

Numerical Approximations of Partial Differential Equations in Theory and Practice

CME 325, winter 2008

Lecture 9

CME325, winter 08, Wednesday Feb 20

1. Initial-value problems (IVP), well-posedness and stability, periodic problems
2. Initial-boundary-value problems (IBVP), well-posedness and stability by energy estimates
3. Stability, Convergence and Accuracy
4. High order discretizations in time and in space
5. Coupled methods + how to measure accuracy
6. Errors: Damping, Dispersion, Conservation
7. Implementation of boundary conditions for hyperbolic IBVP
8. More applications of SBP+SAT
- 9. Boundary conditions for parabolic IBVP+normal mode analysis**
10. Imbedded boundaries and interfaces
11. Non-reflecting boundary conditions

Parabolic IBVP

- SBP+SAT
- general technique using ghost points and extra boundary conditions that yields stable high order accurate methods.

General technique for Parabolic IBVP

Ex:

$$u_t = u_{xx}, \quad 0 \leq x \leq 1, \quad t \geq 0,$$

$$u(0, t) = g_0(t),$$

$$u_x(1, t) = g_1(t),$$

$$u(x, 0) = f(x),$$

Let $x_i, \quad i = -1, 0, \dots, N+1$ be

equidistant points with

$$x_0 = 0, \quad x_{N-1} + x_N = 1,$$

$$\frac{du_i}{dt} = (D_+ D_- - \frac{h^2}{12} D_+^2 D_-^2) u_i, \quad i = 1, \dots, N-1,$$

$$u_0 = g(t)$$

$$u_{-1} = ?$$

$$D_- u_N = g_1(t), \quad \text{only order 2!}$$

$$u_{N+1} = ?$$

$$u_i(0) = f_i$$

General technique for Parabolic IBVP

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$$u(0, t) = g_0(t),$$

$$u_x(1, t) = g_1(t),$$

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Let $x_i, i = -1, 0, \dots, N+1$ be equidistant points with

$$x_0 = 0, \quad x_{N-1} + x_N = 1,$$

$$\frac{du_i}{dt} = (D_+ D_- - \frac{h^2}{12} D_+^2 D_-^2) u_i, \quad i = 1, \dots, N-1,$$

$$u_0 = g(t)$$

$$D_+ D_- u_0 = g_0^{(1)}(t) + \frac{h^2}{12} g_0^{(2)}(t)$$

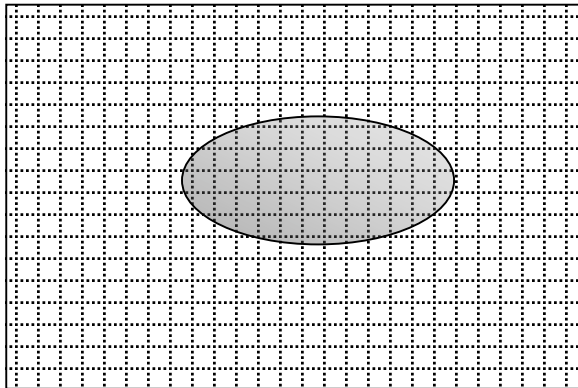
$$D_- u_N = g_1(t) + \frac{h^2}{24} g_1^{(1)}(t)$$

$$D_+ D_-^2 u_N = g_1^{(1)}(t) + \frac{h^2}{8} g_1^{(2)}(t)$$

$$u_i(0) = f_i$$

- The approximation is 4th order and semi-bounded (check this!)
- Generalizeable to higher order, multi-D and to systems

