Chapter 9: Applications to Computing
9.4: Bloom Filters
(From “Probability & Statistics with Applications to Computing” by Alex Tsun)

9.4.1 Motivation

Google Chrome has a huge database of malicious URLs, but it takes a long time to do a database lookup (think of this as a typical Set, but on a different computer than yours). As you may know, Sets have desirable constant-time lookup, but due to the fact it isn’t on your computer, the time bottleneck comes from the communication between the database and your computer. They want to have a quick check in the web browser itself (on your computer), so a space-efficient data structure must be used.

That is, we want to save both time (not in the typical big-Oh sense) and space. But what will we trade for it? It turns out we will have limited operations (fewer than a Set), and some probability of error which turns out to be fine.

9.4.2 Definition

A bloom filter is a probabilistic data structure which only supports the following two operations:

I. \( \text{add}(x) \): Add an element \( x \) to the structure.

II. \( \text{contains}(x) \): Check if an element \( x \) is in the structure. If either returns “definitely not in the set” or “could be in the set”.

It does not support the following two operations:

I. Delete an element from the structure.

II. Give a collection of elements that are in the structure.

The idea is that we can check our bloom filter if a URL is in the set. The bloom filter is always correct in saying a URL definitely isn’t in the set, but may have false positives (it may say a URL is in the set when it isn’t). So most of the time, we get instant time, and only in these rare cases does Chrome have to perform an expensive database lookup to know for sure.

Suppose we have \( k \) bit arrays \( t_1, \ldots, t_k \) each of length \( m \) (all entries are 0 or 1), so the total space required is only \( km \) bits or \( km/8 \) bytes (as a byte is 8 bits). See below for one with \( k = 3 \) arrays of length \( m = 5 \):

\[
\text{bloom filter } t \text{ of length } m = 5 \text{ that uses } k = 3 \text{ hash functions}
\]

<table>
<thead>
<tr>
<th>function initialize((k,m)) for ( i = 1, \ldots, k ); do</th>
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<tbody>
<tr>
<td>( t_i = \text{new bit vector of } m ) 0’s</td>
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</table>

<table>
<thead>
<tr>
<th>Index</th>
<th>0</th>
<th>1</th>
<th>2</th>
<th>3</th>
<th>4</th>
</tr>
</thead>
<tbody>
<tr>
<td>( t_1 )</td>
<td>0</td>
<td>0</td>
<td>0</td>
<td>0</td>
<td>0</td>
</tr>
<tr>
<td>( t_2 )</td>
<td>0</td>
<td>0</td>
<td>0</td>
<td>0</td>
<td>0</td>
</tr>
<tr>
<td>( t_3 )</td>
<td>0</td>
<td>0</td>
<td>0</td>
<td>0</td>
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</tr>
</tbody>
</table>
So regardless of the number of elements $n$ that we want to insert store in our bloom filter, we use the same amount of memory! That being said, the higher $n$ is for a fixed $k$ and $m$, the higher your error rate will be.

Suppose the universe of URL’s is the set $\mathcal{U}$ (think of this as all strings with less than 100 characters), and we have $k$ independent and uniform hash functions $h_1, \ldots, h_k : \mathcal{U} \rightarrow \{0, 1, \ldots, m-1\}$. That is, for an element $x$ and hash function $h_i$, pretend $h_i(x)$ is a discrete $\text{Unif}(0, m-1)$ random variable. Basically, when we see a new URL, we will add it to one random entry per row of our bloom filter.

