# Rad229 – MRI Signals and Sequences

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#### Lecture-01B — The Bloch Equations and Image Contrast Radiofrequency (B1) Pulses and the Rotating Frame

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### Learning Objectives

- Explain the principal function of the RF (B1) field.
  - Describe the magnitude, spatial, and temporal characteristics of the B<sub>1</sub> field.
  - Define  $B_1$  with a mathematical expression.
- Distinguish between spin, precession, and nutation.
- Differentiate between the lab and rotating frames.
- Remember an expression for a circular polarized RF field.
- Contrast the equation of motion in the lab and rotating frames.



# Radiofrequency (B1) Fields

 $\vec{B}_1(t)$ 

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#### **MRI** Hardware



### RF (B1) Field - Characteristics

- B<sub>1</sub> is a
  - radiofrequency (RF)
    - 42.58MHz/T for <sup>1</sup>H (63MHz at 1.5T)
  - short duration pulse (~0.1 to 10ms)
  - small amplitude
    - <25 µT
  - shaped by an envelope function
  - circularly polarized
    - rotates at Larmor frequency
  - magnetic field
  - perpendicular to B<sub>0</sub>
- Principal use: excitation and refocusing.
  - Image contrast (inversion, saturation)
  - Signal spoiling



#### **RF Excitation - Lab Frame**

<sup>1</sup>H has intrinsic Spin  $\omega_0 = \gamma B_0$  Precession Combined with...  $\omega_1 = \gamma B_1$  Nutation

#### RF (B<sub>1</sub>) pulse impart forced precession.



B<sub>0</sub> causes precession about z-axis. B<sub>1</sub> causes forced precession (i.e. nutation). https://en.wikipedia.org/wiki/Nutation

#### **RF Excitation - Lab Frame**



#### Basic RF Pulse - Linear Polarized





#### Linear & Circular Polarized B1 Fields

#### Linear Polarization

 $\vec{B}_1(t) = 2B_1^e(t)\cos(\omega_{RF}t + \theta)\hat{i}'$ 



First Generation MRI Systems Used Linear Polarization; Simple and Cheaper, but higher RF power.



Arrow indicates direction of B-field

### Linear & Circular Polarized B1 Fields



#### Linear & Circular Polarized B1 Fields



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Even with circular polarization many pulse sequences are SAR limited at  $\geq$ 3T.

### RF (B1) Field - Generation

- Birdcage coil
  - Most common design
  - Highly efficient
  - Nearly all of the fields produced contribute to imaging
- Very uniform field
  - Especially radially
  - Decays axially
  - Uniform sphere if  $L \approx D$
- Generates a "quadrature" field
  - Circular polarization

#### Birdcage Body Tx/Rx Coil (B1)



CW (righthand)



CCW (lefthand)

#### Basic RF Pulse - Circular Polarized

$$ec{B_1}(t) = B_1^e(t) \begin{bmatrix} \cos(\omega_{RF}t)\hat{i}' - \sin(\omega_{RF}t)\hat{j}' \end{bmatrix} \begin{bmatrix} \text{Circular} & \text{Polarized} & \text{Polarized} & \text{RF Field} \end{bmatrix}$$



# Lab vs. Rotating Frame

#### Laboratory Frame Coordinates





 $ec{\omega} = \gamma B_0 \hat{k}'$ 

**Rotational Angular Velocity** 

mage Adapted From: http://www.ee.duke.edu/~jshorey

#### Lab vs. Rotating Frame Coordinates

• The rotating frame simplifies the mathematics; more intuitive understanding.



#### **Rotating Frame Coordinates**

- If the rotational frequency of the rotating frame is matched to the bulk magnetization's precessional frequency, then rotational motion of the bulk magnetization is "removed" or demodulated.
- The rotating frame's transverse xy-plane rotates clockwise (left-handed) at frequency ω relative to the scanners x'y'-plane.