Embedded boundaries, preview

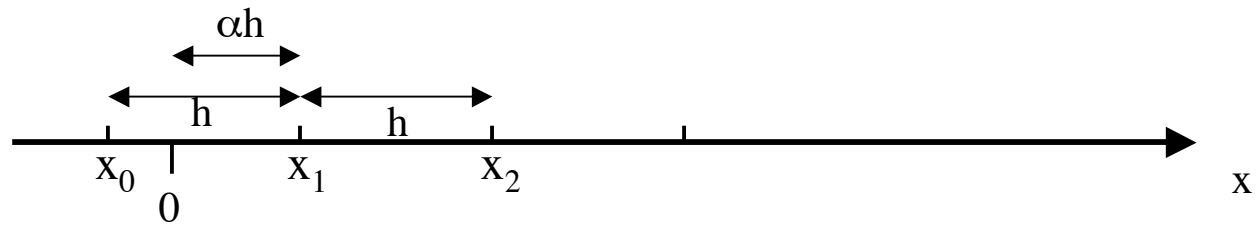


Grid is not aligned with boundary

- + no need for special meshes
- implementing boundary conditions is more difficult
- accuracy and stability difficult to achieve and analyze

Embedded boundary: 1D example

$$u_t + u_x = 0$$
$$u(0, t) = g(t)$$
$$u(x, 0) = f(x)$$



$$\frac{du_j}{dt} = -D_0 u_j, j = 1, \dots$$

$$u_0 = -\frac{\alpha}{1-\alpha} u_1$$

$$u_j(0) = f_j,$$

- Introduce a new grid point at $x=0$?
Small cell leads to severe stability restrictions

- Use extrapolation to ghost point x_0 ?
No general technique for stability and high order accuracy

Normal mode analysis

Cannot derive semi-boundedness?

Analyze each boundary separately by considering a half line problem with extra "boundary condition" $\|u\|_h < \infty$

Look for solutions $\phi_j e^{st}$ where s is a complex number:

$$2sh\phi_j = -\phi_{j+1} + \phi_{j+1}, j = 1, \dots$$

$$\phi_0 = -\frac{\alpha}{1-\alpha} \phi_1$$

$$\|\phi\|_h < \infty$$

Eigenvalue problem for $\tilde{s} = sh$ and gridfunction ϕ

If there is an eigenvalue with $\text{Re } \tilde{s} > 0$ the discretization is unstable. (Why?)

Normal mode analysis

$$\tilde{s}\phi_j = hQ\phi_j, j=1, \dots$$

include only principle part!

$$B_h\phi_0 = 0, \|\phi\|_h < \infty$$

Determinant condition:

- Assume $Re s > 0$
- Determine general solution of difference equation satisfying $\|\phi\|_h < \infty$
- Apply B_h yields $C(s)\sigma = 0$
- ***Det C(s) ≠ 0?***

Godunov - Ryabenkii condition is necessary for stability :

$Det C(\tilde{s}) \neq 0$ for all $Re(\tilde{s}) > 0$

Lemma : If $Det C(\tilde{s}) \neq 0$ for all $Re \tilde{s} \geq 0$ then the approximation

is **boundary stable** : $\int_0^T |u_j(t)|^2 dt \leq K \int_0^T |g(t)|^2 dt$

Does boundary stability imply stability?

What if $Det C(\tilde{s}) \neq 0$ for some $Re \tilde{s}_0 = 0$?

Normal mode analysis

Based on Laplace transform in time:

$$\hat{u}(s) = \int_0^{\infty} e^{-st} u(t) dt, \quad s = \eta + i\xi,$$

$$s\hat{u}_j = Q\hat{u}_j + \hat{F}_j, \quad j = 1, \dots, \quad B_h \hat{u}_0 = \hat{g}, \quad \|\hat{u}\|_h < \infty,$$

$$\int_0^{\infty} e^{-2\eta t} |u(t)|^2 dt = \frac{1}{2\pi} \int_{-\infty}^{\infty} |\hat{u}(\eta + i\xi)|^2 d\xi,$$

Def : the discretization is **stable in the generalized sense** if for $g = f = 0$

$$\int_0^{\infty} e^{-2\eta t} \|u(t)\|_h^2 dt \leq K(\eta) \int_0^{\infty} e^{-2\eta t} \|F(t)\|_h^2 dt, \quad \eta \geq \eta_0$$

Useful for convergence, can include boundary and initial data, lower order terms, two boundaries

Theorem 2.7: for symmetric hyperbolic problems boundary stability implies strong stability