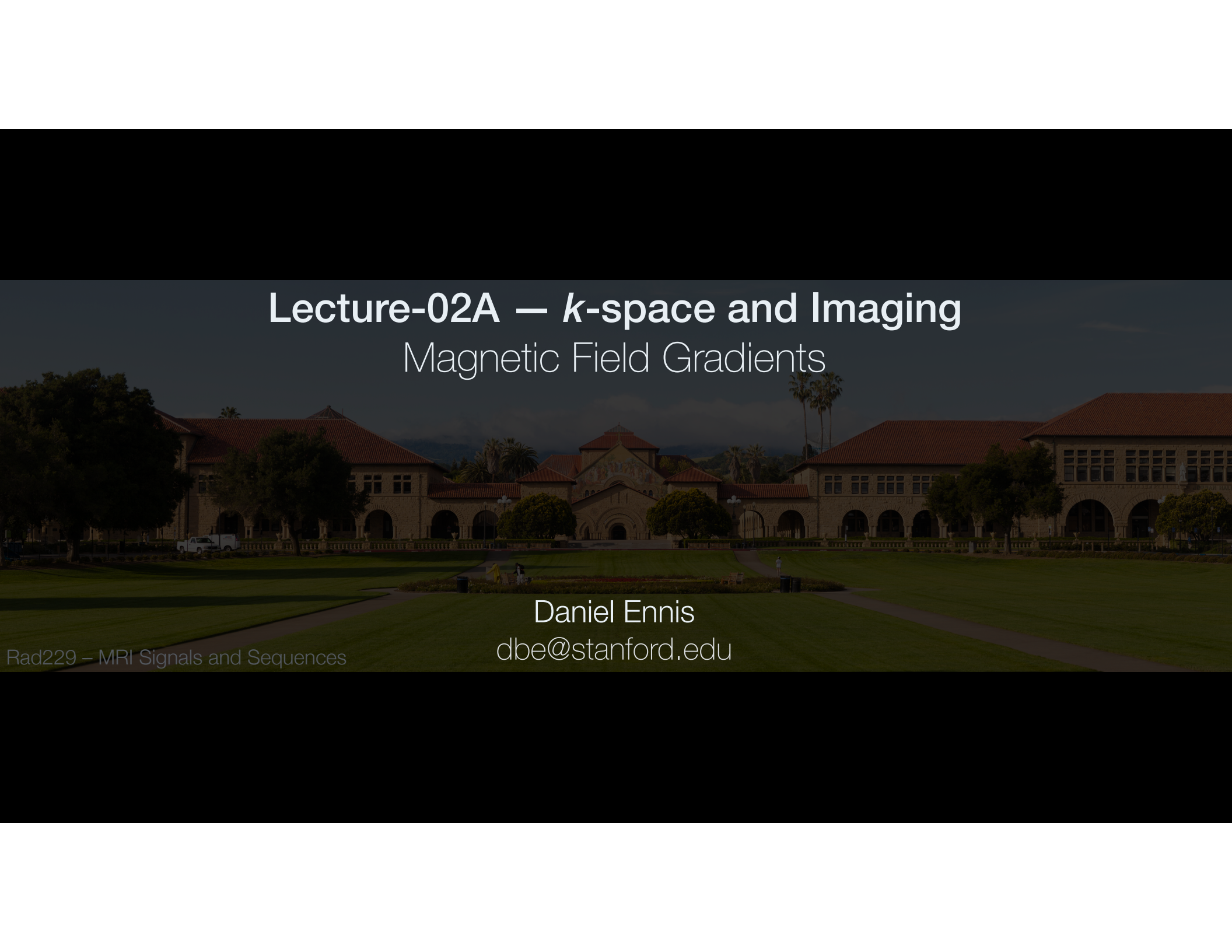


Rad229 – MRI Signals and Sequences

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A wide-angle photograph of the Stanford University Main Quad, featuring the red-tiled Main Building and surrounding green lawns. The image is dimmed to serve as a background for the text.

