

## COMPUTING WORST-CASE EXPECTATIONS GIVEN MARGINALS VIA SIMULATION

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### ABSTRACT

We study a direct Monte-Carlo-based approach for computing the worst-case expectation of two multidimensional random variables given a specification of their marginal distributions. This problem is motivated by several applications in risk quantification and statistics. We show that if one of the random variables takes finitely many values, a direct Monte Carlo approach allows to evaluate such worst case expectation with  $O(n^{-1/2})$  convergence rate as the number of Monte Carlo samples,  $n$ , increases to infinity.

### 1 INTRODUCTION

We focus on the problem of computing lower and upper bounds among any dependence structure for a function of two random vectors whose marginal distributions are assumed to be known. This problem is motivated from several applications in risk quantification and statistics. Before discussing its applications, let us first describe it precisely.

Suppose that  $X \in \mathbb{R}^d$  follows distribution  $\mu$  and  $Y \in \mathbb{R}^l$  follows distribution  $\nu$ . We define  $\Pi(\mu, \nu)$  to be the set of joint distributions  $\pi$  in  $\mathbb{R}^{d \times l}$  such that the marginal of the first  $d$  entries coincides with  $\mu$  and the marginal of the last  $l$  entries coincides with  $\nu$ . In other words, for any probability measure  $\pi$  in  $\mathbb{R}^{d \times l}$  (endowed with the Borel  $\sigma$ -field), if we let  $\pi_X(A) = \pi(A \times \mathbb{R}^l)$  for any Borel measurable set  $A \in \mathbb{R}^d$ , and  $\pi_Y(B) = \pi(\mathbb{R}^d \times B)$  for any Borel measurable set  $B \in \mathbb{R}^l$ , then  $\pi \in \Pi(\mu, \nu)$  if and only if  $\pi_X = \mu$  and  $\pi_Y = \nu$ . We are interested in the quantity (focusing on minimization)

$$V = \min\{\mathbb{E}_\pi[c(X, Y)] : \pi \in \Pi(\mu, \nu)\} \quad (1)$$

where  $c(\cdot, \cdot) \in \mathbb{R}$  is some cost function. Formulation (1) is well-defined as the class  $\Pi(\mu, \nu)$  is non-empty, because the product measure  $\pi = \mu \times \nu$  belongs to  $\Pi(\mu, \nu)$ .

In operations research contexts, problem (1) arises as a means to obtain bounds for performance measures in situations where dependence information is ambiguous. Such situations occur because, in practice, accurately estimating the marginal distributions of random variables is often relatively easy, e.g., by goodness-of-fit against well-chosen parametric distributions. They also occur in scenarios where data from different stochastic sources are collected independently (i.e., rather than in pairs), in which case no dependence information between these sources can be inferred. Indeed, special (i.e., discrete) cases of (1) have been analyzed in the distributionally robust optimization literature (e.g., Doan et al. 2015). Variants of (1) to risk measures have also been studied, regarding both algorithmic approaches (e.g., Rüschemdorf

1983, Embrechts et al. 2013) and sharp bounds over specific geometric classes of marginals (e.g., Wang and Wang 2011, Puccetti 2013, Puccetti and Rüschendorf 2013).

