Lecture 4 Estimating the Covariance Function

Dennis Sun Stanford University Stats 253

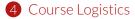
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Generalized Least Squares

We saw that if the model is

$$\mathbf{y} = X\boldsymbol{\beta} + \boldsymbol{\epsilon},$$

where $E[\boldsymbol{\epsilon}|X] = \mathbf{0}$ and $Var[\boldsymbol{\epsilon}|X] = \Sigma$, then the best estimator is

$$\hat{\boldsymbol{\beta}}^{GLS} = (X^T \Sigma^{-1} X)^{-1} X^T \Sigma^{-1} \mathbf{y}.$$



Covariance Functions

- Σ is usually unknown, and there is no hope of estimating it from just n observations.
- So we parametrize Σ , i.e., $\Sigma = \Sigma_{\theta}$.
- There is often a covariance function $\Sigma_{\theta}(\mathbf{s}, \mathbf{s}')$ on the space where the observations lie, and we obtain $(\Sigma_{\theta})_{ij} = \Sigma_{\theta}(\mathbf{s}_i, \mathbf{s}_j)$.
- Examples include

•
$$\Sigma_{\boldsymbol{\theta}}(\mathbf{s}, \mathbf{s}') = \max(\theta_1 - \theta_2 d(\mathbf{s}, \mathbf{s}'), 0)$$

• $\Sigma_{\boldsymbol{\theta}}(\mathbf{s}, \mathbf{s}') = \theta_1 \exp\{\theta_2 d(\mathbf{s}, \mathbf{s}')\}.$



Today

- We estimate $\boldsymbol{\theta}$ from the data.
- We will learn two ways: (1) the HackTM and (2) model-based.







3 Model-Based Approach





"The Chicken or the Egg" Problem

- To calculate $\hat{oldsymbol{eta}}^{GLS}$, we need an estimate of Σ .
- To estimate $\Sigma = \operatorname{Var}({m \epsilon})$, we need an estimate of the error

$$\hat{\boldsymbol{\epsilon}} = \mathbf{y} - X\hat{\boldsymbol{\beta}}^{GLS},$$

so we need $\hat{oldsymbol{eta}}^{GLS}$.

Solution: Use $\hat{\pmb{\beta}}^{OLS}$ as a "preliminary" estimate and estimate Σ using

$$\hat{\boldsymbol{\epsilon}} = \mathbf{y} - X\hat{\boldsymbol{\beta}}^{OLS}$$



Estimating the Covariance

- Now that we have $\hat{\epsilon}$, how do we estimate the covariance?
- $\Sigma_{ij} = \Sigma(d(\mathbf{s}_i, \mathbf{s}_j))$ is assumed to be a function of the distance between the points. So we need to estimate the covariance function $\Sigma(h)$.
- If data is regularly spaced, then estimate Σ(h) by the covariance of the observations spaced h apart:

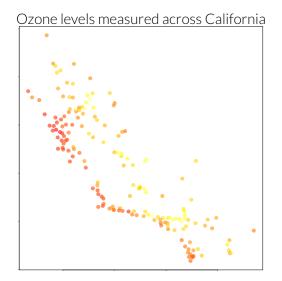
$$\hat{\Sigma}(h) = \frac{\sum_{(i,j)\in S_h} \hat{\epsilon}_i \hat{\epsilon}_j}{|S_h|},$$

where $S_h = \{(i, j) : d(\mathbf{s}_i, \mathbf{s}_j) = h\}.$

If data is irregularly spaced, then we look in a window around
 h.

$$\hat{\Sigma}(h) = \frac{\sum_{(i,j)\in S_{h,\delta}} \epsilon_i \epsilon_j}{|S_{h,\delta}|},$$
where $S_{h,\delta} = \{(i,j) : d(\mathbf{s}_i, \mathbf{s}_j) \in [h - \delta, h + \delta]\}.$





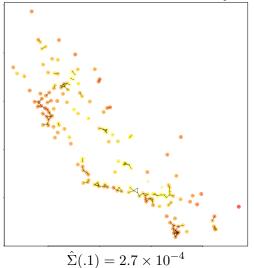


Residuals $\hat{\epsilon}$ after regressing out latitude and longitude



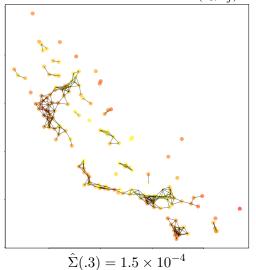


Pairs of observations where $0 \le d(\mathbf{s}_i, \mathbf{s}_j) < .2$



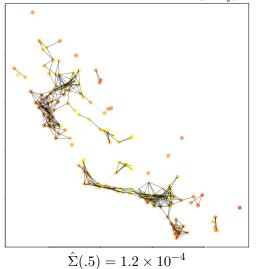


Pairs of observations where $.2 \le d(\mathbf{s}_i, \mathbf{s}_j) < .4$



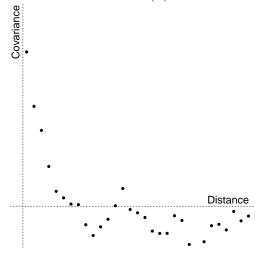


Pairs of observations where $.4 \leq d(\mathbf{s}_i, \mathbf{s}_j) < .6$

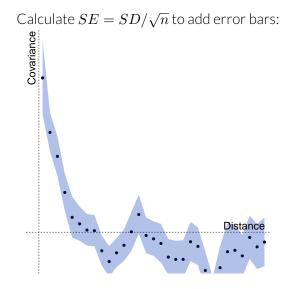




 $\operatorname{Plot} \operatorname{of} \hat{\Sigma}(h)$









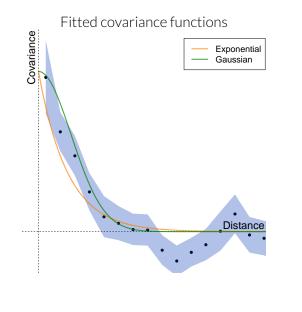
Estimating θ

- Can we just connect the dots and call that the covariance function?
- No! Not guaranteed to be positive definite.
- Parametrizing the covariance as $\Sigma_{\theta}(h)$ helps ensure that the covariance is positive definite.
- Choose **heta** to minimize the difference between the observed and theoretical covariance function:

$$\hat{\boldsymbol{\theta}} = \operatorname*{argmin}_{\boldsymbol{\theta}} \sum_{h} w_h (\hat{\Sigma}(h) - \Sigma_{\boldsymbol{\theta}}(h))^2.$$

