

# EE155/255 F17 Homework 4

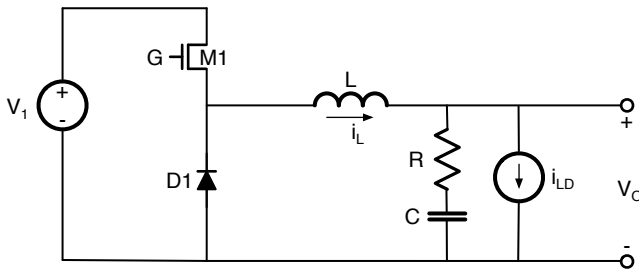
## Feedback Control and Electric Motor Calculations

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Assigned 10/16/17

Due 10/23/17

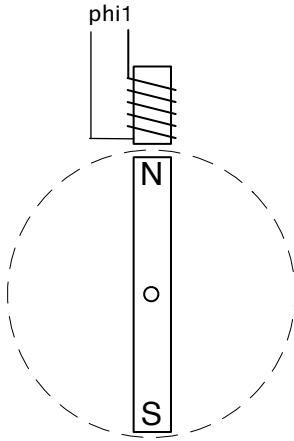
### Problem 1: Feedback Control



Consider the schematic above of a buck converter where we are explicitly modeling the effective series resistance (ESR) of the capacitor. Suppose the duty factor on FET M1 is  $D_M$  and the duty factor of diode D1 is  $D_D = (1 - D_M)$ .

- Write an expression for the open-loop transfer function from  $D_M$  to  $V_o$  – the voltage across the load.
- For the specific values of  $i_{LD} = 10\text{A}$ ,  $R = 0.01\Omega$ ,  $C = 100\mu\text{F}$ ,  $L = 22\mu\text{F}$ , and  $V_1 = 10\text{V}$ , design a PID controller (i.e., specify values of P, Q, and R) that gives a well-damped response (no more than 20% overshoot), zero residual error, and avoids saturating the duty factor on a 1V step in target input voltage. (Hint: You may use feed-forward control in lieu of an integral term in your controller).
- (Extra Credit) Simulate your controller (and the converter) in Matlab. Show the response to a step from a target of 4V to 5V and then back to 4V.
- (Extra Credit) Show Bode plots (phase and amplitude vs frequency) for your plant and your plant with controller. Measure the phase margin.

## Problem 2: Motor Calculations



Suppose you have a single-phase brushless permanent magnet motor (as shown above). The rotor is shown in the  $\theta=0$  position. You may neglect the inductance in the motor windings.

- When the motor has an angular velocity of  $\omega=1$  rad/s you observe a sine wave with amplitude 1V (RMS) and frequency of 1 rad/s across the single open-circuit winding. If you increase the angular velocity to  $\omega = 2$  rad/s, what voltage waveform will you see across the winding? (Express voltage as a function of time,  $t$ ).
- You apply a torque of 2 N-m to the shaft of the motor rotating at 10 rad/s in the direction of rotation. What resistance must be applied across the winding to keep the motor at a steady speed (averaged over a cycle)? How much power is dissipated in this resistor?
- Driving the winding with a DC current source with current  $I_0$  and the rotor "locked" in a stationary position, you observe a torque of 1 N-m with the rotor at  $\theta=30$  degrees. What torque do you expect with the same current and the rotor at  $\theta=90$  degrees?
- What torque do you expect at  $\theta=90$  degrees and a current of  $2I_0$ ?