Radiative transfer modeling of a large pool fire by discrete ordinates, discrete transfer, ray tracing, Monte Carlo, and moment methods

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Five computational methods for solution of the radiative transfer equation in an absorbing-emitting and non-scattering gray medium were compared on a 2 m JP-8 pool fire. The temperature and absorption coefficient fields were taken from a synthetic fire due to the lack of a complete set of experimental data for fires of this size. These quantities were generated by a code that has been shown to agree well with the limited quantity of relevant data in the literature. Reference solutions to the governing equation were determined using the Monte Carlo method and a ray tracing scheme with high angular resolution. Solutions using the discrete transfer method, the discrete ordinate method (DOM) with both $S_4$ and $LC_{11}$ quadratures, and moment model using the $M_f$ closure were compared to the reference solutions in both isotropic and anisotropic regions of the computational domain. DOM $LC_{11}$ is shown to be the more accurate than the commonly used $S_4$ quadrature technique, especially in anisotropic regions of the fire domain. This represents the first study where the $M_f$ method was applied to a combustion problem occurring in a complex three-dimensional geometry. The $M_f$ results agree well with other solution techniques, which is encouraging for future applications to similar problems since it is computationally the least expensive solution technique. Moreover, $M_f$ results are comparable to DOM $S_4$.

1. Motivation and objectives

Accurate prediction of the heat flux to an object exposed in a large fire is important for consideration of the thermal hazard to engineered systems, personnel, and facilities. Such fires could potentially occur from a transportation accident. Fires of this scale have relatively low velocities and high temperatures, and therefore the majority of heat transfer to an object is dominated by the radiative emission from high-temperature soot (Gritz et al. 1998). The computational cost for solution of the radiative transfer equation (RTE) is quite high for simulations of fires of this scale. In addition to the common three-dimensional space variables and time, the governing equation also requires integration over all directions of propagation at each point in the domain, adding two angular variables. The challenge, therefore, is to choose a numerical solution method which predicts the radiative flux to objects in fires with sufficient accuracy. Moreover, the radiative source term, which is coupled to the hydrodynamics, must be computed with low cost and sufficient accuracy to ensure a correct prediction of the evolution of the fire.

In this study, five common numerical methods to solve the radiative transfer were
compared when applied to a realistic, full-field three-dimensional fire data set. The five methods include:

1. **Ray tracing**: straightforward integration of the integral equation by tracing a specified number of rays originating from each point through the domain. The method is accurate but costly since it normally requires a large number of angles.

2. **Discrete transfer method**: similar to ray tracing technique, but works in reverse by tracing rays throughout the domain and adding their energy contribution to each cell it passes through.

3. **Discrete ordinate method**: solution of the transport equation by finite volume methods. The angular integration is performed using selected numerical quadrature schemes. The two quadrature schemes used were $S_4$ (24 angles) and $LC_{11}$ (96 angles).

4. **Moment method with the $M_1$ closure (Maximum entropy closure)**: uses moments of the governing equation to convert the angular dependence into a hyperbolic set of four equations for three-dimensional problems. A closure model is required for the radiative pressure term.

5. **Monte Carlo, Net Exchange Formulation**: statistical Monte Carlo method formulated in terms of net exchange and choosing a form of the probability density function for efficient computations. The cost is normally high due to the number of realizations required for good accuracy.

Of these methods, the $M_1$ method has theoretically the lowest cost because the angular dependency is handled analytically. However, the accuracy of the $M_1$ method in complex three-dimensional cases remains unknown. The main questions addressed in this study are: How does each method perform with low angular resolution? How many angles are required for an accurate solution? What is the accuracy of moment methods for fire problems? Which method is most appropriate for a fire?

### 2. Synthetic fire

The radiative heat transfer in large pool fires is dominated by the thermal emission of high-temperature soot and is gray in nature. Solution of the RTE in the participating medium thus requires knowledge of the gray absorption coefficient and emission temperature throughout the medium. Ideally, a complete, highly-resolved set of experimental measurements would be available for this purpose. However, due to the complex fire dynamics (Tieszen et al. 1996), as well as difficulty in instrumenting dichotics in high temperature, sooting environments, relevant data for large scales fires are not available.