The rotating frame simplifies the mathematical description of spin dynamics and affords a more intuitive understanding.

Equation of Motion

$$\begin{split} \frac{d\vec{M}}{dt} &= \vec{M} \times \gamma \vec{B} \\ \frac{d\vec{M}_{rot}}{dt} &= \vec{M} \times \gamma \vec{B} \\ \frac{d\vec{M}_{rot}}{dt} &= \vec{M}_{rot} \times \gamma \left( \frac{\vec{\omega}_{rot}}{\gamma} + \vec{B}_{rot} \right)^{\text{Equation of motion for an ensemble of spins (isochromats).}}_{\text{[Rotating Frame]}} \\ \frac{d\vec{M}_{rot}}{dt} &= \vec{M}_{rot} \times \gamma \left( \frac{\vec{\omega}_{rot}}{\gamma} + \vec{B}_{rot} \right)^{\text{Equation of motion for an ensemble of spins (isochromats).}}_{\text{[Rotating Frame]}} \\ \vec{B}_{eff} &\equiv \frac{\vec{\omega}_{rot}}{\gamma} + \vec{B}_{rot} \\ \uparrow \\ \vec{F}_{rotating frame.} &\uparrow \\ \vec{h}_{rotating frame.} &\uparrow \\ \vec{h}_{rotating frame.} &\uparrow \\ \vec{h}_{rotating frame.} &\uparrow \\ \vec{h}_{rot} &\uparrow \\ \vec{h}_{rot} &\neq \gamma \vec{B}_{eff} \\ \frac{d\vec{M}_{rot}}{dt} &= \vec{M}_{rot} \times \gamma \vec{B}_{eff} \\ \vec{h}_{rotating frame.} \\ \vec{h}_{rotating frame.} &\downarrow \\ \vec{h}_{rotating frame.} \\ \vec{h}_{rotating frame.} &\downarrow \\ \vec{h}_{rotating frame.} &\downarrow \\ \vec{h}_{rot} &\neq \gamma \vec{B}_{eff} \\ \vec{h}_{rot} &= \vec{h}_{rot} \\ \vec{h}_{rot} &\neq \gamma \vec{H}_{eff} \\ \vec{h}_{rot} &= \vec{h}_{rot} \\ \vec{h}_{rot} &\neq \gamma \vec{H}_{eff} \\ \vec{h}_{rot} &= \vec{h}_{rot} \\ \vec{h}_{rot} &= \vec{h}_{rot} \\ \vec{h}_{rot} &= \vec{h}_{rot} \\ \vec{h}_{rot} &\neq \gamma \vec{H}_{eff} \\ \vec{h}_{rot} &= \vec{h}_{rot} \\ \vec{h}_{rot} \\ \vec{h}_{rot} &= \vec{h}_{rot$$



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Rotating Frame

### Free Precession in the Rotating Frame w/o Relaxation

$$\vec{B}_{eff} = \frac{\vec{\omega}_{rot}}{\gamma} + \vec{B}_{rot}$$

$$= \frac{-\gamma B_0 \hat{k}'}{\gamma} + B_0 \hat{k}' \qquad \frac{d\vec{M}_{rot}}{dt} = \vec{M}_{rot} \times \gamma \vec{B}_{eff}$$

$$= 0$$

$$M_x(t) = M_x^0 \qquad \frac{dM_x}{dt} = 0$$

$$M_y(t) = M_y^0 \qquad \frac{dM_y}{dt} = 0 \qquad \frac{d\vec{M}_{rot}}{dt} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ M_x & M_y & M_z \\ 0 & 0 & 0 \end{vmatrix}$$

$$M_z(t) = M_z^0 \qquad \frac{dM_z}{dt} = 0$$
onstant components

Constant components in the rotating frame without relaxation.



The bulk magnetization components in the rotating frame maintain the initial condition for all time in the absence of relaxation

# How do RF pulses tip the magnetization?

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