



GNSS RFI/Spoofing: Detection, Localization, & Mitigation

***Stanford's 2012 PNT Challenges and
Opportunities Symposium***

14 - November - 2012

Dennis M. Akos

University of Colorado/Stanford University

with contributions from many at CU and Stanford





Presentation Overview

- *Motivation & Background*
- *Concept & Experimental Results*
 - I. RFI Detection/Characterization*
 - II. Spoofers Detection*
 - III. RFI/Spoofers Localization*
 - IV. RFI/Spoofers Mitigation via CPRA*
- *Summary & Conclusions*





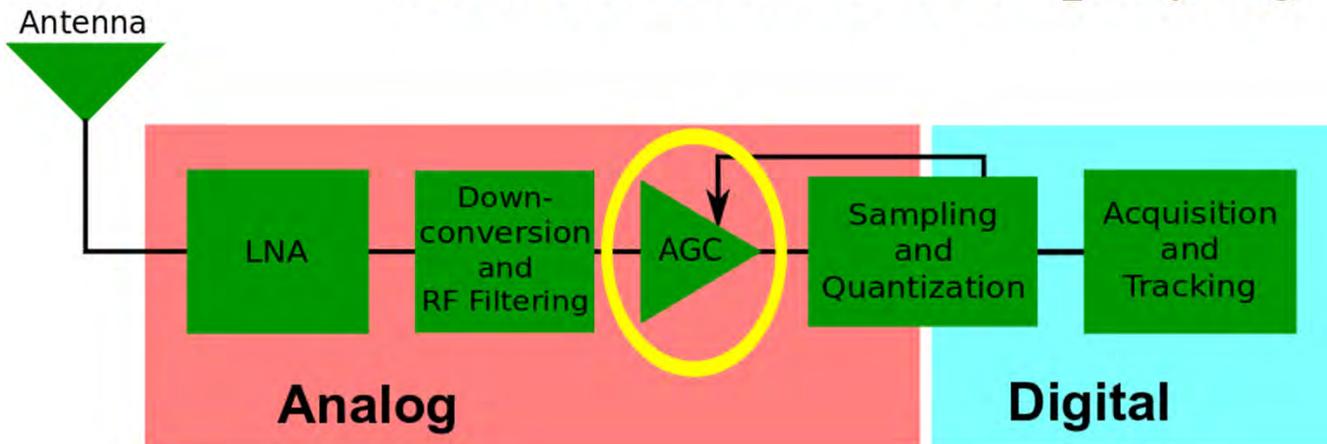
Presentation Overview

- *Motivation & Background*
- *Concept & Experimental Results*
 - I. RFI Detection/Characterization*
 - II. Spoofers Detection*
 - III. RFI/Spoofers Localization*
 - IV. RFI/Spoofers Mitigation via CPRA*
- *Summary & Conclusions*



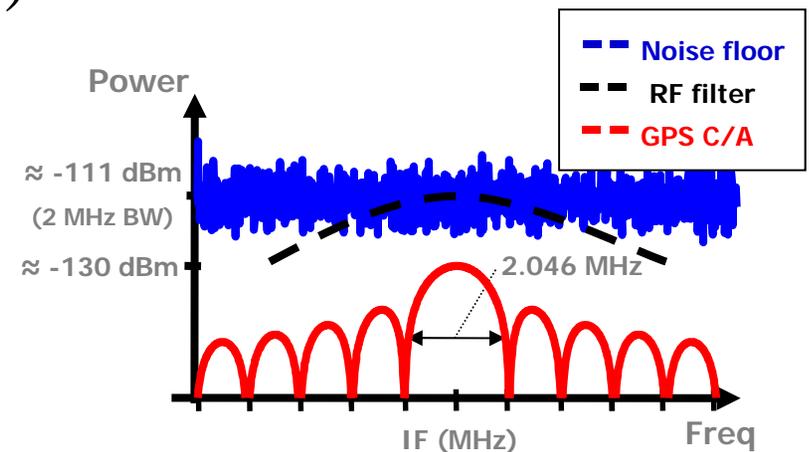


Where to Detect RFI/Spoofing: AGC



To minimize losses the amplitude of the received signal has to be adjusted to the range of the ADC

- *AGC measures the noise floor of the antenna/receiver (signal captured in the ADC)*
- *Any additional energy (RFI or spoofing) in the band will result in an AGC change*
- *Very low computational metric available on any multibit GPS/GNSS receiver*





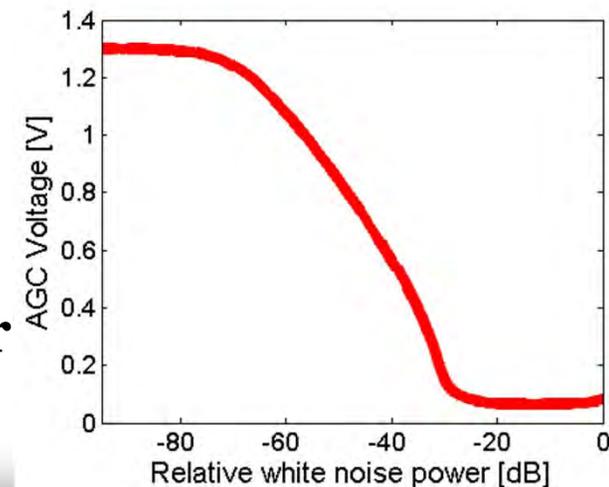
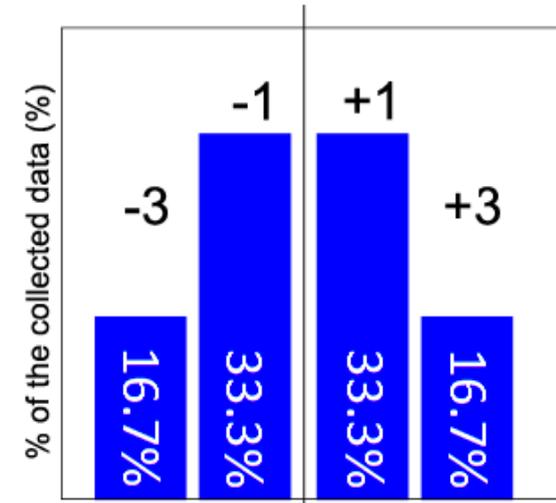
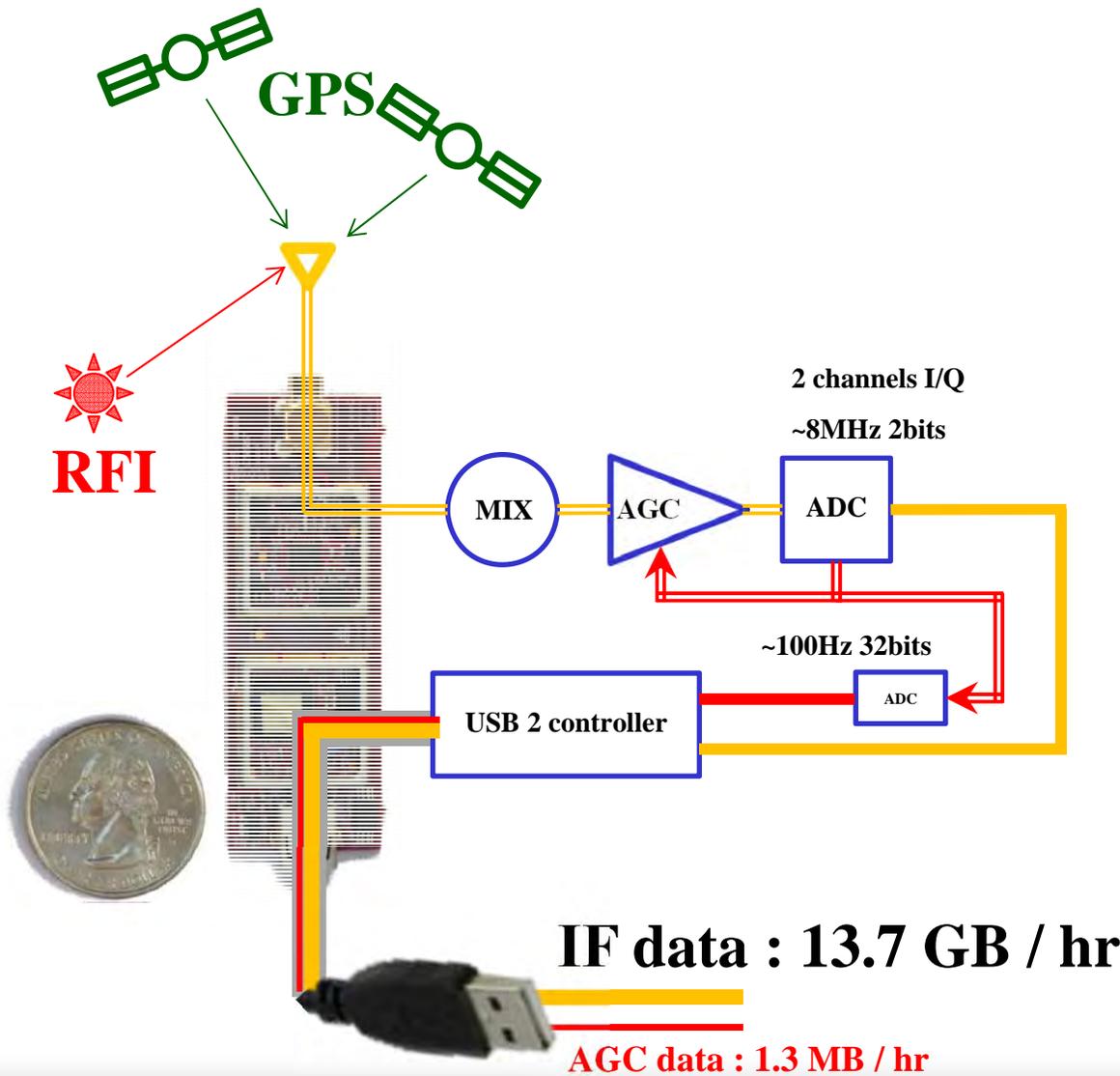
Presentation Overview

- *Motivation & Background*
- ***Concept & Experimental Results***
 - I. RFI Detection/Characterization***
 - II. Spoofers Detection*
 - III. RFI/Spoofers Localization*
 - IV. RFI/Spoofers Mitigation via CPRA*
- *Summary & Conclusions*





