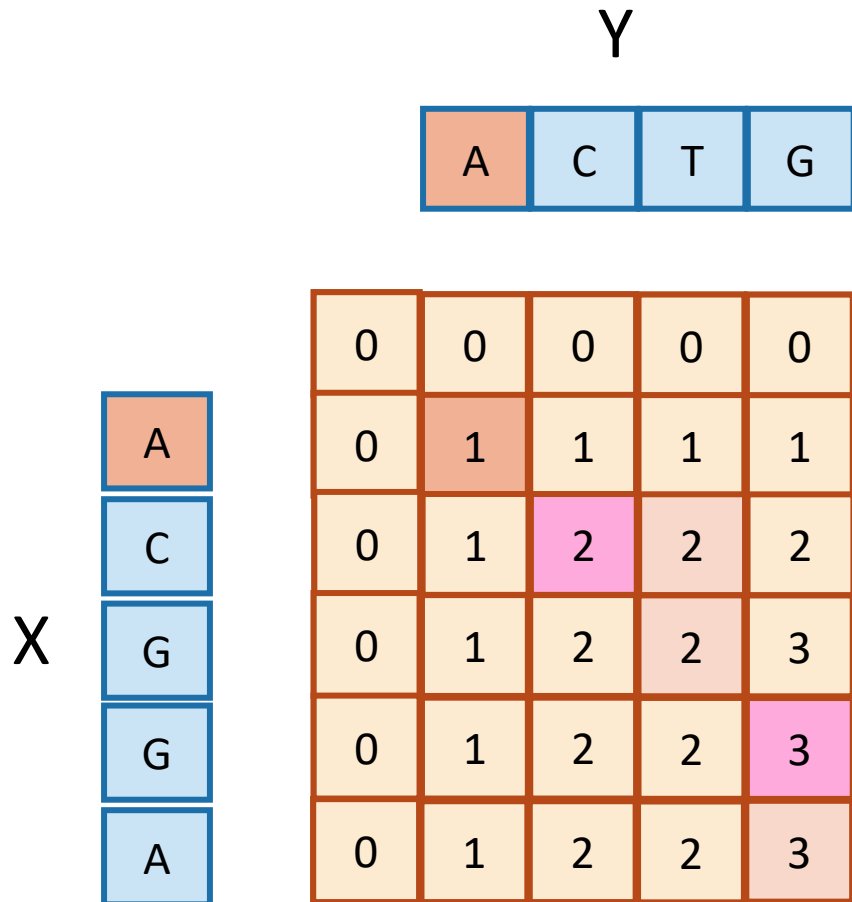


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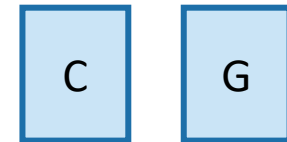


$$C[i, j] = \begin{cases} 0 & \text{if } i = 0 \text{ or } j = 0 \\ C[i - 1, j - 1] + 1 & \text{if } X[i] = Y[j] \text{ and } i, j > 0 \\ \max\{C[i, j - 1], C[i - 1, j]\} & \text{if } X[i] \neq Y[j] \text{ and } i, j > 0 \end{cases}$$

# Example

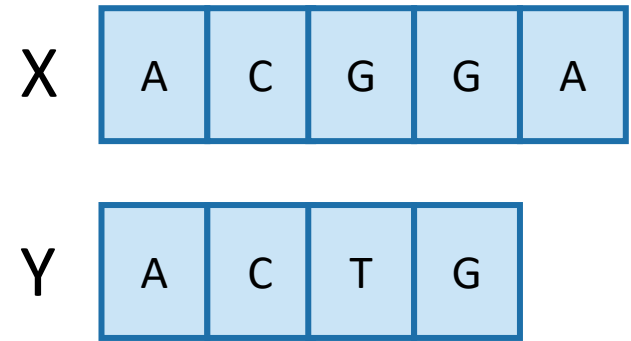
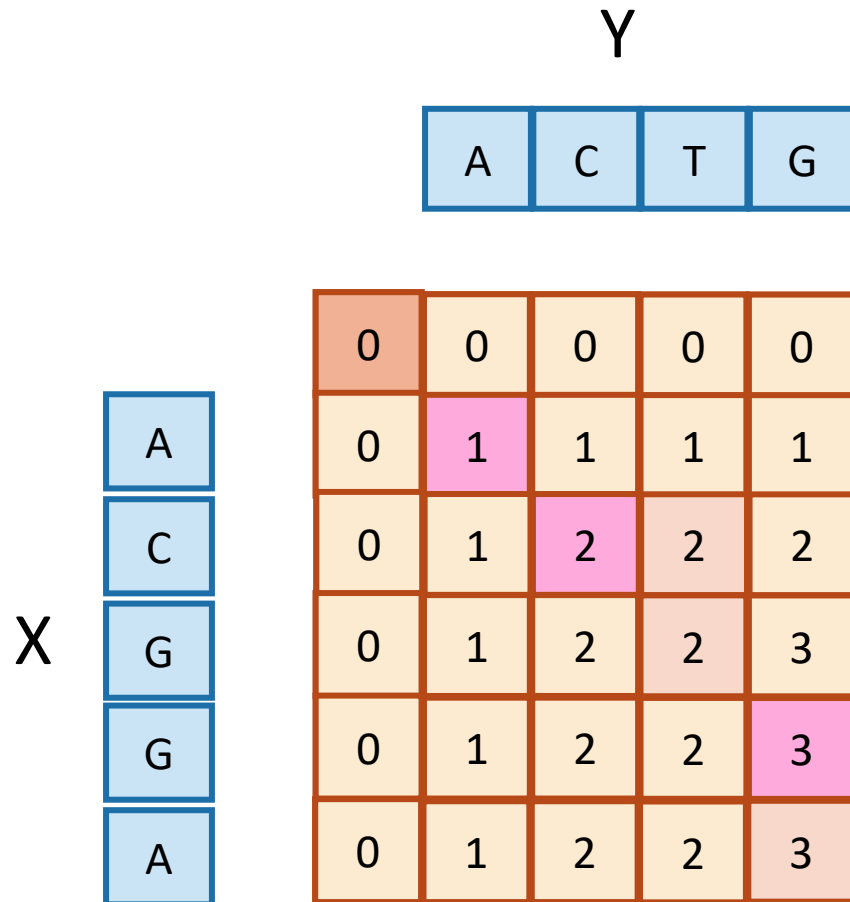


- Once we've filled this in, we can work backwards.
- A diagonal jump means that we found an element of the LCS!

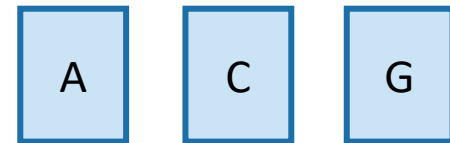


$$C[i, j] = \begin{cases} 0 & \text{if } i = 0 \text{ or } j = 0 \\ C[i - 1, j - 1] + 1 & \text{if } X[i] = Y[j] \text{ and } i, j > 0 \\ \max\{C[i, j - 1], C[i - 1, j]\} & \text{if } X[i] \neq Y[j] \text{ and } i, j > 0 \end{cases}$$

# Example



- Once we've filled this in, we can work backwards.
- A diagonal jump means that we found an element of the LCS!



**This is the LCS!**

$$C[i, j] = \begin{cases} 0 & \text{if } i = 0 \text{ or } j = 0 \\ C[i - 1, j - 1] + 1 & \text{if } X[i] = Y[j] \text{ and } i, j > 0 \\ \max\{C[i, j - 1], C[i - 1, j]\} & \text{if } X[i] \neq Y[j] \text{ and } i, j > 0 \end{cases}$$

# Finding an LCS

- Good exercise to write out pseudocode for what we just saw!
  - Or you can find it in CLRS.
- Takes time  $O(mn)$  to fill the table
- Takes time  $O(n + m)$  on top of that to recover the LCS
  - We walk up and left in an  $n$ -by- $m$  array
  - We can only do that for  $n + m$  steps.
- Altogether, we can find  $\text{LCS}(X,Y)$  in time  $O(mn)$ .

# Recipe for applying Dynamic Programming

- **Step 1:** Identify optimal substructure.
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- **Step 5:** If needed, code this up like a reasonable person.



# Our approach actually isn't so bad

- If we are only interested in the length of the LCS we can do a bit better on space:
  - Since we go across the table one-row-at-a-time, we can only keep two rows if we want.
- If we want to recover the LCS, we need to keep the whole table.
- Can we do better than  $O(mn)$  time?
  - A bit better.
    - By a log factor or so.
  - But doing much better (polynomially better) is an open problem!
    - If you can do it let me know :D

# What have we learned?

- We can find  $\text{LCS}(X,Y)$  in time  $O(nm)$ 
  - if  $|Y|=n$ ,  $|X|=m$
- We went through the steps of coming up with a dynamic programming algorithm.
  - We kept a 2-dimensional table, breaking down the problem by decrementing the length of  $X$  and  $Y$ .

# Example 2: Knapsack Problem

- We have  $n$  items with weights and values:

Item:					
Weight:	6	2	4	3	11
Value:	20	8	14	13	35

- And we have a knapsack:
  - it can only carry so much weight:



Capacity: 10



Capacity: 10

Item:



Weight:

6

2

4

3

11

Value:

20

8

14

13

35

## • Unbounded Knapsack:

- Suppose I have **infinite copies** of all of the items.
- What's the **most valuable way** to fill the knapsack?



Total weight: 10

Total value: 42

## • 0/1 Knapsack:

- Suppose I have **only one copy** of each item.
- What's the **most valuable way** to fill the knapsack?



Total weight: 9

Total value: 35

# Some notation

Item:



Weight:

$W_1$

$W_2$

$W_3$

...

