

Principles of Robot Autonomy II

Section Logistics



Sections

- Modeled after sections in CS 106A/B/X/L
- Provide hands-on experience for commonly-used tools in robotics
- AKA tools you'll be using for your homework and final projects
- Taking feedback from previous years to heart

Section Logistics

- First 15-30 minutes will be a presentation about the aims of the section, references, and a description of the hands-on activity you'll be doing
- Rest of the time (1.5+ hours) will be for you and a partner (your tablemate) to complete the hands-on activity
- You submit your results on Gradescope when you're done

Do I have to stay the whole time?

- Once you complete the activity and submit your results, you can leave

Do I have to arrive on time?

- Yes
- ... unless you have an overlapping class conflict. In that case, you should still arrive ASAP and make a group with someone else that is arriving similarly late
 - If you're the only one that arrives late, then you can join an existing group
- Section slides and the activity handout will be posted online, so you can still catch up
- However, we will not stay after hours

Questions about Section Logistics?

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Section 1: Revisiting AA274A



Aims

- By the end of week 3 (1/24), we want you to
 - Form a team
 - Re-demo AA274A Final project (Food delivery) again with your new team with a TA
 - Test your workspace (VM/Native install/Docker)
- The first couple weeks is to bring everyone on the same page
 - Previous years' AA274 didn't have sections
 - You might have to form a new team for AA274B/CS237B

Section 1

- Show us that you have a working ROS environment on your machine.
- Show us that your team's robot has AA274A autonomy stack.