Lecture-02A — *k*-space and Imaging

Magnetic Field Gradients

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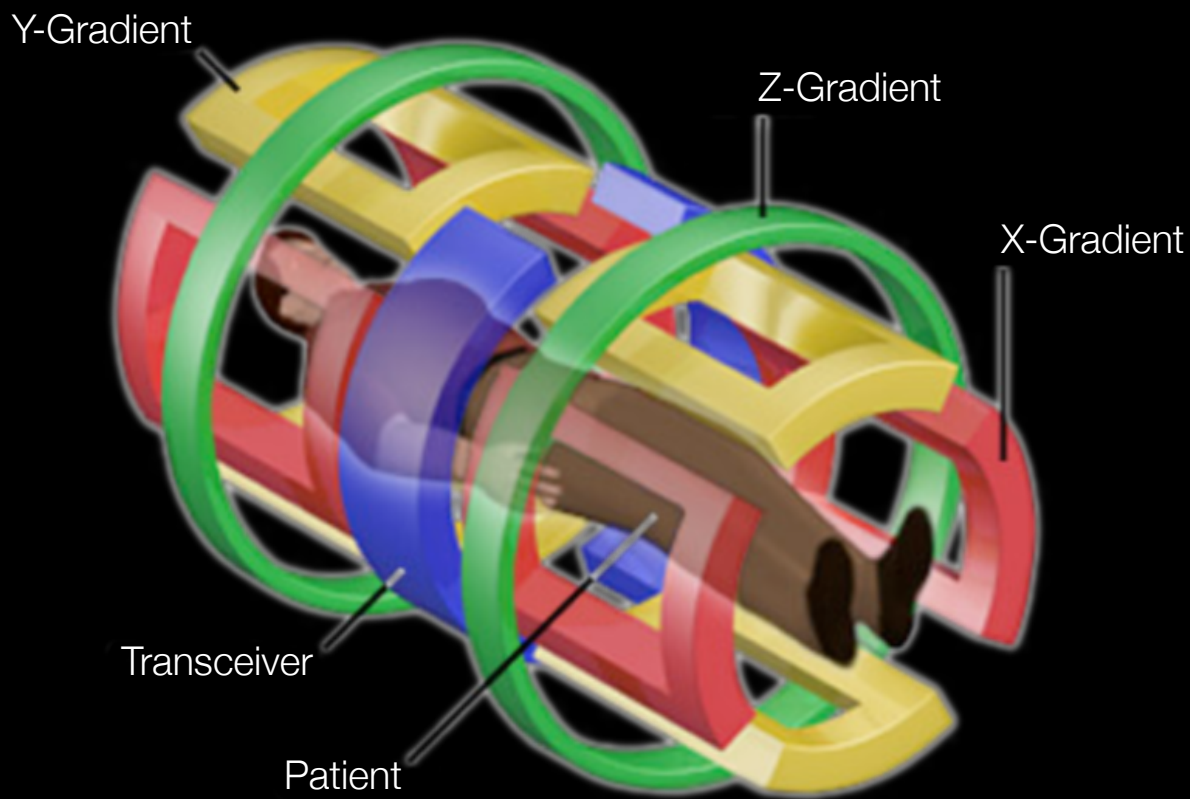
Learning Objectives

- Describe three different roles for gradients.
- Compare the spatial and temporal characteristics of the gradient fields to both B_0 and B_1 .
- Be able to define the magnetic field at any point in space when a gradient is applied.
- Explain how gradients are used to manipulate either spin frequency or phase.
- Compare the assumptions between the B_0 , B_1 , and gradient fields.

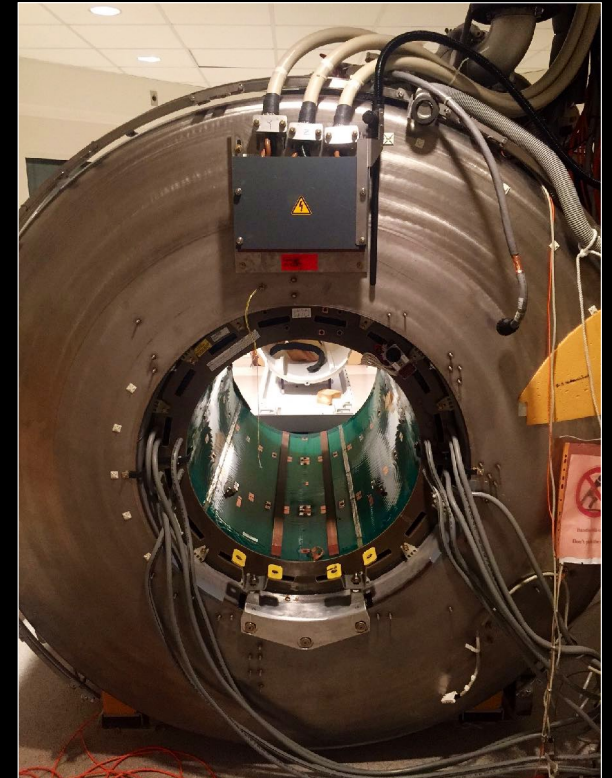


Magnetic Field Gradients (G_x , G_y , G_z)

Gradient Hardware



<http://www.magnet.fsu.edu>



High voltage, high current, and water cooled.

Modern gradient systems operate at the engineering limits of power delivery and heat dissipation.