Given the lack of available and relevant data, a synthetic 2-meter JP-8 pool fire was created with the Vulcan fire simulation tool from Sandia National Laboratories. Vulcan, and its predecessor (Holen et al. 1990), has been successfully used in recent years for simulating such pool fires which resemble those in the Fire Laboratory for Accreditation of Models and Experiments (FLAME) facility in Albuquerque, New Mexico (Brown & Blanchat 2003). Figure 1 shows, from left to right: the exterior of the FLAME facility, a contour along the centerline plane of the facility showing the fuel pan in the center and the inlet air ring at the bottom of the facility; and the temperature profile of the synthetic fire along the central plane. The facility was discretized with a $92 \times 92 \times 120$ three-dimensional Cartesian grid. The full-field data is axially symmetric with the center defined by the fuel pan. In order to compute the fire, the fluid conservation equations are solved using a Reynolds Averaged Navier Stokes (RANS) approach, with sufficient iterations from ignition to reach a steady-state solution.
The absorption coefficients calculated by Vulcan depend on contributions from soot as well as from carbon dioxide and water vapor. The model for this coefficient assumes that the medium is gray since soot is the dominant absorbing and emitting species. When the domain of computation is as complex as the FLAME facility (see Fig. 1), prescribing common boundary conditions for five different codes can become problematic. Here, using a ghost cell technique, the walls, the pan, and the fuel source were prescribed a very large constant opacity on the order of $O(10^3)$ and ambient temperature 293 K. At the exhaust opening at the top of the chimney, it is assumed that all energy leaves unimpeded.

3. Solution methods for the radiative transfer equation

3.1. Problem definition

The gray radiative transfer equation (RTE) describes the change in radiation intensity, $I$, through an absorbing and emitting gray medium along a path of length $ds$ in a solid angle $d\Omega$ (Modest 2003),

$$\frac{dI(s)}{ds} = \kappa I_b - \kappa I(s) \quad (3.1)$$

where $I_b = \sigma T^4 / \pi$ is the blackbody intensity at temperature $T$, $\sigma$ is the Stefan-Boltzman constant, and $\kappa$ is the absorption coefficient.

For most heat transfer applications, the primary engineering quantities of interest are the net incident radiation $G$, the radiative heat flux ($\mathbf{q}_r$) and the divergence of the heat flux ($\nabla \cdot \mathbf{q}_r$), also called radiative source term. These quantities can be derived from the following integrals of the intensity over solid angle:

$$G = \int_{4\pi} I(s) \ d\Omega, \quad \mathbf{q}_r = \int_{4\pi} I(\Omega) \mathbf{\Omega} \ d\Omega \quad \text{and} \quad \nabla \cdot \mathbf{q}_r = \kappa (4\sigma T^4 - G) \quad (3.2)$$

Solution of the RTE, as well as solutions of Eqs. (3.2), using each solution technique is outlined in the following subsections.
3.2. Discrete transfer method (DTM)

The discrete transfer method (DTM) used in Vulcan is an enhanced version of the original model proposed by Shah (1979). The enhancements were selected to obtain an acceptable compromise between accuracy and calculation speed. This will be tested by comparing the results obtained herein with those obtained from verified and highly accurate Monte Carlo and ray tracing techniques.

Within the computational domain a radiation box is defined to speed the calculation by focusing on the region with high thermal emission. This box defines where rays originate in the tracing technique. For this study, the box was defined as the smallest grid-conformal parallelepiped encompassing all control volumes with a temperature greater than 800 K.

For each node on the boundary of the box, a specified number of rays are emitted over a hemisphere and followed to the boundary of the calculation domain; a corresponding ray is followed back from the boundary to the original point. Along these traces, the change of intensity from absorption and emission is calculated over each control volume in the path with proper weighting given to the solid angle and the originating projected area.

The change of intensity for the ray within a control volume is found from a recurrence relation obtained from analytical integration of Eq. (3.1),

$$I_{n+1} = I_n \exp(-\kappa \delta s) + I_b(1 - \exp(-\kappa \delta s))$$

(3.3)

where $\delta s$ is the distance over which the beam passes through the control volume.