$W_n$

Value:

$V_1$

$V_2$


$V_3$

$V_n$



Capacity:  $W$

# Recipe for applying Dynamic Programming

- **Step 1:** Identify optimal substructure. 
- **Step 2:** Find a recursive formulation for the value of the optimal solution.
- **Step 3:** Use dynamic programming to find the value of the optimal solution.
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- **Step 5:** If needed, code this up like a reasonable person.

# Optimal substructure

- Sub-problems:
  - Unbounded Knapsack with a smaller knapsack.
  - $K[x]$  = value you can fit in a knapsack of capacity  $x$



First solve the  
problem for  
small knapsacks



Then larger  
knapsacks



Then larger  
knapsacks

# Optimal substructure



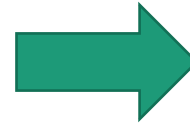
item i

- Suppose this is an optimal solution for capacity  $x$ :

Say that the optimal solution contains at least one copy of item i.

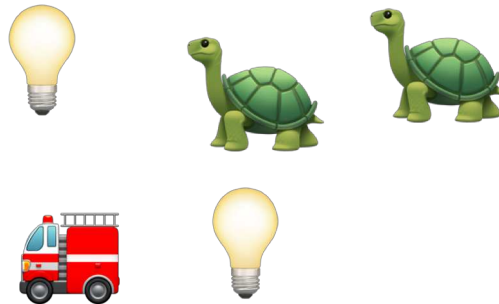


Weight  $w_i$   
Value  $v_i$



Capacity  $x$   
Value  $V$

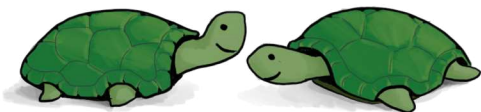
- Then this optimal for capacity  $x - w_i$ :



Capacity  $x - w_i$   
Value  $V - v_i$

**Why?**

1 minute think  
1 minute pair+share



# Optimal substructure



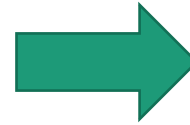
item  $i$

- Suppose this is an optimal solution for capacity  $x$ :

Say that the optimal solution contains at least one copy of item  $i$ .

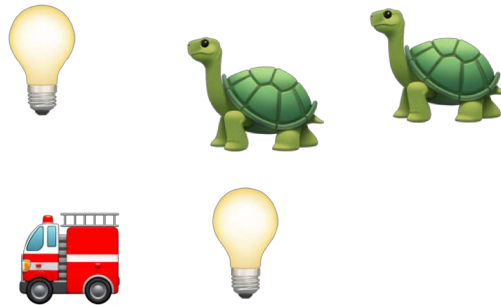


Weight  $w_i$   
Value  $v_i$



Capacity  $x$   
Value  $V$

- Then this optimal for capacity  $x - w_i$ :



Capacity  $x - w_i$   
Value  $V - v_i$

If I could do better than the second solution, then adding a turtle to that improvement would improve the first solution.

# Recipe for applying Dynamic Programming

- **Step 1:** Identify optimal substructure.
- **Step 2:** Find a recursive formulation for the value of the optimal solution.
- **Step 3:** Use dynamic programming to find the value of the optimal solution.
- **Step 4:** If needed, keep track of some additional info so that the algorithm from Step 3 can find the actual solution.
- **Step 5:** If needed, code this up like a reasonable person.



# Recursive relationship

- Let  $K[x]$  be the **optimal value** for capacity  $x$ .

$$K[x] = \max_i \left\{ \text{[Image of a colorful knapsack]} + \text{[Image of a green turtle]} \right\}$$

The maximum is over  
all  $i$  so that  $w_i \leq x$ .

Optimal way to  
fill the smaller  
knapsack

The value of  
item  $i$ .

$$K[x] = \max_i \left\{ K[x - w_i] + v_i \right\}$$

- (And  $K[x] = 0$  if the maximum is empty).
  - That is, if there are no  $i$  so that  $w_i \leq x$

# Recipe for applying Dynamic Programming

- **Step 1:** Identify optimal substructure.
- **Step 2:** Find a recursive formulation for the value of the optimal solution.
- **Step 3:** Use dynamic programming to find the value of the optimal solution.
- **Step 4:** If needed, keep track of some additional info so that the algorithm from Step 3 can find the actual solution.
- **Step 5:** If needed, code this up like a reasonable person.

# Let's write a bottom-up DP algorithm

- UnboundedKnapsack(**W**, **n**, **weights**, **values**):

- $K[0] = 0$

- **for**  $x = 1, \dots, W$ :

- $K[x] = 0$

- **for**  $i = 1, \dots, n$ :

- **if**  $w_i \leq x$ :

- $K[x] = \max\{ K[x], K[x - w_i] + v_i \}$

- **return**  $K[W]$

Running time:  $O(nW)$

$$K[x] = \max_i \{ \text{🎒} + \text{🐢} \}$$
$$= \max_i \{ K[x - w_i] + v_i \}$$

Why does this work?

Because our recursive relationship makes sense.

# Can we do better?

- Writing down  $W$  takes  $\log(W)$  bits.
- Writing down all  $n$  weights takes at most  $n\log(W)$  bits.
- Input size:  $n\log(W)$ .
  - Maybe we could have an algorithm that runs in time  $O(n\log(W))$  instead of  $O(nW)$ ?
  - Or even  $O(n^{1000000} \log^{1000000}(W))$ ?
- Open problem!
  - (But probably the answer is **no**...otherwise  $P = NP$ )

# Recipe for applying Dynamic Programming

- **Step 1:** Identify optimal substructure.
- **Step 2:** Find a recursive formulation for the value of the optimal solution.
- **Step 3:** Use dynamic programming to find the value of the optimal solution.
- **Step 4:** If needed, keep track of some additional info so that the algorithm from Step 3 can find the actual solution.
- **Step 5:** If needed, code this up like a reasonable person.



# Let's write a bottom-up DP algorithm

- UnboundedKnapsack(**W**, **n**, **weights**, **values**):
  - $K[0] = 0$
  - **for**  $x = 1, \dots, W$ :
    - $K[x] = 0$
    - **for**  $i = 1, \dots, n$ :
      - **if**  $w_i \leq x$ :
        - $K[x] = \max\{ K[x], K[x - w_i] + v_i \}$
  - **return**  $K[W]$

$$K[x] = \max_i \{ \text{🎒} + \text{🐢} \}$$
$$= \max_i \{ K[x - w_i] + v_i \}$$

# Let's write a bottom-up DP algorithm

- UnboundedKnapsack( $W$ ,  $n$ ,  $\text{weights}$ ,  $\text{values}$ ):
  - $K[0] = 0$
  - $\text{ITEMS}[0] = \emptyset$
  - **for**  $x = 1, \dots, W$ :
    - $K[x] = 0$
    - **for**  $i = 1, \dots, n$ :
      - **if**  $w_i \leq x$ :
        - $K[x] = \max\{ K[x], K[x - w_i] + v_i \}$
        - If  $K[x]$  was updated:
          - $\text{ITEMS}[x] = \text{ITEMS}[x - w_i] \cup \{ \text{item } i \}$
  - **return**  $\text{ITEMS}[W]$

$$\begin{aligned} K[x] &= \max_i \{ \text{backpack} + \text{turtle} \} \\ &= \max_i \{ K[x - w_i] + v_i \} \end{aligned}$$

# Example

	0	1	2	3	4
K	0				
ITEMS					

- UnboundedKnapsack( $W, n, \text{weights}, \text{values}$ ):
  - $K[0] = 0$
  - $\text{ITEMS}[0] = \emptyset$
  - for  $x = 1, \dots, W$ :
    - $K[x] = 0$
    - for  $i = 1, \dots, n$ :
      - if  $w_i \leq x$ :
        - $K[x] = \max\{K[x], K[x - w_i] + v_i\}$
        - If  $K[x]$  was updated:
          - $\text{ITEMS}[x] = \text{ITEMS}[x - w_i] \cup \{\text{item } i\}$
  - return  $\text{ITEMS}[W]$

Item:



Weight:

1

2

3

Value:

1


4

6



Capacity: 4

# Example

	0	1	2	3	4
K	0	1			
ITEMS					

$ITEMS[1] = ITEMS[0] +$  

- UnboundedKnapsack( $W, n, weights, values$ ):
  - $K[0] = 0$
  - $ITEMS[0] = \emptyset$
  - for  $x = 1, \dots, W$ :
    - $K[x] = 0$
    - for  $i = 1, \dots, n$ :
      - if  $w_i \leq x$ :
        - $K[x] = \max\{K[x], K[x - w_i] + v_i\}$
        - If  $K[x]$  was updated:
          - $ITEMS[x] = ITEMS[x - w_i] \cup \{item\ i\}$
  - return  $ITEMS[W]$

Item:



Weight:

1

2

3

Value:

1




4

6



Capacity: 4

# Example

	0	1	2	3	4
K	0	1	2		
ITEMS			 		

ITEMS[2] = ITEMS[1] + 

- UnboundedKnapsack( $W, n, \text{weights}, \text{values}$ ):
  - $K[0] = 0$
  - ITEMS[0] =  $\emptyset$
  - for  $x = 1, \dots, W$ :
    - $K[x] = 0$
    - for  $i = 1, \dots, n$ :
      - if  $w_i \leq x$ :
        - $K[x] = \max\{K[x], K[x - w_i] + v_i\}$
        - If  $K[x]$  was updated:
          - ITEMS[x] = ITEMS[x -  $w_i$ ]  $\cup$  { item  $i$  }
  - return ITEMS[W]

Item:



Weight:

1

2

3

Value:

1



4

6



Capacity: 4

# Example

	0	1	2	3	4
K	0	1	4		
ITEMS					

ITEMS[2] = ITEMS[0] + 

- UnboundedKnapsack( $W, n, \text{weights}, \text{values}$ ):
  - $K[0] = 0$
  - ITEMS[0] =  $\emptyset$
  - for  $x = 1, \dots, W$ :
    - $K[x] = 0$
    - for  $i = 1, \dots, n$ :
      - if  $w_i \leq x$ :
        - $K[x] = \max\{K[x], K[x - w_i] + v_i\}$
        - If  $K[x]$  was updated:
          - ITEMS[x] = ITEMS[x -  $w_i$ ]  $\cup$  { item  $i$  }
  - return ITEMS[W]

Item:



Weight:

1

2

3

Value:

1





4

6



Capacity: 4

# Example

	0	1	2	3	4
K	0	1	4	5	
ITEMS				 	

$ITEMS[3] = ITEMS[2] +$  

- UnboundedKnapsack( $W, n, weights, values$ ):
  - $K[0] = 0$
  - $ITEMS[0] = \emptyset$
  - for  $x = 1, \dots, W$ :
    - $K[x] = 0$
    - for  $i = 1, \dots, n$ :
      - if  $w_i \leq x$ :
        - $K[x] = \max\{K[x], K[x - w_i] + v_i\}$
        - If  $K[x]$  was updated:
          - $ITEMS[x] = ITEMS[x - w_i] \cup \{item\ i\}$
  - return  $ITEMS[W]$

Item:



Weight:

1

2

3

Value:

1




4

6



Capacity: 4

# Example

	0	1	2	3	4
K	0	1	4	6	
ITEMS					

ITEMS[3] = ITEMS[0] + 

- UnboundedKnapsack( $W, n, \text{weights}, \text{values}$ ):
  - $K[0] = 0$
  - ITEMS[0] =  $\emptyset$
  - for  $x = 1, \dots, W$ :
    - $K[x] = 0$
    - for  $i = 1, \dots, n$ :
      - if  $w_i \leq x$ :
        - $K[x] = \max\{K[x], K[x - w_i] + v_i\}$
        - If  $K[x]$  was updated:
          - ITEMS[x] = ITEMS[x -  $w_i$ ]  $\cup$  { item  $i$  }
  - return ITEMS[W]

Item:



Weight:

1

2

3

Value:

1






4

6



Capacity: 4

# Example

	0	1	2	3	4
K	0	1	4	6	7
ITEMS					 

$\text{ITEMS}[4] = \text{ITEMS}[3] +$  

- UnboundedKnapsack( $W, n, \text{weights}, \text{values}$ ):
  - $K[0] = 0$
  - $\text{ITEMS}[0] = \emptyset$
  - for  $x = 1, \dots, W$ :
    - $K[x] = 0$
    - for  $i = 1, \dots, n$ :
      - if  $w_i \leq x$ :
        - $K[x] = \max\{K[x], K[x - w_i] + v_i\}$
        - If  $K[x]$  was updated:
          - $\text{ITEMS}[x] = \text{ITEMS}[x - w_i] \cup \{\text{item } i\}$
  - return  $\text{ITEMS}[W]$

Item:



Weight:

1

2

3

Value:

1






4

6



Capacity: 4

# Example

	0	1	2	3	4
K	0	1	4	6	8
ITEMS					 

ITEMS[4] = ITEMS[2] + 

- UnboundedKnapsack( $W, n, \text{weights}, \text{values}$ ):
  - $K[0] = 0$
  - ITEMS[0] =  $\emptyset$
  - for  $x = 1, \dots, W$ :
    - $K[x] = 0$
    - for  $i = 1, \dots, n$ :
      - if  $w_i \leq x$ :
        - $K[x] = \max\{K[x], K[x - w_i] + v_i\}$
        - If  $K[x]$  was updated:
          - ITEMS[x] = ITEMS[x -  $w_i$ ]  $\cup$  { item  $i$  }
  - return ITEMS[W]

Item:



Weight:

1

2

3

Value:

1

4

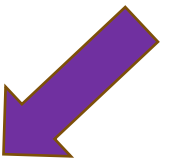
6



Capacity: 4

# Recipe for applying Dynamic Programming

- **Step 1:** Identify optimal substructure.
- **Step 2:** Find a recursive formulation for the value of the optimal solution.
- **Step 3:** Use dynamic programming to find the value of the optimal solution.
- **Step 4:** If needed, keep track of some additional info so that the algorithm from Step 3 can find the actual solution.
- **Step 5:** If needed, code this up like a reasonable person.



(Pass)

# What have we learned?

- We can solve unbounded knapsack in time  $O(nW)$ .
  - If there are  $n$  items and our knapsack has capacity  $W$ .
- We again went through the steps to create DP solution:
  - We kept a one-dimensional table, creating smaller problems by making the knapsack smaller.



Capacity: 10

Item:



Weight:

6

2

4

3

11

Value:

20

8

14

13

35

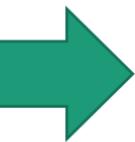
- Unbounded Knapsack:

- Suppose I have **infinite copies** of all of the items.
- What's the **most valuable way to fill the knapsack?**



Total weight: 10

Total value: 42



- 0/1 Knapsack:


- Suppose I have **only one copy** of each item.
- What's the **most valuable way to fill the knapsack?**



Total weight: 9

Total value: 35

# Recipe for applying Dynamic Programming

- **Step 1:** Identify optimal substructure. 
- **Step 2:** Find a recursive formulation for the value of the optimal solution.
- **Step 3:** Use dynamic programming to find the value of the optimal solution.
- **Step 4:** If needed, keep track of some additional info so that the algorithm from Step 3 can find the actual solution.
- **Step 5:** If needed, code this up like a reasonable person.

# Optimal substructure: try 1

- Sub-problems:
  - Unbounded Knapsack with a smaller knapsack.



First solve the  
problem for  
small knapsacks



Then larger  
knapsacks



Then larger  
knapsacks

# This won't quite work...

- We are only allowed **one copy of each item**.
- The sub-problem needs to “know” what items we’ve used and what we haven’t.



# Optimal substructure: try 2

- Sub-problems:
  - 0/1 Knapsack with fewer items.

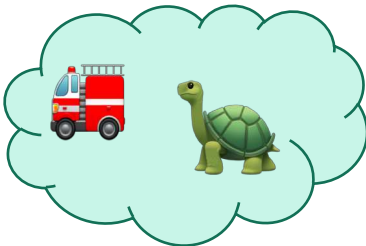


First solve the problem with few items



We'll still increase the size of the knapsacks.

Then more items



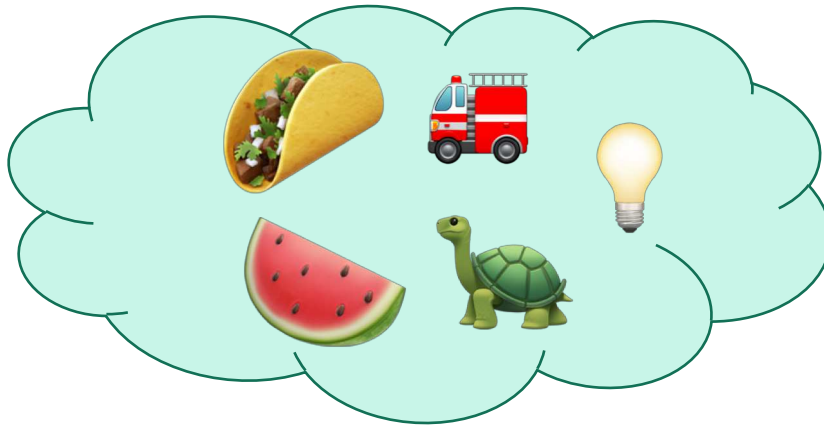
Then yet more items



*(We'll keep a two-dimensional table).*

# Our sub-problems:

- Indexed by  $x$  and  $j$



First  $j$  items

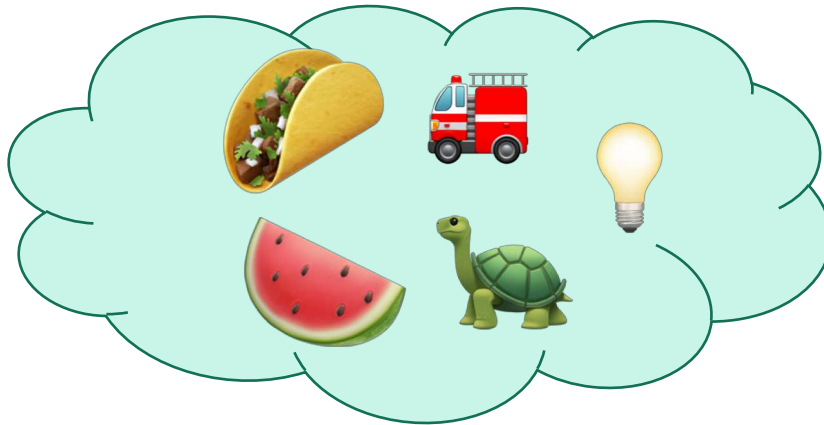


Capacity  $x$

$K[x,j]$  = optimal solution for a knapsack of size  $x$  using only the first  $j$  items.

# Relationship between sub-problems

- Want to write  $K[x,j]$  in terms of smaller sub-problems.



