

Monte Carlo Methods for Spatial Extremes

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What is our Goal?

Our goal is to enable efficient Monte Carlo of extreme events in space...

Our focus here is on Max-stable Fields.

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- **Textbook Example:** Given storm surges observed over the last 100 yrs in NYC, what's the maximum height of a storm surge which gets exceeded only about once in 1000 yrs?
- **Answer:** One must *extrapolate*...

Theorem (Fisher-Tippett-Gnedenko)

Suppose X_1, \dots, X_n is an IID sequence and define $Z_n = \max\{X_1, \dots, X_n\}$. **If there exists $\{(a_n, b_n)\}_{n \geq 1}$ deterministic numbers such that**

$$Z_n \stackrel{D}{\approx} b_n M + a_n,$$

then M must be a max-stable distribution.

Max-stable Distributions

- A max-stable r.v. M is characterized by the fact that if M_1, M_2, \dots, M_n are i.i.d. copies of M then

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- We also have that

$$P(M \leq x) = \exp\left(- (1 + \gamma x)^{-1/\gamma}\right) \quad 1 + \gamma x > 0.$$

$$P(M \leq x) = \exp(-\exp(-x)); \quad \gamma = 0 \text{ (the Gumbel case).}$$

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- In practice $Z_m = \max\{X_{(m-1)n+1}, \dots, X_{mn}\} \stackrel{D}{=} a + bM_m$, apply MLE to estimate a, b, γ & ready to extrapolate...
- **But in many cases it is important to account for spatial dependence...**

What is a Catastrophe Bond?

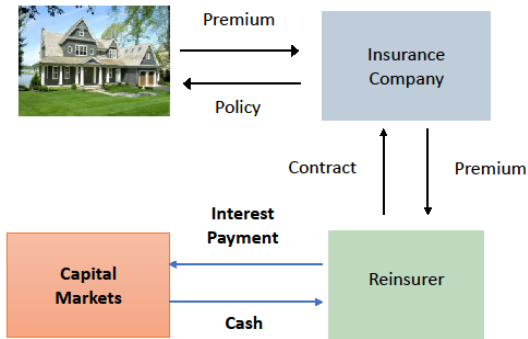
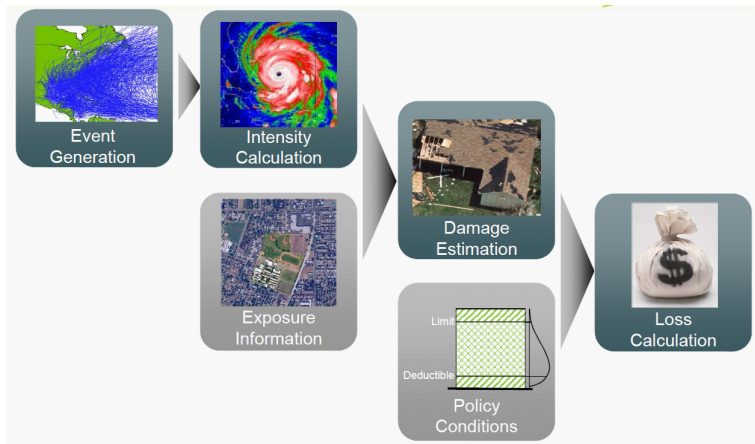


Diagram Illustrating Catastrophe Bonds Risk Calculation



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- Motivated by high insurance costs after Hurricane Sandy in 10/2012.
- The parametric trigger is based on weighted average of maximum water levels in several locations.



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- **Definition:** $M(\cdot)$ is a max-stable field if

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- How to construct max-stable fields?

Characterizations of Max-stable Fields

- A large class of max-stable fields can be represented as:

$$M(t) = \sup_{n \geq 1} \{-\log(A_n) + X_n(t)\},$$

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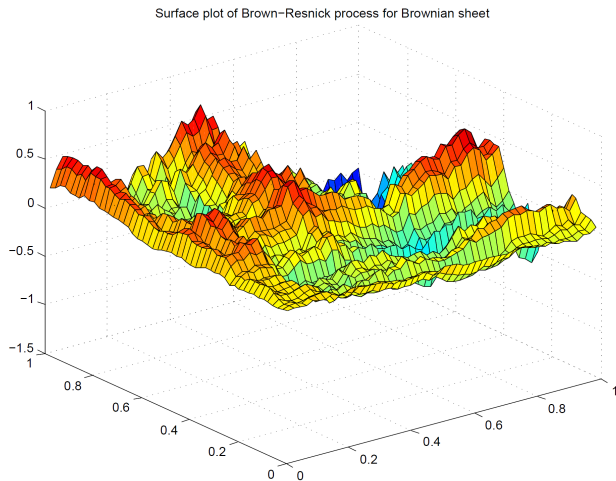
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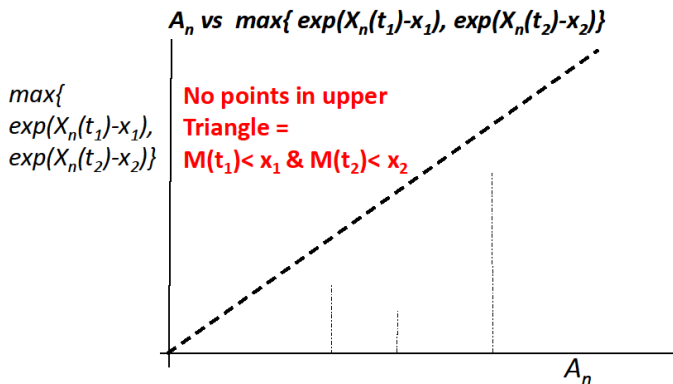
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- Brown-Resnick, de Haan, Smith, Schlather, Kabluchko,...

This is How a Max-Stable Field Looks Like



Computing Joint CDFs

$$P\left(e^{M(t_1)} \leq e^{x_1}, e^{M(t_2)} \leq e^{x_2}\right) = P(\text{Poisson r.v.} = 0) \\ = \exp\left(-E \max\{\exp(X_n(t_1) - x_1), \exp(X_n(t_2) - x_2)\}\right)$$



Max-Stable Fields: Computational Challenges

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- Joint densities for $M(t_1), \dots, M(t_d)$ quickly become intractable ($d = 10$ contains more than 10^5 terms).
- Likelihood methods applicable in low dimensions only.
- In the end we want to efficiently evaluate quantities such as

$$P\left(\int_T w(t) M(t) dt > b\right), \text{ <-CAT Bond Example}$$

$$f_{M(t_1), \dots, M(t_k)}(x_1, \dots, x_k),$$

$$f_{M(t_1), \dots, M(t_k) | M(s_1), \dots, M(s_d)}(x_1, \dots, x_k \mid z_1, \dots, z_d).$$

Theorem 1 (B., Dieker, Liu, Mikosch '16): Algorithm for sampling $M(t_1), \dots, M(t_d)$ with virtually the same asymptotic complexity as sampling $X_1(t_1), \dots, X_1(t_d)$ as $d \rightarrow \infty$.

In other words, $M(t_1), \dots, M(t_d)$ is basically as "easy" as $X_1(t_1), \dots, X_1(t_d)$...

- **Theorem 2** (B. and Liu '16): Construction of a finite variance $W(y_1, \dots, y_d)$ such that

$$f_{M(t_1), \dots, M(t_d)}(y_1, \dots, y_d) = E(W(y_1, \dots, y_d)).$$

The estimator takes $O(\varepsilon^{-2} \log^2(1/\varepsilon))$ samples to achieve ε error.

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- **Theorem 3** (B. and Liu '16): Construction of $W(y_1, \dots, y_k, z_1, \dots, z_d)$ such that

$$\begin{aligned} & f_{M(t_1), \dots, M(t_k) | M(s_1), \dots, M(s_d)}(y_1, \dots, y_k \mid z_1, \dots, z_d) \\ = & E(W(y_1, \dots, y_k, z_1, \dots, z_d)), \end{aligned}$$

similar complexity as Theorem 2.

A Quick Review of Current Methodology

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- Summary of computational complexity (BDML = Our method):

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$$\text{DEO} = \text{BDML} \quad \times d.$$

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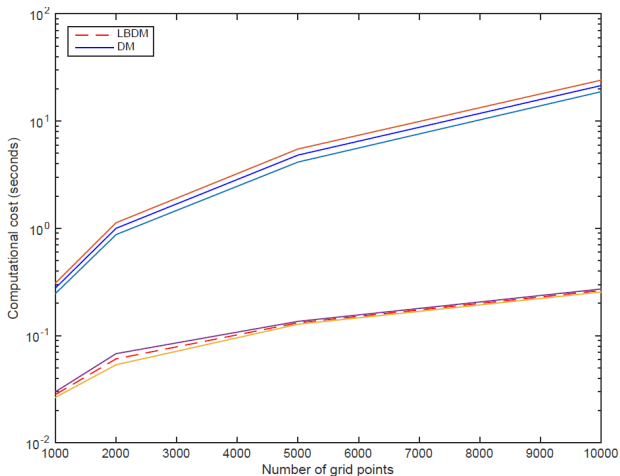
$$\text{Dieker \& Mikosch} = \text{BDML} \quad \times d \times \log(d).$$

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- For example if $X_n(\cdot)$ is Brownian motion our method takes $O(d)$ complexity to sample $M(t_1), \dots, M(t_d)$. Both DM and DEO take at least $O(d^2)$ complexity.