Low-Cost GPS RFI Detection/Characterization Sensor





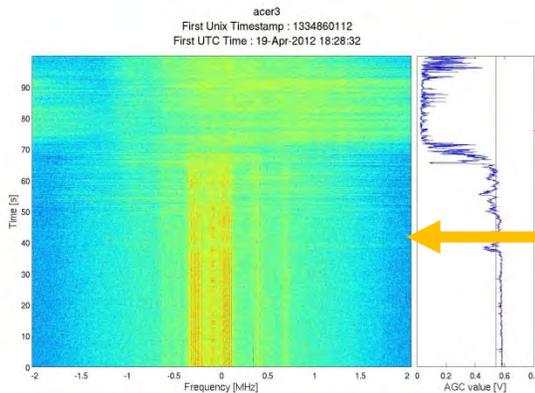
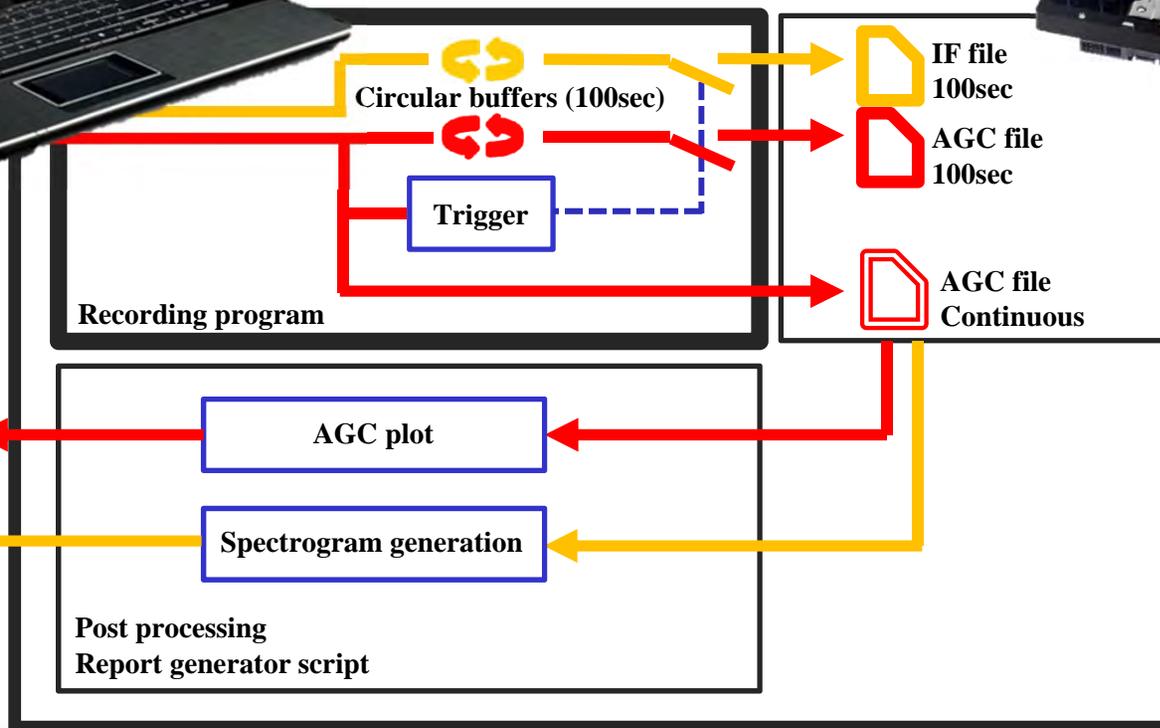
Add Notebook PC for Complete System



Laptop
Low computational requirements
Low cost CPU + 3GB RAM

IF data : 13.7 GB / hr

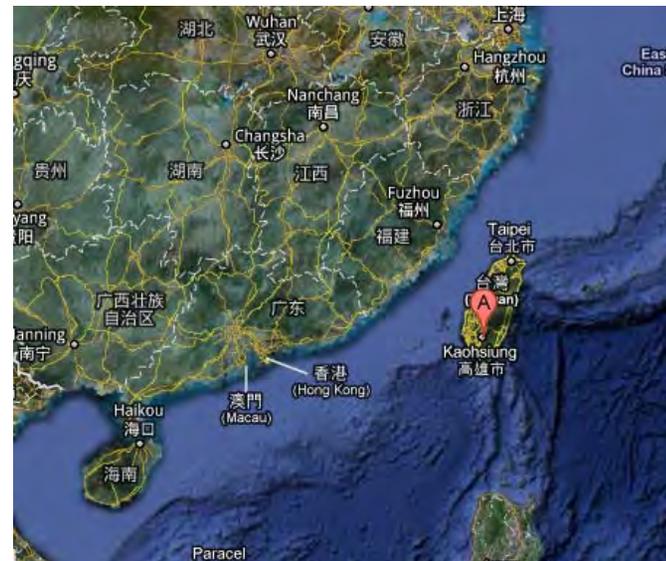
AGC data : 1.3 MB / hr





System Deployment at Two Airports

- *Systems were deployed at two different airports and data logged during Aug-2011*
 - » *LLA – Luleå, Sweden*
 - » *KHH - Kaohsiung, Taiwan*





Description of Luleå, Sweden [LLA]



- *Position : 65.550N, 22.122E*
- *~ 900k passengers in 2010*
- *7km from the town of Luleå*
- *No highways within 5km*
- *Significant marine traffic in the area*



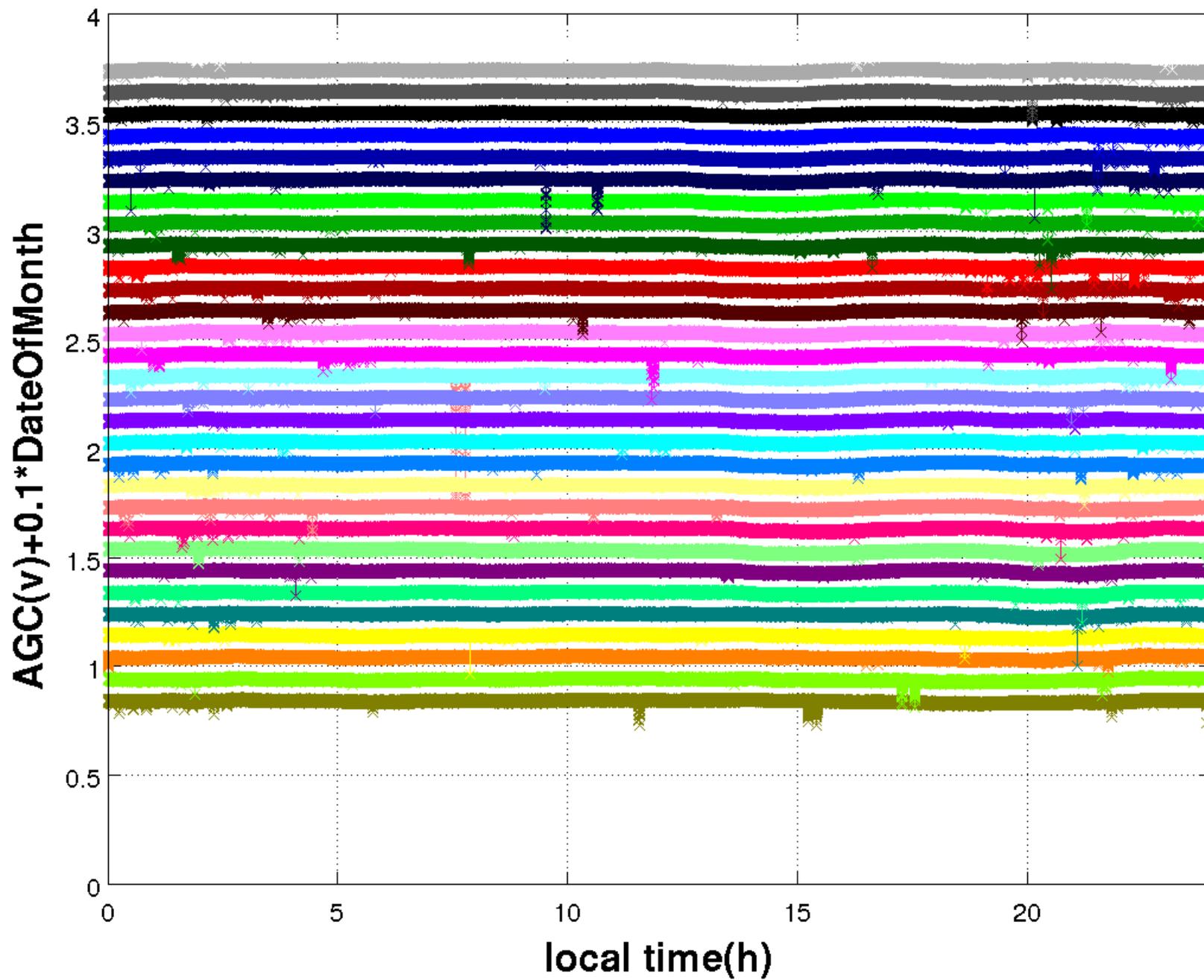


Description of Kaohsiung, Taiwan [KHH]

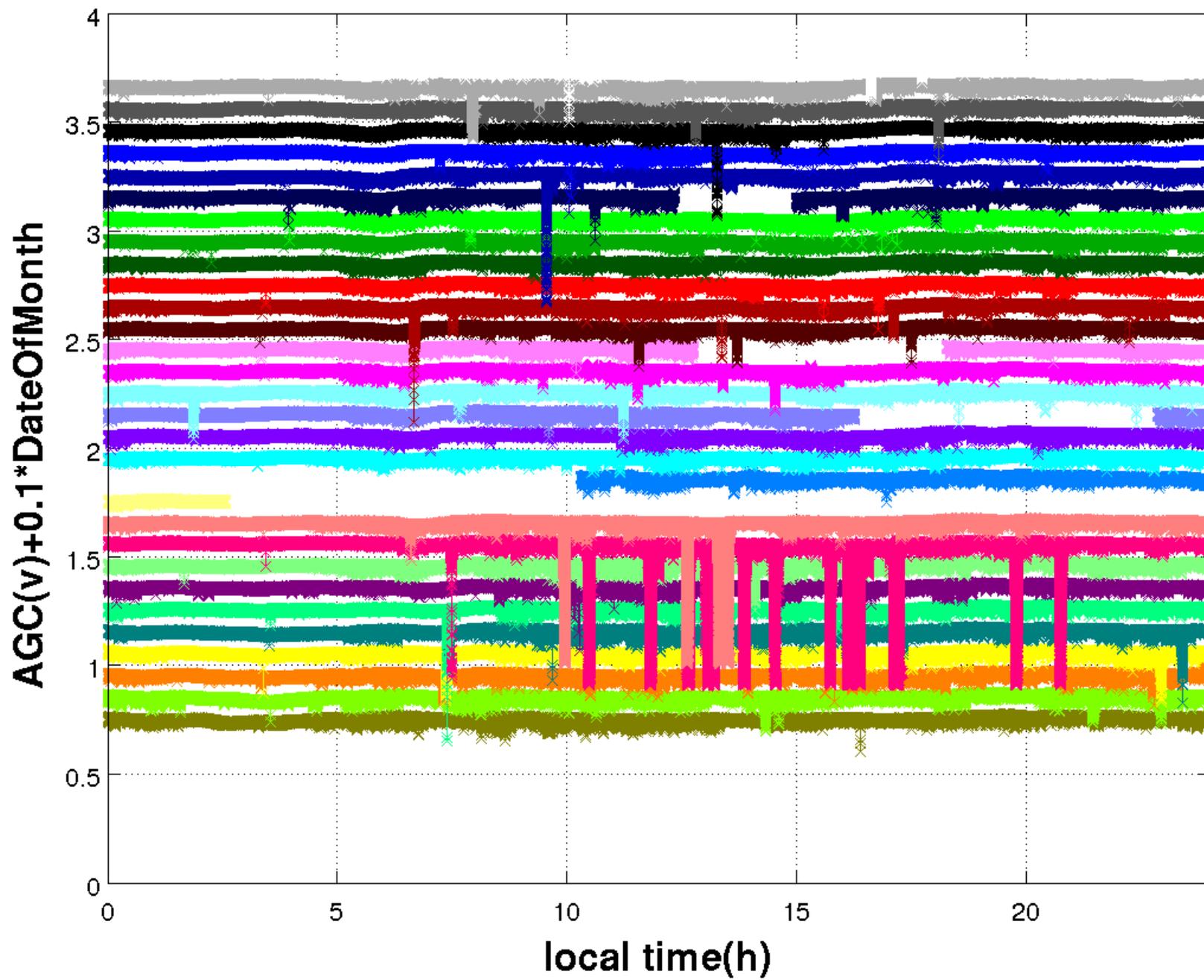
- *Position: 22.580N, 120.332E*
- *~4000k passengers in 2010*
- *Locate at the downtown of Kaohsiung city*
- *Neighbors with the Kaohsiung harbor*
- *Surrounded by several major roads*
- *Heavy traffic nearby*