• The w_h are weights. We may want to downweight bins for which we have less data, i.e., $w_h \propto N_h$.







Now that we've estimated the covariance function as

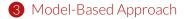
$$\hat{\Sigma}(h) = .00025e^{-2.496h^2}$$

we can go back and fit generalized least squares!













Model-Based Approach

- The Hack suffers from two drawbacks:
 - We used $\hat{\beta}^{OLS}$ to get a preliminary estimate of ϵ when we really should be using $\hat{\beta}^{GLS}$.
 - The final fitting of the covariance function to the data requires manual tuning of parameters: bin size, weights w_h , etc.
- Another approach is to assume a parametric model and estimate the parameters by maximum likelihood.



The Model

The model is still

$$\mathbf{y} = X\boldsymbol{\beta} + \boldsymbol{\epsilon},$$

with $E[\boldsymbol{\epsilon}|X] = \mathbf{0}$ and $Var[\boldsymbol{\epsilon}|X] = \Sigma_{\boldsymbol{\theta}}$, except now we further assume that $\boldsymbol{\epsilon}$ is normal.

We can now write down a likelihood for our data:

$$\frac{1}{(2\pi)^{n/2} (\det \Sigma_{\boldsymbol{\theta}})^{1/2}} \exp\left\{-\frac{1}{2} (\mathbf{y} - X\boldsymbol{\beta})^T \Sigma_{\boldsymbol{\theta}}^{-1} (\mathbf{y} - X\boldsymbol{\beta})\right\},\,$$

which we can optimize over $\boldsymbol{\beta}$ and $\boldsymbol{\theta}$ simultaneously.



Calculating the MLE

$$\frac{1}{(2\pi)^{n/2} (\det \Sigma_{\boldsymbol{\theta}})^{1/2}} \exp\left\{-\frac{1}{2} (\mathbf{y} - X\boldsymbol{\beta})^T \Sigma_{\boldsymbol{\theta}}^{-1} (\mathbf{y} - X\boldsymbol{\beta})\right\}.$$

The log-likelihood is

$$-\frac{1}{2}\log \det \Sigma_{\boldsymbol{\theta}} - \frac{1}{2}(\mathbf{y} - X\boldsymbol{\beta})^T \Sigma_{\boldsymbol{\theta}}^{-1}(\mathbf{y} - X\boldsymbol{\beta}).$$

Let's first optimize over β for any fixed θ . That is, what is $\hat{\beta}(\theta)$?

Why, it's the GLS estimator! $\hat{\boldsymbol{\beta}}(\boldsymbol{\theta}) = (X^T \Sigma_{\boldsymbol{\theta}}^{-1} X)^{-1} X^T \Sigma_{\boldsymbol{\theta}}^{-1} \mathbf{y}.$

Let's plug this into the log-likelihood:

$$-\frac{1}{2}\log \det \Sigma_{\boldsymbol{\theta}} - \frac{1}{2}(\mathbf{y} - X\hat{\boldsymbol{\beta}}(\boldsymbol{\theta}))^T \Sigma_{\boldsymbol{\theta}}^{-1}(\mathbf{y} - X\hat{\boldsymbol{\beta}}(\boldsymbol{\theta})).$$

Now we "just" have to optimize this over $\boldsymbol{\theta}$.



Calculating the MLE

$$-\frac{1}{2}\log \det \Sigma_{\boldsymbol{\theta}} - \frac{1}{2}(\mathbf{y} - X\hat{\boldsymbol{\beta}}(\boldsymbol{\theta}))^{T}\Sigma_{\boldsymbol{\theta}}^{-1}(\mathbf{y} - X\hat{\boldsymbol{\beta}}(\boldsymbol{\theta}))$$

= ...
= $-\frac{1}{2}\log \det \Sigma_{\boldsymbol{\theta}} - \frac{1}{2}\mathbf{y}^{T}\Sigma_{\boldsymbol{\theta}}^{-1}(I - X(X^{T}\Sigma_{\boldsymbol{\theta}}^{-1}X)^{-1}X^{T}\Sigma_{\boldsymbol{\theta}}^{-1})\mathbf{y}$

To optimize this, you'll need to:

- compute derivative with respect to ${m heta}$
- solve a highly non-convex problem.

However, the dimensionality of $\boldsymbol{\theta}$ is usually small, so you can do a brute-force grid search.



Summary

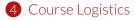
- The Hack is simple and fairly robust. We don't make any distributional assumptions.
- The model-based approach is more principled. But it may be difficult or impossible to compute the MLE in practice, and it is sensitive to the assumption of normality.





2 The Hack

3 Model-Based Approach





Logistics

- Homework 1 will be released tonight and due next Friday.
- It is a data analysis assignment that involves implementing some of the methods we've discussed.
- It is also a prediction competition. There will be prizes for the winners.
- I will provide starter code in R and maybe Python.
- Jingshu Wang, the TA for this course, will have office hours Thursdays 2-4pm.

