

Geostationary Satellite Update

Richard Fuller

Wide Area Differential GPS Laboratory

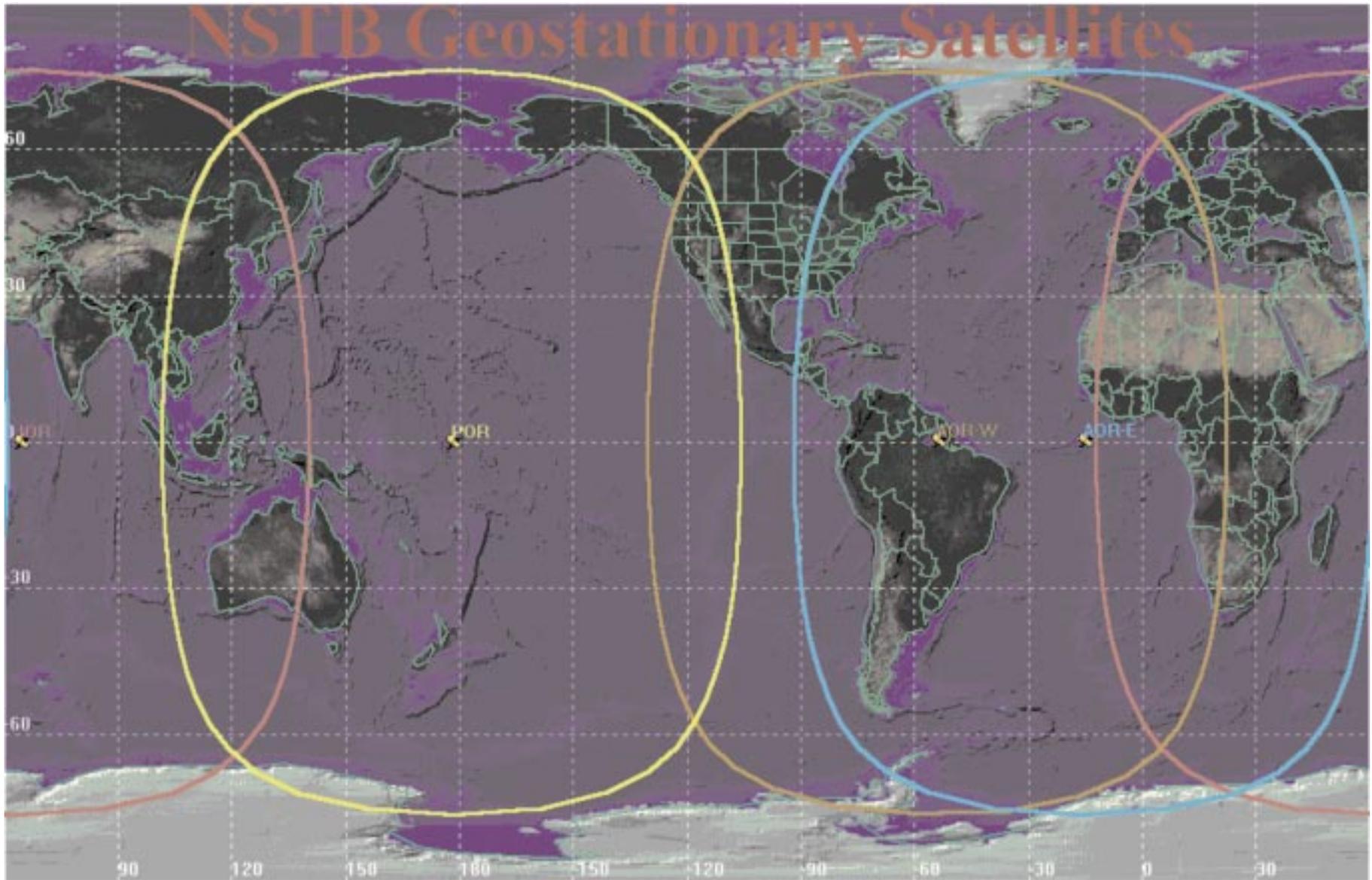
June 30, 1998



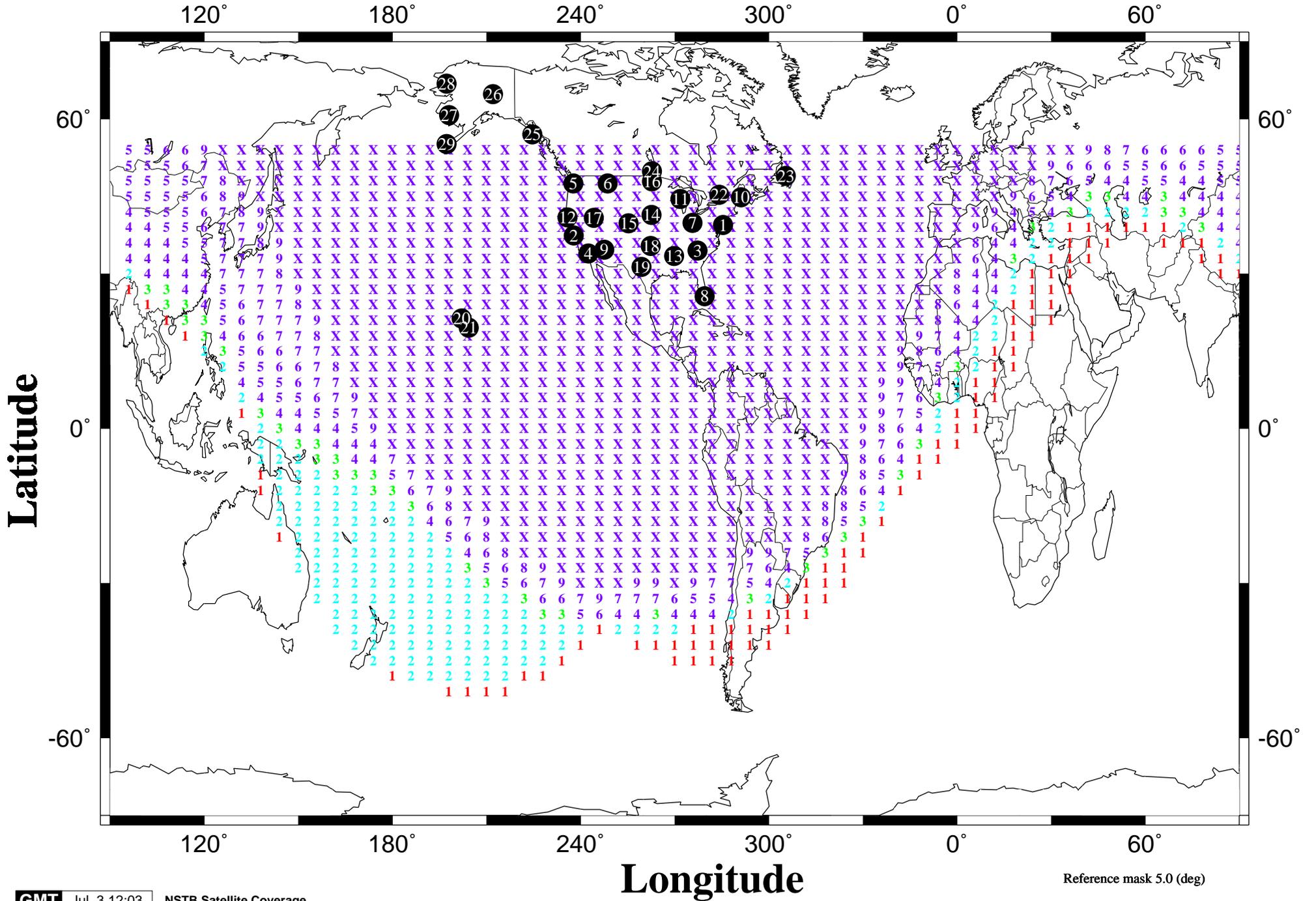
Outline

- Geostationary Coverage Regions
 - ⇒ User Visibility
 - ⇒ Satellite Visibility
- POR Access
 - ⇒ Preparations
 - ⇒ Signals
 - ⇒ User Positioning
 - ⇒ Upcoming work