The source term for the energy equation, Eq. (3.2), is found by summing the net gain or loss of radiation energy in each control volume intersected during a ray trace. The contribution to the source term from one beam $i$ passing through a control volume $n$ is given by: $S_{n,i} = (I_{n+1} - I_n)\Omega_i dA \Omega_i$, where $dA$ is the area from the element at the ray origin boundary and $\Omega_i$ is the solid angle represented by the beam. The total radiant source term for the $n$th control volume is found by summing over $N$ total beams:

$$Q_r dV = \sum_{i=1,N} S_{n,i}$$

The heat flux to a surface is not calculated throughout the field of Vulcan, but rather at selected surfaces (e.g., cell faces). The hemispherical flux in W/m$^2$ is derived from this model by integrating all incoming rays on a surface. This integration requires a large number of rays to be traced from each node of the radiation box to be accurate, but from experience it has been found to be quite fast when a limited number of selected surfaces are used. To compare to the other methods, the hemispherical fluxes to the common surface shared by two adjacent cells were summed for the equivalent of a $4\pi$ integration.

3.3. Discrete ordinates method (DOM)

The DOM is based on the discretization of the RTE (see Eq. (3.1)) over a chosen number $N_{dir}$ of discrete directions, $\mathbf{s}_i(\mu_i, \eta_i, \xi_i)$, contained in the solid angle $4\pi$ and associated with weights $w_i$. Koch & Becker (2004) compare several types of angular quadratures, two of which are used here: the $S_4$ (24 directions) for its efficiency and the $LC_{11}$ (96 directions) for its accuracy.

The RTE is solved for every discrete direction $\mathbf{s}_i$ using a finite volume approach. The integration of the RTE over the volume $V$ of an element limited by a surface $\Sigma$ with outer unit normal $\mathbf{n}$ and the application of the divergence theorem yield:

$$\int_{\Sigma} I \mathbf{s} \cdot \mathbf{n} d\Sigma = \int_V (\kappa I_b - \kappa I(\mathbf{s})) dV$$

(3.4)
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The domain is discretized in control volumes (in this study regular hexahedra). Taking $I_j$ to be the average intensity over the $j^{th}$ face, associated with the center of that face, and taking $I_{h,P}$ and $I_P$ to be the average intensities over the volume $V$, associated with the center of the cell, $P$, Eq. (3.4) can be discretized as follows:

$$
N_{\text{face}} \sum_{j=1}^{N_{\text{face}}} I_j(s_i \cdot n_j) A_j = \kappa V (I_{h,P} - I_P) \tag{3.5}
$$

The scalar product of the $i^{th}$ discrete direction vector with the normal vector of the $j^{th}$ face of the considered cell is defined by $D_{ij} = s_i \cdot n_j = \mu_t m_{xj} + \eta_t m_{yj} + \xi_t m_{zj}$.

$I_h$ is assumed to be constant and equal to $I_{h,P}$ over the volume $V$, and $I_j$ is taken constant over each face. For each cell, the incident radiation $G$, given in Eq. (3.2) is evaluated at the center by

$$
G \simeq \sum_{i=1}^{N_{\text{cell}}} w_i I_P(s_i) \tag{3.6}
$$

For a gray medium, one obtains the divergence of the radiative heat flux using Eq. (3.2). To solve Eq. (3.5), a spatial differencing scheme based on the mean flux (DMFS), proposed by Ströhle et al. 2001, is used. This scheme uses the following decomposition:

$$
I_P = \frac{1}{2} I_{\text{out}} + \frac{1}{2} I_{\text{in}} \tag{3.7}
$$

where $I_{\text{in}}$ is the weighted average of the intensities at the entering faces of the cell and $I_{\text{out}}$ the weighted average of the intensities leaving the cell. Substituting $I_{\text{out}}$ from Eq. (3.7) into Eq. (3.5) and after some algebra (see Joseph et al. 2003 for more details), one obtains:

$$
I_P = \left( \frac{1}{2} \kappa V I_h - \sum_{D_{ij} < 0} D_{ij} A_j \right) \left/ \left( \frac{1}{2} \kappa V + \sum_{D_{ij} > 0} D_{ij} A_j \right) \right. \tag{3.8}
$$

After the calculation of $I_P$ from Eq. (3.8), the radiation intensities at those cell faces at which $D_{ij} > 0$ are set equal to $I_{\text{out}}$, obtained from Eq. (3.7).