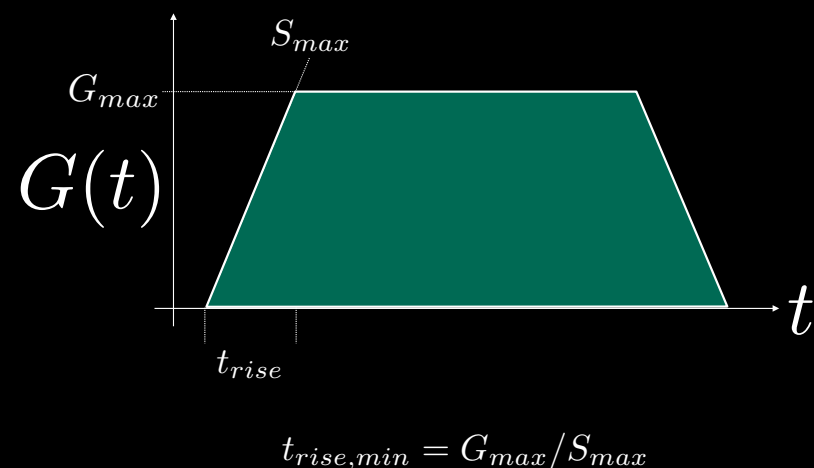
Gradient - Principles

- **Primary function**
 - Encode spatial information
 - Slice selection
 - Phase encoding
 - Frequency encoding
- **Secondary functions**
 - Spin **de**-phasing to minimize artifacts (crushers & spoilers)
 - Spin **re**-phasing after slice selection
 - Spin **pre**-phasing before readout
 - Sensitize/de-sensitize images to motion



Gradient – Characteristics

- Intermediate strength
 - $<80\text{-}100\text{mT/m}$ ($<8\text{-}10\text{ G/cm}$)
 - $<0.0150\text{T}$ (150G) @ edge of 30cm FOV
 - Adds/Subtracts to the B_0 field
 - Parallel to B_0 ; only adds to B_0 in Z-direction
- Spatially varying
 - Linear B-field gradients
- Temporally dynamic (kHz)
 - Slewrate Max. $<200\text{T/m/s}$
 - Risetime $\sim 500\mu\text{s}$
- Gradients are NOT:
 - Fields perpendicular to B_0



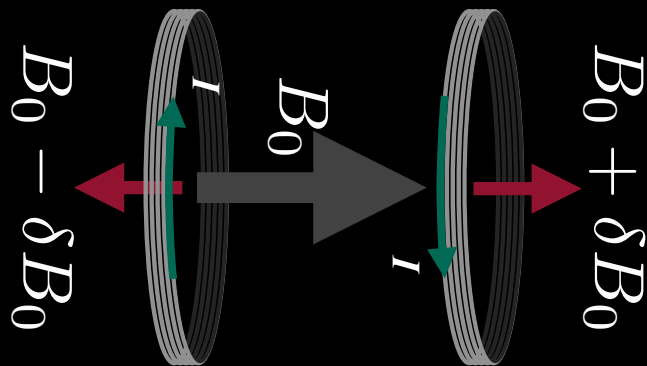
Gradients are “linear” over $\sim 40\text{-}50\text{cm}$ on each axis.



Gradient – Hardware

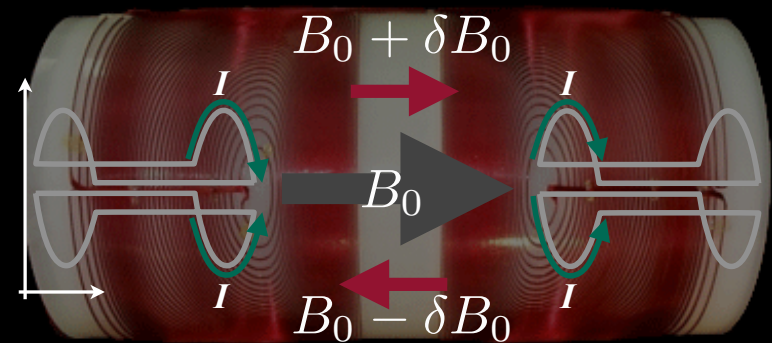
Z-Gradient

- Typically Maxwell pair coil
- Linear B-field variation along z-
- Highly uniform in the xy-plane
- Currents are equal-and-opposite