In statistics and machine learning contexts, the value of (1) is the Wasserstein distance (of order 1) between  $X$  and  $Y$  when  $c(\cdot, \cdot)$  is taken as a metric. The optimization can be viewed as the classical Kantorovich relaxation to Monge's problem in optimal transport (e.g., Rachev and Rüschendorf 1998, Villani 2008), where solutions based on differential properties have been extensively studied. Wasserstein distance is of central importance in probabilistic analysis (e.g., quantifying model discrepancies in Bayesian settings (Minsker et al. 2014) and convergence rates of ergodic processes (Boissard and Le Gouic 2014), among many others). The estimation of the distance itself is also suggested as a tool for statistical inference, including the use in goodness-of-fit tests (Del Barrio et al. 1999, Del Barrio et al. 2005) and in applications such as image recognition (Sommerfeld and Munk 2016). It has also been used to quantify model uncertainty in stochastic optimization problems (e.g., Esfahani and Kuhn 2015, Blanchet and Kang 2016, Blanchet and Murthy 2016, Gao and Kleywegt 2016) and in the application of distributionally robust optimization in machine learning settings (Blanchet et al. 2016). As such, there have been growing studies on the convergence behaviors of its empirical estimation. Central limit theorems (CLTs) on the empirical estimation of (1), based on representations using quantile functions, have been investigated in the one-dimensional case (e.g., Bobkov and Ledoux 2014, Del Barrio et al. 1999). More generally, concentration bounds have been studied in the line of work including Horowitz and Karandikar (1994), Bolley et al. (2007), Boissard (2011), Sriperumbudur et al. (2012), Trillos and Slepčev (2014) and Fournier and Guillin (2015), so do laws of large numbers in some special cases (e.g., Dobrić and Yukich 1995).

Since classical methods for solving (1), based for instance on Euler-Lagrange equations, may not yield straightforward computational schemes in general, we resort to Monte Carlo for an easy-to-implement approximation. Our contribution is precisely to quantify the rate of convergence of such Monte Carlo schemes. Our results also add to the literature of empirical Wasserstein estimation when these Monte Carlo samples are viewed as data. We focus on the setting where one of the marginals, say  $Y$ , is a finite-support distribution, and another, say  $X$ , is a multi-dimensional distribution that can be continuous. To approximate  $V$ , we consider the drawn samples from the continuous variable  $X$ , and replace the infinite-dimensional linear program (LP) in (1) by its sampled counterpart, which can be solved by standard LP solvers.

Our main result shows that the error of our procedure is  $O(n^{-1/2})$  where  $n$  is the sample size, independent of the dimension  $d$  or  $l$ . We also identify the limiting distribution in the associated CLT. The closest work to our results, as far as we know, is the recent work of Sommerfeld and Munk (2016), who derive a CLT when both marginal distributions are finitely discrete. Our result here can be viewed as a generalization to theirs when one of the distributions is continuous. We remark that our obtained rate differs from the typical rate of  $O(n^{-1/d})$  in high-dimensional empirical Wasserstein estimation where  $d \geq 3$  is the dimension of the marginal distributions. As we will see, the finite-support property of one of the marginals plays a crucial role in applying classical results in sample average approximation (SAA) that maintain the standard Monte Carlo rate in our scheme.

In the rest of this paper, we will first describe our algorithm, followed by our main results on the convergence analysis.

## 2 ALGORITHMIC DESCRIPTION

Suppose that the distribution  $\nu$  for  $Y$  has finite support  $\{y_1, \dots, y_m\} \subset \mathbb{R}^l$ . Supposing that  $X$  can be simulated, we sample  $n$  i.i.d. observations  $X_1, \dots, X_n$  from  $\mu$ , and approximate  $V$  by

$$V_n = \min\{\mathbb{E}_\pi[c(X, Y)] : \pi \in \Pi(\mu_n, \nu)\} \quad (2)$$

where  $\mu_n$  is the empirical distribution of  $X$  constructed from the  $X_i$ 's, i.e.,

$$\mu_n(A) = \frac{1}{n} \sum_{i=1}^n I(X_i \in A)$$

for any Borel measurable  $A$ .

Note that (2) is a finite-dimensional LP, which can be written more explicitly as

$$\begin{aligned} \min \quad & \sum_{i=1}^n \sum_{j=1}^m c(X_i, y_j) p_{ij} \\ \text{subject to} \quad & \sum_{j=1}^m p_{ij} = \frac{1}{n} \quad \forall i = 1, \dots, n \\ & \sum_{i=1}^n p_{ij} = \nu\{y_j\} \quad \forall j = 1, \dots, m \\ & p_{ij} \geq 0 \quad \forall i = 1, \dots, n, j = 1, \dots, m \end{aligned} \quad (3)$$

where the decision variables  $p_{ij}$  represent the probability masses on  $(X_i, y_j)$ , and  $\nu\{y_j\}$  denotes the mass on  $y_j$  under  $\nu$ . Problem (3) is an assignment problem, which is a special type of minimum cost problem and can be solved by, e.g., successive shortest path algorithms in polynomial time of order  $O(n^2m + n(n+m) \log(n+m))$  (see, e.g., R.K.Ahuja et al. 2000 pp. 471, 500).