First  $j$  items



Capacity  $x$

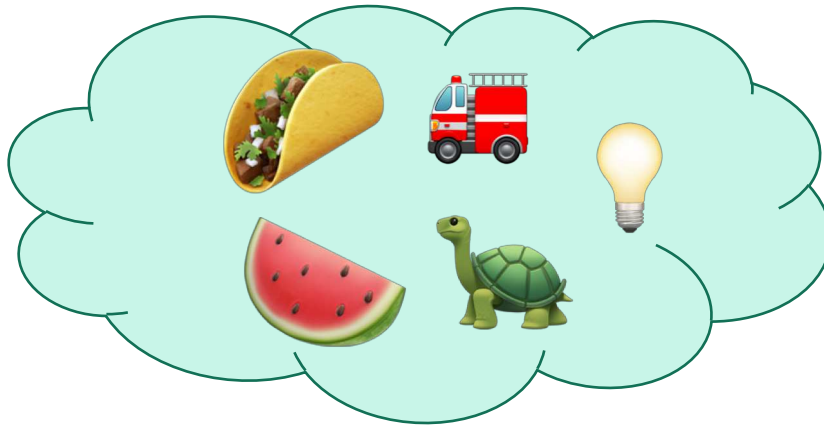
$K[x,j]$  = optimal solution for a knapsack of size  $x$  using only the first  $j$  items.

# Two cases



item j

- **Case 1:** Optimal solution for  $j$  items does not use item  $j$ .
- **Case 2:** Optimal solution for  $j$  items does use item  $j$ .



First  $j$  items



Capacity  $x$

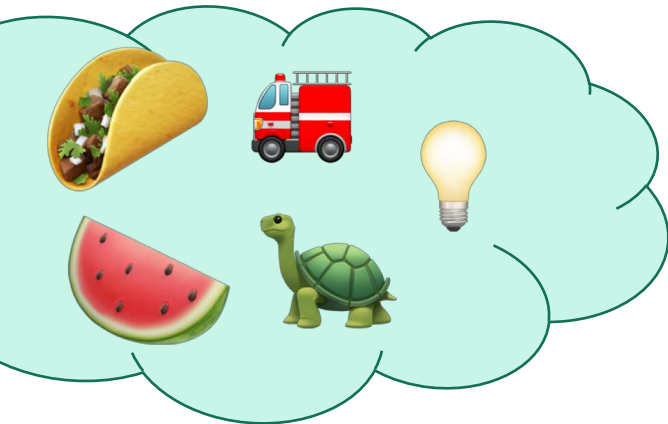
$K[x,j]$  = optimal solution for a knapsack of size  $x$  using only the first  $j$  items.

# Two cases

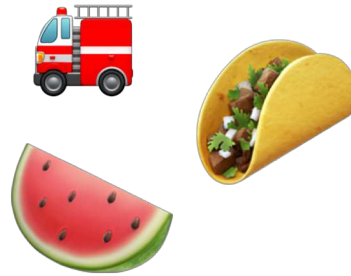


item  $j$

- **Case 1:** Optimal solution for  $j$  items does not use item  $j$ .



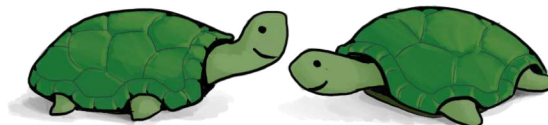
First  $j$  items



Capacity  $x$   
Value  $V$

Use only the first  $j$  items

What lower-indexed  
problem should we solve  
to solve this problem?

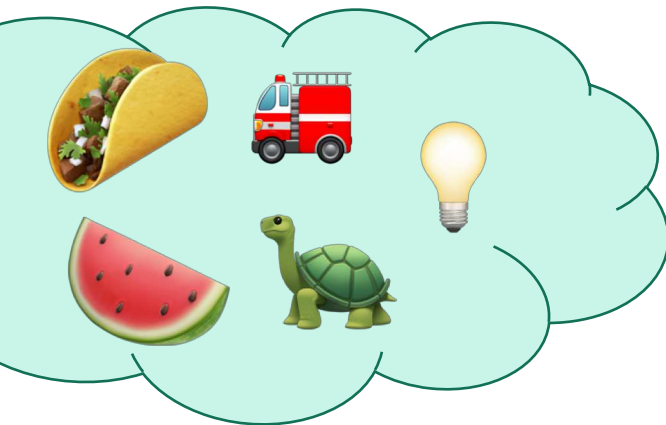


# Two cases

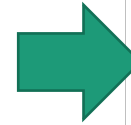
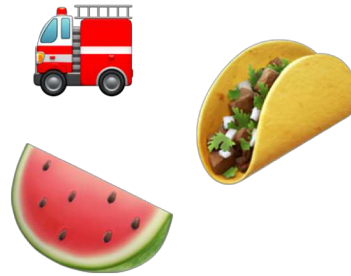


item j

- **Case 1:** Optimal solution for  $j$  items does not use item  $j$ .



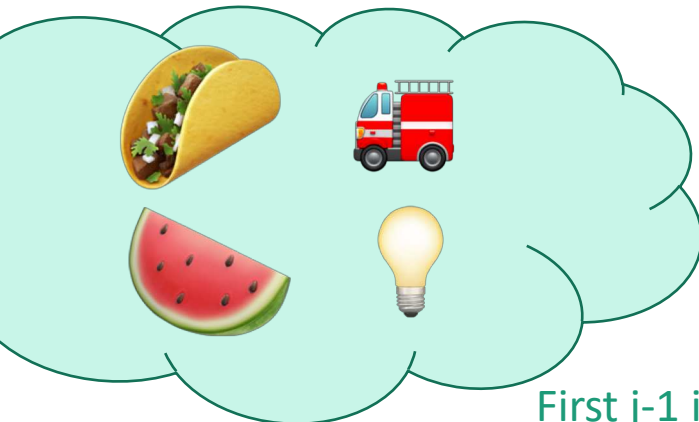
First  $j$  items



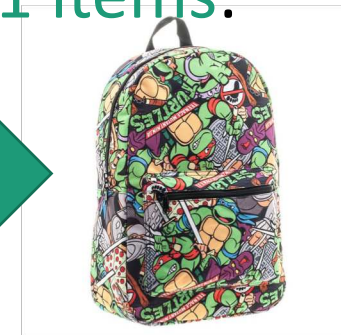
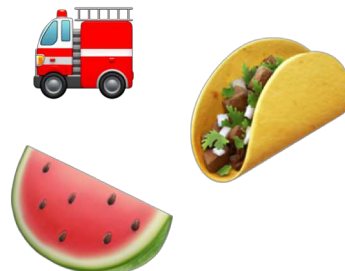
Capacity  $x$   
Value  $V$

Use only the first  $j$  items

- Then this is an optimal solution for  $j-1$  items:



First  $j-1$  items



Capacity  $x$   
Value  $V$

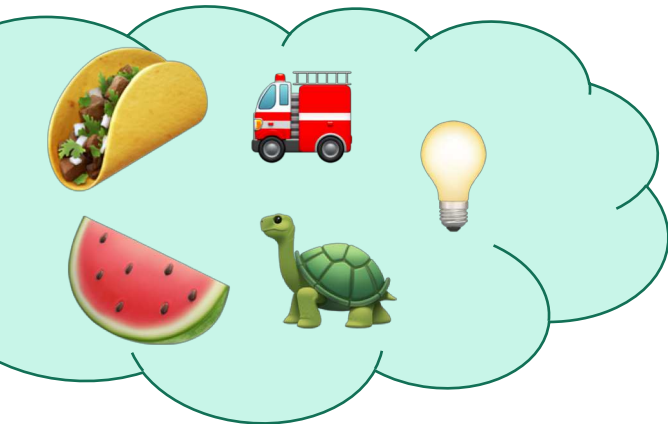
Use only the first  $j-1$  items.

# Two cases

- **Case 2:** Optimal solution for  $j$  items uses item  $j$ .



item  $j$



First  $j$  items



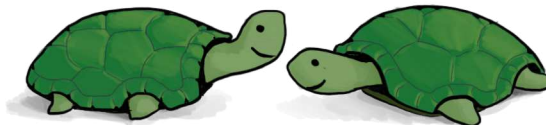
Weight  $w_j$   
Value  $v_j$



Capacity  $x$   
Value  $V$

Use only the first  $j$  items

What lower-indexed  
problem should we solve  
to solve this problem?

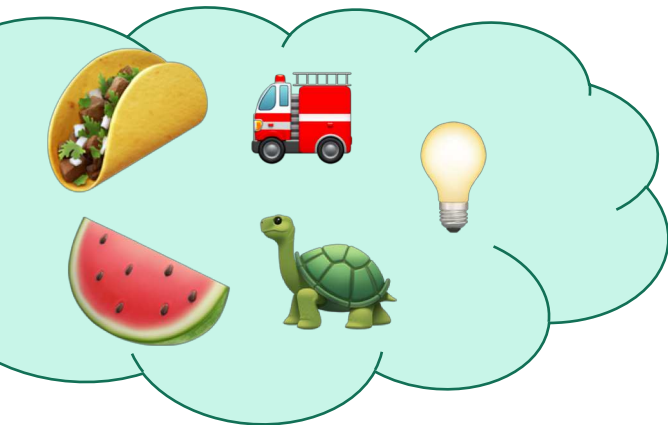


# Two cases



item  $j$

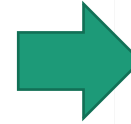
- **Case 2:** Optimal solution for  $j$  items uses item  $j$ .



First  $j$  items



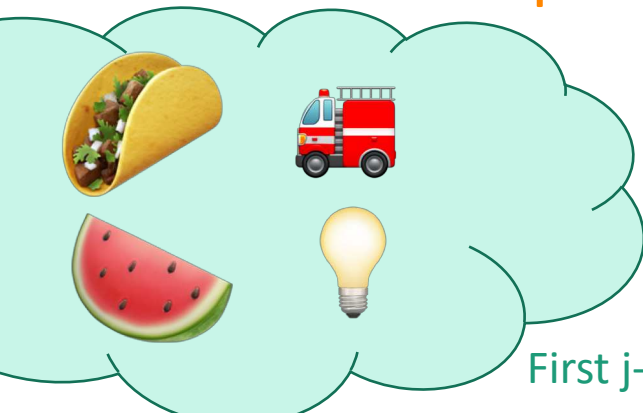
Weight  $w_j$   
Value  $v_j$



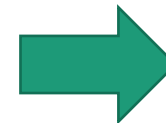
Capacity  $x$   
Value  $V$

Use only the first  $j$  items

- Then this is an optimal solution for  $j-1$  items and a smaller knapsack:



First  $j-1$  items



Capacity  $x - w_j$   
Value  $V - v_j$

Use only the first  $j-1$  items.