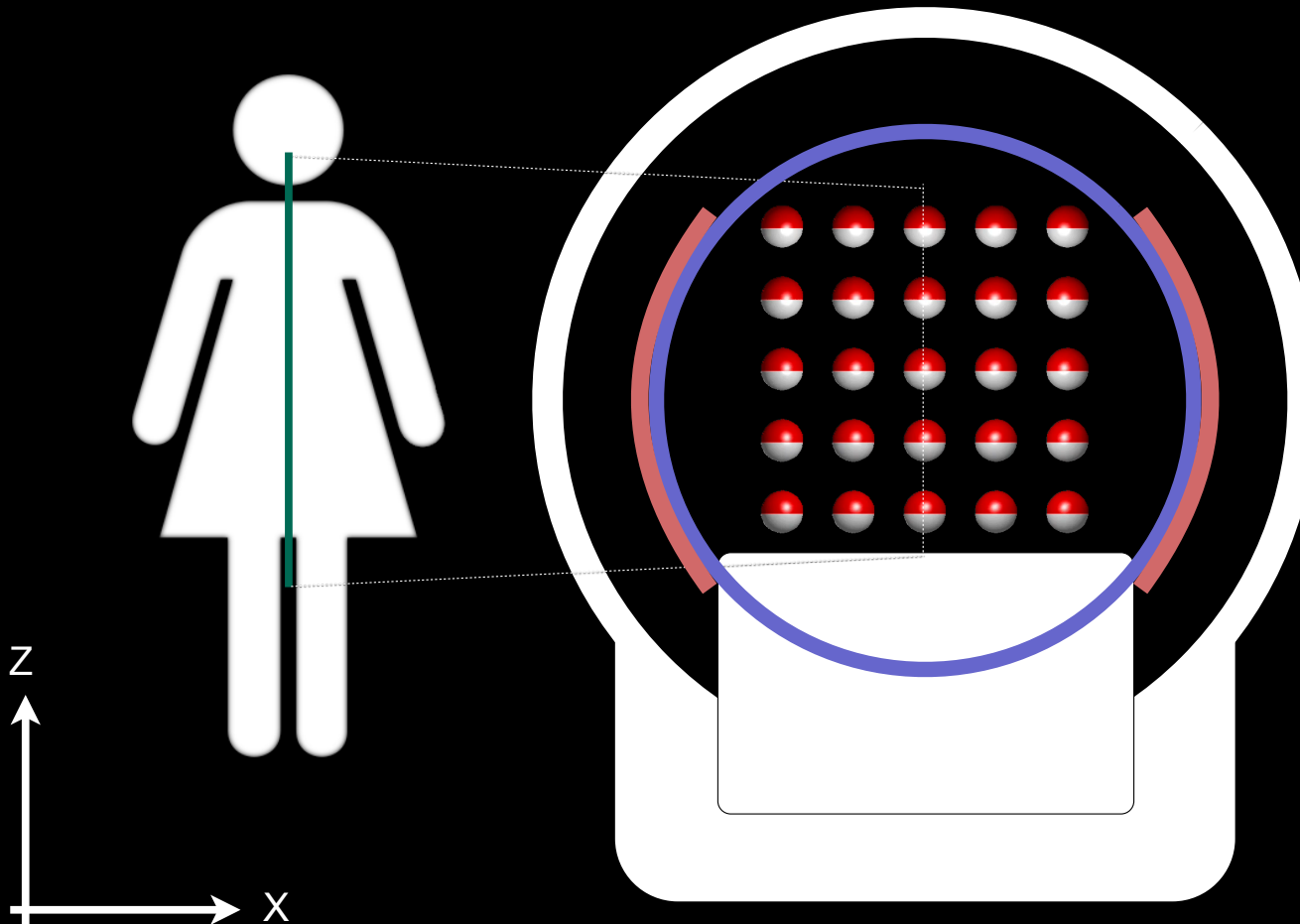
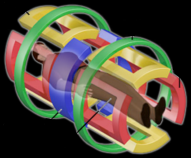


X- and Y-Gradients

- Typically “saddle coils”; Golay Coil Pairs
- Linear B-field variation along x- or y-
- Highly uniform in yz- or xz-plane
- Innermost turns produce gradient field



Spins and X-Gradients

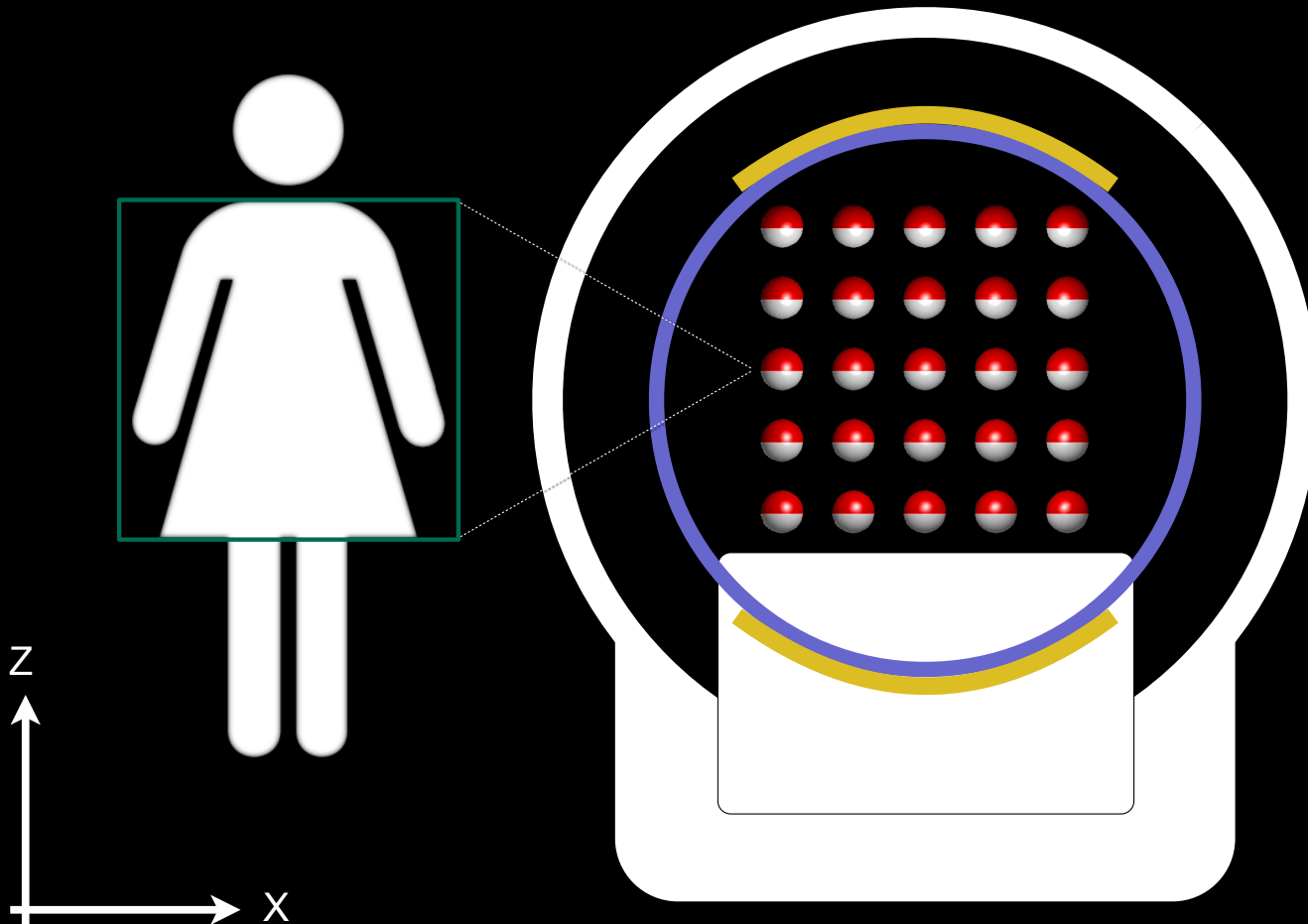
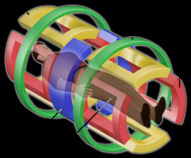


