

- Solutions should be complete and concisely written. Please, use a separate sheet (or set of sheets) for each problem.
- We will be using Gradescope (<https://www.gradescope.com>) for homework submission (you should have received an invitation) - no paper homework will be accepted. Handwritten solutions are still fine though, just make a good quality scan and upload it to Gradescope.
- You are welcome to discuss problems with your colleagues, but should write and submit your own solution.

## # 1: Convex compact parameter space

Let  $\mathcal{P} = \{P_\theta : \theta \in \Theta\}$  be a statistical model with  $\Theta \subseteq \mathbb{R}^d$  a convex compact set, and  $\Theta$  is not a singleton ( $\Theta$  contains at least two points). Let  $\Theta^\varepsilon = \{\theta : d(\theta, \Theta) \leq \varepsilon\}$ , where  $d(\theta, \Theta) \equiv \inf\{v \in \Theta : \|v - \theta\|_2\}$ . Assume the estimator  $\hat{\theta}$  to take values in  $\mathbb{R}^d$  (i.e. the decision space is  $\mathcal{A} = \mathbb{R}^d$ ).

- Consider the case of square loss  $L(\hat{\theta}, \theta) = \|\hat{\theta} - \theta\|_2^2$ . Assume that (for some  $\varepsilon, \delta > 0$ )  $P_\theta(\hat{\theta}(\mathbf{X}) \notin \Theta^\varepsilon) > \delta$  for all  $\theta \in \Theta$ . Prove that  $\hat{\theta}(\cdot)$  cannot be minimax optimal.
- Keeping to the square loss, consider now the linear model  $P_\theta = N(\mathbf{D}\theta, \sigma^2 I_n)$ , where  $\mathbf{D} \in \mathbb{R}^{n \times d}$  is a known design matrix, of rank  $d$ , and  $\sigma^2 > 0$  is known noise variance. Prove that no affine estimator (i.e. no estimator of the form  $\hat{\theta}(\mathbf{y}) = \mathbf{M}\mathbf{y} + \theta_0$ ) can be minimax optimal.
- Produce a counter-example showing that the conclusion at point (a) does no longer hold if  $\Theta$  is not convex.
- Consider the case  $d = 1$ ,  $\Theta = [\theta_{\min}, \theta_{\max}]$ , and assume that  $L$  is continuous, with  $a \mapsto L(a, \theta)$  is strictly decreasing for  $a < \theta$ , and strictly increasing for  $a > \theta$ . Assume that (for some  $\varepsilon, \delta > 0$ )  $P_\theta(\hat{\theta}(\mathbf{X}) \notin \Theta^\varepsilon) > \delta$  for all  $\theta \in \Theta$ , and that the risk function  $\theta \mapsto R(\hat{\theta}; \theta)$  is continuous. Prove that  $\hat{\theta}$  cannot be minimax optimal.

What can you conclude if  $a \mapsto L(a, \theta)$  is decreasing (but not necessarily strictly decreasing) for  $a < \theta$  and increasing (but not necessarily strictly decreasing) for  $a > \theta$ .

## # 2: On the minimax estimator of a binomial parameter

Let  $X \sim P_\theta = \text{Binom}(n, \theta)$ , where  $\theta \in \Theta = [0, 1]$ , and we consider the square loss  $L(\hat{\theta}, \theta) = (\hat{\theta} - \theta)^2$ . Recall that a minimax estimator is given by

$$\hat{\theta}_{\text{MM}}(X) = \frac{\sqrt{n}}{1 + \sqrt{n}} \cdot \frac{X}{n} + \frac{1}{1 + \sqrt{n}} \cdot \frac{1}{2}. \quad (1)$$

We know already that this is Bayes optimal with respect to the prior distribution  $Q = \text{Beta}(\sqrt{n}/2, \sqrt{n}/2)$ .

- Consider the case  $n = 1$ . Construct a two points prior  $Q = q\delta_{\theta_1} + (1 - q)\delta_{\theta_2}$  whose Bayes optimal estimator coincides with  $\hat{\theta}_{\text{MM}}$ .

(b) Show that, for any  $n$ , there exists a prior supported on  $m$  number of points for some integer  $m$ , whose Bayes estimators coincides with  $\hat{\theta}_{\text{MM}}$ .

[You can assume that the linear system  $\sum_{i=0}^m q_i(i/m)^k = \int \theta^k Q(d\theta)$ ,  $k \in \{0, \dots, n+1\}$  has a solution  $\mathbf{q} = (q_0, \dots, q_m) \geq 0$  for  $m$  large enough. (Here  $Q = \text{Beta}(\sqrt{n}/2, \sqrt{n}/2)$ .)]

### # 3: Minimax estimation of sparse vectors

Let  $\Theta \subseteq \mathbb{R}^d$  and consider estimation with a loss  $L : \mathcal{A} \times \mathbb{R}^d \rightarrow \mathbb{R}_{\geq 0}$  upper bounded by  $L_0$ :  $\sup_{a \in \mathcal{A}, \theta \in \Theta} L(a, \theta) \leq L_0$ .