# Recipe for applying Dynamic Programming

- **Step 1:** Identify optimal substructure.
- **Step 2:** Find a recursive formulation for the value of the optimal solution.
- **Step 3:** Use dynamic programming to find the value of the optimal solution.
- **Step 4:** If needed, keep track of some additional info so that the algorithm from Step 3 can find the actual solution.
- **Step 5:** If needed, code this up like a reasonable person.



# Recursive relationship

- Let  $K[x,j]$  be the optimal value for:
  - capacity  $x$ ,
  - with  $j$  items.

$$K[x,j] = \max\{ \text{Case 1} \quad K[x, j-1] \quad , \quad \text{Case 2} \quad K[x - w_j, j-1] + v_j \}$$

Case 1

Case 2

- (And  $K[x,0] = 0$  and  $K[0,j] = 0$ ).

# Recipe for applying Dynamic Programming

- **Step 1:** Identify optimal substructure.
- **Step 2:** Find a recursive formulation for the value of the optimal solution.
- **Step 3:** Use dynamic programming to find the value of the optimal solution.
- **Step 4:** If needed, keep track of some additional info so that the algorithm from Step 3 can find the actual solution.
- **Step 5:** If needed, code this up like a reasonable person.









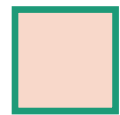
# Bottom-up DP algorithm

- Zero-One-Knapsack( $W, n, w, v$ ):
  - $K[x,0] = 0$  for all  $x = 0, \dots, W$
  - $K[0,i] = 0$  for all  $i = 0, \dots, n$
  - **for**  $x = 1, \dots, W$ :
    - **for**  $j = 1, \dots, n$ :
      - $K[x,j] = K[x, j-1]$  Case 1
      - **if**  $w_j \leq x$ :
        - $K[x,j] = \max\{ K[x,j], K[x - w_j, j-1] + v_j \}$  Case 2
  - **return**  $K[W,n]$

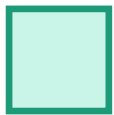
Running time  $O(nW)$

# Example

	x=0	x=1	x=2	x=3
j=0	0	0	0	0
 j=1	0			
  j=2	0			
   j=3	0			



current  
entry



relevant  
previous entry

Item:



Weight:

1

Value:

1



2

4



3

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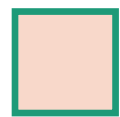


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# Example

	x=0	x=1	x=2	x=3
j=0	0	0	0	0
j=1	0	0		
j=2	0			
j=3	0			



current  
entry



relevant  
previous entry

Item:

Weight:

Value:



1

1



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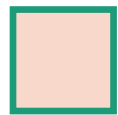
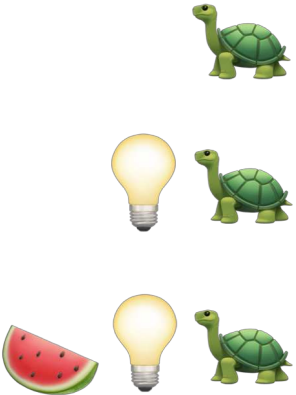


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j=1	0	1		
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j=3	0			



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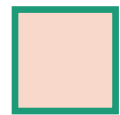
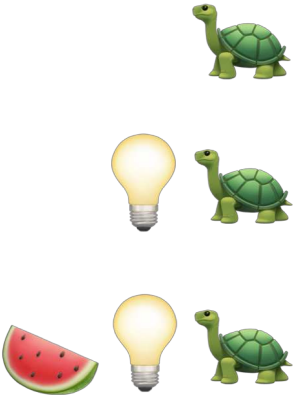


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j=3	0			



current  
entry



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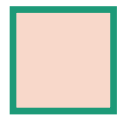


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j=0		0	0	0	0
j=1		0	1 		
j=2	 	0	1 		
j=3	  	0	1 		



current  
entry



relevant  
previous entry

Item:



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j=1		0	1 	0	
j=2	 	0	1 		
j=3	  	0	1 		



current  
entry



relevant  
previous entry

Item:



Weight:

1

Value:

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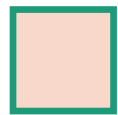


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# Example

		x=0	x=1	x=2	x=3
j=0		0	0	0	0
j=1		0	1 	1 	
j=2	 	0	1 		
j=3	  	0	1 		



current  
entry



relevant  
previous entry

Item:



Weight:

1

Value:

1



2

4



3

6














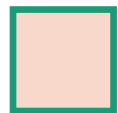
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j=1		0	1 	1 	
j=2	 	0	1 	1 	
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current  
entry



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1

1



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3






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# Example

	x=0	x=1	x=2	x=3
j=0	0	0	0	0
j=1	0	1 	1 	
j=2	0	1 	4 	
j=3	0	1 		



current  
entry



relevant  
previous entry

Item:

Weight:

Value:



1

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6



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		x=0	x=1	x=2	x=3
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j=1		0	1 	1 	
j=2	 	0	1 	4 	
j=3	  	0	1 	4 	



current  
entry



relevant  
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# Example

	x=0	x=1	x=2	x=3
j=0	0	0	0	0
j=1	0	1 	1 	0
j=2	0	1 	4 	
j=3	0	1 	4 	



current  
entry



relevant  
previous entry

Item:

Weight:

Value:



1

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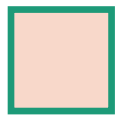


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# Example

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j=1	0	1 	1 	1 
j=2	0	1 	4 	
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current  
entry



relevant  
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current  
entry



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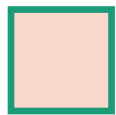


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# Example

	x=0	x=1	x=2	x=3
j=0	0	0	0	0
j=1	0	1 	1 	1 
j=2	0	1 	4 	5  
j=3	0	1 	4 	



current  
entry



relevant  
previous entry

Item:

Weight:

Value:



1

1



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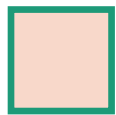


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j=2	0	1 	4 	5  
j=3	0	1 	4 	6 



current  
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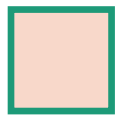


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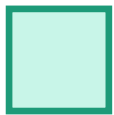
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  - return  $K[W, n]$

So the optimal solution is to put one watermelon in your knapsack!

# Recipe for applying Dynamic Programming

- **Step 1:** Identify optimal substructure.
- **Step 2:** Find a recursive formulation for the value of the optimal solution.
- **Step 3:** Use dynamic programming to find the value of the optimal solution.
- **Step 4:** If needed, keep track of some additional info so that the algorithm from Step 3 can find the actual solution.
- **Step 5:** If needed, code this up like a reasonable person.



You do this one!  
(We did it on the slide in the previous example, just not in the pseudocode!)



# What have we learned?

- We can solve 0/1 knapsack in time  $O(nW)$ .
  - If there are  $n$  items and our knapsack has capacity  $W$ .
- We again went through the steps to create DP solution:
  - We kept a two-dimensional table, creating smaller problems by restricting the set of allowable items.

# Question

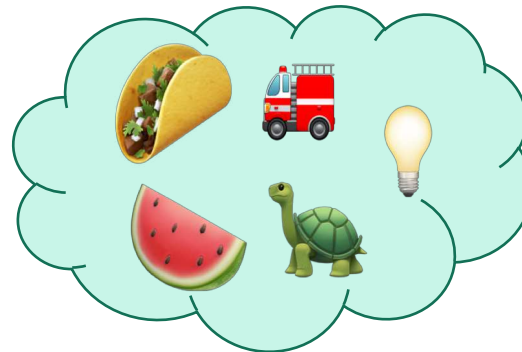
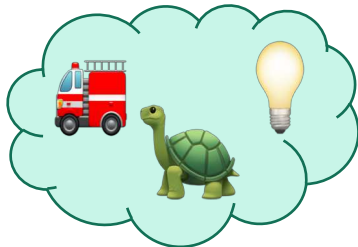
- How did we know which substructure to use in which variant of knapsack?



Answer in retrospect:

This one made sense for unbounded knapsack because it doesn't have any memory of what items have been used.

VS.