### 3.4. Monte Carlo method - net exchange formulation (MCM-NEF)

Monte Carlo Methods (MCM) have been often used to produce highly accurate solutions in the process of validating other numerical methods (Coelho et al. 2003; Perez et al. 2004). They first appeared in the literature as strict numeric implementations of stochastic photon transport models (Hammersley & Handscomb 1967). The very large number of realizations required to achieve convergence shows the limitations of the classical Monte Carlo algorithms, particularly when optically thick media are encountered (Farmer & Howell 1994). To overcome these difficulties, a mathematical formulation using the Net Exchange Formulation (NEF) (Cherkaoui et al. 1996), together with adapted probability density functions, have been proposed to improve the variance reduction procedures (de Lattilade et al. 2002). Taking $P_1$ as a point within the volume $V_i$ and $P_2$ within $V_j$, we denote the position vectors of $P_1$ and $P_2$ as $r_{P_1}$ and $r_{P_2}$. The net radiative exchange between two volumes $V_i$ and $V_j$, $\varphi(V_i, V_j)$, or a volume $V_i$ and a surface $S_j$, $\varphi(V_i, S_j)$, or two surfaces $S_i$ and $S_j$, $\varphi(S_i, S_j)$, is expressed as follows for black walls and

† the formulation provided here is also valid for non regular mesh.
non-scattering media

\[
\varphi(v_i,v_j) = \int_{V_i} \int_{V_j} \frac{\kappa(r_{P_i}) \kappa(r_{P_j}) \tau(s_{ij})}{s_{ij}^2} [I_0(r_{P_i}) - I_0(r_{P_j})] dV_i dV_j
\]  
\[
\varphi(v_i,S_j) = \int_{V_i} \int_{S_j} \frac{|n(r_{P_j}) \cdot \mathbf{s}| \kappa(r_{P_j}) \tau(s_{ij})}{s_{ij}^2} [I_0(r_{P_i}) - I_0(r_{P_j})] dV_i dS_j
\]  
\[
\varphi(S_i,S_j) = \int_{S_i} \int_{S_j} \frac{|n(r_{P_j}) \cdot \mathbf{s}| |n(r_{P_j}) \cdot \mathbf{s}| \tau(s_{ij})}{s_{ij}^2} [I_0(r_{P_i}) - I_0(r_{P_j})] dS_i dS_j
\]

where

\[
s_{ij} = s_j - s_i = |r_{P_j} - r_{P_i}|, \quad s = \frac{(r_{P_j} - r_{P_i})}{|r_{P_j} - r_{P_i}|}, \quad \text{and} \quad \tau(s_{ij}) = \exp\left(-\int_{s_{ij}} \kappa(s) ds\right)
\]

with \( n \) the normal vector to the surface \( S_i \), \( \kappa \) the gray absorption coefficient, and \( \tau(s_{ij}) \) is the spectral transmittance along a straight line between \( P_i \) and \( P_j \).

The radiative source term for a volume \( V_i \) and the net heat flux at a surface \( S_i \) are computed by taking into account their radiative exchanges with all the other volumes and surfaces:

\[
S_r(r_{P_i}) = \int_{V_i} \nabla \cdot \mathbf{q}_r dV_i = \sum_{j=1}^{N_s} \varphi(v_i,S_j) + \sum_{j=1}^{N_v} \varphi(v_i,v_j)
\]

and

\[
q_{w,net,i} = \sum_{j=1}^{N_s} \varphi(S_i,S_j) + \sum_{j=1}^{N_v} \varphi(S_i,v_i)
\]

where \( N_s \) is the number of surfaces and \( N_v \) the number of volumes.

One way of evaluating the multiple integrals in the expressions for the net exchange rates, Eqs. (3.9), (3.10), (3.11), is to use a Monte Carlo Method, which is now described.

Considering that each radiative exchange can be represented as an integral \( \mathcal{I} \), of a function \( f \), over a domain \( D \); \( \mathcal{I} = \int_{D} f(x) dx \). An arbitrary probability density function (pdf), \( p \), defined and strictly positive on the integration domain \( D \) is introduced. The weight function \( W(x) = f(x)p(x) \) is used to write

\[
\mathcal{I} = \int_{D} f(x)p(x) dx = \int_{D} W(x)p(x) dx
\]

Given a random variable \( X \), distributed according to \( p \), and a function of that variable, \( g(X) \), we let \( \mathcal{I} \) represent the expectation of \( g(X) \). Estimating \( \mathcal{I} \) with \( N \) samples \( g(x_i) \), where \( x_i \) is the \( i \)th realization of the random variable \( X \) gives

\[
\mathcal{I} = E[g(X)] \approx \frac{1}{N} \sum_{i=1}^{N} g(x_i) =< g(X) >_N, \quad \text{where} \quad \mathcal{I} = \lim_{N \to \infty} < g(X) >_N
\]