AGC from LLA (Sweden) 1/8-31/8

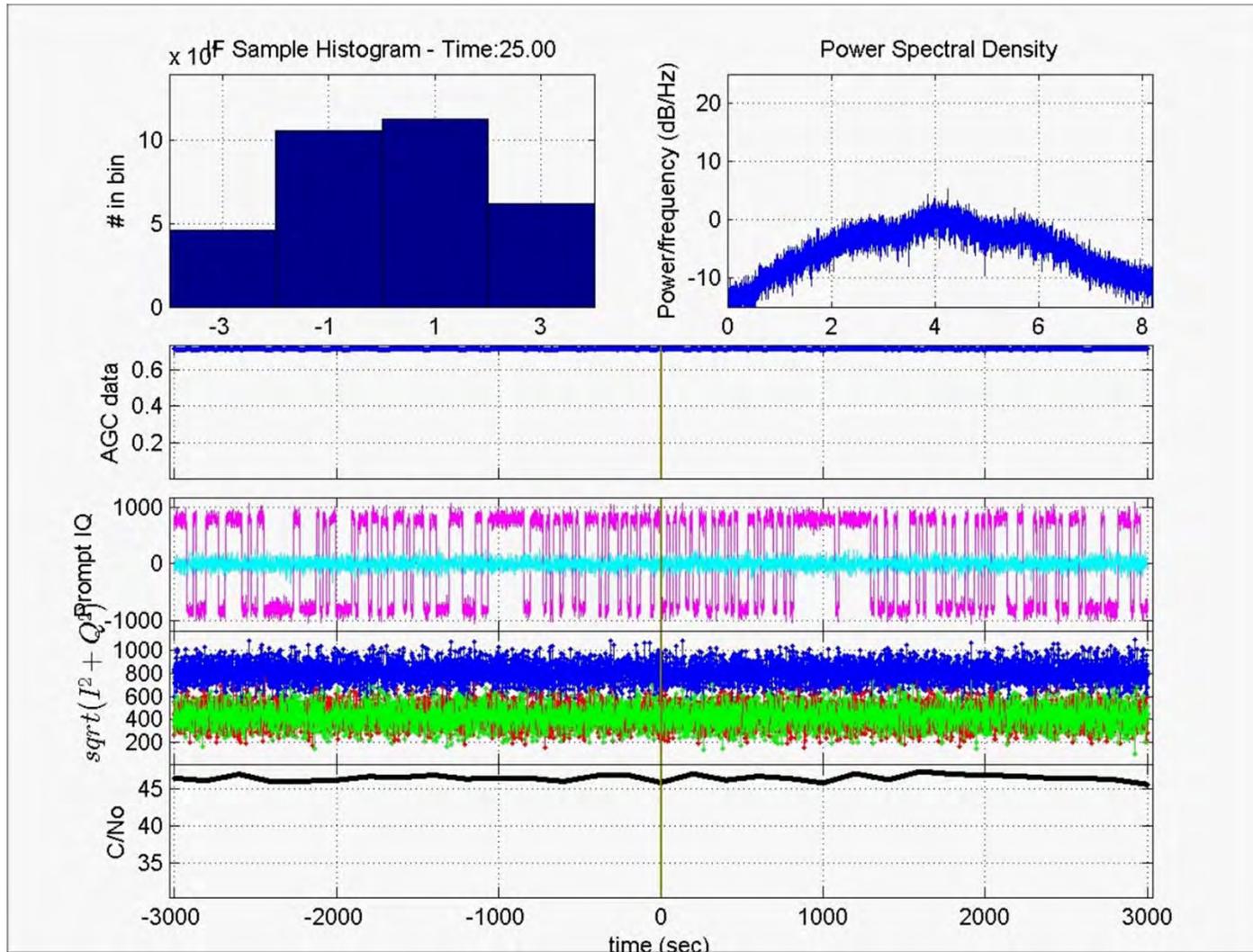


AGC from KHH (Taiwan) 1/8-31/8





Animation of a KHH Trigger/Capture



In addition to spectrogram, it is possible to animate the captured data

Summary

- *Developed and deployed a low-cost computationally efficient GPS RFI detection & characterization system*
- *Currently operating 5 different stations*





Presentation Overview

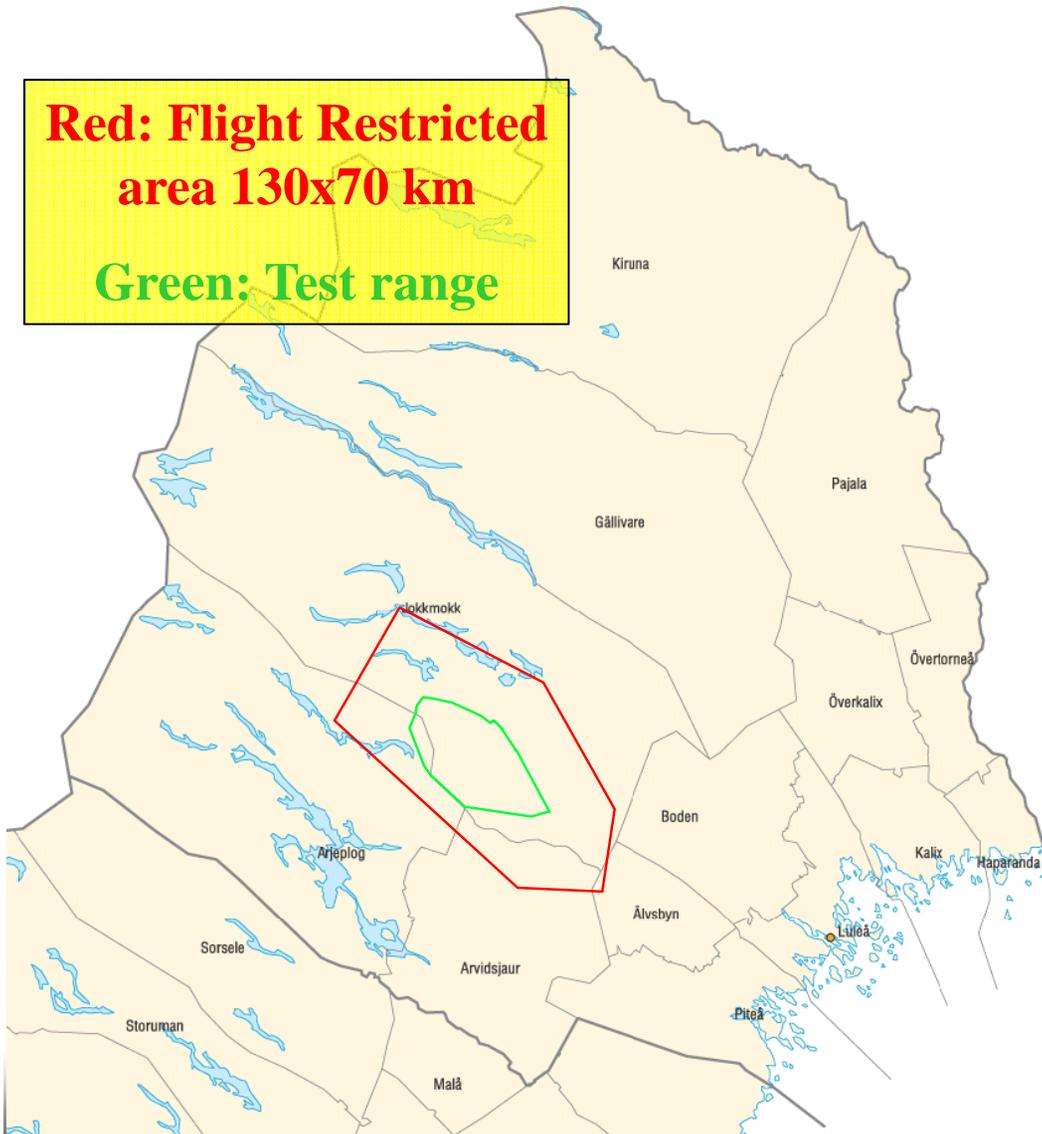
- *Motivation & Background*
- ***Concept & Experimental Results***
 - I. RFI Detection/Characterization*
 - II. Spoofers Detection***
 - III. RFI/Spoofers Localization*
 - IV. RFI/Spoofers Mitigation via CPRA*
- *Summary & Conclusions*





Swedish Military Test Range: Robotförsökplats Norrland (RFN)

**Red: Flight Restricted
area 130x70 km**
Green: Test range

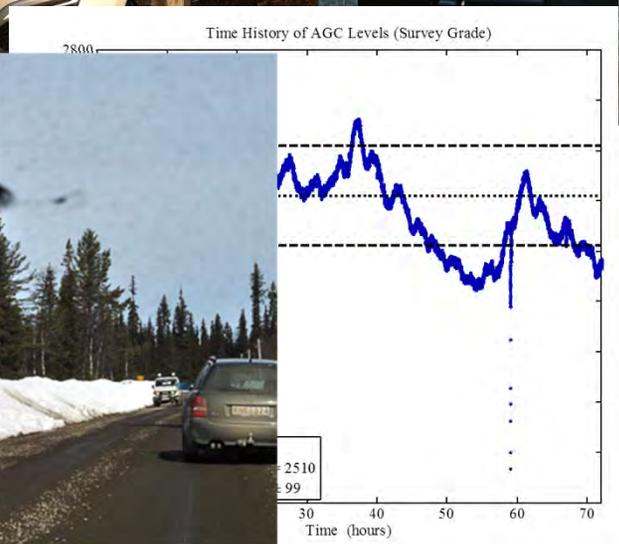
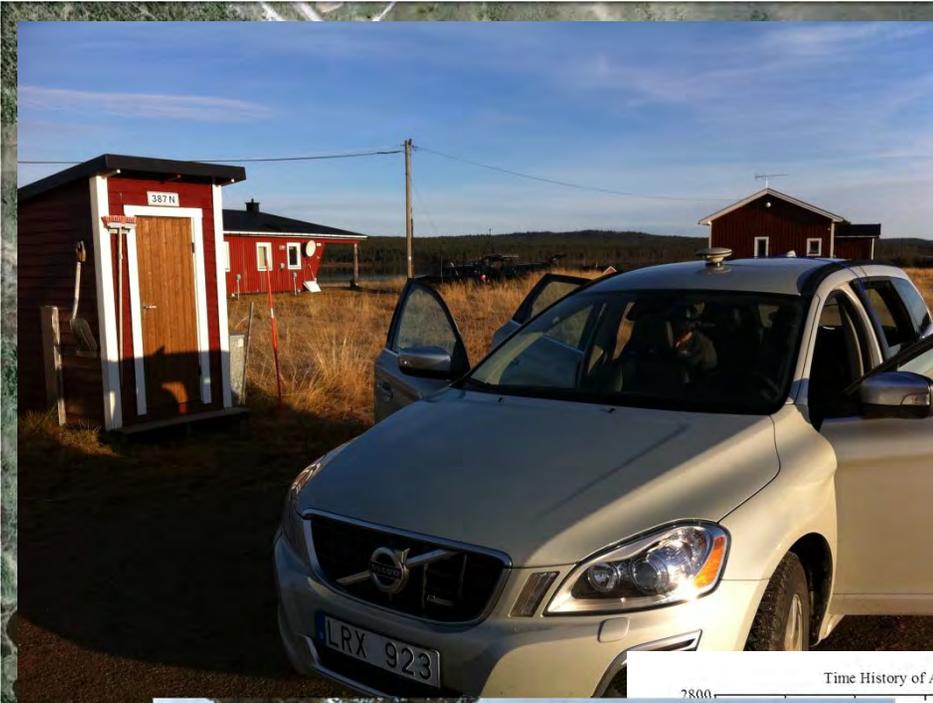


- *Developed experiment to assess AGC's ability to detect spoofing*
- *Difficult to perform such experiments outside of a laboratory environment*
- *Utilize a simplistic repeater spoofer (meaconing) in live testing*





