CS224N/Ling280



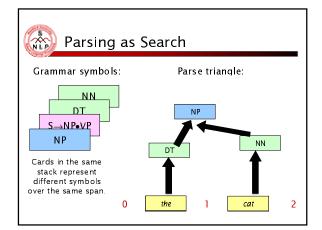
Statistical parsing: Search

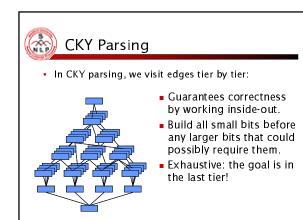


🚵 General Problem

- Someone gives you a PCFG G
- · For any given sentence, you might want to:
 - Find the best parse according to G
 - Find a bunch of reasonably good parses
 - Find the total probability of all parses licensed by ${\it G}$
- Techniques:
 - CKY (for best; can extend to k-best (at high space and time cost - k^2 time cost or all parses - the inside algorithm)

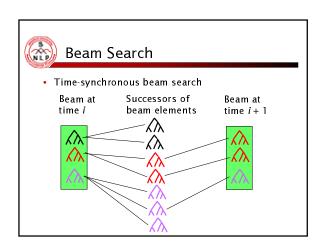
 - Agenda/chart-based search





Beam Search

- · State space search
- States are partial parses with an associated probability
 - Keep only the top scoring elements at each stage of the
- · Find a way to ensure that all parses of a sentence have the same number N steps
 - Leftmost top-down CFG derivations in true CNF
 - Shift-reduce derivations in true CNF
 - (Use a binary grammar or binarize what you've got, and remove unaries.)





📸)) Kinds of beam search

- Constant beam size k
- · Constant beam width relative to best item
- · Defined either additively or multiplicatively
- Sometimes combination of the above two
- Sometimes do fancier stuff like trying to keep the beam elements diverse
- Beam search can be made very fast
- No measure of how often you find model optimal answer
 - · But can track correct answer to see how often/far gold standard optimal answer remains in the beam



🚵 Beam search for assignment?

- · Would probably want to do bottom up parsing (shift-reduce parsing or a version of left-corner parsing)
 - For treebank grammars, not much grammar constraint, so want to use data-driven constraint
- Don't actually want to store states as partial parses
 - Store them as the last rule applied, with backpointers to the previous states that built those constituents (and a probability)



📸) Agenda-Based Parsing

- · For general grammars
- Start with a table recording δ(X,i,j)
 - Records the best score of a parse of X over [i,j]
 - If the scores are negative log probabilities, then entries start at ∞ , and small is good
 - This can be a sparse or a dense map
 - Again, you may want to record backtraces as well like CKY
- Step 1: Initialize with the sentence and lexicon:
 - For each word w and each tag t Set δ(X,i,j) = lex.score(w,t)



🪵 Agenda-based parsing

- · Keep a list of edges called an agenda
 - Edges are triples [X,i,j]
 - The agenda is a priority queue
- Every time the score of some δ(X,i,j) improves (i.e. gets lower):
 - ullet Stick the edge [X,i,j]-score into the agenda
 - (Update the backtrace for $\delta(X,i,j)$

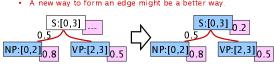


Agenda-Based Parsing

- · The agenda is a holding zone for edges.
- Visit edges by some ordering policy.
 - · Combined edge with already-visited edges.
 - · Resulting new edges go wait in the agenda.



A new way to form an edge might be a better way





🧥 Agenda-based parsing

- · Step II: While agenda not empty
 - Get the "next" edge [X,i,j] from the agenda
 - Fetch all compatible neighbors [Y,j,k] or [Z,k,i]
 - Compatible means that there are rules $A \rightarrow X Y$ or $B \rightarrow X Z$
 - Build all parent edges [A,i,k] or [B,k,j] found
 - $\delta(A,i,k) \leq \delta(X,i,j) + \delta(Y,j,k) + P(A \rightarrow X Y)$
 - If we've improved $\delta(A,i,k)$, then stick it on the agenda
 - · Also project unary rules:
 - Fetch all unary rules A→X, score [A,i,j] built from this rule on [X,i,j] and put on agenda if you've improved δ(A,i,k)
- When do we know we have a parse for the root?



🚵 Agenda-based parsing

- Open questions:
 - Agenda priority: What did "next" mean?
 - Efficiency: how do we do as little work as possible?
 - Optimality: how do we know when we find the best parse of a sentence?
- If we use δ(X,i,j) as the priority:
 - Each edge goes on the agenda at most once
 - When an edge pops off the agenda, its best parse is known (why?)
 - This is basically uniform cost search (i.e., Dijkstra's algorithm)



🚵 What can go wrong?

- · We can build too many edges.
 - · Most edges that can be built, shouldn't.
 - · CKY builds them all!

Speed: build promising edges first.

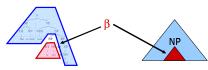
- We can build in an bad order.
 - Might find bad parses before good parses.
 - Will trigger best-first propagation.

Correctness: keep edges on the agenda until you're sure you've seen their best parse.



🚵 Uniform-Cost Parsing

• Let β be the score of an edge's Viterbi parse.



- "Distance" or "cost" is the negative log probability of the rules in a tree structure.
- Uniform-cost parsing: visit edges in order of increasing β (rather than increasing span)



🚵 Uniform-Cost Parsing

- We want to work on good parses inside-out.

 CKY does this synchronously, by tiers.

 - Uniform-cost does it asynchronously, ordering edges by their best known parse score
- Why it's correct:

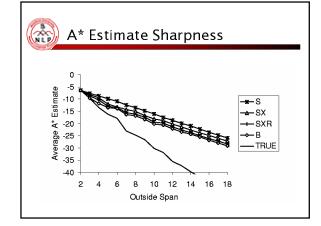


- Adding structure incurs probability cost.
- Trees have lower probability than their sub-parts.
- The best-scored edge in the agenda cannot be waiting on any of its sub-edges.



🃸 Speeding up agenda-based parsers

- · Two options for doing less work
 - The optimal way: A* parsing
 - Klein and Manning (2003)
 - The ugly but practical way: "best-first" parsing · Caraballo and Charniak (1998)
 - Charniak, Johnson, and Goldwater (1998)





Modern statistical parsers

- Klein and Manning (2003) do optimal A* search
 - Done in a restricted space of lexicalized PCFGs that "factors", allowing very efficient A* search
- Collins (1999) exploits both the ideas of beams and agenda based parsing
 - He places a separate beam over each span (and then, roughly, doing uniform cost search
- Charniak (2000) uses inadmissable heuristics to guide search
 - He uses very good (but inadmissable) heuristics dub "best first search" to find good parses quickly
 - Perhaps unsurprisingly this is the fastest of the 3.