Then the standard deviation of the estimate is calculated as \( \sigma(< g(X) >_N) = \frac{1}{\sqrt{N}} \sigma(g(X)) \), where \( \sigma(g(X)) \) is the standard deviation of \( g(X) \). It will be approximated by

\[
\sigma(< g(X) >_N) \approx \frac{1}{\sqrt{N}} \sqrt{< g(X)^2 >_N - < g(X) >_N^2}
\]

In this last expression the variance depends on the function \( g \) which itself depends on the
pdf. To perform efficient MC simulations, the choice of the pdf is crucial. More details are described in (de Lavaillaume et al. 2002; Eymet et al. 2004). The results presented in this paper have a standard deviation of about 1 percent.

3.5. Ray tracing method

This method treats the RTE as a set of first-order ODEs, with one ODE for each spatial point and directional angle. At each spatial point \( x \), a set of rays is considered to project inward toward the point, with the set being chosen to sample solid angle space in such a way as to allow accurate integration over that space to compute the net incident radiation and the heat flux. For the fire problem, the rays are followed outward from the chosen point until they intercept a wall or the exit of the chimney. At such a boundary point the initial value of the incoming radiative intensity is set to equilibrium \((I = I_b)\). From this initial value, the RTE is integrated forward along the ray to the chosen spatial point, and the value at that point is saved for inclusion in angular integrals involving \( I(x, \Omega) \).

The method of integration along a ray assumes that, within each step of the quadrature, the source \( I_0 \) and opacity \( \kappa \) are constants equal to their interpolated values at the center of the step. With this assumption, \( I(s, \Omega) \) can be advanced from one end of the step, \( s_0 \), to the other, \( s_1 \), according to the following rule

\[
I(s_1, \Omega) = I(s_0, \Omega) \exp(-\kappa|s_1 - s_0|) + I_b(1 - \exp(-\kappa|s_1 - s_0|))
\]  

(3.17)

Once the full set of angular values \( I(x, \Omega) \) is obtained at the point \( x \), angular integrals, such as those in Eqs. (3.2), are performed to compute quantities of interest.

3.6. Moment methods and the \( M_1 \) closure

A system of equations for two moments, the net incident radiation \( G \) and the radiative flux \( q_r \), can be extracted from the gray RTE, Eq. (3.1), by integrating it over all directions. The system is given by

\[
\frac{1}{c} \partial_t G + \nabla \cdot q_r = \kappa (4\sigma T^4 - G)
\]  

(3.18)

\[
\frac{1}{c} \partial_t q_r + \nabla \cdot (D_r \cdot G) = -\sigma q_r
\]  

(3.19)

The \( M_1 \) closure (Levermore 1984; Fort 1997) is given by the following Eddington tensor \( D_r \). It is computed from the Eddington factor \( \chi \) and the anisotropic factor \( f = q_r/G \) as follows

\[
D_r = \frac{1 - \chi}{2} \mathrm{Id} + \frac{3\chi - 1}{2} \frac{f \otimes f}{f^2} \quad \text{with} \quad \chi(f) = \frac{3 + 4f^2}{5 + 2\sqrt{4 - 3f^2}}
\]  

(3.20)

where \( \mathrm{Id} \) denotes the identity matrix, \( f \) the euclidian norm of \( f \), and \( \otimes \) the dyadic product. The Eddington tensor \( D_r \), which plays the role of a flux limiter, comes from an underlying radiative intensity which is able to describe both a beam (by a Dirac function) as well as isotropic radiation (by a Planck function). Hence, the \( M_1 \) model is able to predict radiation in opaque, semi-opaque or transparent media and, as we show below, is particularly suited for the computation of radiation in fires. The numerical scheme used to solve this model is given in Ripoll et al. 2002.

† more references concerning this model can be found in Ripoll 2004.
4. Results and discussion

4.1. Angular resolution and coupling

In this section, the number of angles (or rays) needed for the fire computation is investigated using the ray tracing code, which helped define the required angular resolution and quadrature schemes for comparison of the solution methods. Figures (2) and (3) (left) show the radiative source term and radial heat flux profiles calculated at various angular resolutions. It is found that a low resolution, less than 50 angles, leads to poor results both inside and outside the fire. When only 5 or 10 angles are used, a hot source might be hit or not according to the angles chosen, in other words, ray effects are dominant and the results vary greatly based on this choice.