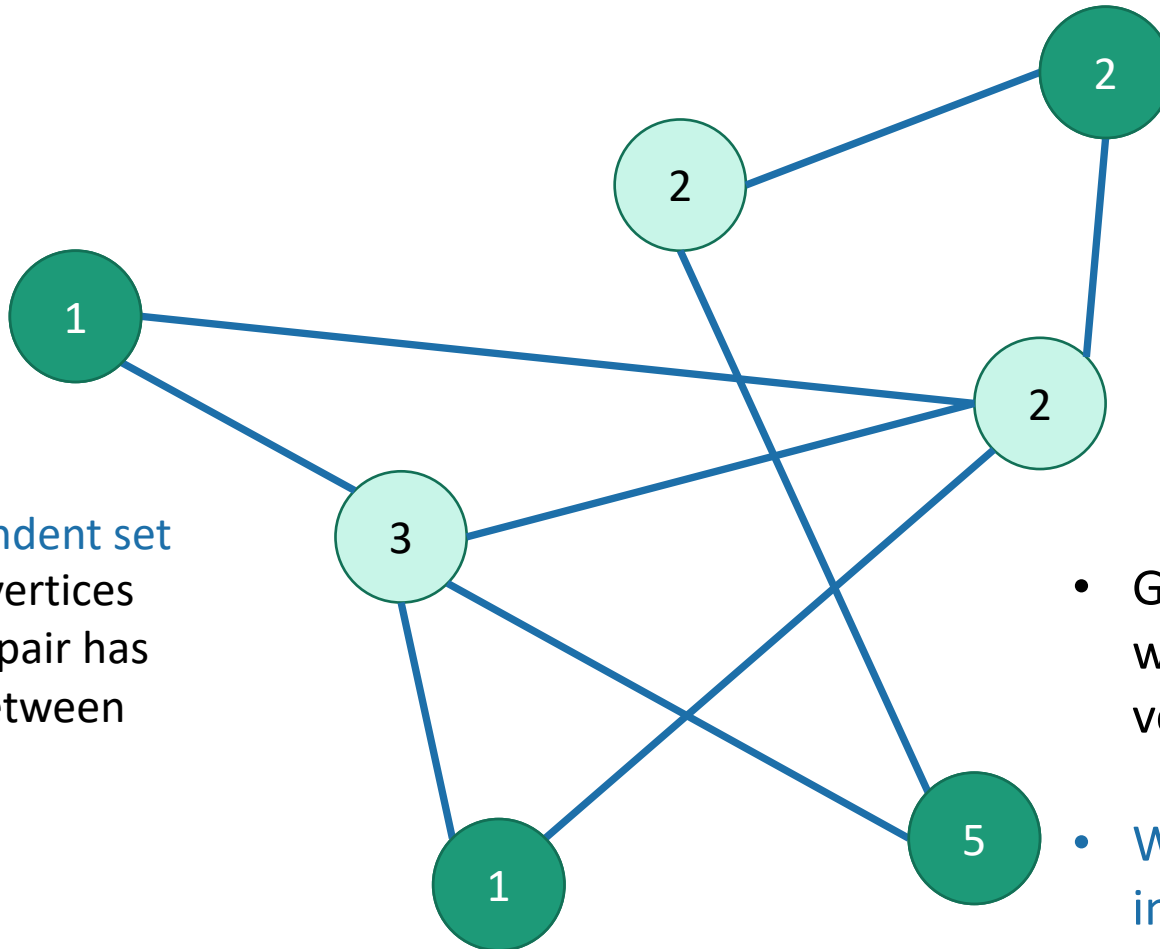


In 0/1 knapsack, we can only use each item once, so it makes sense to leave out one item at a time.

**Operational Answer:** try some stuff, see what works!

# Example 3: Independent Set

if we still have time



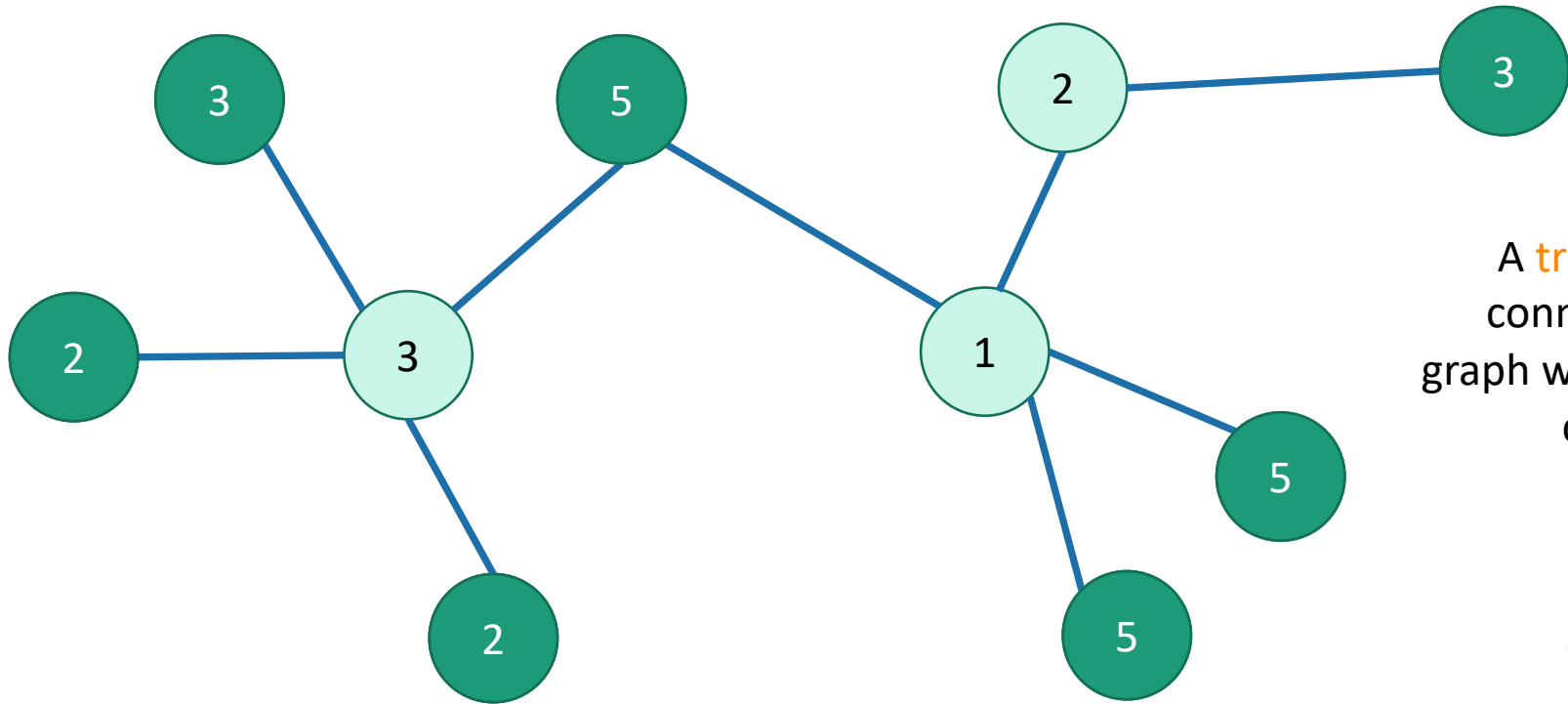
An **independent set** is a set of vertices so that no pair has an edge between them.



- Given a graph with weights on the vertices...
- What is the independent set with the largest weight?

Actually this problem is NP-complete.  
So we are unlikely to find an efficient algorithm

- But if we also assume that the graph is a **tree**...




A tree is a connected graph with no cycles.



## Problem:

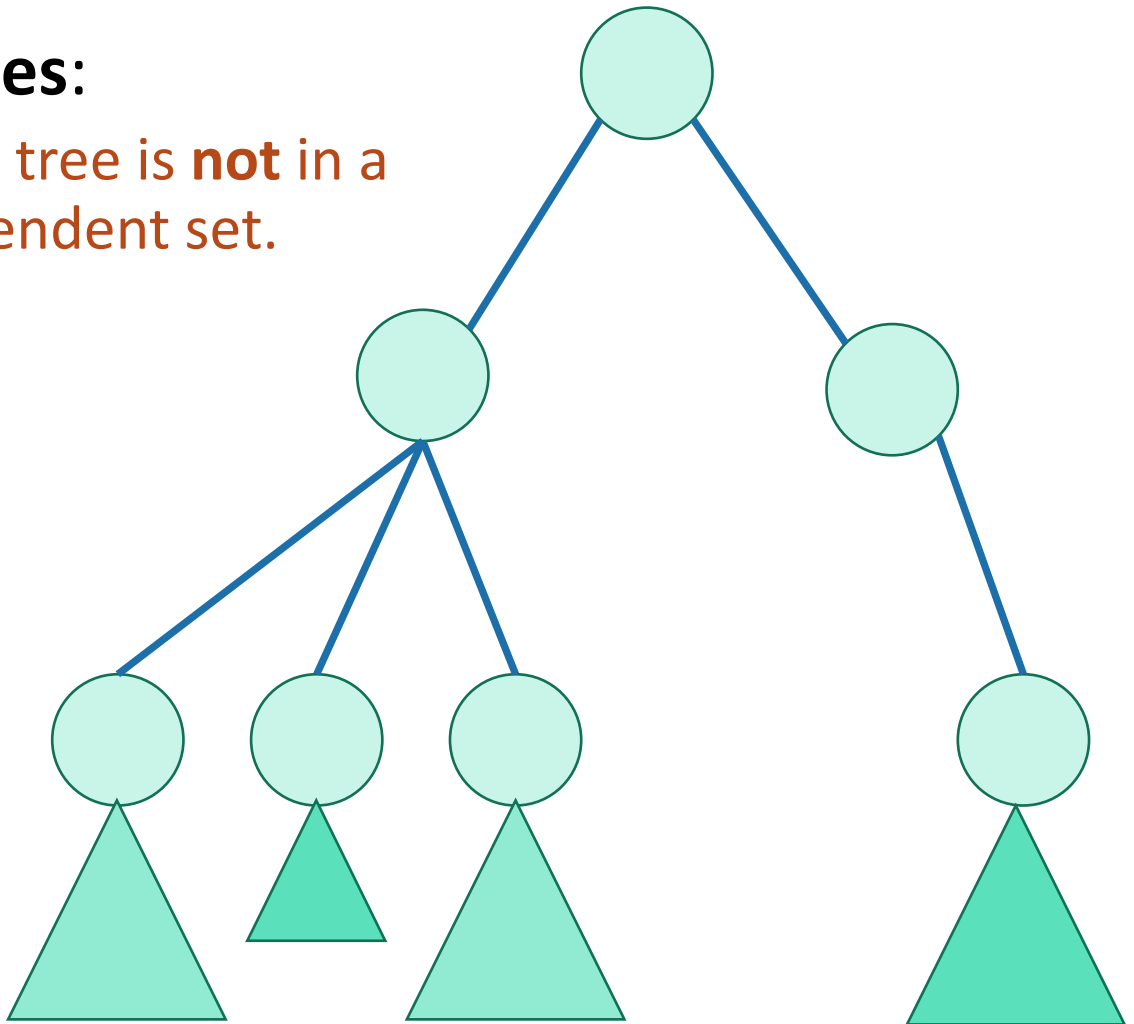
find a maximal independent set in a tree (with vertex weights):