AGC Spoofing Detection Experiment



Repeater/Spoofing Source Antenna

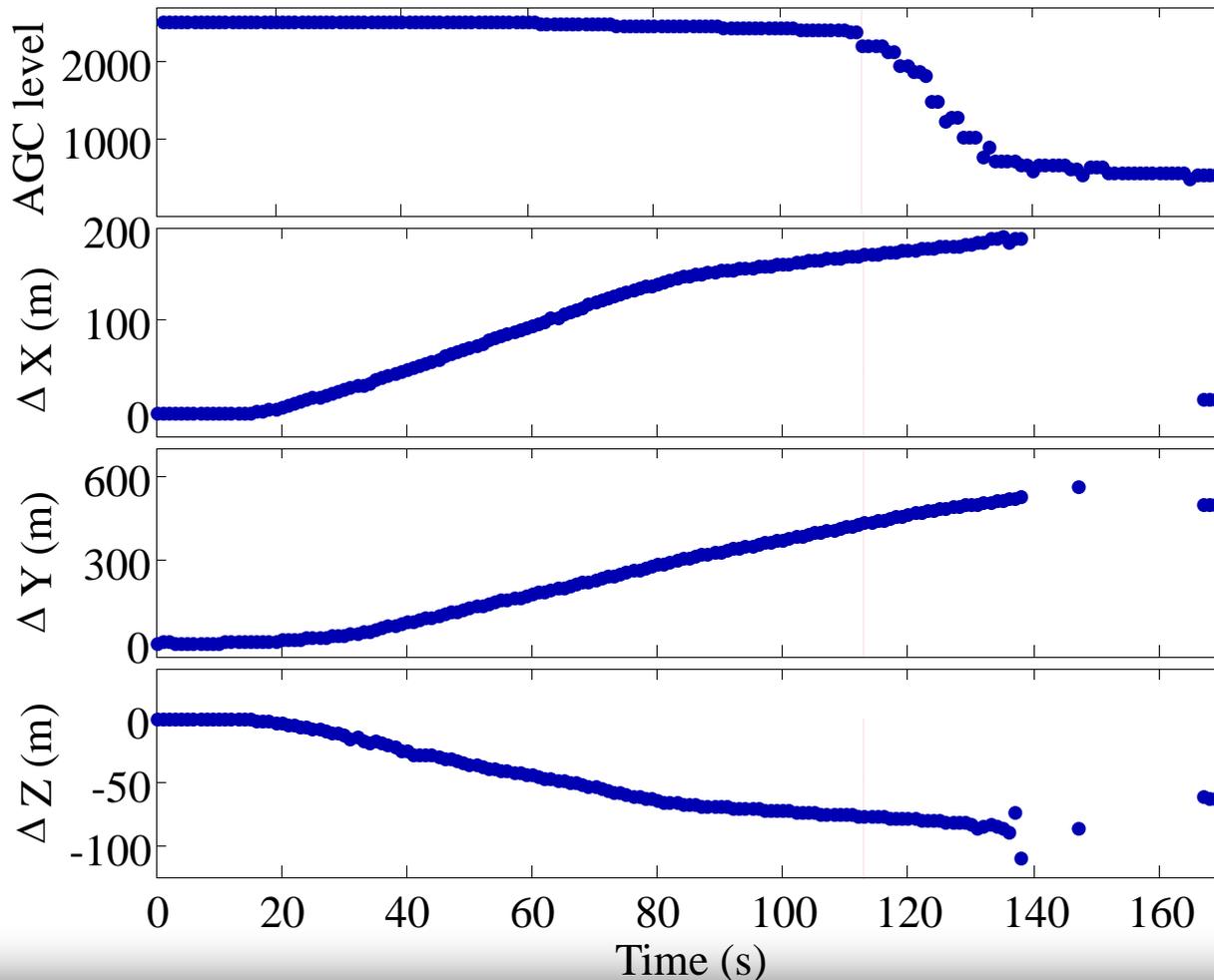
Repeater/Spoofing Transmission Antenna





GPS AGC & XYZ Position Data - Driving Toward Spoofer

Survey Grade Receiver Triggers: Driving Toward Spoofer



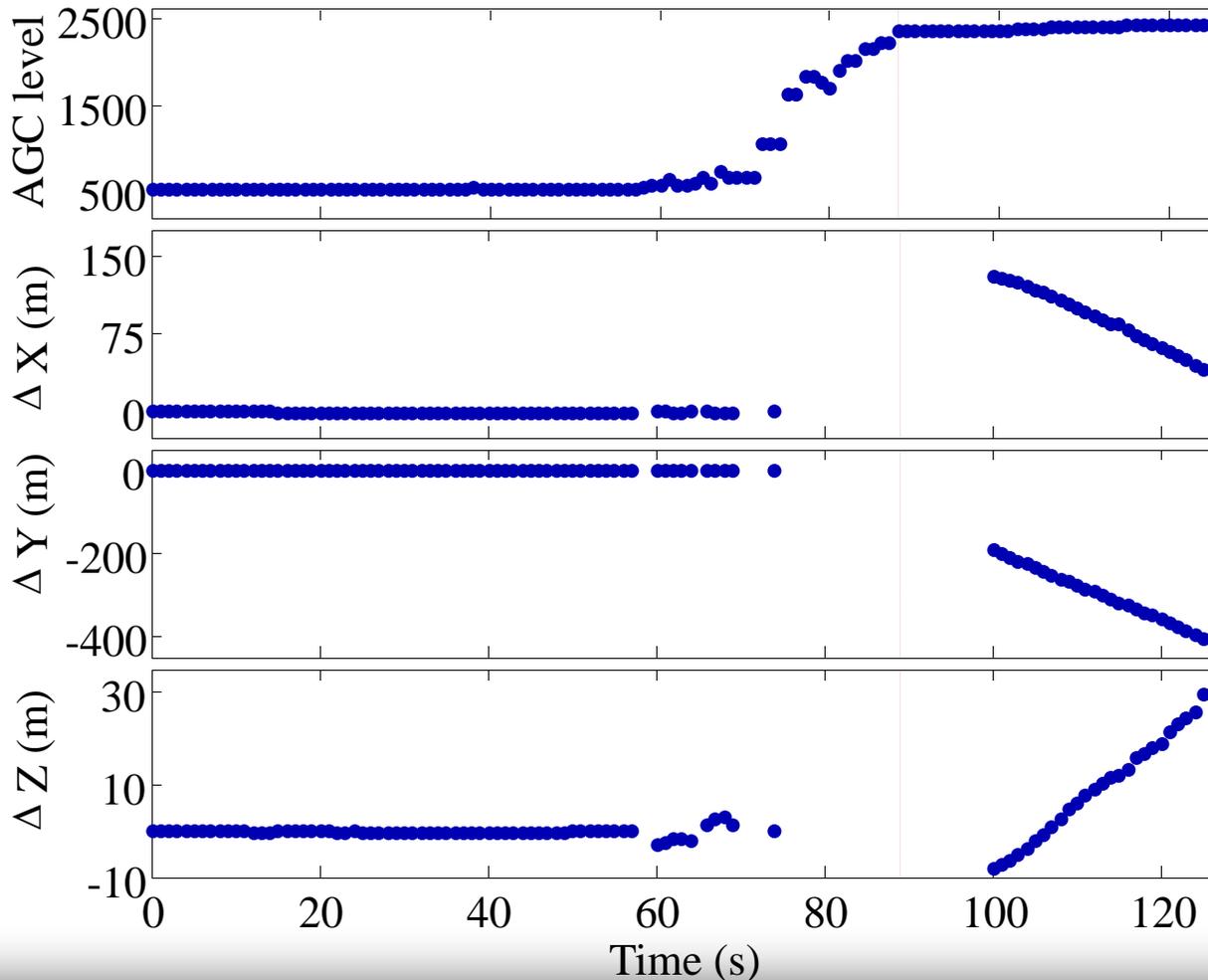
- *AGC 2-sigma threshold flagged well before GPS RX is captured by spoofer*
- *Other receivers under test showed similar results*





GPS AGC & XYZ Position Data - Driving Away Spoofer

Survey Grade Receiver Triggers: Driving Away From Spoofer



- *AGC 2-sigma threshold exceed when receiver is powered on*
- *True position only after AGC returns to normal levels*
- *Other receivers under test showed similar results*





Presentation Overview

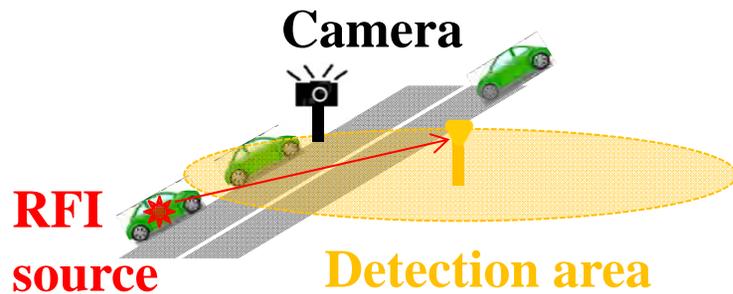
- *Motivation & Background*
- ***Concept & Experimental Results***
 - I. RFI Detection/Characterization*
 - II. Spoofers Detection*
 - III. RFI/Spoofers Localization***
 - IV. RFI/Spoofers Mitigation via CPRA*
- *Summary & Conclusions*





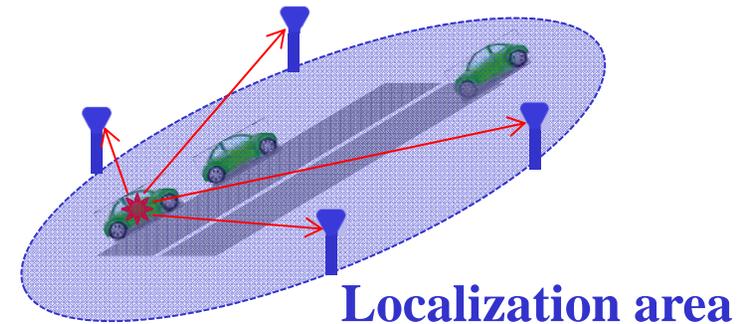
Update Detection System for Localization

Detection configuration

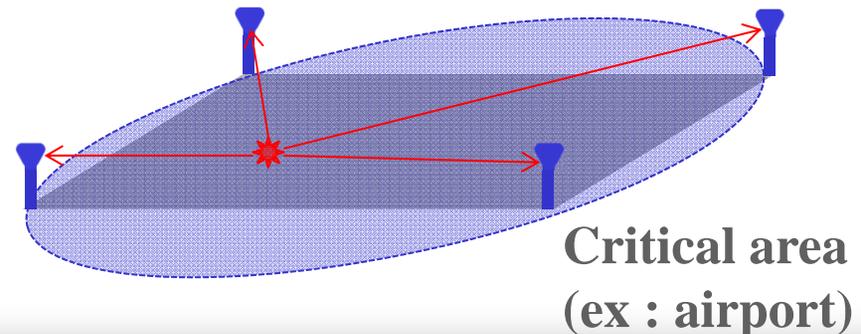


- » *How often does RFI occur ?*
- » *What kind of RFI (CW, narrowband, white noise) ?*
- » *Add camera capability*