### 3 CONVERGENCE ANALYSIS

Our main result is a convergence analysis on  $V_n$  to  $V$ . We impose the assumptions:

**Assumption 1** For each  $y_j$ ,  $c(\cdot, y_j)$  is non-negative and lower semicontinuous.

**Assumption 2** Suppose that  $\nu$  has finite support  $\{y_1, \dots, y_m\} \subset \mathbb{R}^l$ . We have

$$\mathbb{E}_\mu [c(X, y_j)^2] < \infty, \quad \forall j = 1, \dots, m.$$

Denote

$$V' = \max_{\beta_1, \dots, \beta_m \in \mathbb{R}} \mathbb{E}_\mu \left[ \min_{j=1, \dots, m} \{c(X, y_j) - \beta_j\} + \sum_{j=1}^m \beta_j \nu\{y_j\} \right] \quad (4)$$

which is the dual problem of (1) (see Lemma 1 for an explanation in the special case of finite-dimensional settings). Under Assumptions 1 and 2, strong duality (known as the Kantorovich duality) holds and  $V' = V$ ; see, e.g., Theorem 5.10 in Villani (2008).

In order to state our main result, we need to introduce a Gaussian random field  $G(\cdot) : \mathbb{R}^m \rightarrow \mathbb{R}$  with covariance structure given by

$$\text{Cov}(G(\beta), G(\beta')) = \text{Cov} \left( \min_{j=1, \dots, m} \{c(X, y_j) - \beta_j\}, \min_{j=1, \dots, m} \{c(X, y_j) - \beta'_j\} \right)$$

for any  $\beta = (\beta_j)_{j=1}^m$  and  $\beta' = (\beta'_j)_{j=1}^m$ . Our main result is the following.

**Theorem 1** Under Assumption 2,  $V_n \xrightarrow{P} V'$  as  $n \rightarrow \infty$ . Moreover,

$$n^{1/2} (V_n - V') \Rightarrow G^*$$

as  $n \rightarrow \infty$ , where

$$G^* = \max_{\beta = (\beta_1, \dots, \beta_m) \in \mathbb{S}} G(\beta).$$

Here  $\mathbb{S}$  is the set of all optimal solutions  $\beta = (\beta_j)_{j=1}^m \in \mathbb{R}^m$  for the convex optimization problem

$$\max_{\substack{\beta_1, \dots, \beta_m \in \mathbb{R} \\ \sum_{j=1}^m \beta_j = 0}} \mathbb{E}_\mu \left[ \min_{j=1, \dots, m} \{c(X, y_j) - \beta_j\} + \sum_{j=1}^m \beta_j \nu\{y_j\} \right]. \quad (5)$$

**Remark 1** The significance of this result is that one can approximate worst-case expectations by sampling with a rate of convergence (as measured by the sample size of the continuous distribution) of order  $O(n^{-1/2})$ . As we mentioned earlier, this might be somewhat surprising given that standard empirical estimators for Wasserstein distances exhibit a degradation which becomes quite drastic in high dimensions.

### 3.1 Proof of Theorem 1

We first note that adding a constant to  $\beta_j$  in the objective function of the dual does not change the objective value. To remove this ambiguity we introduce the next result.

**Lemma 1** Define

$$\widehat{V}_n := \max_{\substack{\beta_j \in \mathbb{R}, j=1, \dots, m. \\ \sum_{j=1}^m \beta_j = 0}} \left\{ \frac{1}{n} \sum_{i=1}^n \min_{j=1, \dots, m} \{c(X_i, y_j) - \beta_j\} + \sum_{j=1}^m \beta_j \nu\{y_j\} \right\}. \quad (6)$$

We have  $V_n = \widehat{V}_n$ .