# Recipe for applying Dynamic Programming

- **Step 1:** Identify optimal substructure. 
- **Step 2:** Find a recursive formulation for the value of the optimal solution
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# Optimal substructure

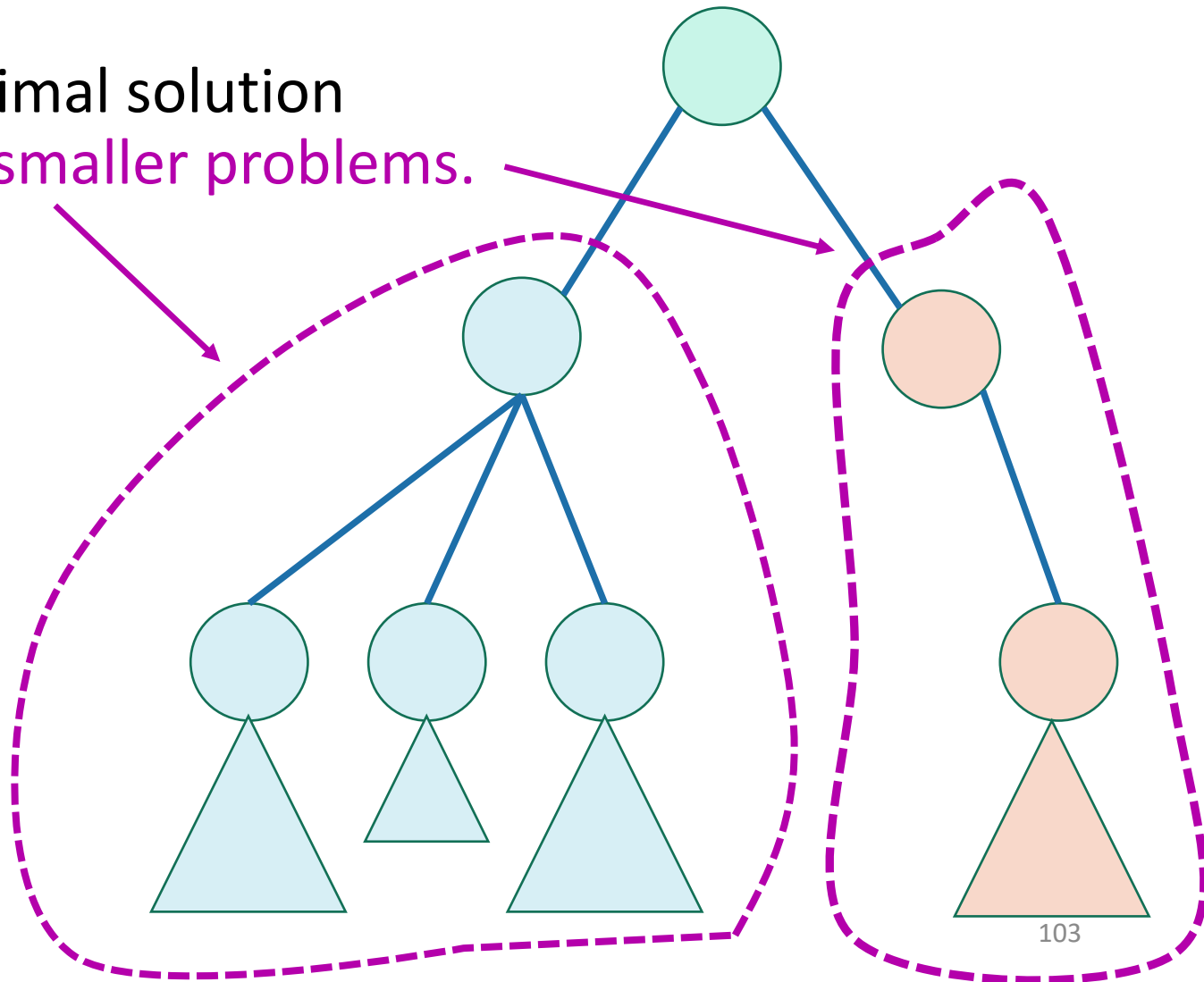
- **Subtrees** are a natural candidate.
- There are **two cases**:
  1. The root of this tree is **not** in a maximal independent set.
  2. Or it is.



# Case 1:

the root is **not** in an maximal independent set

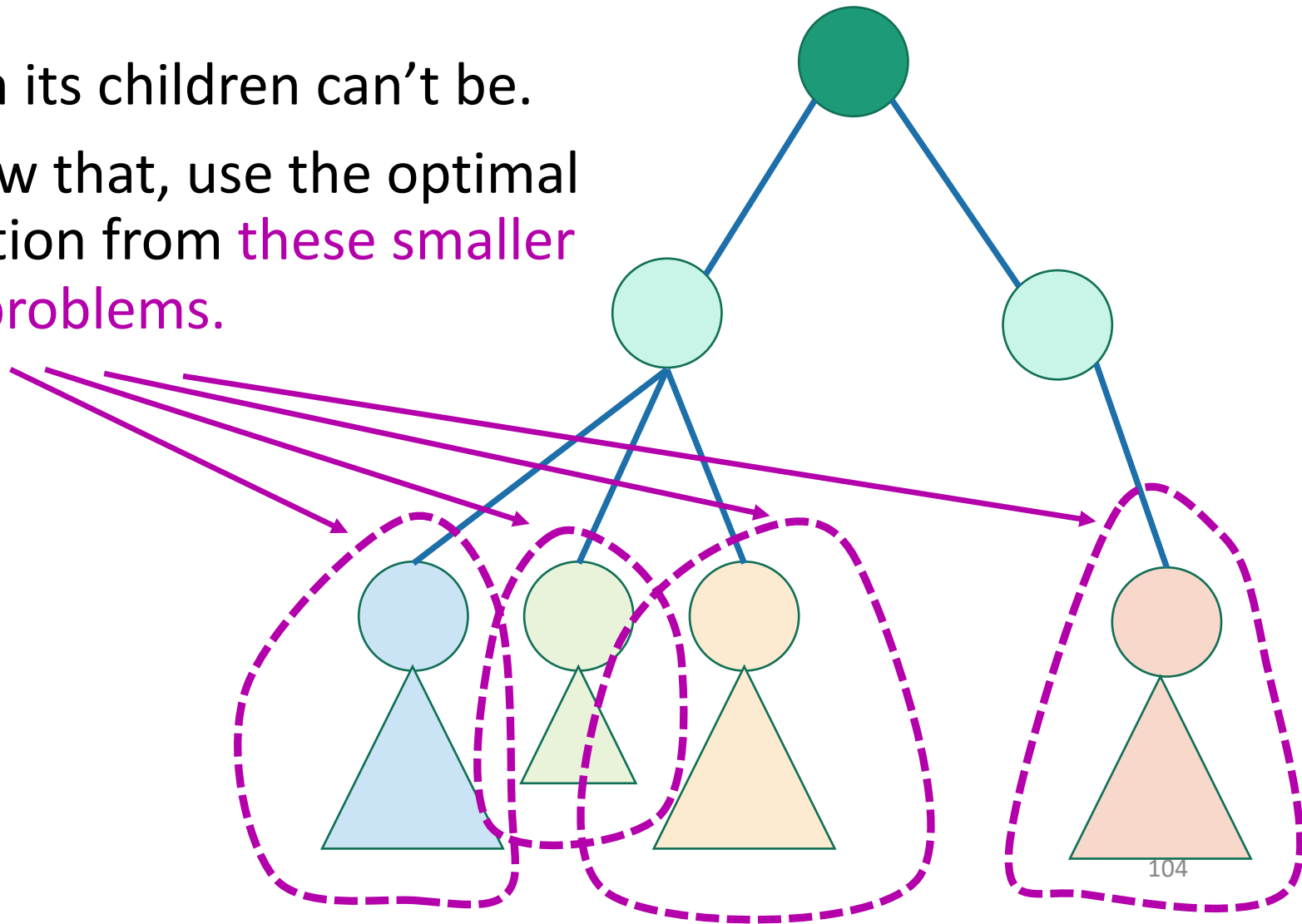
- Use the optimal solution from these smaller problems.



## Case 2:

the root is in an maximal independent set

- Then its children can't be.
- Below that, use the optimal solution from **these smaller subproblems**.



# Recipe for applying Dynamic Programming

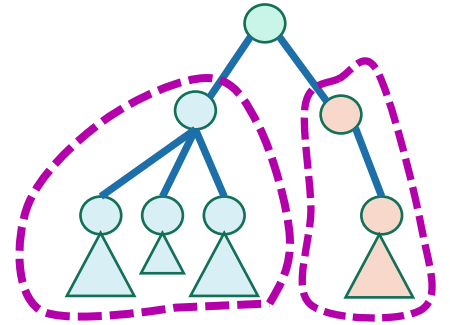
- **Step 1:** Identify optimal substructure.
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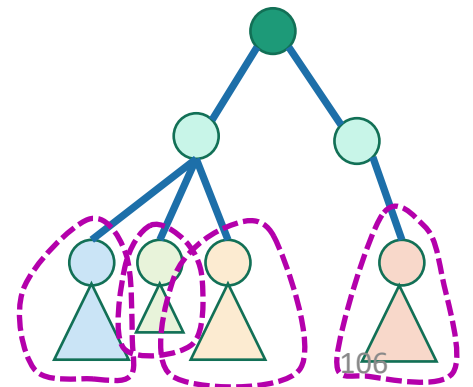
# Recursive formulation: try 1

- Let  $A[u]$  be the weight of a maximal independent set in the tree rooted at  $u$ .