Inside the fire, it is found that at least 50 rays are needed to get a solution close to the converged one† (see Fig. 2). However outside the fire, Fig. 3 (left), it is found that 350 angles are needed to get an acceptable solution and to reduce ray effects. Hence, because such resolutions are needed for accuracy, a high computational cost is expected. Nevertheless, these results must be balanced by the fact that neither special quadratures, nor particular choices of angles have been used herein to try to improve the accuracy of the results for low angular resolution. In the ray tracing solver, angles are uniformly distributed in $\mu = \cos(\theta)$ and $\phi$, which is not the optimal choice. Undoubtedly a better choice of angles and/or quadratures would decrease the number of angles needed to get accurate results‡.

In Fig. 3 (right), it is shown how the angular resolution does affect the time-dependent coupled problem. Here, radiation and hydrodynamics are solved coupled by Vulcan and evolve in time. Radiation is solved by the DTM method. It is found that 24 angles do not lead to an accurate solution and induce strong temporal variation of the radiative flux, which leads to fluctuations in the hydrodynamic quantities. Moreover, since the coupling between radiation and hydrodynamics is very strong in fires, a poor computation of the

† Angular convergence was obtained with 20,000 angles (100 x 200). All results presented with the RTE ray tracing solver in this study were obtained with this resolution.

‡ The reader might be interested in seeing which angular quadrature is needed for radiation in a solar atmosphere Stein et al. in this volume.
Figure 3. Left: Radial component of the radiative flux (W/m²) as a function of elevation from the fuel pan computed by ray tracing for different resolutions (θ, φ) at r = 2.55 m from the centerline of the fuel pan. Right: time evolution profiles of the radial component of the radiative flux at r = 0.5 and z = 0.5 m inside the fire for several angular resolutions using DTM.

radiation can, for instance, lead to extinction or to an over/under-estimation of soot formation.

Starting from 80 angles, which seems to be a good compromise between speed and accuracy, the Vulcan results are close to convergence, but the fluctuations are still significant. Results are considered converged for a resolution of 350 angles. As a result of these observations, the code is usually run with 80 angles to quickly obtain a fully developed fire. The results are converged afterward using 350 angles over a smaller time interval.

4.2. Radiative source term

A comparison of the radiative source terms (di/dt(q)) obtained by all methods is now provided. Since this quantity is the coupling term used by the hydrodynamics solver, its accurate computation is mandatory to compute the correct final fire profile. The ray tracing code and the Monte Carlo code are used for the reference solutions. Both codes find similar solutions at all points in the facility. In Fig. 4 (left), the results are presented for points inside the fire. Good global agreement is found between all methods, though the DTM profile is slightly shifted from the ray tracing reference solution; DTM, M, and DOM S slightly overestimate the maximum value, and DOM LC slightly underestimates it. These small differences of less than 3% are sufficiently small to not have strong effects on the coupled energy equation. The accuracy and general agreement between these results is expected for this case where the radiation field inside the fire is mainly isotropic, f < 0.2, making it less sensitive to angular resolution.

For points outside, but still adjacent to, the fire, at r = 1.5 m (see Fig. 4 (right)), more discrepancies are seen among the methods. The DOM S method is found to be less accurate, though still acceptable, compared to the DOM LC because the angular

† All results presented here with the DTM have been obtained with 350 angles.

‡ when this term is positive (negative), net emission (absorption), is occurring.

§ The Monte Carlo code was primarily used to ensure that the solution given by the ray tracing was fully correct. It has been applied only at selected positions and not for all nodes of the domain.

∥ a large error far outside the fire would not affect the dynamics of the fire and is hence not damaging.
variation is not fully captured by $S_4$ and ray effects occur. The $M_1$ model gives results as accurate as those of the DOM $S_4$, which is encouraging. These methods slightly underestimate absorption while the DTM method overestimates it. Despite the discrepancies, the magnitude of the source term is sufficiently small compared to that inside the fire that less accuracy is acceptable.