Localization configuration

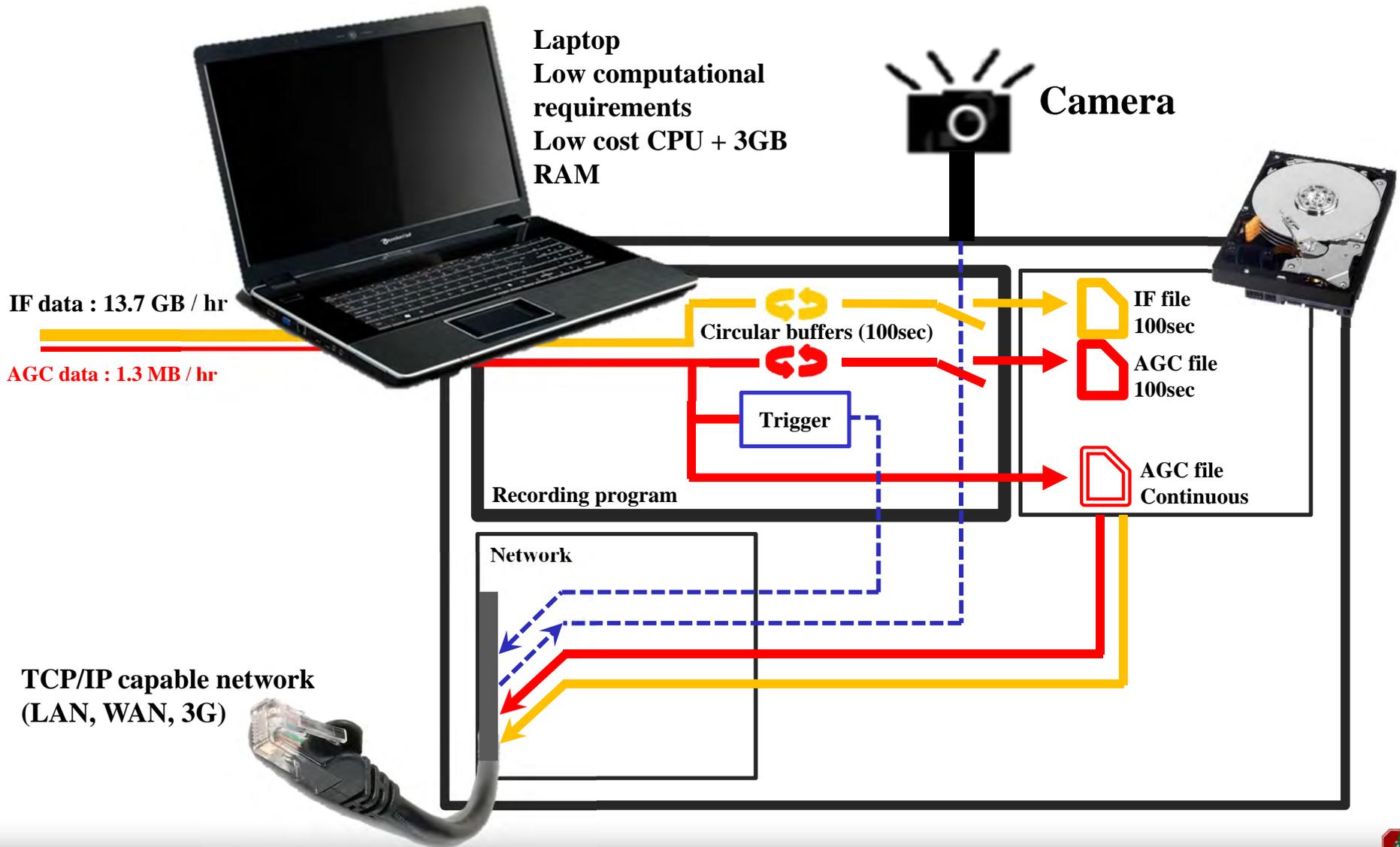


- » *Type of vehicle (car, truck, motorcycle)*
- » *Quickly identify spurious RFI sources*





System : Host Computer for Localization

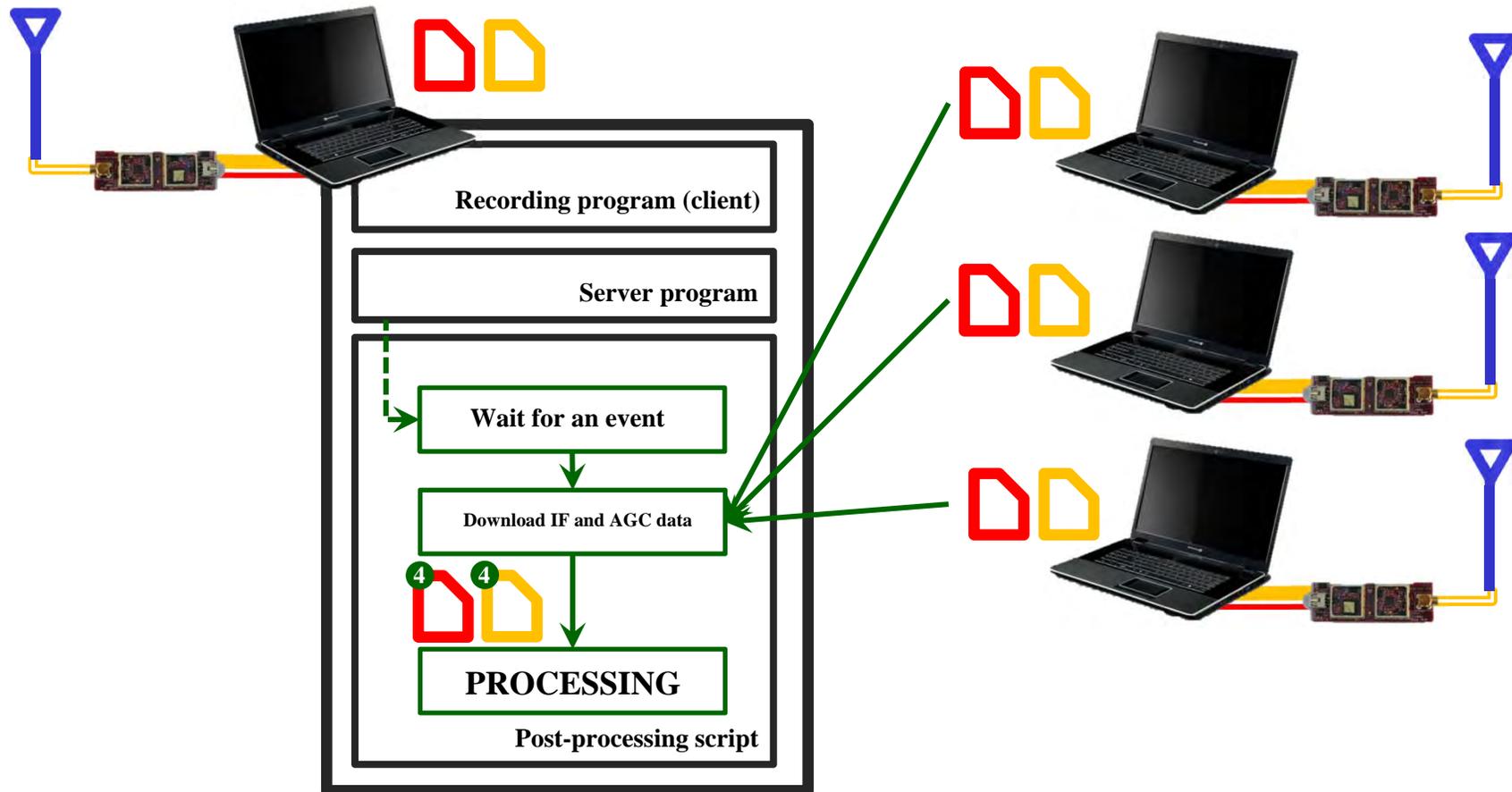




System : Network Operation

Running as a client + server

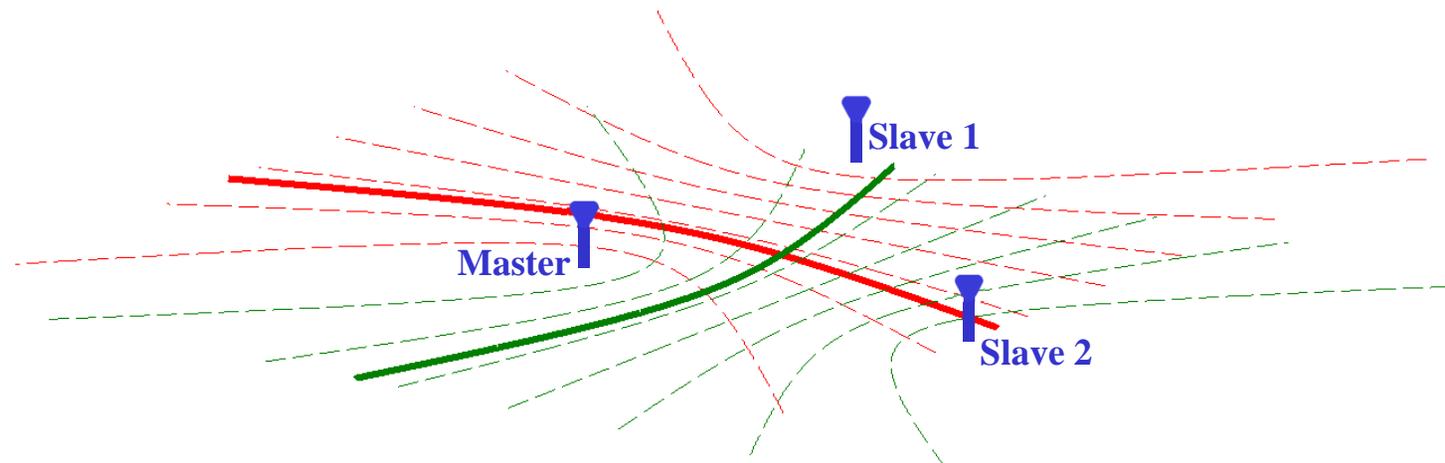
Running as clients





Processing Principles

- *Two possible methods*
 - » *Time Difference of Arrival : cross-correlation*
 - » *Power Difference of Arrival : AGC processing*
- *Both result in hyperbolic equations (like LORAN)*



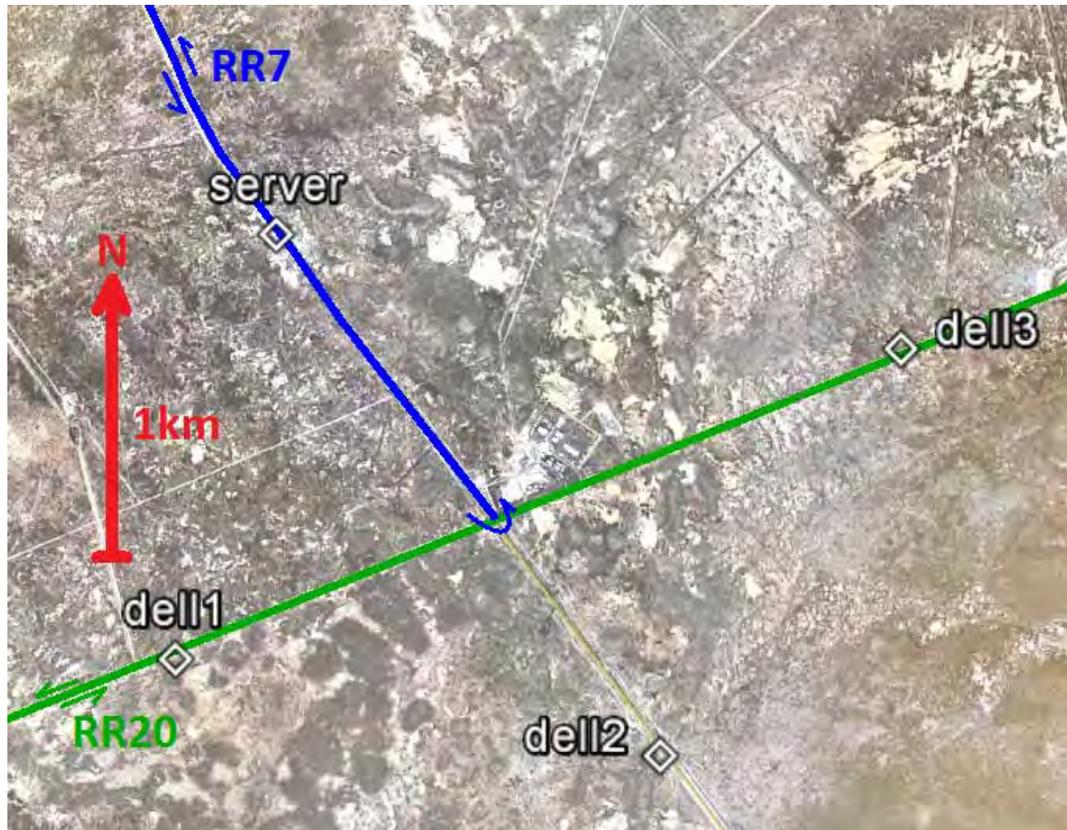
- *Cross-correlation requires coherent signals*
 - » *File alignment & clock error model leverage “clean” 40 sec of GPS data*