Which coordinate frame is used to display the spins?

Gradients give rise to isochromats (planes of common frequency).

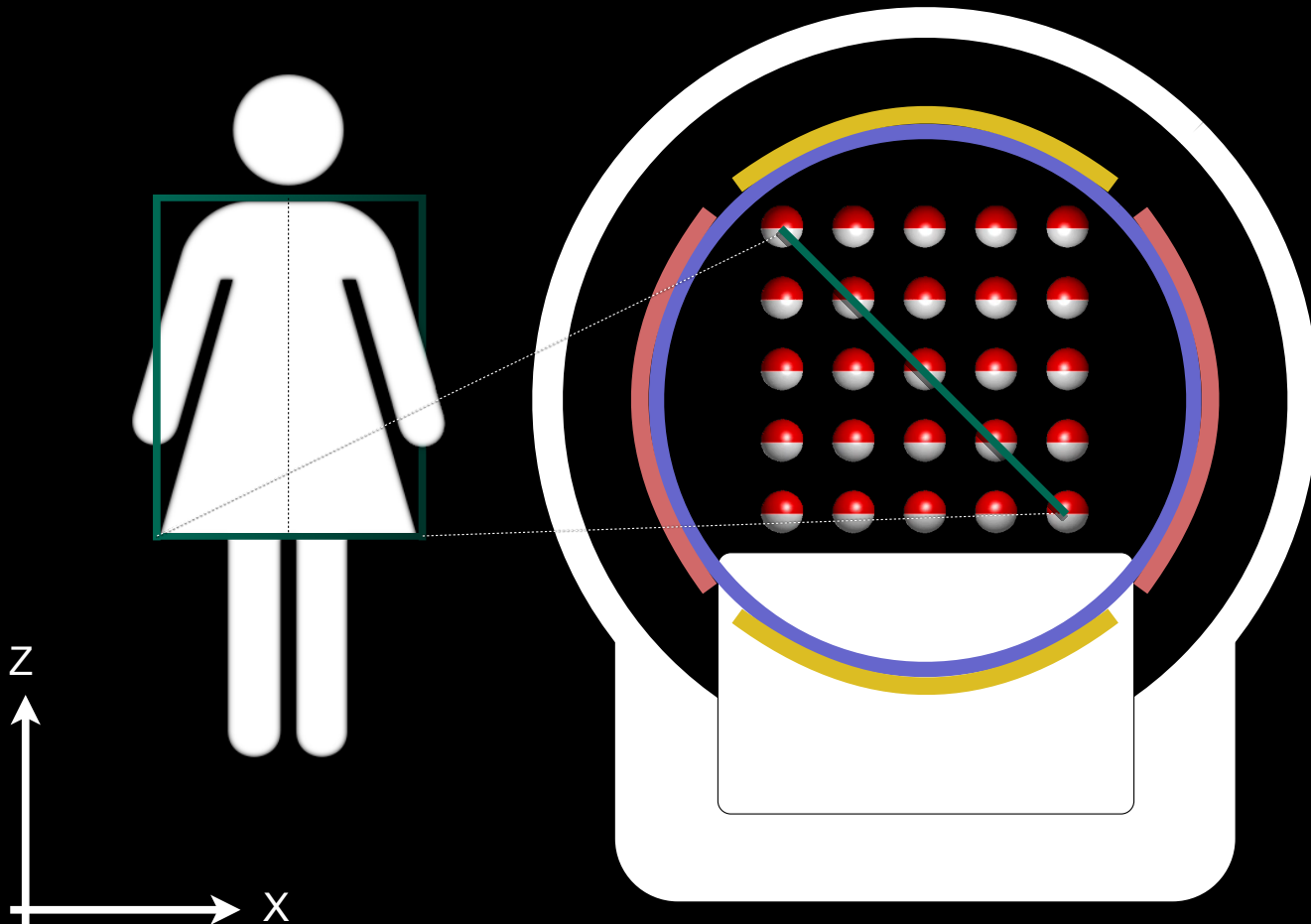
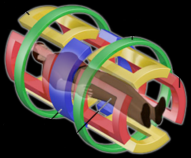