*Proof.* The dual formulation of  $V_n$ , depicted as the LP (3), is given by

$$\begin{aligned} & \max \quad \frac{1}{n} \sum_{i=1}^n \alpha_i + \sum_{j=1}^m \beta_j \nu\{y_j\} \\ & \text{subject to} \quad \alpha_i + \beta_j \leq c(X_i, y_j) \quad \forall i = 1, \dots, n, \quad j = 1, \dots, m \end{aligned} \quad (7)$$

where  $(\alpha_i)_{i=1}^n, (\beta_j)_{j=1}^m$  are the dual variables. Note that the constraint in (7) can be written as  $\alpha_i \leq \min_{j=1, \dots, m} \{c(X_i, y_j) - \beta_j\} \quad \forall i = 1, \dots, n$ , which implies that (7) is equivalent to

$$\max_{\beta_j \in \mathbb{R}, j=1, \dots, m} \left\{ \frac{1}{n} \sum_{i=1}^n \min_{j=1, \dots, m} \{c(X_i, y_j) - \beta_j\} + \sum_{j=1}^m \beta_j \nu\{y_j\} \right\} \quad (8)$$

Since shifting any  $(\beta_j)_{j=1}^m$  to  $(\beta_j + \lambda)_{j=1}^m$  by an arbitrary constant  $\lambda$  does not affect the objective value of (8), we can always set  $\lambda = -\frac{1}{m} \sum_{j=1}^m \beta_j$  to enforce the constraint  $\sum_{j=1}^m \beta_j = 0$ , so that (8) is equal to (6). Finally, since (3) is feasible by choosing an independent distribution, strong duality holds. We therefore conclude the lemma.  $\square$

Next we show that  $\widehat{V}_n$  can be further reduced to a problem with compact feasible region, which will subsequently facilitate the invocation of classical results in SAA:

**Proposition 2** Define

$$\widehat{V}_n^b := \max_{\substack{\beta_j \in \mathbb{R}, |\beta_j| \leq b, j=1, \dots, m \\ \sum_{j=1}^m \beta_j = 0}} \left\{ \frac{1}{n} \sum_{i=1}^n \min_{j=1, \dots, m} \{c(X_i, y_j) - \beta_j\} + \sum_{j=1}^m \beta_j \nu\{y_j\} \right\}. \quad (9)$$

There exists some large enough constant  $b > 0$  such that

$$V_n = \widehat{V}_n^b \quad (10)$$

eventually, i.e., holds for any  $n > N$  for some  $N < \infty$  almost surely.

*Proof.* By Lemma 1, we have

$$\begin{aligned} V_n &= \widehat{V}_n \\ &= \max \left\{ \max_{\substack{\beta_j \in \mathbb{R}, |\beta_j| \leq b, j=1, \dots, m \\ \sum_{j=1}^m \beta_j = 0}} \left\{ \frac{1}{n} \sum_{i=1}^n \min_{j=1, \dots, m} \{c(X_i, y_j) - \beta_j\} + \sum_{j=1}^m \beta_j \nu\{y_j\} \right\}, \right. \\ & \quad \left. \max_{\substack{\beta_j \in \mathbb{R}, j=1, \dots, m, |\beta_j| > b \text{ for some } j \\ \sum_{j=1}^m \beta_j = 0}} \left\{ \frac{1}{n} \sum_{i=1}^n \min_{j=1, \dots, m} \{c(X_i, y_j) - \beta_j\} + \sum_{j=1}^m \beta_j \nu\{y_j\} \right\} \right\}. \end{aligned} \quad (11)$$

Note that the first term inside the outer max is  $\widehat{V}_n^b$  by our definition (9). We will show that there exists a deterministic  $b > 0$  such that the first term dominates the second term eventually, which will then conclude the proposition.