Department of Homeland Security (DHS) GPS Jammer Testing at White Sands Missile Range (WSMR) – 18-22 June 2012

Focused on two testing days



- **20-June-2012: Dynamic 250mW/2.5W jammers**

» *Station deployment : ~1.8km apart*

- Scenario 3 02:45 to 03:30
 - 1 vehicle RR7
 - 1 vehicle RR20
 - 2.5W jammers

- **22-June-2012: Stationary 25W jammers**

» *Station deployment : ~15km apart (9.4 mi)*

 Station

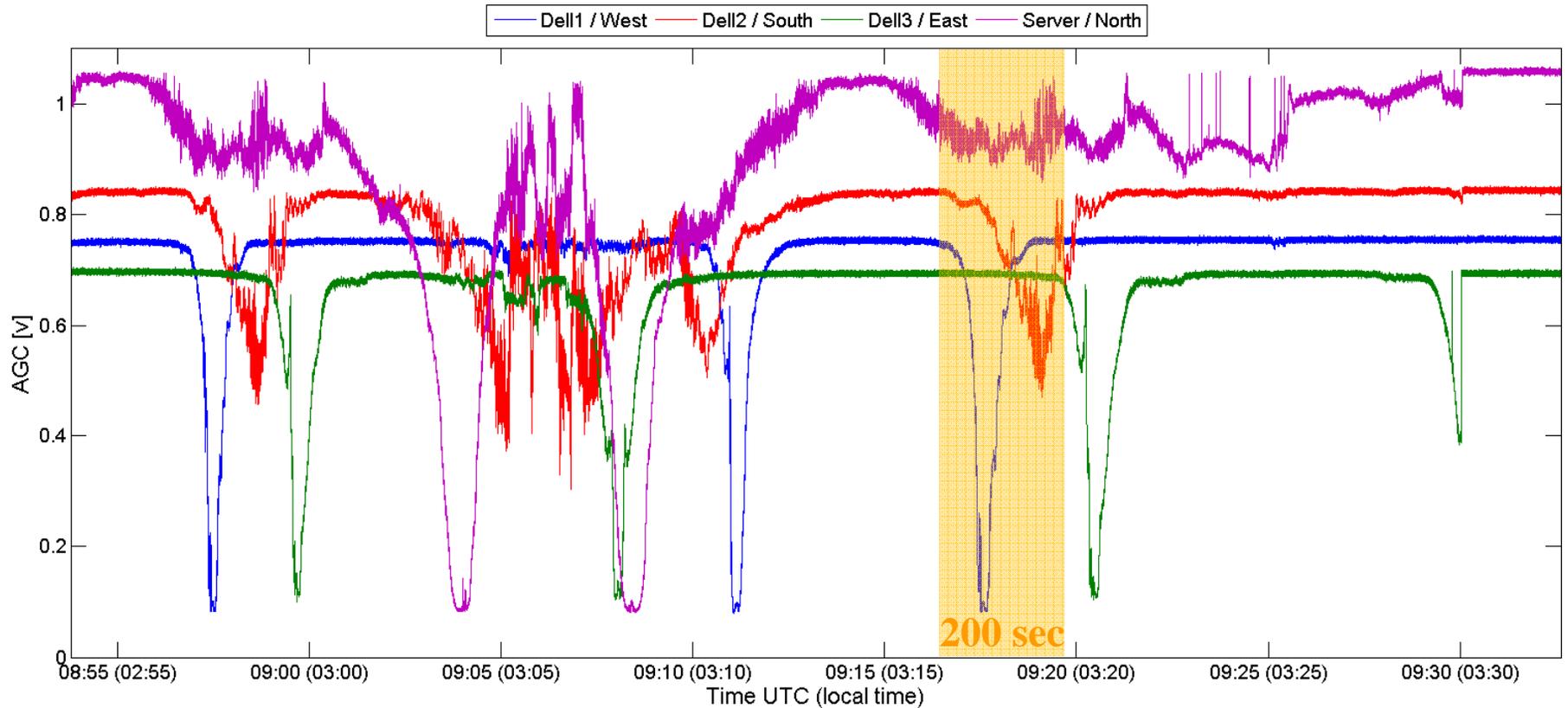


Jammer's path



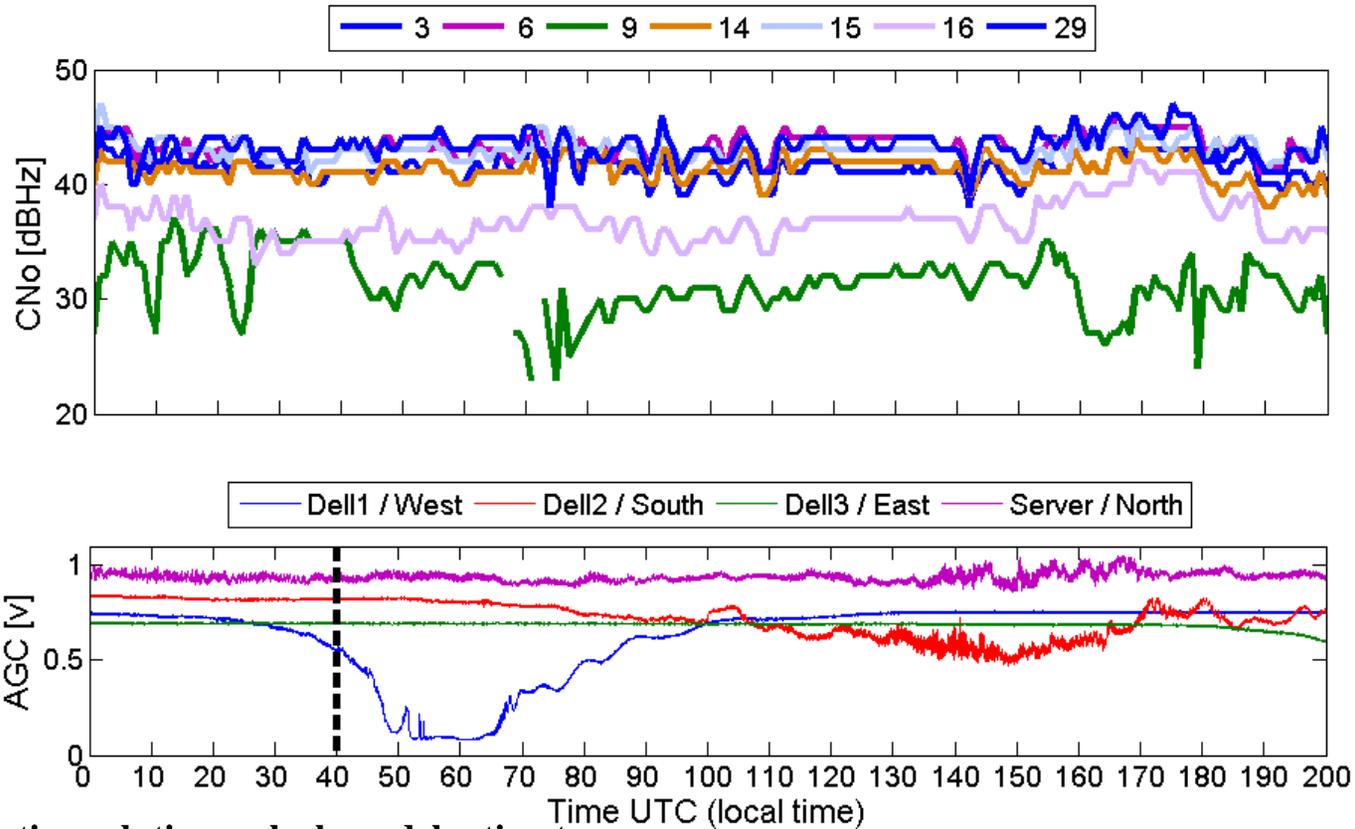


Experiment : Dynamic 250mW/2.5W jammers





Zoomed View: Dynamic 2.5W jammers



Navigation solution + clock model estimate



Cross-correlation + jammer localization





Localization Results: Animation





Presentation Overview

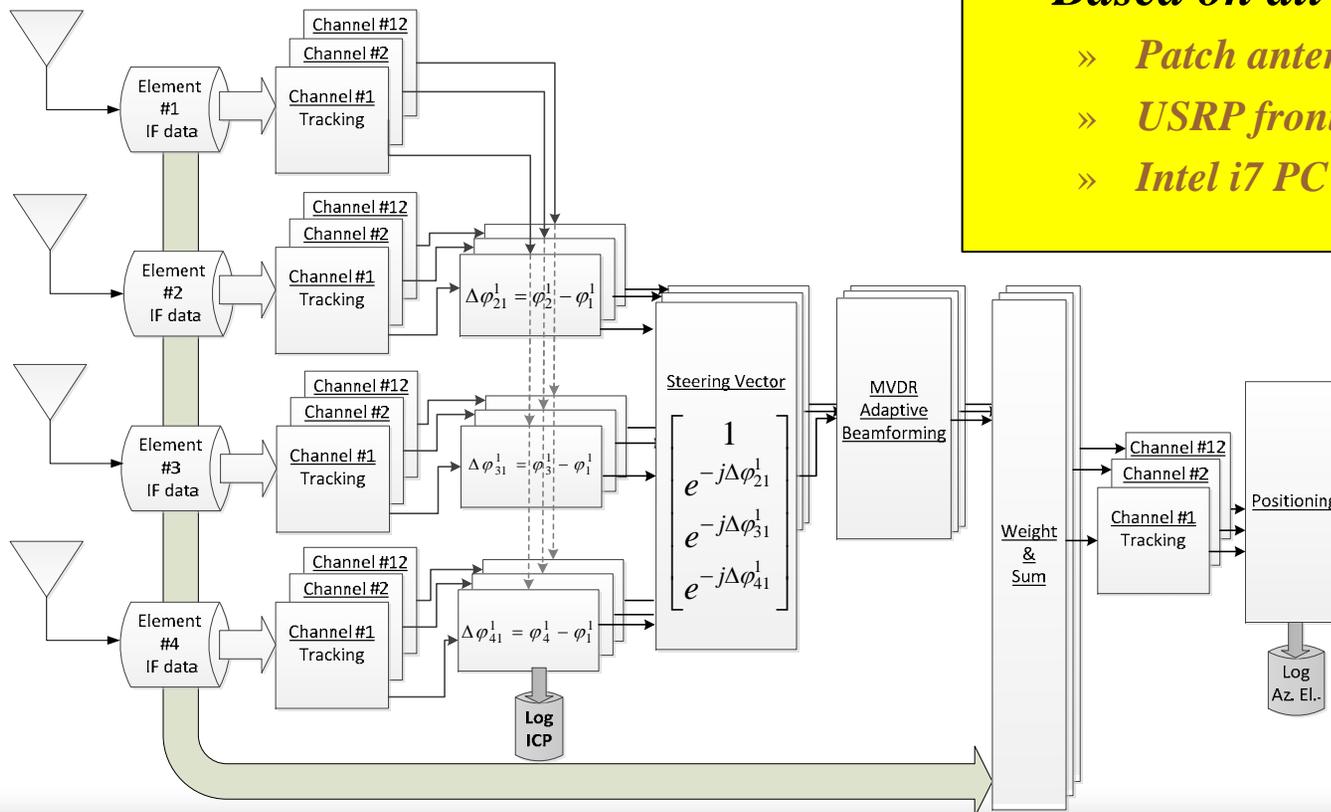
- *Motivation & Background*
- ***Concept & Experimental Results***
 - I. RFI Detection/Characterization*
 - II. Spoofers Detection*
 - III. RFI/Spoofers Localization*
 - IV. RFI/Spoofers Mitigation via CPRA***
- *Summary & Conclusions*