Spins and Y-Gradients



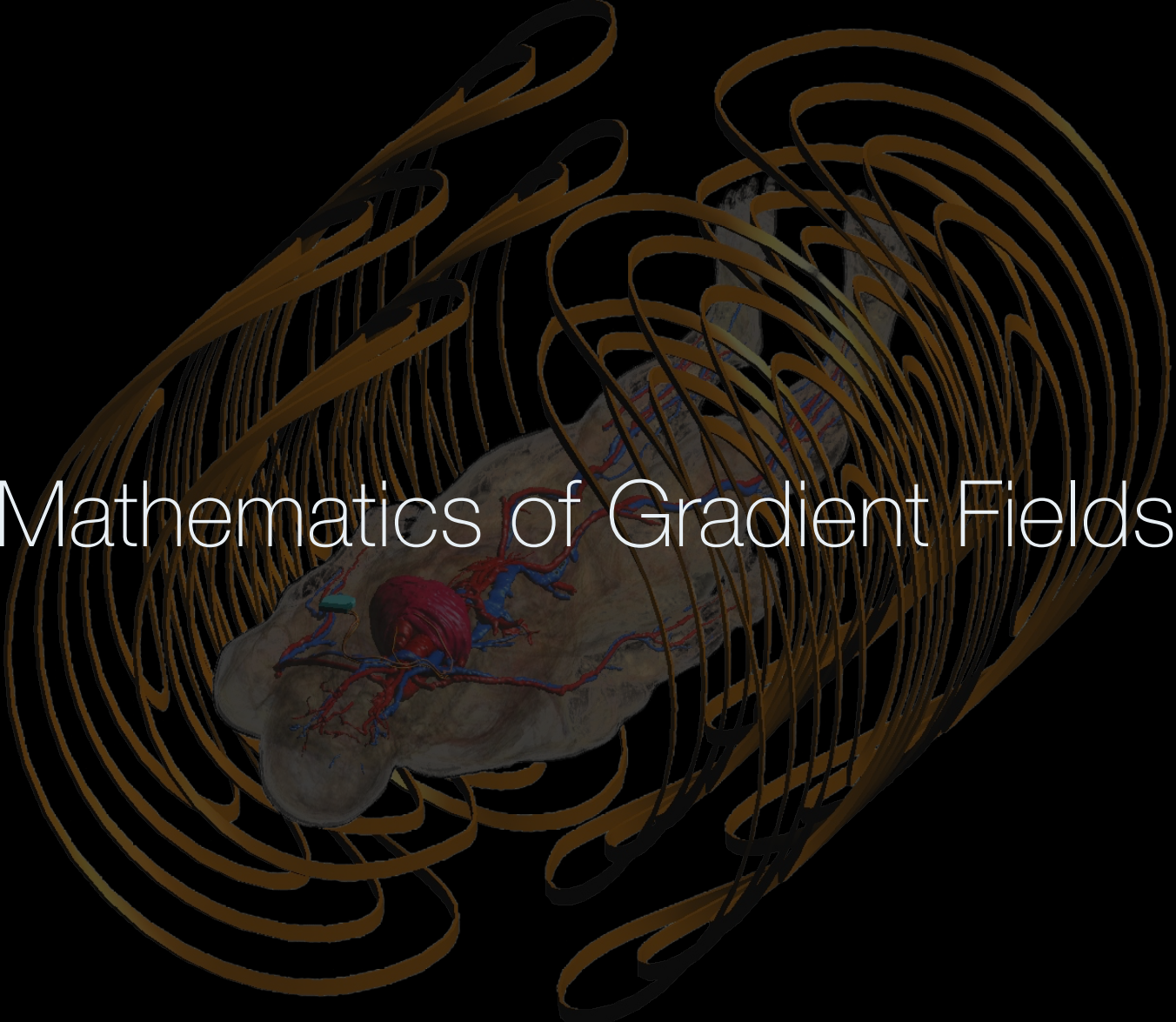
Gradients add/subtract to B_0 along a specific direction.

Spins and X- & Y-Gradients



Simultaneous gradients create an arbitrary isochromat plane.