To this end, consider the second term in (11)

$$\begin{aligned} & \max_{\substack{\beta_j \in \mathbb{R}, j=1, \dots, m, |\beta_j| > b \text{ for some } j \\ \sum_{j=1}^m \beta_j = 0}} \left\{ \frac{1}{n} \sum_{i=1}^n \min_{j=1, \dots, m} \{c(X_i, y_j) - \beta_j\} + \sum_{j=1}^m \beta_j \nu\{y_j\} \right\} \\ \leq & \max_{\substack{\beta_j \in \mathbb{R}, j=1, \dots, m, |\beta_j| > b \text{ for some } j \\ \sum_{j=1}^m \beta_j = 0}} \left\{ \min_{j=1, \dots, m} \{-\beta_j\} + \sum_{j=1}^m \beta_j \nu\{y_j\} \right\} + \frac{1}{n} \sum_{i=1}^n \max_{j=1, \dots, m} c(X_i, y_j). \end{aligned} \quad (12)$$

We analyze

$$\max_{\substack{\beta_j \in \mathbb{R}, j=1, \dots, m, |\beta_j| > b \text{ for some } j \\ \sum_{j=1}^m \beta_j = 0}} \left\{ \min_{j=1, \dots, m} \{-\beta_j\} + \sum_{j=1}^m \beta_j \nu\{y_j\} \right\}. \quad (13)$$

Denote  $M = \max_{j=1, \dots, m} |\beta_j|$ , so that  $M > b$  for any  $\beta$  inside the feasible region. There must exist either a  $\beta_{j^*} = M$  or  $\beta_{j^*} = -M$ . In the first case, we have

$$\begin{aligned} & \max_{\substack{\beta_j \in \mathbb{R}, j=1, \dots, m, |\beta_j| > b \text{ for some } j \\ \sum_{j=1}^m \beta_j = 0}} \left\{ \min_{j=1, \dots, m} \{-\beta_j\} + \sum_{j=1}^m \beta_j \nu\{y_j\} \right\} \\ \leq & -M + \left\{ \begin{array}{l} \max \quad \sum_{j=1}^m \beta_j \nu\{y_j\} \\ \text{subject to } \beta_j \leq M \quad \forall j = 1, \dots, m \\ \sum_{j=1}^m \beta_j = 0 \end{array} \right\} \\ = & -M + M \times \left\{ \begin{array}{l} \max \quad \sum_{j=1}^m \beta_j \nu\{y_j\} \\ \text{subject to } \beta_j \leq 1 \quad \forall j = 1, \dots, m \\ \sum_{j=1}^m \beta_j = 0 \end{array} \right\} \end{aligned} \quad (14)$$

where the last equality follows by a change of variable from  $\beta_j$  to  $\beta_j/M$  in the optimization. Note that the optimal value of

$$\begin{aligned} & \max \quad \sum_{j=1}^m \beta_j \nu\{y_j\} \\ & \text{subject to } \beta_j \leq 1 \quad \forall j = 1, \dots, m \\ & \quad \quad \quad \sum_{j=1}^m \beta_j = 0 \end{aligned}$$

is strictly less than 1. To see this, observe that the optimal value is at most 1 by using the first constraint. The value of exactly 1 is attained under the first constraint by the unique solution  $\beta_j = 1, j = 1, \dots, m$ , which is ruled out because it would violate the second constraint. With this claim, we conclude that (14) is equal to  $\theta M$  for some  $\theta < 0$ , which is bounded from above by  $\theta b$ .

In the second case, we have  $\beta_{j^*} = -M$ . Let  $\tilde{j}^* = \operatorname{argmax}_{j=1, \dots, m} \{\beta_j\}$ . By the constraint  $\sum_{j=1}^m \beta_j = 0$  in (13), we must have  $\beta_{\tilde{j}^*} \geq M/(m-1)$ . Therefore, applying our argument for the first case gives that (13) is bounded from above by  $\theta M/(m-1) \leq \theta b/(m-1)$  for the same  $\theta < 0$  chosen before.