4.3. Radial heat flux

Since the Monte Carlo code, by its formulation, does not allow the computation of the radiative fluxes which are compared herein, the ray tracing results are used as the reference. In Figs. 5 and 6, net radial heat flux inside the fire are compared. All methods qualitatively agree and predict the same trends. Higher up, for $z > 1.5$ m, all methods fully agree since strong temperature and opacity gradients are absent. The three methods, $M_1, S_4$ and $LC_{11}$ are in good agreement with the reference solution, but slightly underestimate the flux. The DTM method agrees globally with the other methods and the reference solution, but overestimates slightly, similar to $LC_{11}$, fluxes close to the outer edge of the fuel pan at $r = 1$ and $z = 0$ m. Similarly to the source term computation, the $M_1$ and $S_4$ methods give comparable results. No noticeable difference is observed between $S_4$ and $LC_{11}$, whose results agree well with those of the ray tracing method.

The fact that $S_4$ computes both flux and source terms relatively well, when linked with the angular studies of section 4.1, implies that 24 angles should be enough inside the fire provided that the $S_4$ set of angles is chosen. This constitutes an improvement by a factor of two of the number of angle needed, compared to the use of uniformly distributed angles†.

In Fig. 7, the fluxes outside the fire are compared. The DTM method gives results in agreement with the ray tracing solver. The DOM $LC_{11}$ gives similar results, which suggest that approximately a hundred angles should be enough to compute radiation at 1 or 2 diameters away from the fire provided an accurate quadrature is chosen. This constitutes an improvement by a factor 3 compared to a uniformly spaced angular set which apparently needs 350 angles (see section 4.1). The DOM $S_4$ does not have enough angular

† It should be noted that the 24 angles of DTM used in the time evolution computation are uniformly distributed. This explains the inaccurate results of the time dependent problem for this angular resolution.
5. Conclusions

Five different methods have been used to compute the radiative field of a synthetic 2-meter JP-8 pool fire: Monte Carlo ray tracing, DOM $S_4$, and $LC_{11}$, DTM, and the $M_1$ moment model. Particular interest has been given to the $M_1$ method which is applied for the first time to a combustion problem occurring in a complex three-dimensional

\[ \text{a ray effect can be seen at } z = 0.1 \text{ m due to the pan}. \]
geometry. Theoretically, this model should have the lowest computational cost of the five, since the directional integration has been modeled.

An angular resolution study has shown that roughly 50 angles inside and 350 outside the fire are needed to accurately compute radiation when a uniformly distributed set of angles is chosen. This choice of angles is not optimum, however, and the number of angles needed can be reduced to 24 inside and to roughly 100 outside when an optimum set is chosen, as is the case for both the $S_4$ and LC11 quadratures. Unfortunately, these numbers are still too high to guarantee a low cost computation. It has also been shown that if an insufficient angular distribution is used, then significant changes to the time dependent solution occur. It is thus not possible to accurately compute a time-evolving fire if the aforementioned angular requirements are not satisfied.

The ray tracing and Monte Carlo methods, which are the most accurate methods when their convergence is ensured, and the results of which were found to be consistent, were used to compute the reference solutions. Both of these methods, which need, respectively, a large number of angles or a large realization sample, are too costly to be used for a three-dimensional time dependent fire. The goal was then to quantify the accuracy of the four other methods, compared to the reference solutions, and to assess their usability.

The five methods were compared first through the computation of the radiative source term. It was found that, inside the fire, all methods correctly compute this term, which is needed for coupling with the hydrodynamics. Close to the fire, this term is underestimated by $S_4$ and $M_1$ and overestimated by DTM, but these deviations of less than 3% are quite admissible.

The computation of the radiative flux brought other conclusions. Inside the fire, all methods agree pretty well. Once again, $M_1$ gives a comparable solution to the DOM methods. However, outside the fire both $S_4$ and $M_1$ methods inaccurately compute the flux; $S_4$ suffers from ray effects and $M_1$ overestimates, by almost a factor two, the maximal value region. These two methods are thus not effective far away from the fire. On the other hand, LC11 and DTM give an accurate solution far away the fire, but deviate slightly close to the outer edge of the fuel pan.

Overall, it is found that $M_1$ gives results similar to DOM $S_4$, in the sense that its results are accurate in regions where $S_4$ is accurate. The DTM and DOM LC11 methods were found to give results very close to the Monte-Carlo and ray tracing codes. The
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comparison of the accuracy and speed of the five solution methods suggest that the $M_1$ model is a good alternative to $S_0$ when solving the RTE in complex cases such the large pool fire in this study. For the limited case where highly-accurate heat flux in the highly anisotropic area, e.g., the flux to an object a few diameters away from the fire, better accuracy is only achieved with higher angular resolution offered by DOM $LC_{11}$ or a large number of angles using ray tracing or the DTM method.

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