Mathematics of Gradient Fields

Gradients and B-Fields

- Gradients are a special kind of inhomogeneous B-field whose z-component varies linearly along a specific direction called the gradient direction.

$$\underbrace{B_G}_{\text{B-field from a gradient}}, \underbrace{z}_{\substack{\text{Points} \\ \text{along the} \\ \text{z-direction}}} \underbrace{(x)}_{\substack{\text{Varies} \\ \text{with the} \\ \text{x-direction}}} = \underbrace{G_x}_{\text{x-gradient amplitude}} \underbrace{x}_{\substack{\text{x-position} \\ \text{relative to} \\ \text{isocenter}}}$$

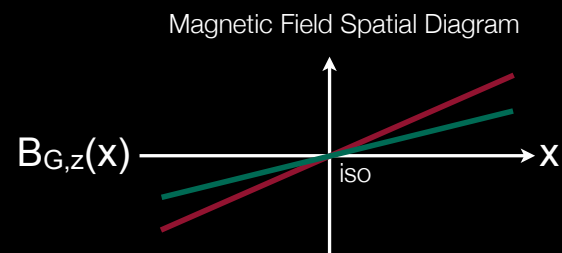
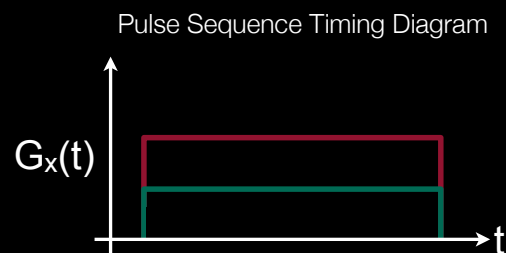


Gradients and B-Fields

$$B_{G,z}(x) = G_x x \quad \text{x-gradient}$$

$$B_{G,z}(y) = G_y y \quad \text{y-gradient}$$

$$B_{G,z}(z) = G_z z \quad \text{z-gradient}$$



Each gradient coil can be activated independently and simultaneously.



Gradients and B-Fields

$$\begin{aligned}\vec{B}_{G,z}(\vec{r}, t) &= (G_x(t) \cdot x + G_y(t) \cdot y + G_z(t) \cdot z) \hat{k}' \\ &= \left(\vec{G}(t) \cdot \vec{r} \right) \hat{k}'\end{aligned}$$

Each gradient coil can be activated independently and simultaneously

$$\begin{aligned}\vec{B}(\vec{r}, t) &= (B_0 + B_{G,z}) \hat{k}' \\ &= \left(B_0 + \vec{G}(t) \cdot \vec{r} \right) \hat{k}'\end{aligned}$$

Gradients contribute to the net B-field, but only along the z-direction



The magnetic field at a position depends on the magnitude of the applied gradient.

Comparison of B-fields Assumptions

- B_0 -field is:

- Perfectly uniform over space.

- “ B_0 homogeneity”

- Perfectly stable with time.

$$\vec{B} = B_0 \hat{k}$$

- B_1 -field is:

- Perfectly uniform over space.

- “ B_1 homogeneity”

- Temporally modulated exactly as specified.

$$\vec{B}_1(t) = B_1^e(t) \left[\cos(\omega_{RF}t) \hat{i}' - \sin(\omega_{RF}t) \hat{j}' \right]$$

- Gradient fields are:

- Perfectly linear over space.

- “Gradient linearity”

- Temporally modulated exactly as specified.

$$\vec{B}_{G,z}(\vec{r}, t) = \left(\vec{G}(t) \cdot \vec{r} \right) \hat{k}'$$



Pay particular attention to the direction of each B -field.

Frequency from a Gradient

$$\vec{\omega} = -\gamma \vec{B}$$

Larmor equation arises from free precession and the equation of motion.

$$\downarrow$$
$$-\gamma \vec{G}(t) \cdot \vec{r}$$

$\downarrow$
Gradients contribute and additional B-field that is space and time dependent.



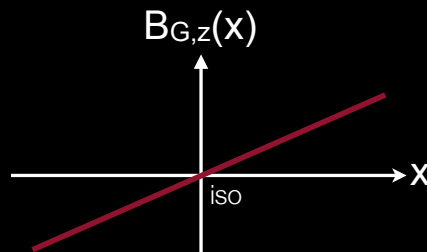
The ability to spatially manipulate the B-field enables spatial encoding with frequency and phase.

Frequency from a Gradient

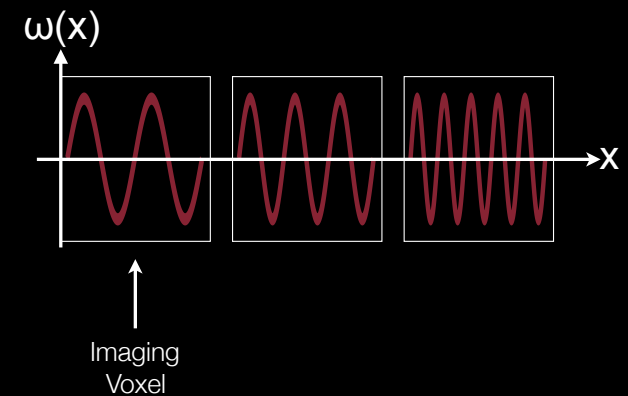
Pulse Sequence Timing Diagram



Magnetic Field Spatial Diagram



Frequency Spatial Diagram



What happens when the gradient is turned off?