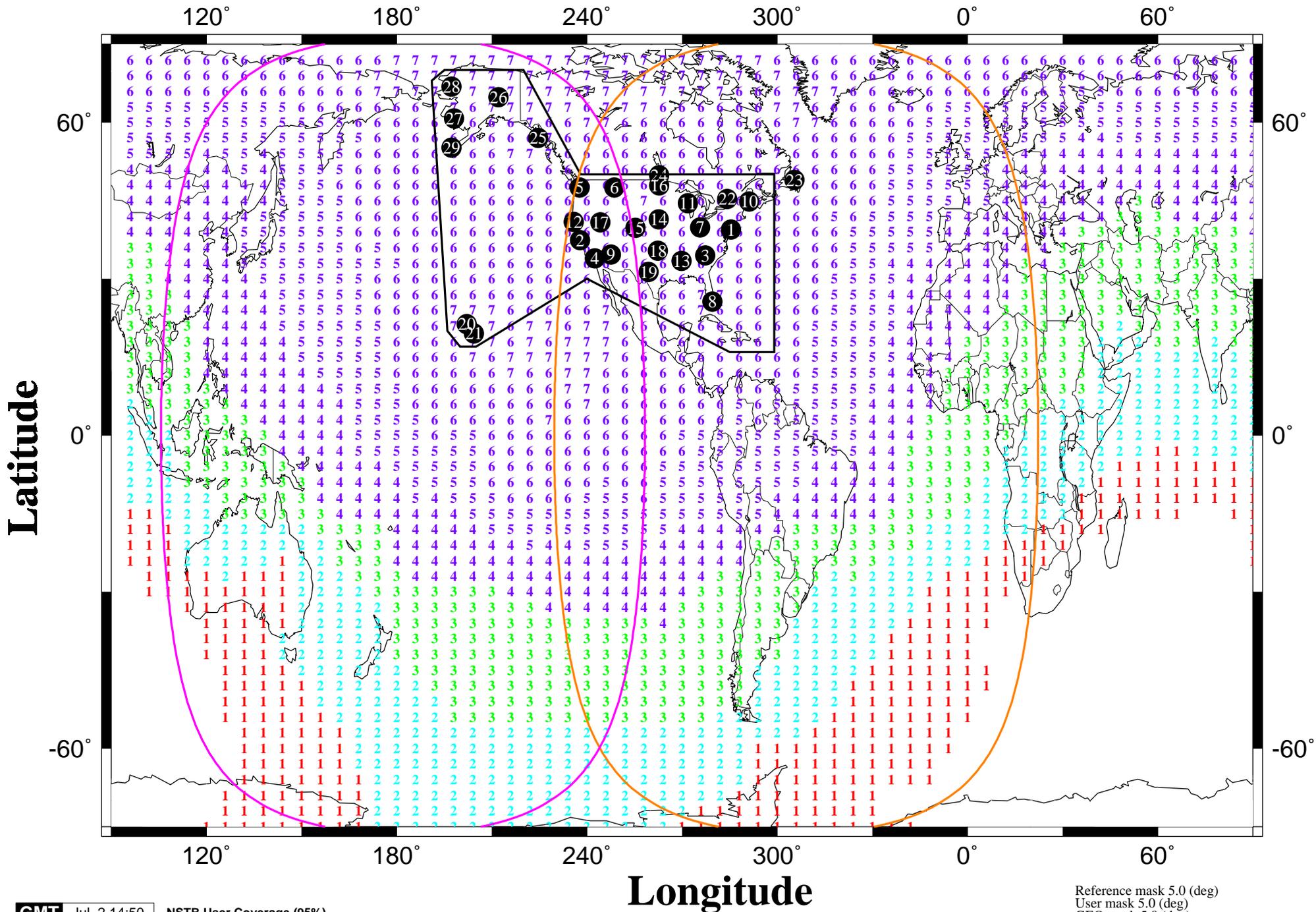
NSTB Geostationary Satellites



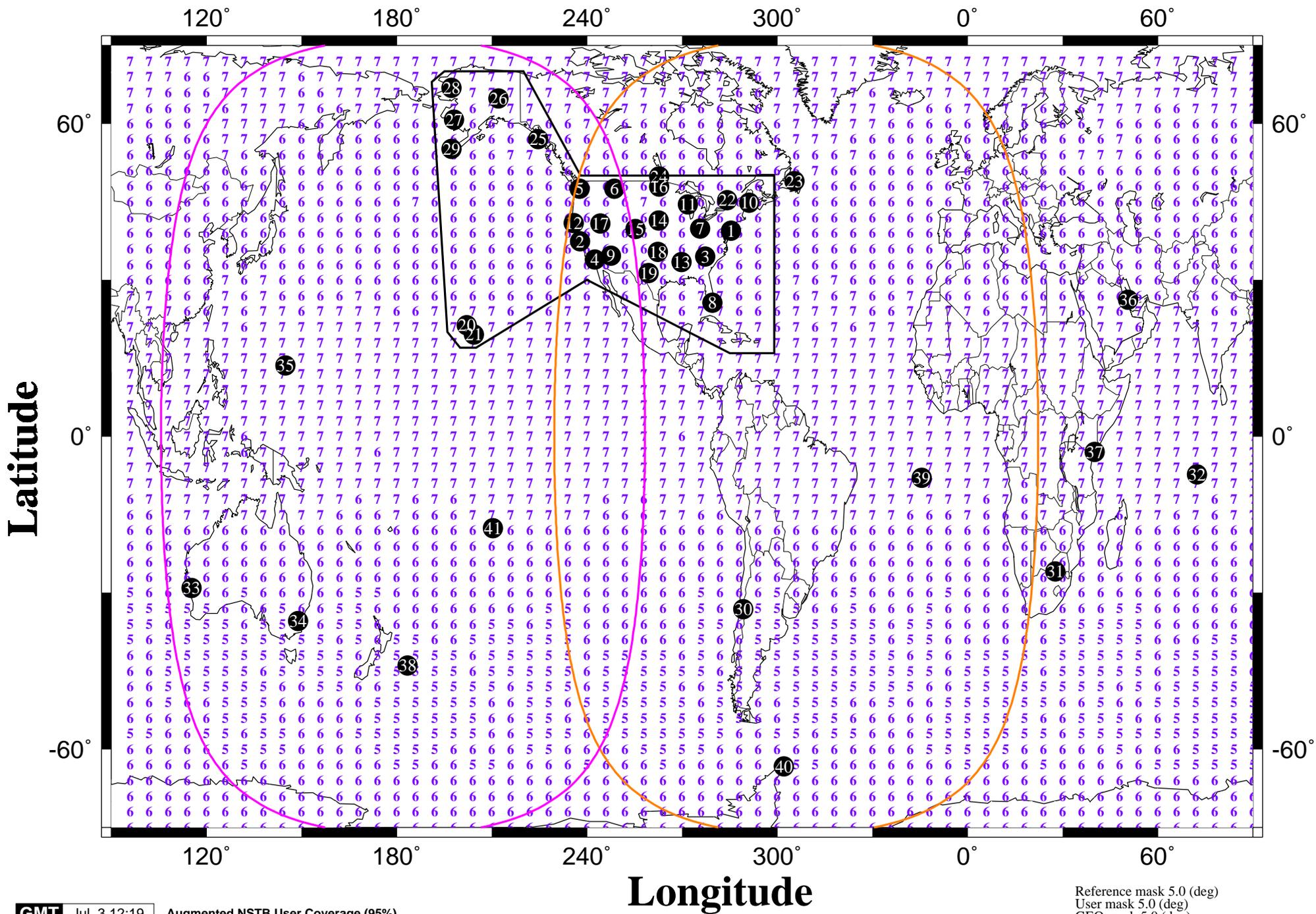