Controlled Radiation Pattern Antenna (CRPA) Software Receiver

- *All-in-view real-time CRPA software receiver for GPS/WAAS L1 C/A*
 - » *4 elements, 12 channels, 4 MHz sampling rate, 14 bits ADC resolution for I/Q*
 - » *Minimum Variance Distortionless Response (MVDR) & power minimization algorithms*

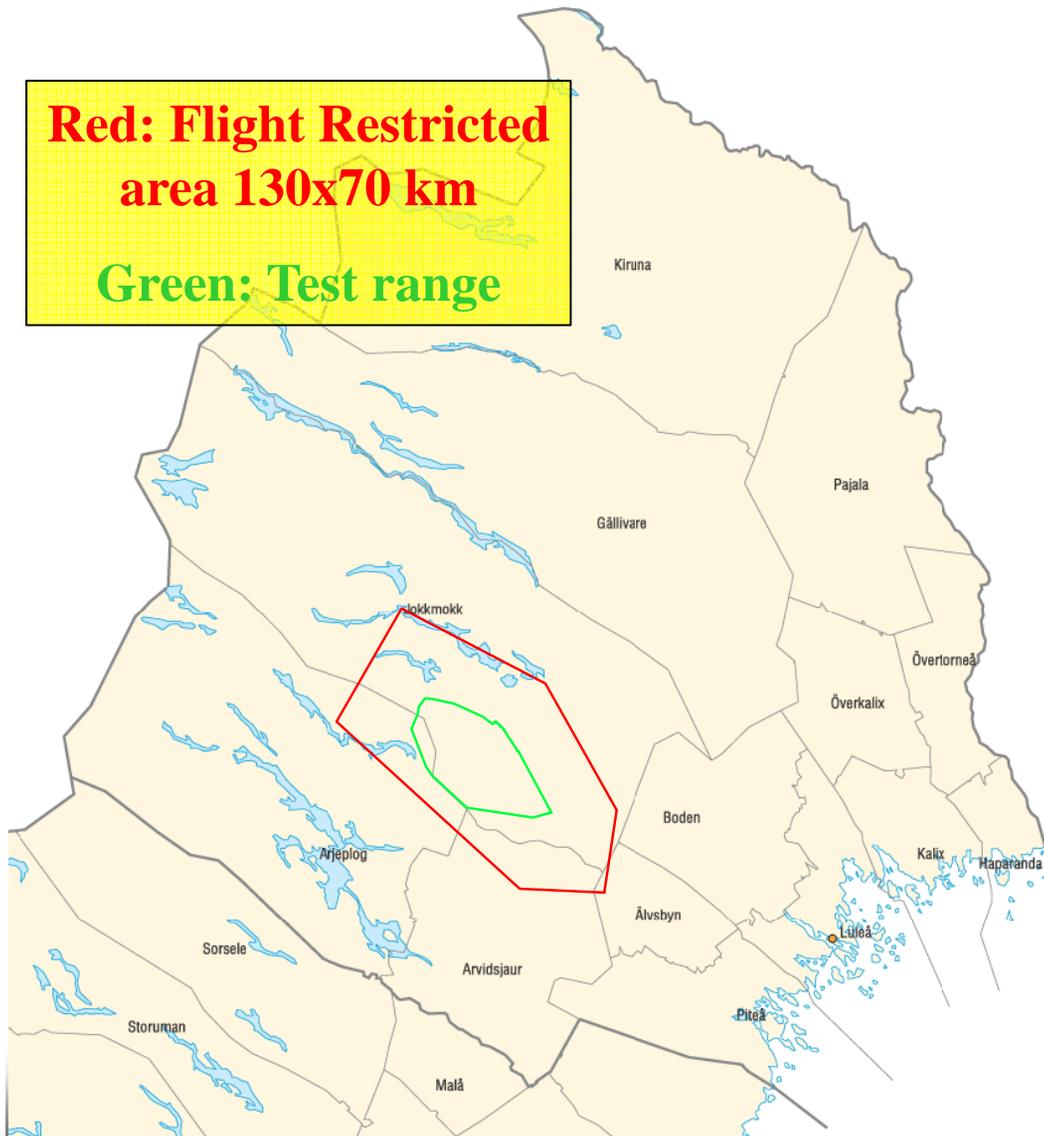


- *Based on all COTS components*
 - » *Patch antennas*
 - » *USRP front-ends*
 - » *Intel i7 PC processing computer*





Return to Swedish RFN Test Range: Oct 2012



- *Testing Panavia Tornado aircraft with munitions in GPS denied conditions*
 - » *“Piggybacking” on this test*
- *Operating Stanford 4 element CRPA in parallel with mass market RX*
 - » *Provides real time operation & IF recording*
- *Assess/compare performance in RFI environment*