(a) Prove that, for any probability distribution  $Q$  on  $\mathbb{R}^d$ ,

$$R_M(\Theta) \geq R_B(Q) - L_0 Q(\Theta^c), \quad (2)$$

where  $Q(\Theta^c) = \int_{\Theta^c} Q(d\theta)$  is the probability of  $\Theta^c$  under  $Q$ , and  $R_B(Q) = \int_{\mathbb{R}^d} R(A; \theta) Q(d\theta)$ . (Here we assume that  $P_\theta$  is not only defined for  $\theta \in \Theta$ , but for any  $\theta \in \mathbb{R}^d$ .)

Given two integers  $1 \leq k \leq d$ , and a real number  $M \geq 0$ , define the set of vectors

$$\Theta(d, k; M) = \left\{ \theta \in \{0, +M, -M\}^d : \|\theta\|_0 \leq k \right\}, \quad (3)$$

where  $\|\theta\|_0 = |\text{supp}(\theta)|$  is the number of non-zero entries in  $\theta$ . We are interested in the minimax error for the Gaussian location model with this parameters space  $\mathcal{P} = \{P_\theta : \theta \in \Theta(d, k; M)\}$ , action space  $\mathbb{R}^d$ , and square loss  $L(\hat{\theta}, \theta) = \|\hat{\theta} - \theta\|_2^2$ . We will denote this minimax risk by  $R_M(d, k; M)$ .

(b) Prove that, in determining the minimax error, we can restrict ourselves to estimators that take values in  $\mathcal{A} = B^d(\mathbf{0}; M\sqrt{k}) = \{\theta \in \mathbb{R}^d : \|\theta\|_2 \leq M\sqrt{k}\}$ . Further, we can replace the square loss by  $\tilde{L}(\hat{\theta}, \theta) = \min(\|\hat{\theta} - \theta\|_2^2; 4M^2k)$

(c) Prove that there exists a least favorable prior  $Q_*$ , and that it can be taken of the form

$$Q_* = \sum_{\ell=0}^k p_\ell Q_\ell \quad (4)$$

where  $p = (p_\ell)_{0 \leq \ell \leq k}$  is a probability distribution over  $\{0, 1, \dots, k\}$ , and  $Q_\ell$  is the uniform distribution over vectors in  $\theta \in \Theta(d, k; M)$  with  $\|\theta\|_0 = \ell$ .

[Hint: Note that this claim is equivalent to  $Q_*(\{\theta_1\}) = Q_*(\{\theta_2\})$ , for any  $\theta_1, \theta_2 \in \Theta(d, k; M)$  with  $\|\theta_1\|_0 = \|\theta_2\|_0$ .]

Computing the Bayes risk for the prior  $Q_*$  described above is somewhat intricate. We thus consider a simpler prior  $Q_{M, \varepsilon}$ . Under  $Q_{M, \varepsilon}$  the coordinates of  $\theta$  are independent with  $Q_{M, \varepsilon}(\{\theta_i = M\}) = Q_{M, \varepsilon}(\{\theta_i = -M\}) = \varepsilon/2$ , and  $Q_{M, \varepsilon}(\{\theta_i = 0\}) = 1 - \varepsilon$ . Equivalently  $Q_{M, \varepsilon} = \mathbf{q}_{M, \varepsilon} \times \dots \times \mathbf{q}_{M, \varepsilon}$ , where  $\mathbf{q}_{M, \varepsilon}$  is the three points distribution  $\mathbf{q}_{M, \varepsilon} = (1 - \varepsilon)\delta_0 + (\varepsilon/2)\delta_M + (\varepsilon/2)\delta_{-M}$ .

(d) Prove that

$$R_M(d, k; M) \geq \tilde{R}_B(Q_{M, \varepsilon}) - 4M^2k \mathbb{P}(\text{Binom}(d, \varepsilon) > k). \quad (5)$$

where  $\tilde{R}_B$  is the Bayes risk for the loss function  $\tilde{L}$ .

Setting  $\varepsilon = (k/d)(1 - \eta)$ , it is possible to show (for instance by Bernstein inequality [BLM13]) that

$$\mathbb{P}\left(\text{Binom}(d, \varepsilon) > k\right) \leq e^{-k\eta^2/4}. \quad (6)$$

Let  $R_B$  denote the Bayes risk for the square loss. It is also possible to show that

$$\tilde{R}_B(Q_{M,\varepsilon}) \geq R_B(Q_{M,\varepsilon}) - (M^2 + 1)o_\eta(k), \quad (7)$$

where  $o_\eta(k)$  is a quantity such that  $\lim_{k \rightarrow \infty} o_\eta(k)/k = 0$  for any  $\eta > 0$ .

(e) Prove that the above implies implies

$$R_M(d, k; M) \geq d R_B(Q_{M,\varepsilon}) - (M^2 + 1)o_\eta(k). \quad (8)$$

where  $R_B(Q_{M,\varepsilon})$  is the Bayes risk for the one-dimensional problem of estimating  $\theta \sim q_{M,\varepsilon}$  from  $X = \theta + Z$ ,  $Z \sim N(0, 1)$ .

## Optional

This question will not be graded and is mainly food for thought:

- Continuing from the previous problem, what is the behavior of  $R_B(Q_{M,\varepsilon})$  with  $\varepsilon$  and  $M$ ? What are the consequences for  $R_M(d, k; M)$ ? Of particular interest is the regime  $\varepsilon \ll 1$  (corresponding to  $k \ll d$ ).

## References

[BLM13] Stéphane Boucheron, Gábor Lugosi, and Pascal Massart. *Concentration inequalities: A nonasymptotic theory of independence*. Oxford university press, 2013.