NSTB Satellite Coverage



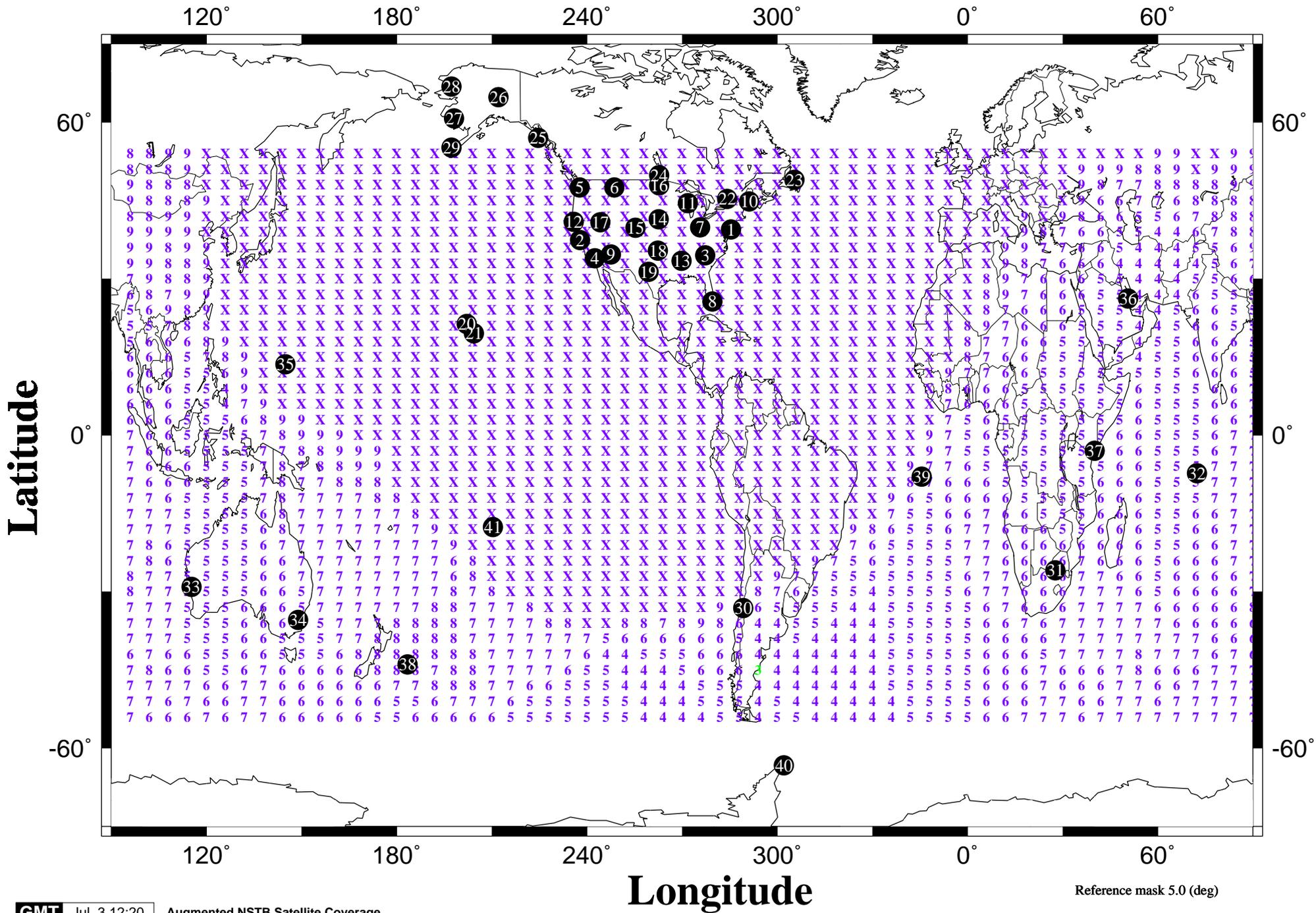
NSTB User Coverage (95%)



Augmented NSTB User Coverage (95%)



