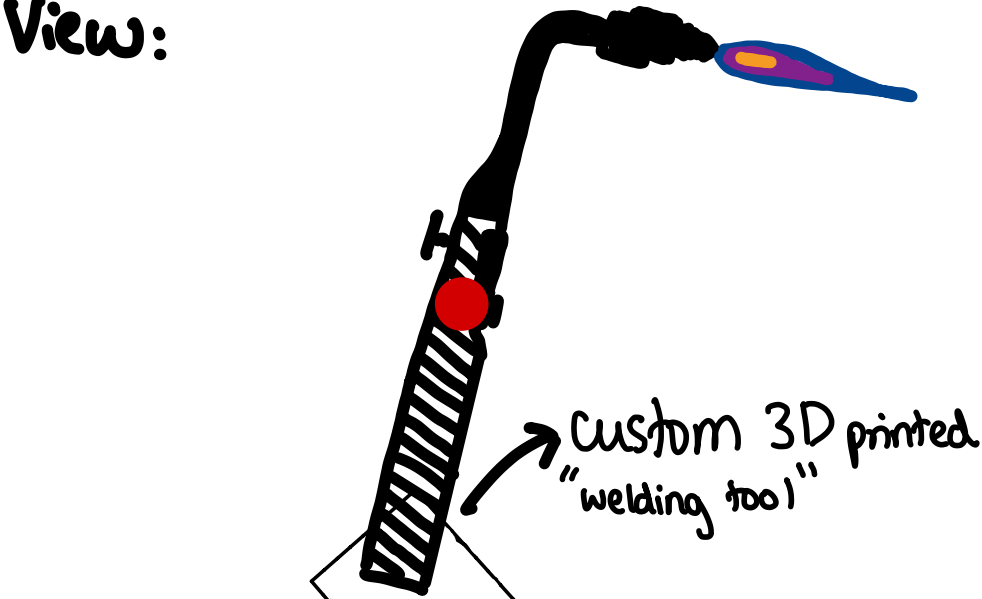
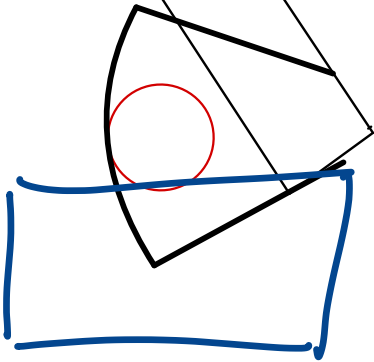


Top View:



custom 3D printed  
"welding tool"

nice box to  
cover the  
mechanics

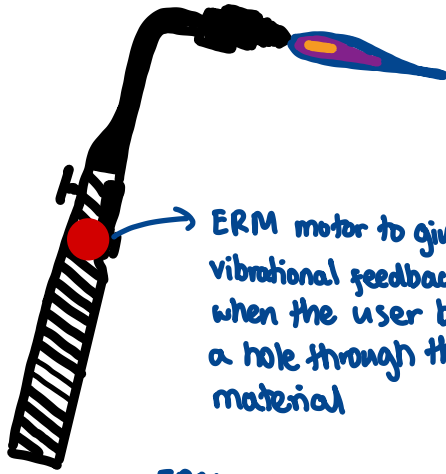


adapted haptic  
handle

haptic motor  
and Arduino  
uno

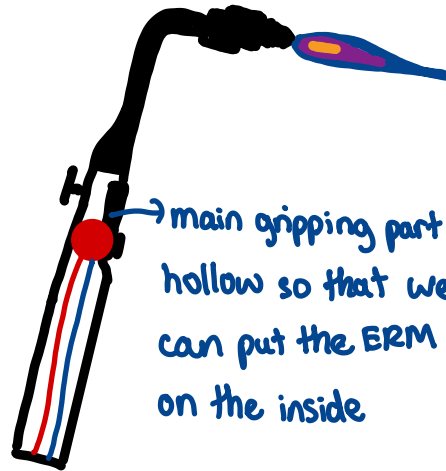
base to fix  
the haptic  
base

## Side View of torch:



ERM motor to give vibrational feedback when the user blows a hole through the material

- ERM motor will be vibrating at a weaker amplitude when the flame is on



main gripping part is hollow so that we can put the ERM on the inside

# Side View of Contraction