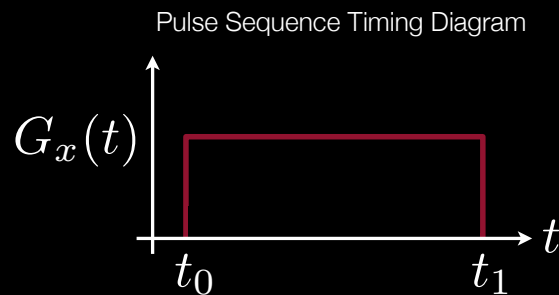
Active control of the magnetic field gradients spatially manipulates the B-field and local Larmor frequency.



Phase from a Gradient

$$\phi_G(\vec{r}, t) = -\gamma \int_0^t \vec{G}(\tau) \cdot \vec{r}(\tau) d\tau \quad \text{Phase from a gradient.}$$

$$\phi_G(x, t) = -\gamma G_x \cdot x \cdot t \quad \text{Phase from a 1-D rectangular gradient waveform.}$$



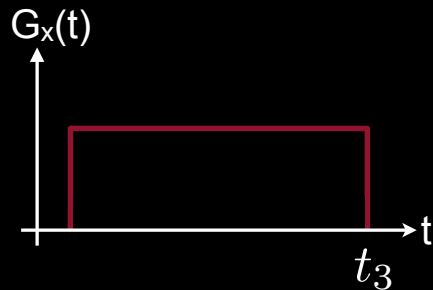
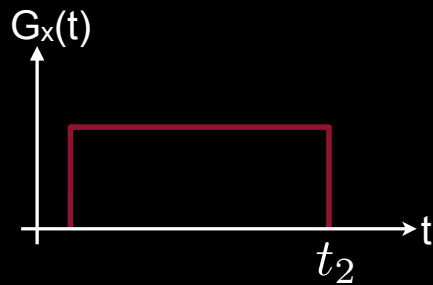
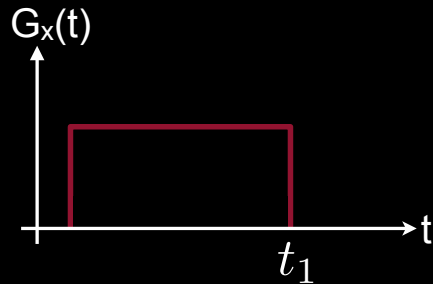
- Longer times confer more phase.
- Stronger gradients impart phase more quickly.



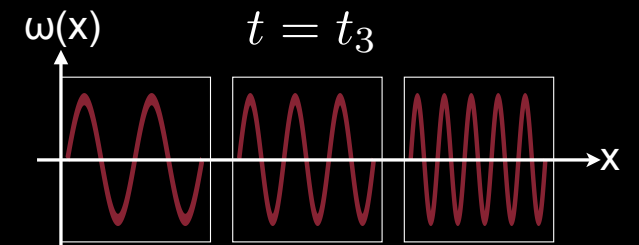
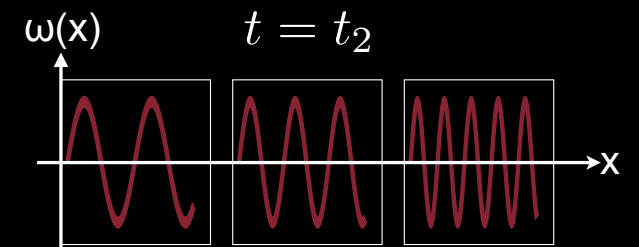
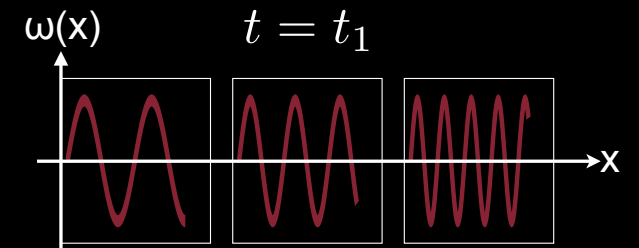
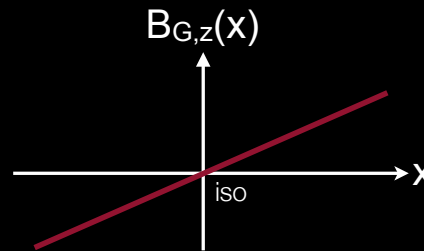
The application of a gradient for a finite period of time “labels” the spins with a spatially dependent amount of phase.

Phase from a Gradient

Pulse Sequence Timing Diagram



Magnetic Field Spatial Diagram



Active control of the magnetic field gradients spatially manipulates the B-field and local Larmor frequency.



How are gradients used
for spatial localization?

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