Augmented NSTB Satellite Coverage

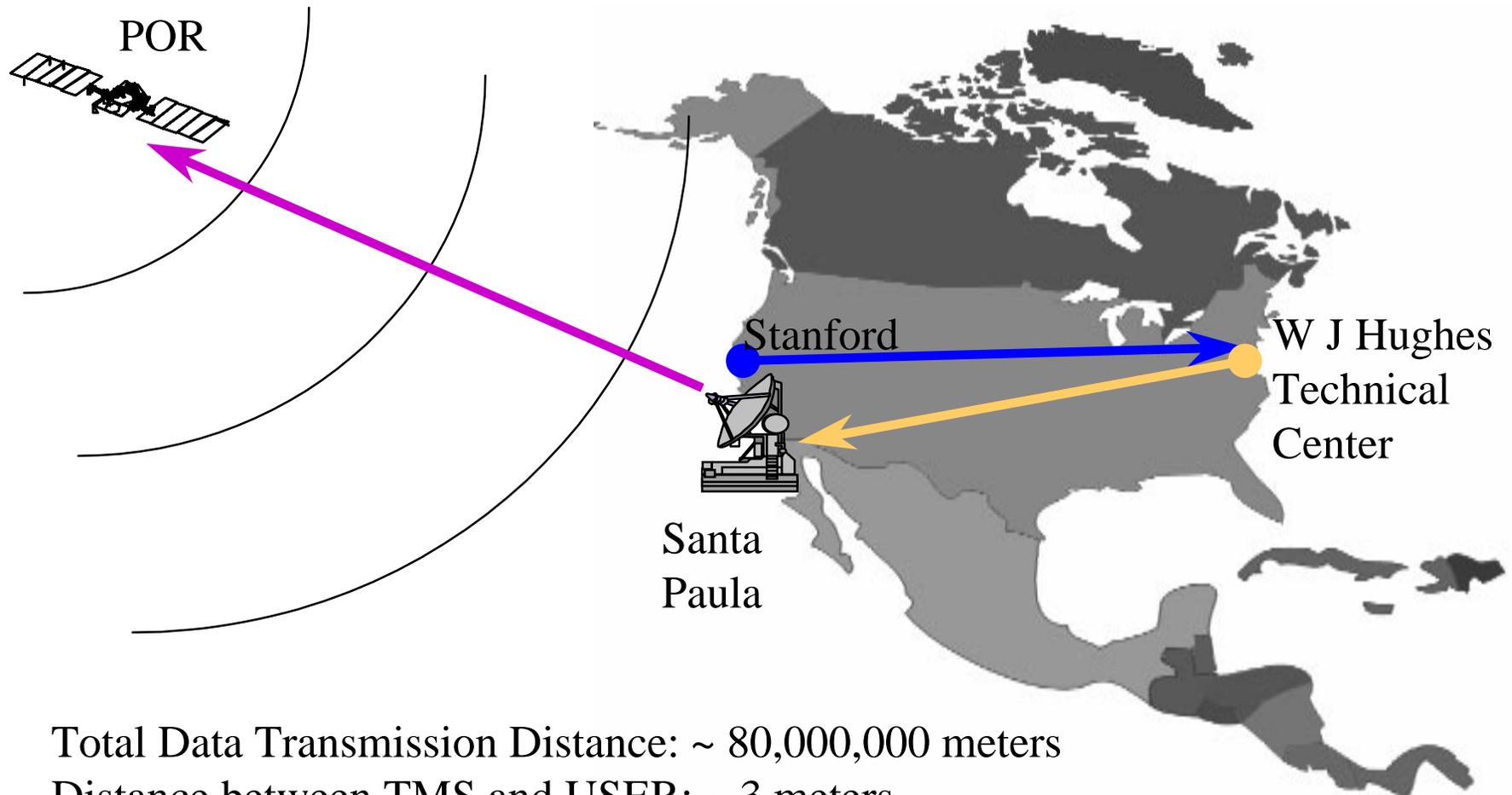


Geostationary Preparations



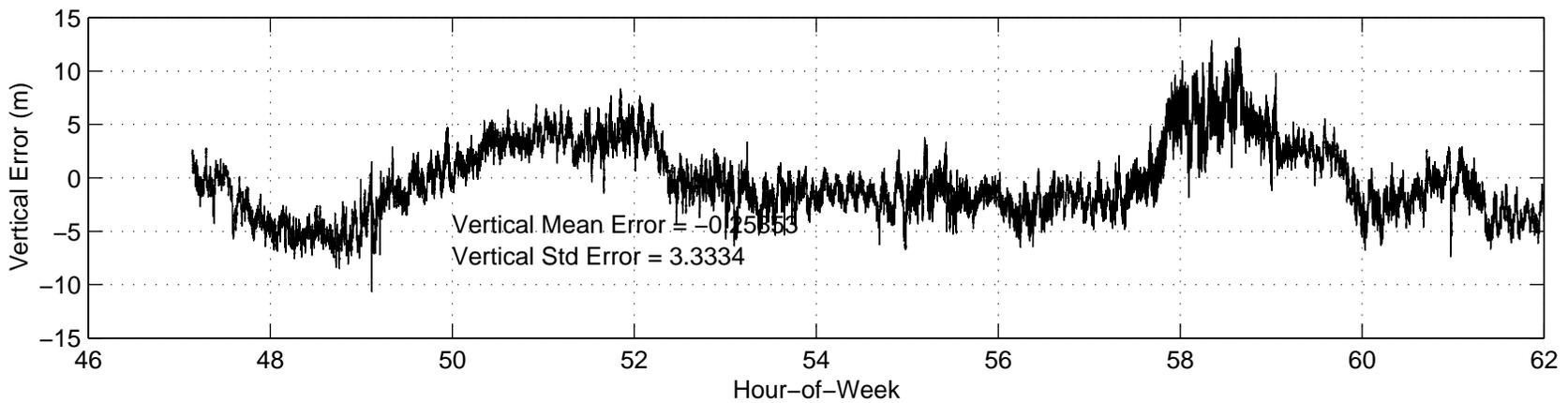
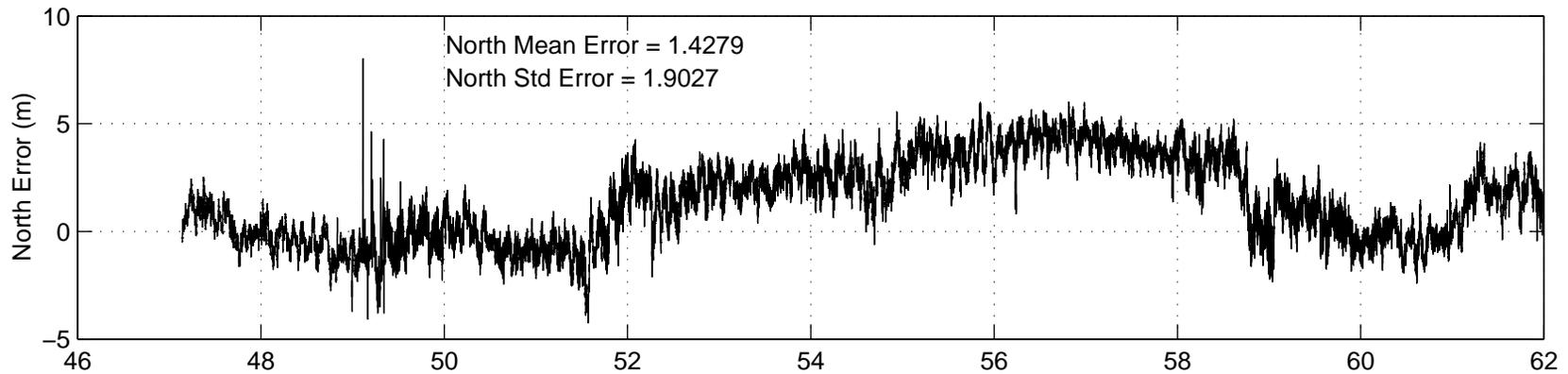
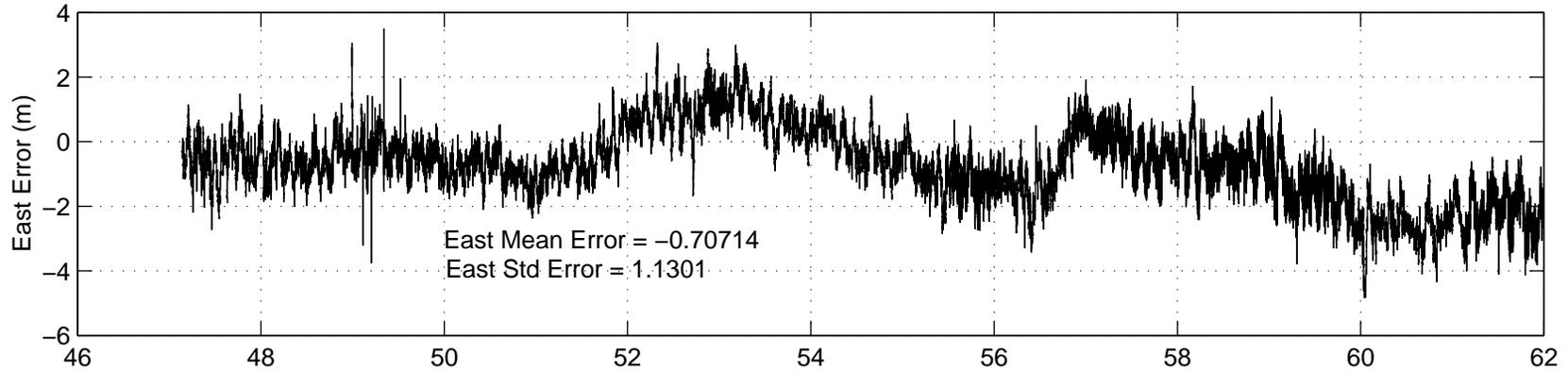
- Upgraded the Ethernet aiding protocol
 - ⇒ Rudiments previously implemented in the Stanford TMS
 - ⇒ Added proper formatting and sequence to data stream
 - ⇒ Changed the timing sequence of the correction messages (account for latency)
 - ⇒ Passed the Tech Center's 'WibServer' timing analysis on May 15
- Obtained a Millenium 10-1 receiver from NovAtel
 - ⇒ Updated the Stanford WAASUSER code to accept WAAS data messages from the Millenium receiver
- First transmitted to POR TUS in Santa Paula on June 15
 - ⇒ Since then we have 7 complete days of transmission on POR
 - ⇒ POR received power levels continue to remain *below* AOR-W

POR Satellite Data Path



Total Data Transmission Distance: ~ 80,000,000 meters
Distance between TMS and USER: ~ 3 meters

Static GEO-Corrected WAAS Position Error



Future Work



- Extend User and Satellite Coverage Analysis
 - ⇒ Add DOP, UDRE, and GIVE plots
 - ⇒ Minimize number of stations while maximizing siting reliability
- Flight Tests with Geostationary Data Link
 - ⇒ Ground tests have collected roughly 1 GB of positioning and raw measurement data
 - ◆ Analysis ongoing
 - ⇒ Flight tests begin today (June 30) and will continue through the summer
 - ◆ Major goal: flight test demonstration in Alaska in August
 - ⇒ Work towards Geo-ranging capability
 - ◆ Dependent on determining Millenium station tracking problems
 - ⇒ Update the USER code to utilize 3rd generation TMS software