See the image below to see how we add the URL “thisisavirus.com” into our bloom filter.

```
function ADD(x)
    for $i = 1, \ldots, k$: do
        $t_i[h_i(x)] = 1$
```

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<tbody>
<tr>
<td>$t_1$</td>
<td>0</td>
<td>0</td>
<td>1</td>
<td>0</td>
<td>0</td>
</tr>
<tr>
<td>$t_2$</td>
<td>0</td>
<td>1</td>
<td>0</td>
<td>0</td>
<td>0</td>
</tr>
<tr>
<td>$t_3$</td>
<td>0</td>
<td>0</td>
<td>0</td>
<td>0</td>
<td>1</td>
</tr>
</tbody>
</table>

For each of our $k = 3$ hash functions (corresponding to each row), we hash our URL $x$ as $h_i(x)$ to get a random integer from $\{0, 1, \ldots, 4\}$ ($0$ to $m-1$). It happened that $h_1(x) = 2$, $h_2(x) = 1$ and $h_3(x) = 4$ in this example: each hash function is independent of the others and chooses a position uniformly at random.

**But if we hash the same URL, we will get the same hash.** In other words, if I tried to add this URL one more time, nothing would change because all the entries were already set to 1. Notice we never “unset” an entry: once a URL sets an entry to 1, it will stay 1 forever.

Now let’s see how the contains function is implemented. When we check whether the URL we just added is contained in the bloom filter, we should definitely return yes.

```
function CONTAINS(x)
    return $t_1[h_1(x)] = 1 \land t_2[h_2(x)] = 1 \land \cdots \land t_k[h_k(x)] = 1$
```

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</table>

**Since all conditions satisfied, returns True (correctly)**
We say that a URL $x$ is contained in the bloom filter, if when we apply each hash function $h_i(x)$, the corresponding entries are already set to 1. We added this URL “thisisavirus.com” right before this, so we are guaranteed that $t_1[2] == 1$, $t_2[1] == 1$, and $t_3[4] == 1$, and so we return TRUE overall! You might now see how this could lead to false positives: returning TRUE even though the URL was never added! Don’t worry if not, we’ll see some examples below.

That’s all there is for bloom filters!

Example(s)

Starting with the current state of the bloom filter above:

1. Add the URL $x$ = “totallynotsuspicious.com” which has $h_1(x) = 1$, $h_2(x) = 0$ and $h_3(x) = 4$. Draw the resulting bloom filter.

2. Check whether or not the URL “verynormalsite.com” is in the bloom filter, which has $h_1(x) = 2$, $h_2(x) = 0$ and $h_3(x) = 4$.

Solution

Notice that $t_3[4]$ was already set to 1 by the previous entry, and that’s okay! We just leave it set to 1.

Notice here we got a false positive: that means, saying a URL is in the bloom filter when it wasn’t. This is a tradeoff we make in exchange for using much less space.
9.4.3 Analysis

You might be dying to know, what is the **false positive rate (FPR)** for a bloom filter, and how should I choose $k$ and $m$? These are great questions, and we actually have the tools to figure this out already.

**Theorem 9.4.1: Bloom Filter FPR**

After inserting $n$ distinct URLs to a $k \times m$ bloom filter ($k$ hash functions/rows, $m$ columns), suppose we had a new URL and wanted to check whether it was contained in the bloom filter. The false positive rate (probability the bloom filter returns True incorrectly), is

\[
\left(1 - \left(1 - \frac{1}{m}\right)^n\right)^k
\]

**Proof of Bloom Filter FPR.** We get a match for new URL $x$ if in each row, the bit assigned by the hash function $h_i(x)$ is set to 1.

For $i = 1, \ldots, k$, let $E_i$ be the event that $h_i(x)$ is set to 1 already. Then,

\[
P(\text{false positive}) = P(h_1(x) = 1, h_2(x) = 1, \ldots, h_k(x) = 1) = P(E_1 \cap E_2 \cap \cdots \cap E_k) = \prod_{i=1}^k P(E_i)
\]

where the last equality is because each hash function is assumed to be independent of the others.

Now, let’s focus on a single row $i$ (all the rows are the “same”). The probability that the bit is set to 1 $P(E_i)$, is the probability that at least one of the $n$ URLs hashed to that entry. Seeing “at least one” should tell you that: you should try the complement instead (otherwise, use inclusion-exclusion)!