- $A[u] = \max \begin{cases} \sum_{v \in u.\text{children}} A[v] \\ \text{weight}(u) + \sum_{v \in u.\text{grandchildren}} A[v] \end{cases}$

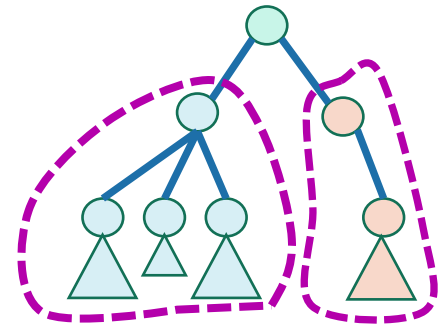


When we implement this, how do we keep track of **this term**?

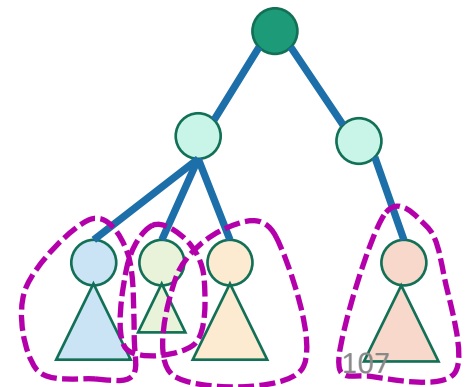


## Keep two arrays!

- Let  $A[u]$  be the weight of a maximal independent set in the tree rooted at  $u$ .
  - Let  $B[u] = \sum_{v \in u.\text{children}} A[v]$
- 



$$\bullet A[u] = \max \begin{cases} \Sigma_{v \in u.\text{children}} A[v] \\ \text{weight}(u) + \Sigma_{v \in u.\text{children}} B[v] \end{cases}$$



# Recipe for applying Dynamic Programming

- **Step 1:** Identify optimal substructure.
- **Step 2:** Find a recursive formulation for the value of the optimal solution.
- **Step 3:** Use dynamic programming to find the value of the optimal solution.
- **Step 4:** If needed, keep track of some additional info so that the algorithm from Step 3 can find the actual solution.
- **Step 5:** If needed, code this up like a reasonable person.



# A top-down DP algorithm

- MIS\_subtree(u):

- **if** u is a leaf:

- $A[u] = \text{weight}(u)$
    - $B[u] = 0$

- **else:**

- **for** v in u.children:
    - MIS\_subtree(v)

- $A[u] = \max\{ \sum_{v \in u.\text{children}} A[v], \text{weight}(u) + \sum_{v \in u.\text{children}} B[v] \}$

- $B[u] = \sum_{v \in u.\text{children}} A[v]$

- MIS(T):

- MIS\_subtree(T.root)
  - **return** A[T.root]

*Initialize global arrays A, B  
that we will use in all of  
the recursive calls.*

## Running time?

- We visit each vertex once, and at every vertex we do  $O(1)$  work:
  - Make a recursive call
  - look stuff up in tables
- Running time is  $O(|V|)$

# Why is this different from divide-and-conquer?

That's always worked for us with tree problems before...

- **MIS\_subtree(u):**

- **if** u is a leaf:

- **return** weight(u)

- **else:**

- **return**  $\max\{ \sum_{v \in u.\text{children}} \text{MIS\_subtree}(v),$

- $\text{weight}(u) + \sum_{v \in u.\text{grandchildren}} \text{MIS\_subtree}(v) \}$

*This is exactly the same pseudocode, except we've ditched the table and are just calling MIS\_subtree(v) instead of looking up A[v] or B[v].*

- **MIS(T):**

- **return** MIS\_subtree(T.root)

# Why is this different from divide-and-conquer?

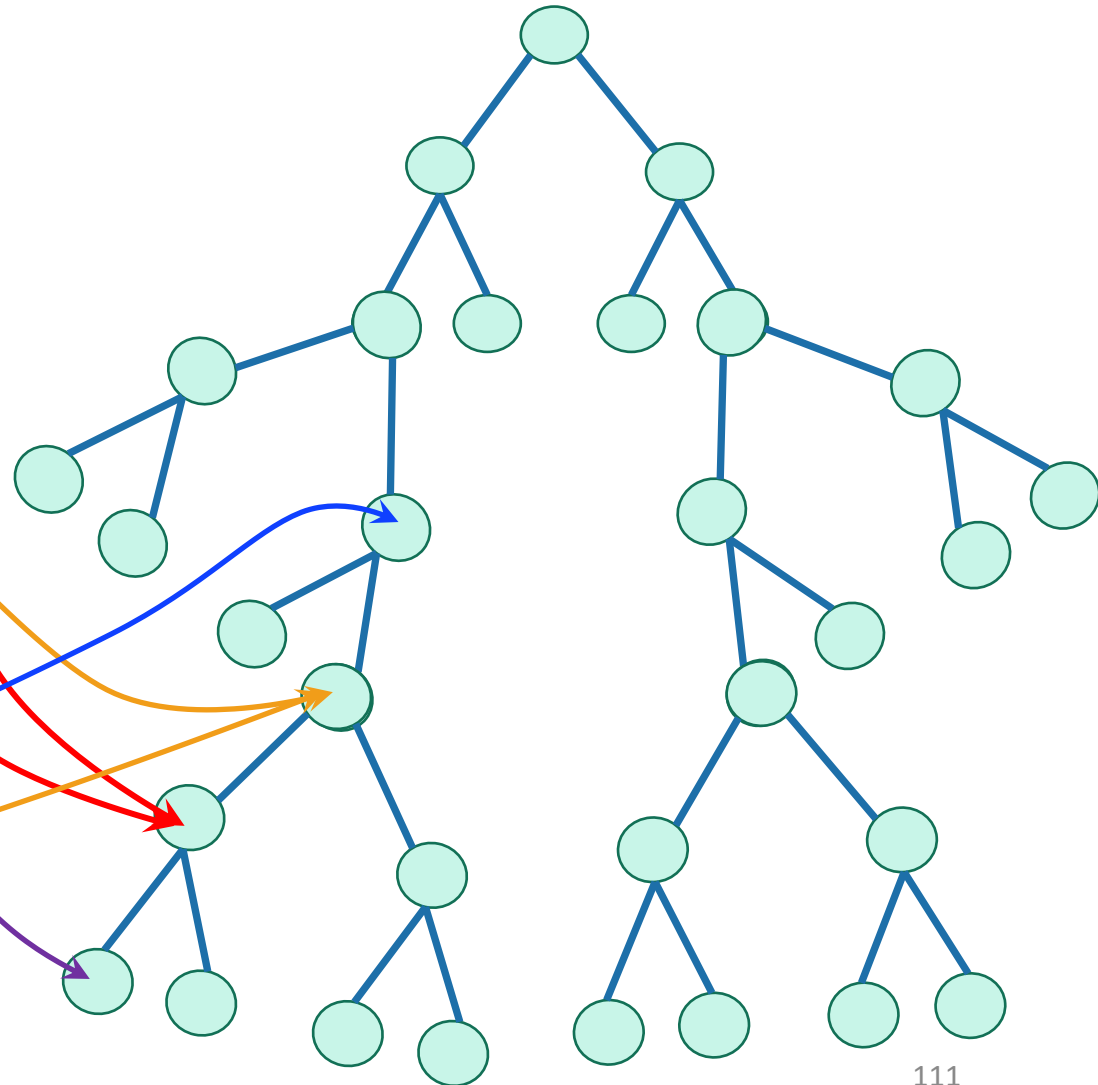
That's always worked for us with tree problems before...

How often would we ask about the subtree rooted **here?**

Once for **this node** and once for **this one**.

But we then ask about **this node** twice, **here** and **here**.

This will blow up exponentially without using dynamic programming to take advantage of **overlapping subproblems**.



# Recipe for applying Dynamic Programming

- **Step 1:** Identify optimal substructure.
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You do this one!



# What have we learned?

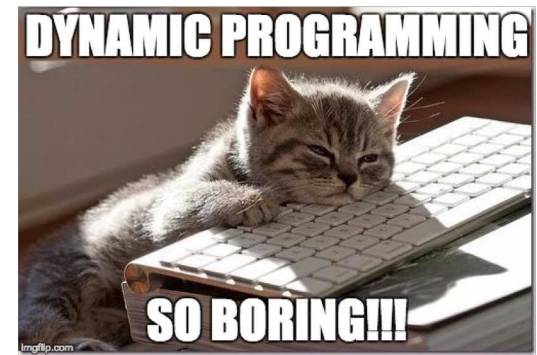
- We can find maximal independent sets in trees in time  $O(|V|)$  using dynamic programming!
- For this example, it was natural to implement our DP algorithm in a top-down way.

# Recap

- Today we saw examples of how to come up with dynamic programming algorithms.
  - Longest Common Subsequence
  - Knapsack two ways
  - (If time) maximal independent set in trees.
- There is a **recipe** for dynamic programming algorithms.

# Recipe for applying Dynamic Programming

- **Step 1:** Identify optimal substructure.
- **Step 2:** Find a recursive formulation for the value of the optimal solution.
- **Step 3:** Use dynamic programming to find the value of the optimal solution.
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# Recap

- Today we saw examples of how to come up with dynamic programming algorithms.
  - Longest Common Subsequence
  - Knapsack two ways
  - (If time) maximal independent set in trees.
- There is a **recipe** for dynamic programming algorithms.
- Sometimes coming up with the right substructure takes some creativity
  - You got some practice on HW6 and you'll get more on HW7! 😊
  - For even more practice check out additional examples/practice problems in Algorithms Illuminated or CLRS or section!

# Next week

- Greedy algorithms!

## Before next time

- Pre-lecture exercise: Greed is good!