**Interoperation of Distributed
Satellite Based Augmentation Systems:
Implementation and Applications**

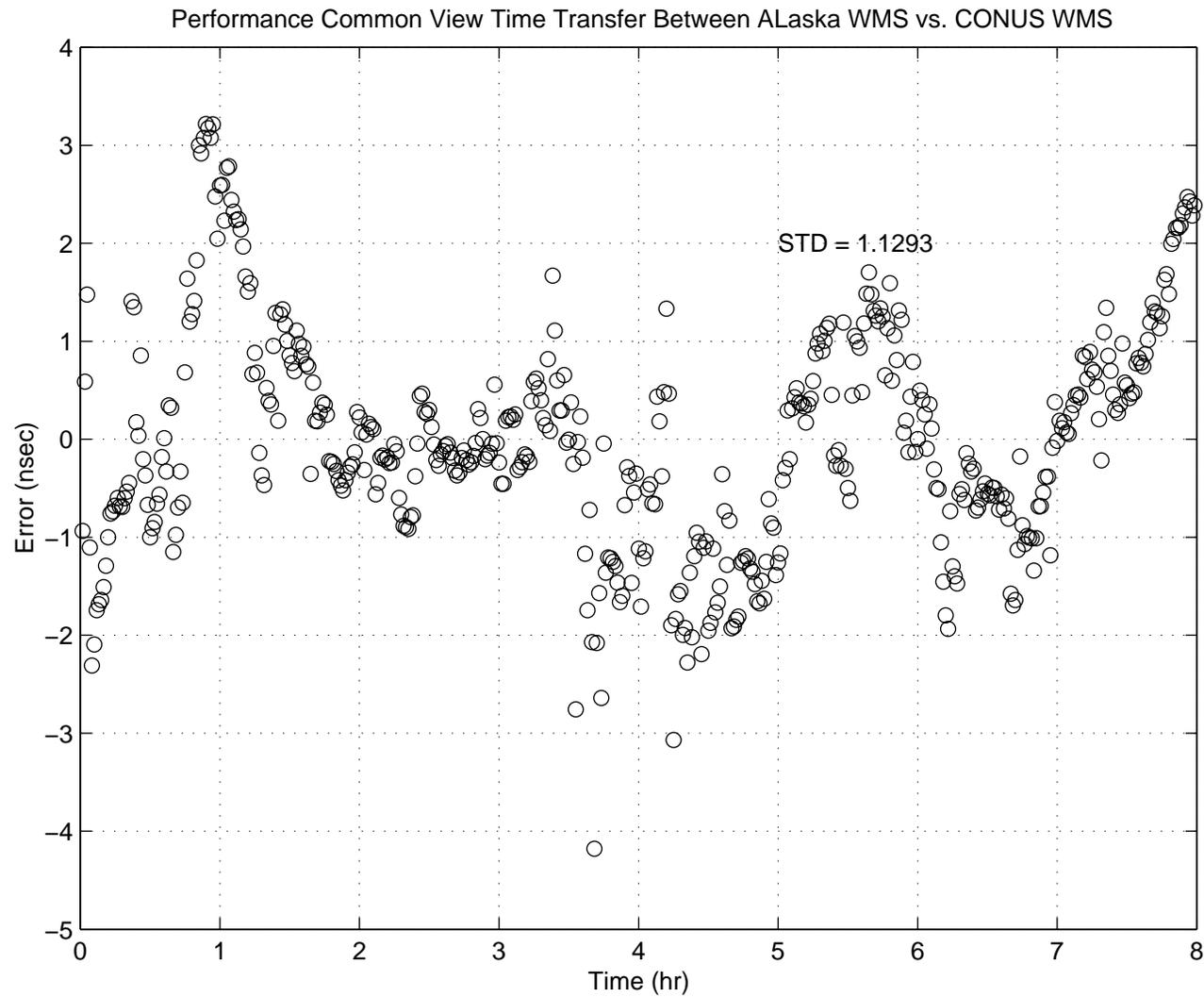
Donghai Dai
Stanford University



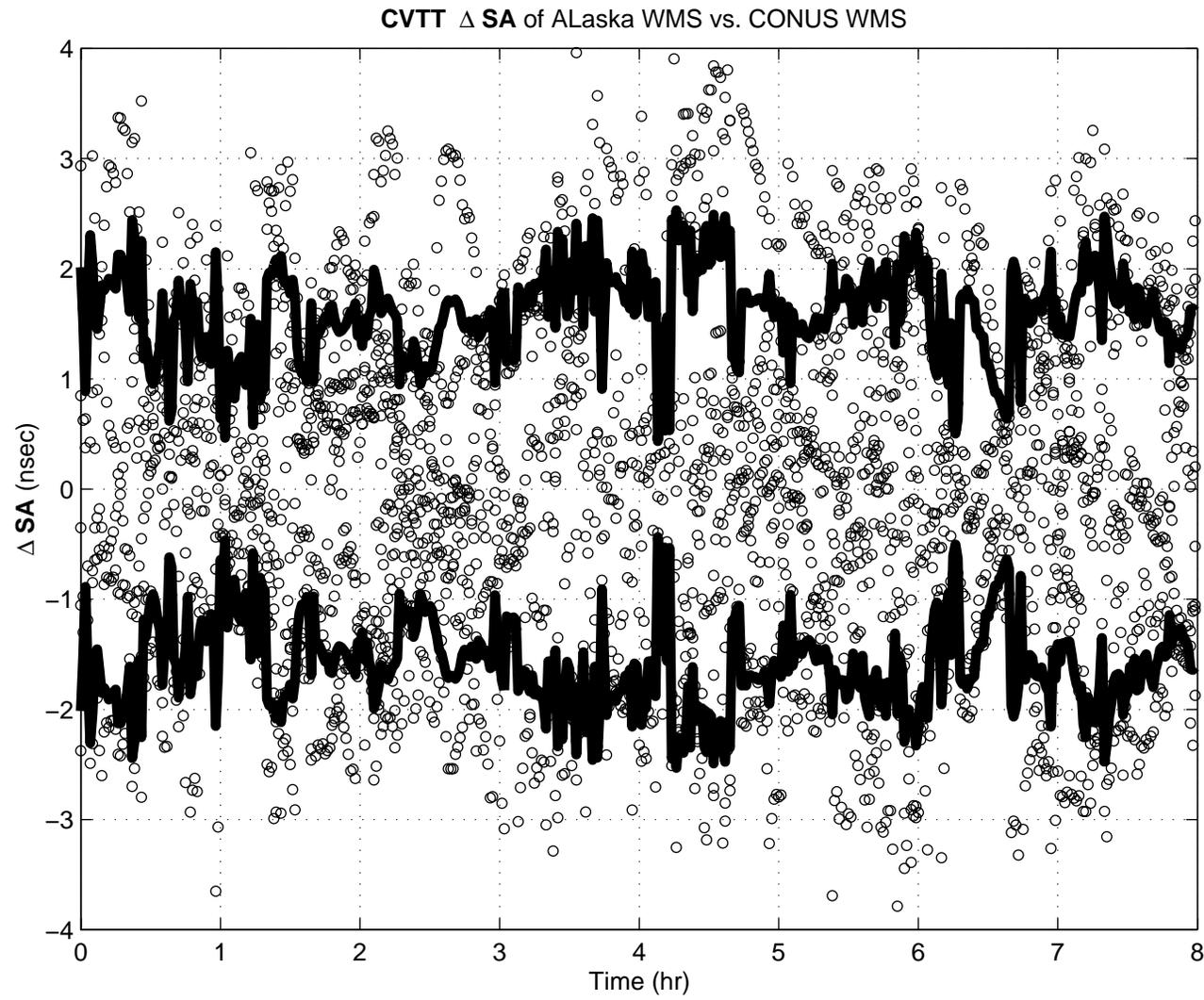
Alaska/CONUS Example

- **Senario**
- **Clock/Ephemeris**
 - Clock Synchronization
 - Clock/Ephemeris Integration
- **Ionospheric**