So the probability a bit remains at 0 after $n$ entries are added $(E_i^C)$ is

\[
P(E_i^C) = \left(1 - \frac{1}{m}\right)^n
\]

because the probability of missing this bit for a single URL is $1 - 1/m$. Hence,

\[
P(E_i) = 1 - P(E_i^C) = 1 - \left(1 - \frac{1}{m}\right)^n
\]

Finally, combining this result with the previous gives our final answer, since each row has the same probability:

\[
P(\text{false positive}) = \prod_{i=1}^k P(E_i) = \left(1 - \left(1 - \frac{1}{m}\right)^n\right)^k
\]

So based on $n$, the number of malicious URLs Google Chrome would like to store, should definitely play a part in how large they should choose $k$ and $m$ to be.

Let’s now see (by example) the kind of time and space improvement we can get.
### Example(s)

1. Let’s compare this approach to using a typical `Set` data structure. Google wants to store 5 million URLs, with each URL taking (on average) 40 bytes. How much space (in MB, 1 MB = 1 million bytes) is required if we store all the elements in a set? How much space (in MB) is required if we store all the elements in a bloom filter with $k = 30$ hash functions and $m = 900,000$ buckets? Recall that 1 byte = 8 bits.

2. Let’s analyze the time improvement as well. Let’s say an average Chrome user attempts to visit 102,000 URLs in a year, only 2,000 of which are actually malicious. Suppose it takes half a second for Chrome to make a call to the database (the `Set`), and only 1 millisecond for Chrome to check containment in the bloom filter. Suppose the false positive rate on the bloom filter is 3%; that is, if a website is not malicious, the bloom filter will incorrectly report it as malicious with probability 0.03. What is the time (in seconds) taken if we only use the database, and what is the *expected* time taken (in seconds) to check all 102,000 strings if we used the bloom filter + database combination described earlier?

### Solution

1. For the set, we would require 5 million times 40 bytes, for a total of 200 MB.
   For the bloom filter, we need just $km/8 = 27/8$ million bytes, or 3.375 MB, wow! Note how this doesn’t depend (directly) at all on how many URLs, or the size of each one as we just hash it to a few bits. Of course, $k$ and $m$ should increase with $n$ though :) to keep the FPR low.

2. If we only use the database, it will take $102,000 \cdot \frac{1}{2} = 51,000$ seconds.
   If we use the bloom filter + database combination, we will definitely call the bloom filter 102,000 times at 0.001 seconds each, for a total of 102 seconds. Then for about 3% of the 100,000 other URLs (3,000 of them), we’ll have to do a database lookup, costing $3,000 \cdot \frac{1}{2} = 1,500$ seconds. For the 2,000 actually malicious URLs, we also have to do a database lookup, costing $2,000 \cdot \frac{1}{2} = 1000$ seconds. So in total, $102 + 1500 + 1000 = 2602$ seconds.

   Just take a second to stare at how much memory savings we had (the first part), and the time savings we had (the second part)!

### 9.4.4 Summary

Hopefully now you see the pros and cons of bloom filters. We cannot delete from the bloom filter (why?) nor list out which elements are in it because we never stored the string! Below summarizes the operations of a bloom filter.
Algorithm 1 Bloom Filter Operations

1: function INITIALIZE($k, m$)
2: for $i = 1, \ldots, k$: do
3: $t_i$ = new bit array of $m$ 0's
4: function ADD($x$)
5: for $i = 1, \ldots, k$: do
6: $t_i[h_i(x)] = 1$
7: function CONTAINS($x$)
   return $t_1[h_1(x)] == 1 \land t_2[h_2(x)] == 1 \land \cdots \land t_k[h_k(x)] == 1$

If you imagine coding this up, it’s so short, only a few lines of code! We just saw how probability and randomness can be used to save space and time, in exchange for accuracy! In our application, we didn’t even mind the accuracy part because we would just do the lookup in that case just to be certain anyway! We saw it being used for a data structure, and in our next application, we’ll see it being used for an algorithm.

Randomness just makes our lives (as a computer scientist) better, and can lead to elegant and beautiful data structures algorithms which often outperform their deterministic counterparts.