Therefore, in either case (13) is bounded from above by  $\theta b/(m-1)$ . Note that the first term inside the outer max in (11), namely  $\widehat{V}_n^b$ , satisfies  $\widehat{V}_n^b \geq (1/n) \sum_{i=1}^n \min_{j=1, \dots, m} c(X_i, y_j)$  by plugging in the feasible solution given by  $\beta_j = 0, j = 1, \dots, m$ . Thus, with the law of large numbers, by choosing  $b > 0$  large enough such that

$$\frac{\theta b}{m-1} + \mathbb{E}_\mu \left[ \max_{j=1, \dots, m} c(X, y_j) \right] < \mathbb{E}_\mu \left[ \min_{j=1, \dots, m} c(X, y_j) \right] \quad (15)$$

the first term dominates the second term inside the outer max in (11) as  $n \rightarrow \infty$  almost surely.  $\square$

We are now ready to prove Theorem 1:

*Proof of Theorem 1.* Note that the function

$$F(X, \beta) := \min_{j=1, \dots, m} \{c(X, y_j) - \beta_j\} + \sum_{j=1}^m \beta_j v\{y_j\} \quad (16)$$

on  $\beta = (\beta_j)_{j=1}^m \in \mathbb{R}^m$  is Lipschitz continuous in the sense that

$$|F(X, \beta) - F(X, \beta')| \leq (1 + \|v\|) \|\beta - \beta'\|$$

where  $\|\cdot\|$  denotes the  $L_2$ -norm, and  $v$  is interpreted as a vector  $(v\{y_j\})_{j=1}^m$ . This follows since

$$\left| \min_{j=1, \dots, m} \{c(X, y_j) - \beta_j\} - \min_{j=1, \dots, m} \{c(X, y_j) - \beta'_j\} \right| \leq \|\beta - \beta'\|_\infty$$

and

$$\left| \sum_{j=1}^m \beta_j v\{y_j\} - \sum_{j=1}^m \beta'_j v\{y_j\} \right| \leq \|v\| \|\beta - \beta'\|$$

by the Cauchy-Schwarz inequality. Since the set  $\mathbb{B} := \{\beta \in \mathbb{R}^m : \sum_{j=1}^m \beta_j = 0, |\beta_j| \leq b, \forall j = 1, \dots, m\}$  is compact and  $\mathbb{E}_\mu[F(X, \beta)^2] < \infty$  by Assumption 2, by using Theorem 5.7 in Shapiro et al. (2009), we have

$$\widehat{V}_n^b \xrightarrow{P} V^b \quad (17)$$

and

$$\sqrt{n}(\widehat{V}_n^b - V^b) \Rightarrow G^{*,b} \quad (18)$$

where

$$V^b = \max_{\substack{\beta_j \in \mathbb{R}, |\beta_j| \leq b, j=1, \dots, m \\ \sum_{j=1}^m \beta_j = 0}} \mathbb{E}_\mu \left[ \min_{j=1, \dots, m} \{c(X, y_j) - \beta_j\} + \sum_{j=1}^m \beta_j v\{y_j\} \right] \quad (19)$$

and

$$G^{*,b} = \max_{\beta = (\beta_1, \dots, \beta_m) \in \mathbb{S}^b} G(\beta)$$

with  $\mathbb{S}^b$  denoting the set of optimal solutions for (19) and  $G(\cdot)$  is defined as in Theorem 1 but restricted to the domain  $\mathbb{B}$ .

By Proposition 2, we have  $\sqrt{n}(\widehat{V}_n^b - V_n) \xrightarrow{P} 0$  as  $n \rightarrow \infty$ . Thus, together with (17), we have

$$V_n \xrightarrow{P} V^b$$

and together with (18), we have

$$\sqrt{n}(V_n - V^b) \Rightarrow G^{*,b}$$

by Slutsky's Theorem.