NCVTT Accuracy

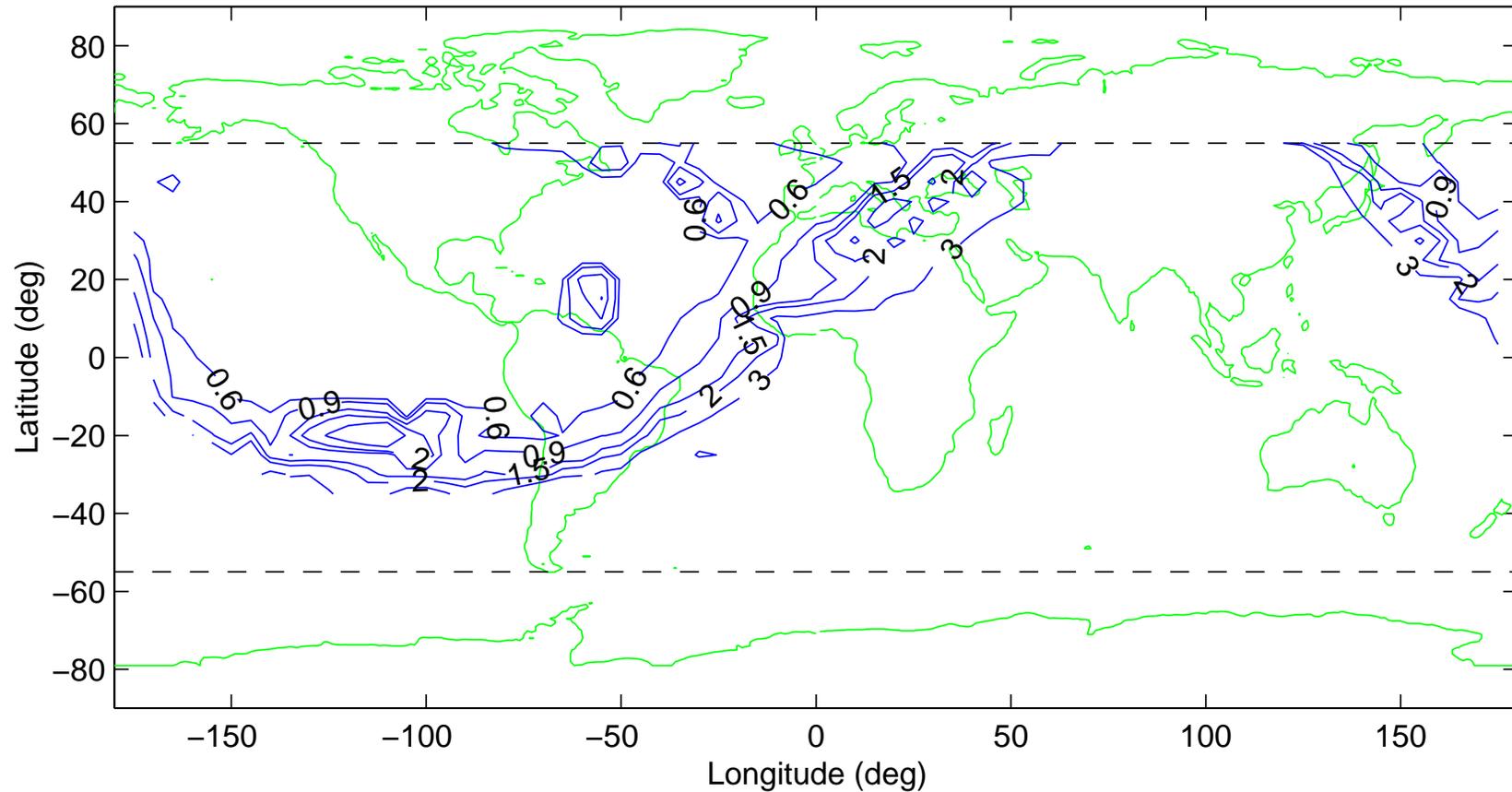


NCVTT Consistency



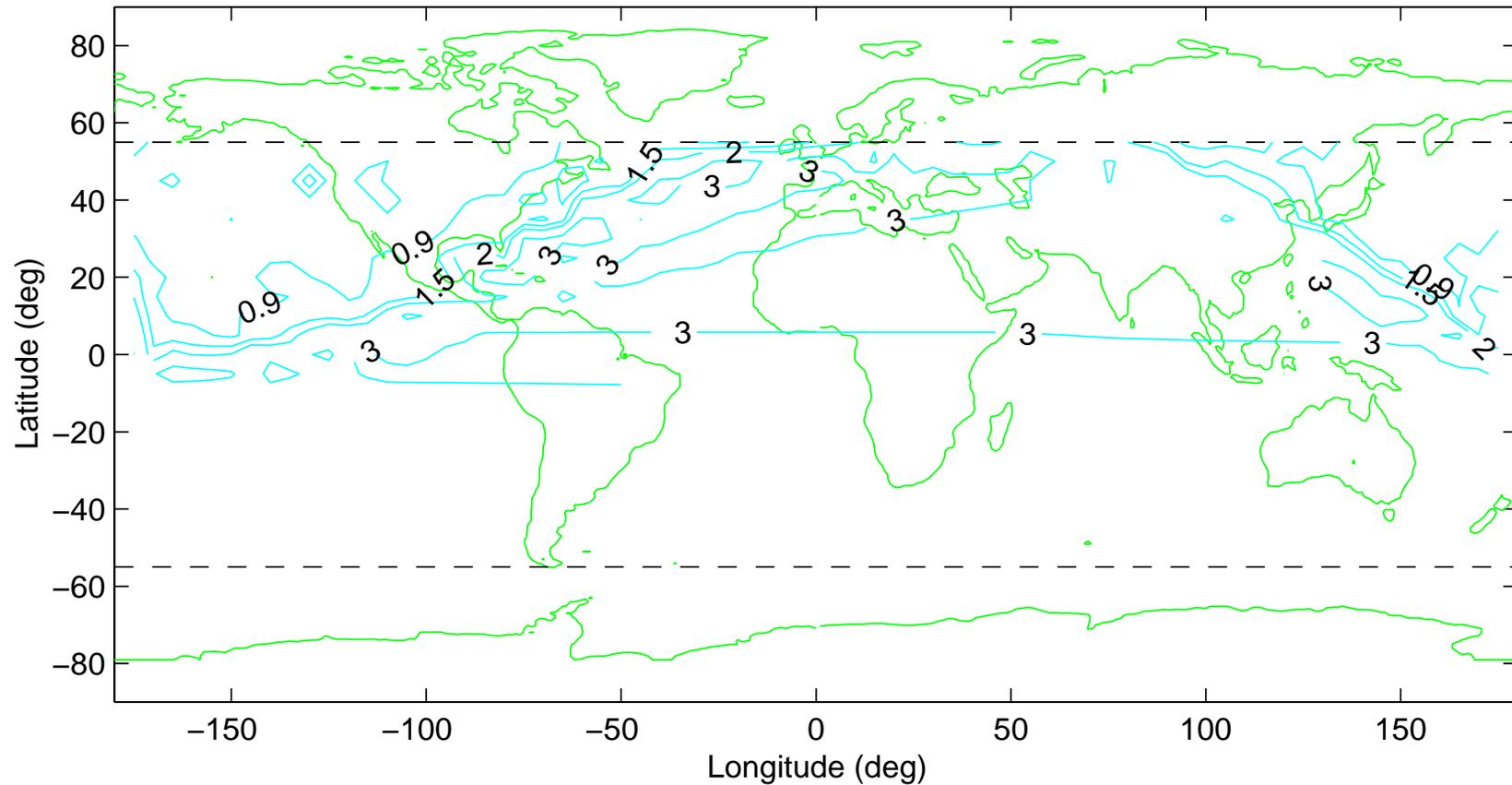
99.9% UDRE : NSTB CONUS

99.9% UDRE Map: NSTB CONUS Networks



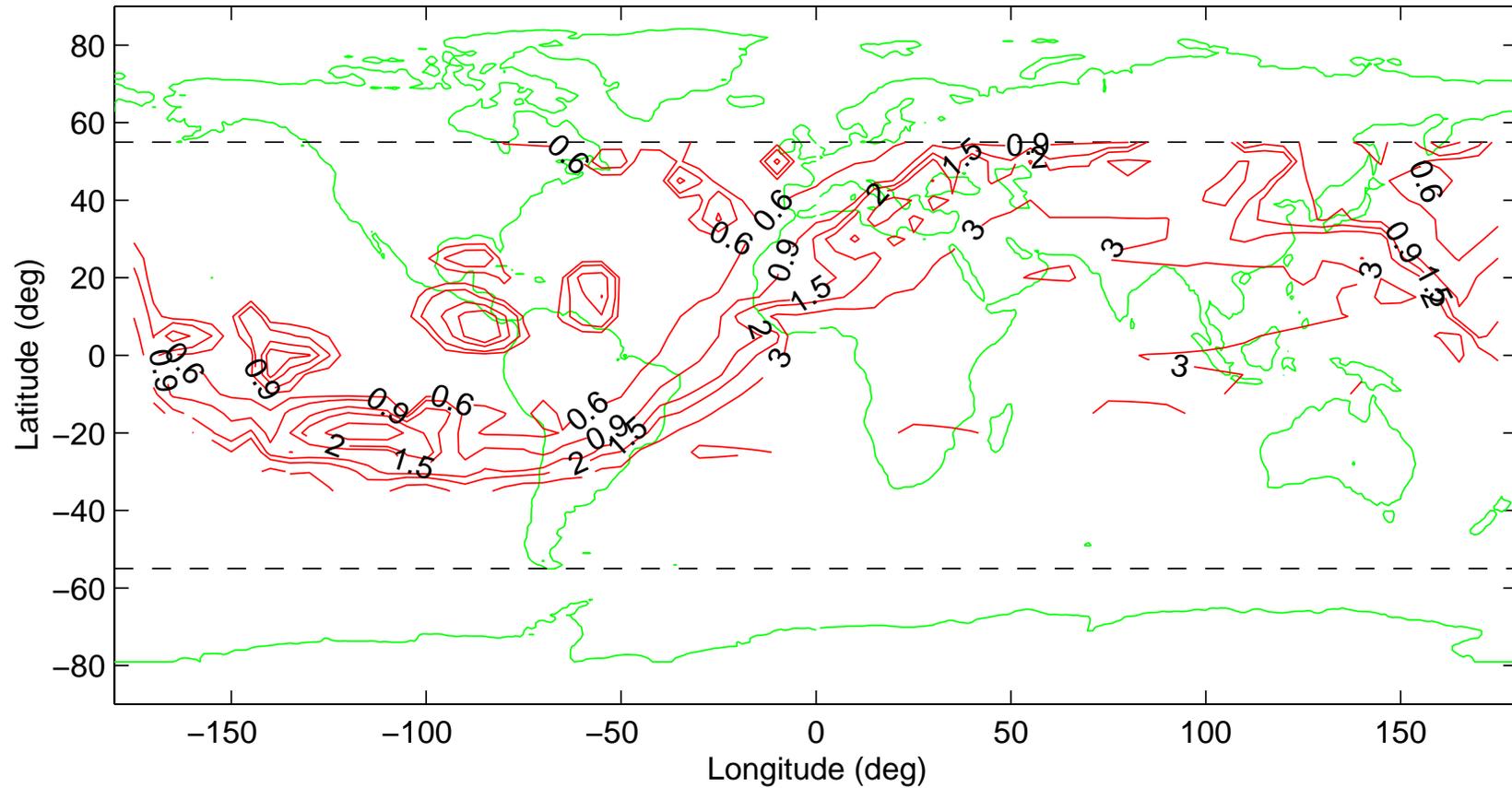
99.9% UDRE : NSTB Alaska

99.9% UDRE Map: NSTB Alaska Networks