RFN Antenna Array Testing – Oct 2012



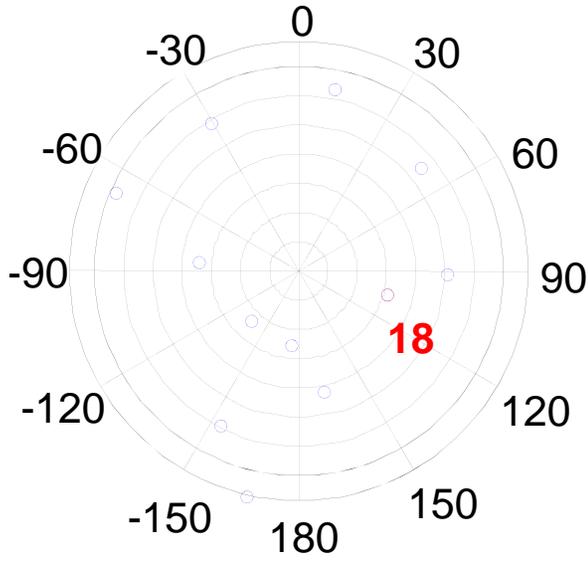


RFN Antenna Array Testing – 14-Oct-2012

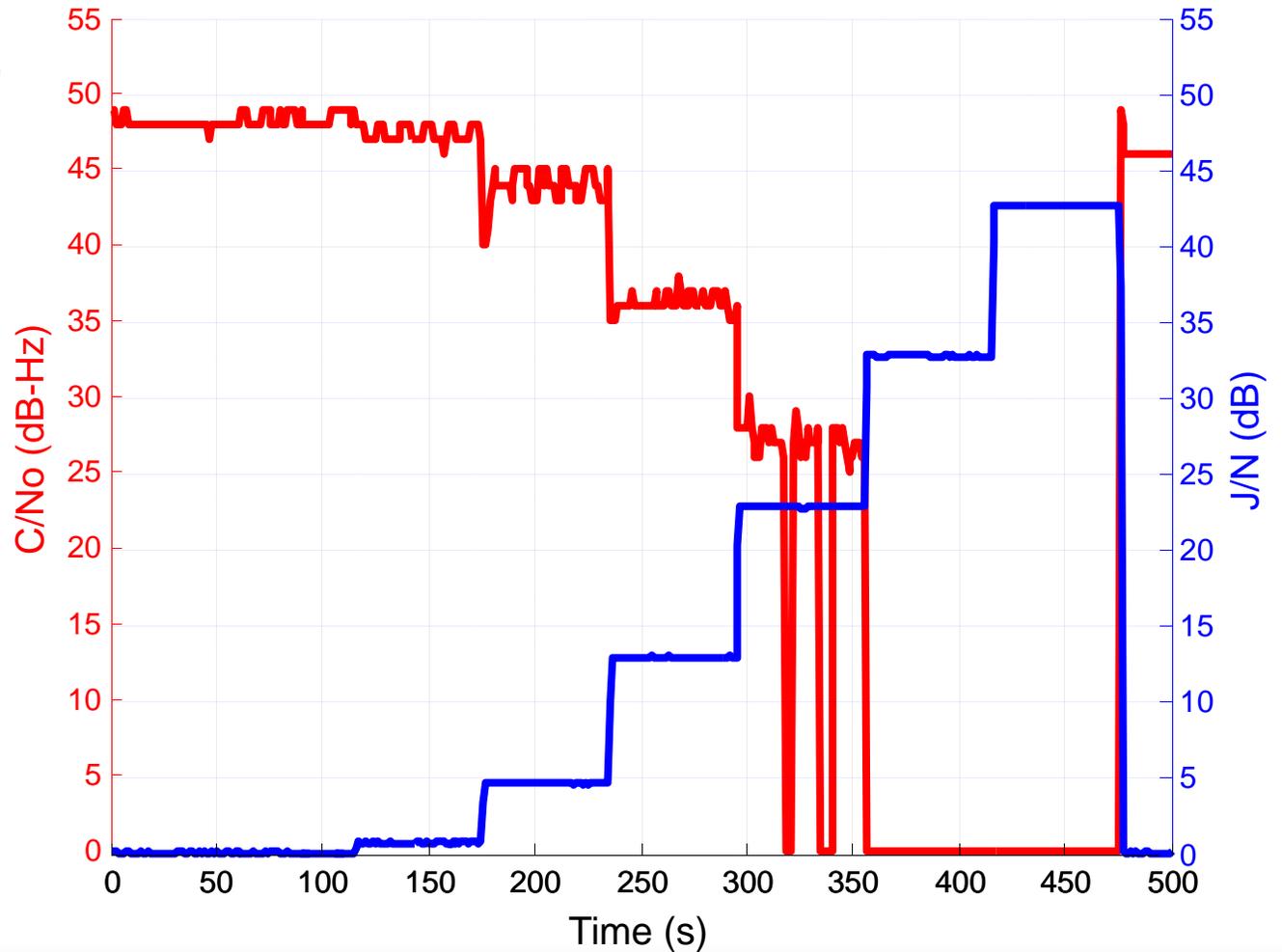




J/N & PRN18 C/No for Power Ramp Test



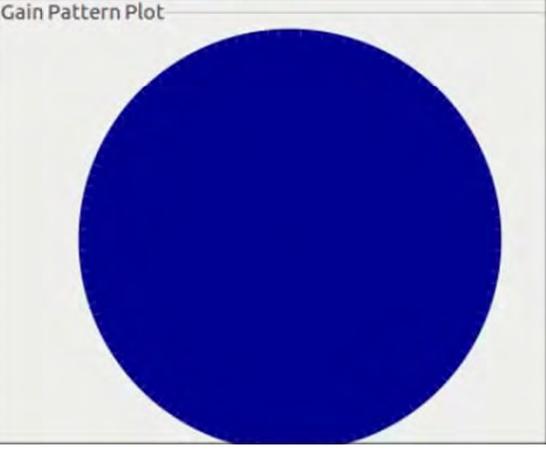
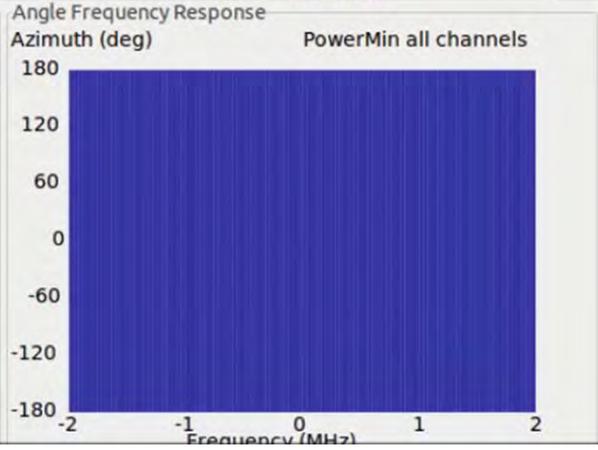
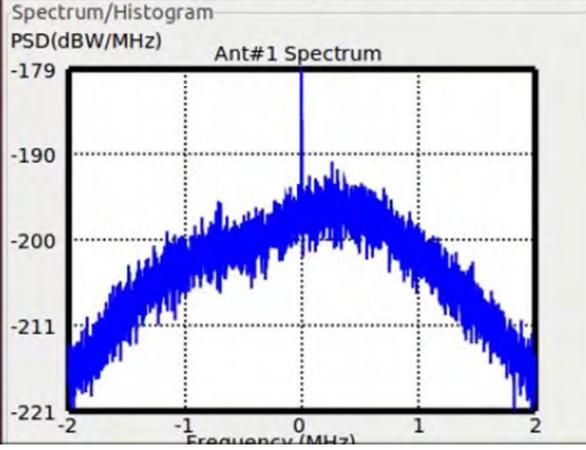
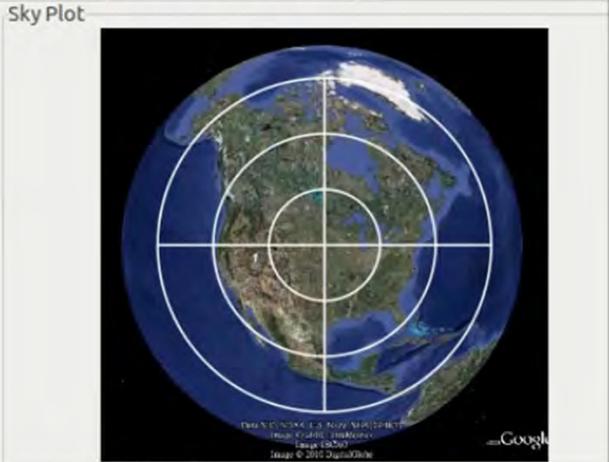
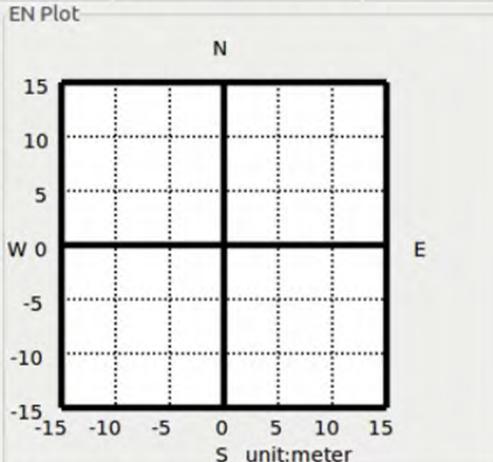
- *Shown are the J/N and C/No (PRN18 - mass market GPS RX) for stepped BBN jamming*
- *Assess/compare performance of CRPA processing*



Beamforming Software Receiver

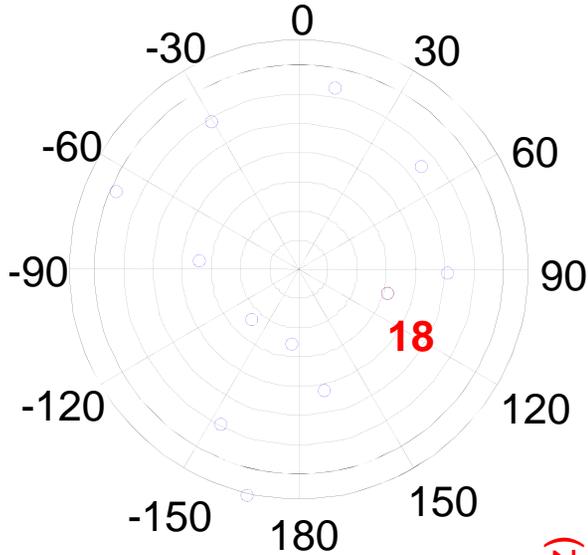
MVDR				PoweMin				Antenna #1				Antenna #2				Antenna #3				Antenna #4				Antenna Layout							
PRN	STA	FRQ	CNO	PRN	STA	FRQ	CNO	PRN	STA	FRQ	CNO	PRN	STA	FRQ	CNO	PRN	STA	FRQ	CNO	PRN	STA	FRQ	CNO	PRN	STA	FRQ	CNO	PRN	STA	FRQ	CNO
3	Lock	4304	55.3	3	Lock	4292	43.9	3	Lock	4303	45.6	3	Lock	4303	50.3	3	Lock	4305	51.9	3	Lock	4309	51.2								
16	Nav	816	48.1	16	Lock	806	44.2	16	Nav	816	48.1	16	Nav	816	39.8	16	Lock	817	42.7	16	Lock	815	47.3								
18	Lock	4698	52.5	18	Lock	4698	43.1	18	Lock	4694	47.6	18	Lock	4701	48.6	18	Lock	4691	44.1	18	Lock	4710	44.3								
19	Nav	6441	51.6	19	Nav	6439	42.2	19	Nav	6434	43.5	19	Nav	6450	45.9	19	Nav	6443	46.6	19	Nav	6437	48.1								
6	Lock	3270	52.4	6	Lock	3264	43.6	6	Lock	3267	46.4	6	Lock	3261	43.9	6	Lock	3276	48.2	6	Lock	3270	46.6								
7	Lock	1982	40.5	7	Lock	2001	0.0	7	Lock	1957	40.5	7	Lock	1968	43.6	7	Pull	1973	0.0	7	Lock	1971	41.5								
15	Lock	4601	47.3	15	Lock	4600	39.7	15	Lock	4600	41.5	15	Lock	4606	46.1	15	Lock	4593	38.7	15	Lock	4594	42.2								
21	Nav	1725	50.4	21	Lock	1717	42.1	21	Nav	1717	45.1	21	Nav	1727	45.4	21	Nav	1726	43.2	21	Nav	1727	45.9								
30	Lock	-45	36.6	30	Lock	-62	33.2	30	Lock	-45	36.6	30	Conf	-99	0.0	30	Lock	-46	36.7	30	Nav	-45	33.7								
8	Nav	4610	43.5	8	Nav	4619	40.9	8	Nav	4613	43.5	8	Lock	4557	29.7	8	Nav	4603	42.4	8	Nav	4596	40.1								
26	Nav	2533	43.8	26	Nav	2491	37.4	26	Nav	2519	39.0	26	Nav	2540	39.1	26	Nav	2531	36.8	26	Nav	2526	37.4								
22	Nav	6993	52.7	22	Lock	7008	43.4	22	Nav	6992	48.4	22	Nav	6994	46.8	22	Nav	6987	45.8	22	Nav	6998	49.7								

Carrier Phase Difference				Position	
PRN	Ant2-1	Ant3-1	Ant4-1	Item	Value
3	-129.25	-170.66	-134.99	Streaming Time(s)	14
16	-137.42	160.82	6.21	Latitude	0.0
18	23.48	64.29	-152.46	Longitude	0.0
19	-156.70	-82.88	-141.88	Height	0.0
6	-112.28	121.07	-132.23	Cable Delay 2-1	0.000000
7	NaN	NaN	NaN	Cable Delay 3-1	0.000000
15	89.75	129.54	93.02	Cable Delay 4-1	0.000000
21	51.53	19.60	128.79	AGC Gain 1	841
30	NaN	NaN	NaN	AGC Gain 2	715
8	NaN	NaN	NaN	AGC Gain 3	727
26	23.85	-122.34	22.91	AGC Gain 4	611
22	-6.35	77.74	-5.76	Adaptation Step	0.00182432

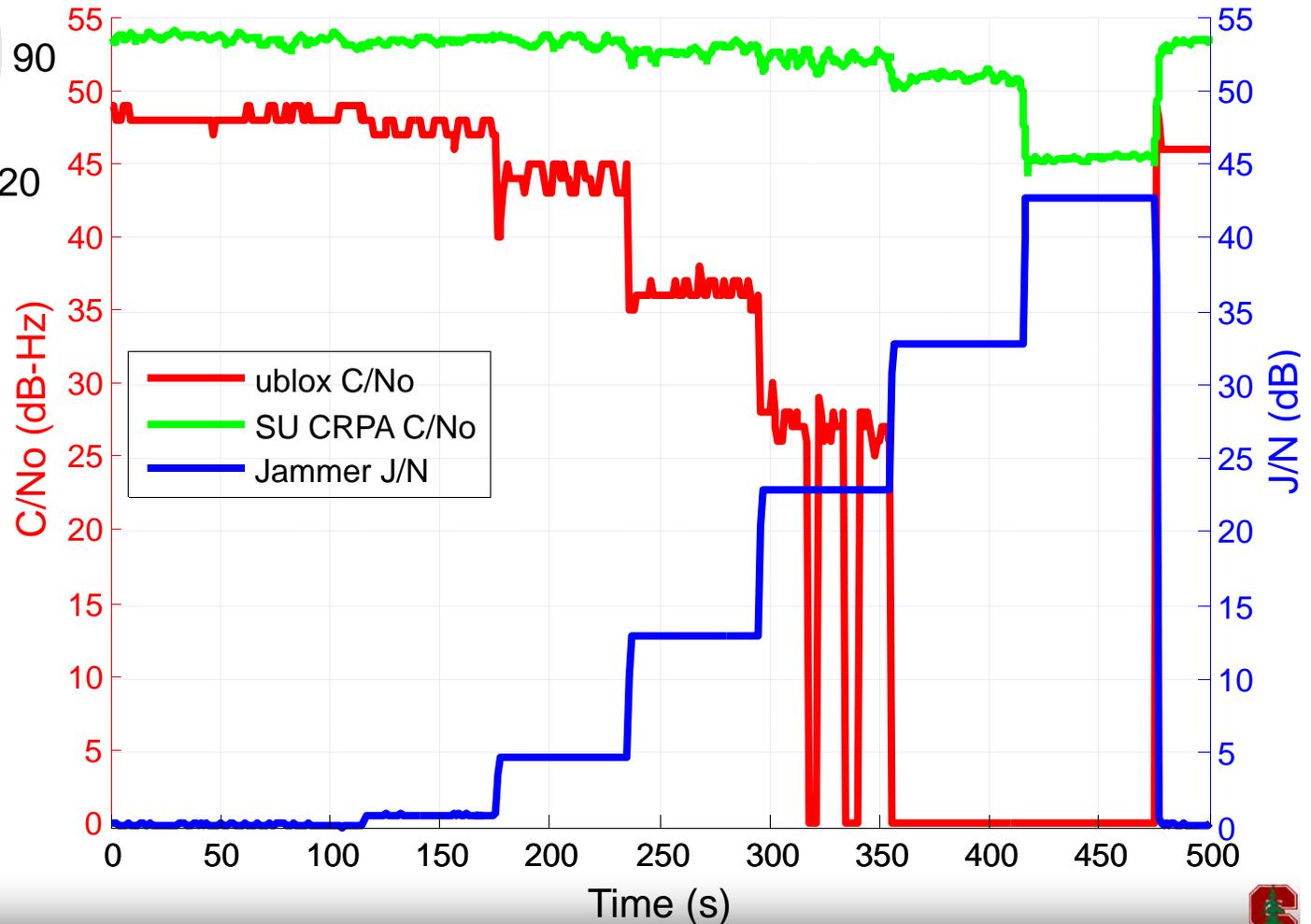




J/N & PRN18 C/No for Power Ramp Test



- *SU CRPA (MVDR) maintained lock for the entire jamming cycle*
- *SDR implementation using low cost COTS components*





Presentation Overview

- *Motivation & Background*
- *Concept & Experimental Results*
 - I. RFI Detection/Characterization*
 - II. Spoofers Detection*
 - III. RFI/Spoofers Localization*
 - IV. RFI/Spoofers Mitigation via CPRA*
- ***Summary & Conclusions***





Summary & Conclusions

- *Automatic Gain Control (AGC) is a powerful yet computational simplistic means to detect RFI/spoofing*
- *Localization of RFI/spoofing sources can be done effectively, easily and low-cost via time/power difference of arrival*
- *CRPAs can be developed using COTS hardware and provide a powerful tool to mitigate RFI/spoofing*