To conclude the theorem, we show that  $V^b = V'$ , and  $\mathbb{S}^b = \mathbb{S}$  so that  $G^{*,b} = G^*$ . By using essentially the same argument as for Proposition 2 (with the empirical expectation replaced by  $\mathbb{E}_\mu[\cdot]$ ) and choosing the same  $b$  as in (15), we have

$$\begin{aligned}
 V' &= \max_{\beta_j \in \mathbb{R}, j=1, \dots, m} \mathbb{E}_\mu \left[ \min_{j=1, \dots, m} \{c(X, y_j) - \beta_j\} + \sum_{j=1}^m \beta_j v\{y_j\} \right] \\
 &= \max_{\substack{\beta_j \in \mathbb{R}, j=1, \dots, m \\ \sum_{j=1}^m \beta_j = 0}} \mathbb{E}_\mu \left[ \min_{j=1, \dots, m} \{c(X, y_j) - \beta_j\} + \sum_{j=1}^m \beta_j v\{y_j\} \right] \\
 &\quad \text{by shifting any } (\beta_j)_{j=1}^m \text{ to } (\beta_j - (1/m) \sum_{k=1}^m \beta_k)_{j=1}^m \text{ which does not affect the objective value and} \\
 &\quad \text{enforces the constraint } \sum_{j=1}^m \beta_j = 0 \\
 &= \max \left\{ \max_{\substack{\beta_j \in \mathbb{R}, |\beta_j| \leq b, j=1, \dots, m \\ \sum_{j=1}^m \beta_j = 0}} \mathbb{E}_\mu \left[ \min_{j=1, \dots, m} \{c(X, y_j) - \beta_j\} + \sum_{j=1}^m \beta_j v\{y_j\} \right], \right. \\
 &\quad \left. \max_{\substack{\beta_j \in \mathbb{R}, j=1, \dots, m, |\beta_j| > b \text{ for some } j \\ \sum_{j=1}^m \beta_j = 0}} \mathbb{E}_\mu \left[ \min_{j=1, \dots, m} \{c(X, y_j) - \beta_j\} + \sum_{j=1}^m \beta_j v\{y_j\} \right] \right\}
 \end{aligned}$$

where

$$\begin{aligned}
 &V^b \\
 &= \max_{\substack{\beta_j \in \mathbb{R}, |\beta_j| \leq b, j=1, \dots, m \\ \sum_{j=1}^m \beta_j = 0}} \mathbb{E}_\mu \left[ \min_{j=1, \dots, m} \{c(X, y_j) - \beta_j\} + \sum_{j=1}^m \beta_j v\{y_j\} \right] \\
 &> \max_{\substack{\beta_j \in \mathbb{R}, j=1, \dots, m, |\beta_j| > b \text{ for some } j \\ \sum_{j=1}^m \beta_j = 0}} \mathbb{E}_\mu \left[ \min_{j=1, \dots, m} \{c(X, y_j) - \beta_j\} + \sum_{j=1}^m \beta_j v\{y_j\} \right]
 \end{aligned}$$

so that  $V' = V^b$  and  $\mathbb{S}^b = \mathbb{S}$ . □

#### 4 ADDITIONAL DISCUSSION AND EXTENSIONS

Finally, we briefly discuss the challenge in generalizing our procedure to the case when both  $X$  and  $Y$  are continuous. Here, one may attempt to sample both variables (assuming both can be simulated) and formulate a sampled program like (2) or (3). However, the analog of its reformulation in (6) and (9) will have a growing number of variables  $\beta_j$  and an analogous limit of (5) that involves an infinite-dimensional variable, which challenges the use of standard SAA machinery. In fact, consider a special example where  $X, Y \sim U[0, 1]^d$  and  $c(x, y) = \|x - y\|$ . In this case, (1) corresponds to the Wasserstein distance (of order 1) between  $X$  and  $Y$ , which is of course 0. It is known that sampling  $X$  and keeping  $Y$  continuous will give, for  $d \geq 3$ , an expected optimal value of (2) that is of order  $n^{-1/d}$ , i.e.,  $C_1 n^{-1/d} \leq EV_n \leq C_2 n^{-1/d}$  for all  $n$  for some  $C_1, C_2 > 0$  (e.g., Problem 5.11 in van Handel 2014). Thus, the convergence rate deteriorates with the dimension and the standard Monte Carlo rate  $O(n^{-1/2})$  cannot be maintained without assuming additional structure or information available to the modeler on the primal problem. It is of interest to investigate reasonable assumptions which are useful in applications and which would mitigate such rate-of-convergence deterioration.

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