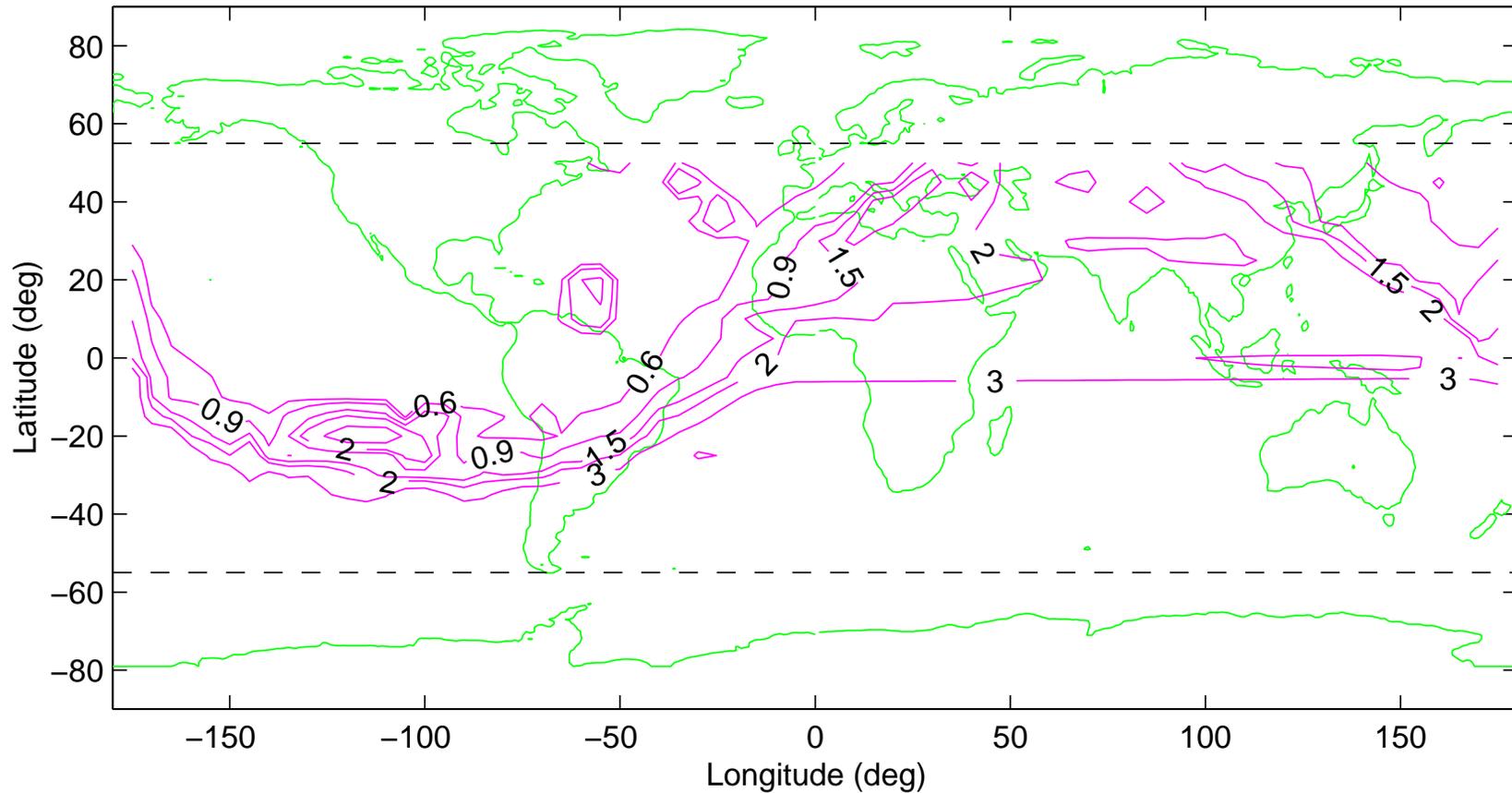
99.9% UDRE : CONUS & Alaska

99.9% UDRE Map: NSTB CONUS & Alaska Networks



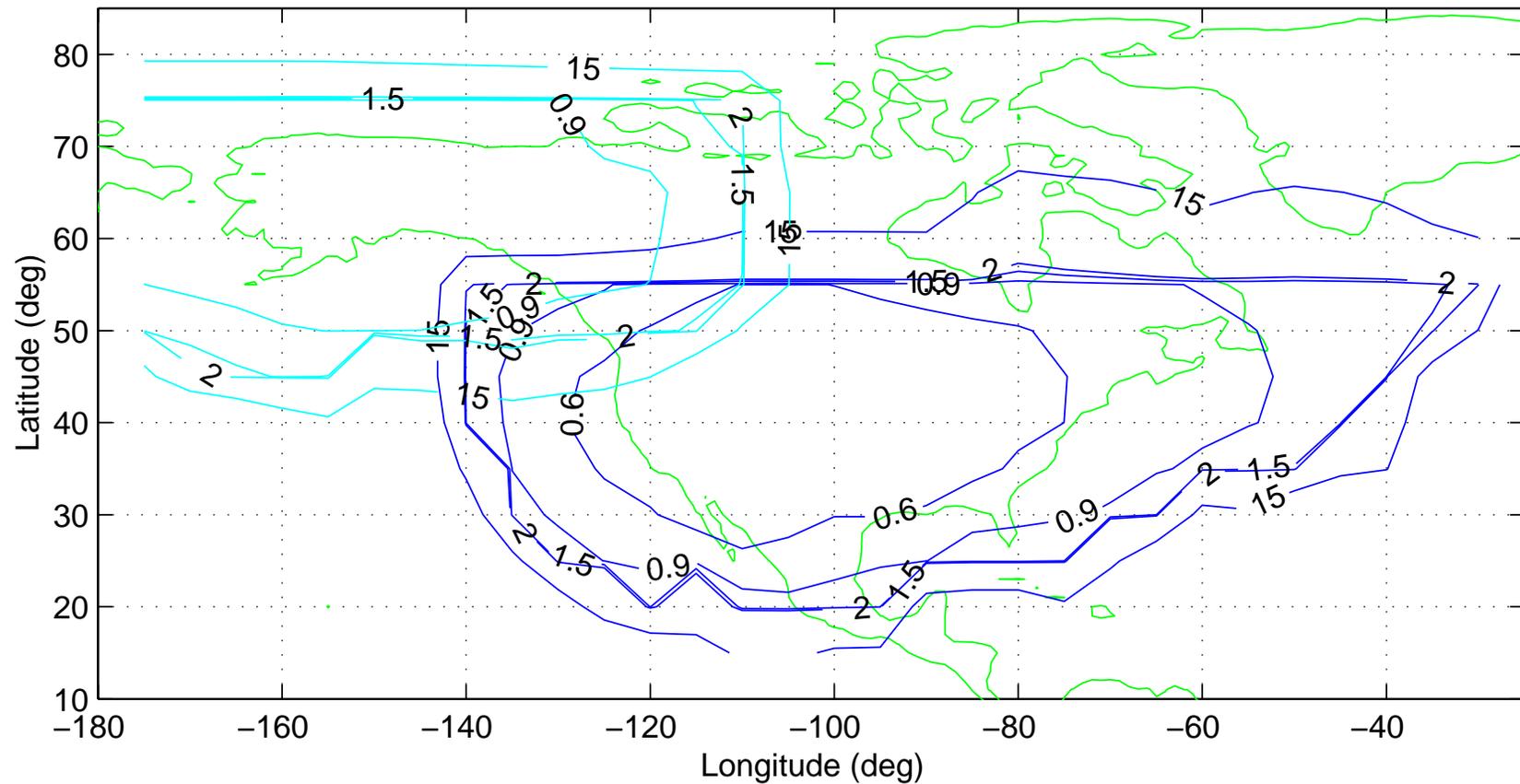
99.9% UDRE : NSTB Integration

99.9% UDRE Map: NSTB CONUS/Alaska Networks



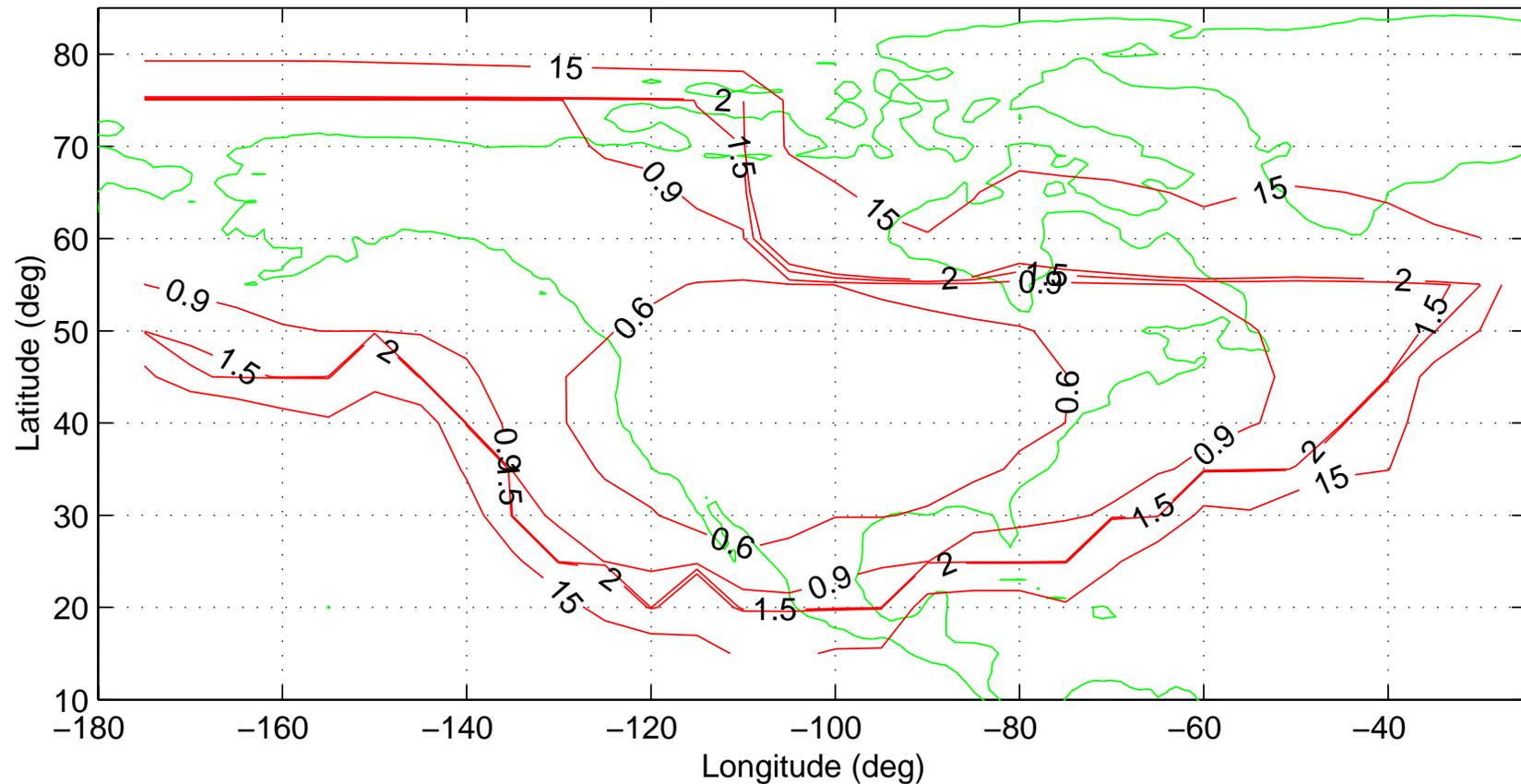
99.9% GIVE : CONUS/Alaska

99.9% GIVE Contour: NSTB CONUS/Alaska Networks



99.9% GIVE : CONUS&Alaska

99.9% GIVE Contour: NSTB CONUS&Alaska Networks



99.9% GIVE : NSTB Integration

99.9% GIVE Contour: NSTB CONUS/Alaska Networks (Correction Level Integration)