Log-log plot: Grid points vs time in seconds

RED = Our Method vs BLUE = Alternative method.



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- ② N_A such that for $n \geq N_A$:

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- Note that for $m \geq \max(N_A, N_X)$

$$\max_{n \geq m} \{X_n(t_i) - \log(A_n)\} \leq -\frac{\log(m+1)}{2} + \log(2).$$

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- Need to detect when

$$-\log(m+1)/2 + \log(2) \leq \min_{i=1}^d X_1(t_i) - \log(A_1).$$

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- So detection of N_X and N_A should take $O(1)$ time as $d \rightarrow \infty$.

The Milestone / Record Breaking Events Technique

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- Let us write $X_n = \{X_n(t_i)\}_{i=1}^d$ so $\|X_n\|_\infty = \max_{i=1}^d |X_n(t_i)|$.
- Let $\tau_0 = n_0 - 1$ (n_0 chosen later) and let

$$\begin{aligned}\tau_{k+1} &= \inf\{n > \tau_k : \|X_n\|_\infty > \frac{1}{2} \log(n+1)\}, \\ N_X &= \sup\{\tau_k : \tau_k < \infty\}.\end{aligned}$$

Can we sample Bernoulli with $P(\tau_1 < \infty)$? Can we simulate $X_1(\cdot), \dots, X_{\tau_1}(\cdot)$ given $\tau_1 < \infty$?

Borrow from Rare Event Simulation Intuition

- Say n_0 is large: How does the rare event

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$$\begin{aligned} P(\tau_1 = n | \tau_1 < \infty) &= \frac{P(\|X_n\|_{\infty} > \frac{1}{2} \log(n+1), \tau_1 > n-1)}{P(\tau_1 < \infty)} \\ &\approx \frac{P(\|X_n\|_{\infty} > \frac{1}{2} \log(n+1))}{P(\tau_1 < \infty)} \approx \frac{\sum_{i=1}^d P(|X_n(t_i)| > \frac{1}{2} \log(n+1))}{P(\tau_1 < \infty)} \end{aligned}$$

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- This suggests a natural importance sampling strategy...

Will the First Record Breaking Event Occur?

- 1 Sample K so that for $K \geq n_0$

$$Q(K = n) = \frac{\sum_{i=1}^d P(|X_n(t_i)| > \frac{1}{2} \log(n+1))}{\sum_{k=n_0}^{\infty} \sum_{i=1}^d P(|X_k(t_i)| > \frac{1}{2} \log(k+1))}.$$

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- 2 Define $h(n) = P(\tau_1 = n) / Q(K = n)$ then

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- 3 **If $h(k) \leq 1$ then $I\{\tau_1 < \infty\}$ is Bernoulli($h(K)$) with K sampled under Q .**

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- 2 **Sample a Bernoulli with parameter:**

$$\frac{P \left(\|X_n\|_{\infty} > \frac{1}{2} \log(n+1) \right)}{\sum_{i=1}^d P \left(|X_n(t_i)| > \frac{1}{2} \log(n+1) \right)}.$$

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- 2 Given $J = j$, sample $X_n = \{X_n(t_i)\}_{i=1}^d$

$$\begin{aligned} & Q(X_n(t_i) \in dx_i, \dots, X_n(t_d) \in dx_d \mid J = j) \\ = & P\left(X_n(t_i) \in dx_i, \dots, X_n(t_d) \in dx_d \mid |X_n(t_j)| > \frac{1}{2} \log(n+1)\right) \\ = & \frac{P(X_n(t_i) \in dx_i, \dots, X_n(t_d) \in dx_d) \cdot I(|x_n(t_j)| > \frac{1}{2} \log(n+1))}{P(|X_n(t_j)| > \frac{1}{2} \log(n+1))}. \end{aligned}$$

Computing the Likelihood Ratio

- Likelihood of X_n under Q

$$\begin{aligned} Q(X_n) &= \sum_j Q(X_n | J = j) Q(J = j) \\ &= \sum_j P(X_n) \frac{I(|x_n(t_j)| > \frac{1}{2} \log(n+1))}{P(|X_n(t_j)| > \frac{1}{2} \log(n+1))} Q(J = j) \\ &= P(X_n) \sum_j \left(\frac{I(|x_n(t_j)| > \frac{1}{2} \log(n+1))}{P(|X_n(t_j)| > \frac{1}{2} \log(n+1))} \right. \\ &\quad \left. \times \frac{P(|X_n(t_j)| > \frac{1}{2} \log(n+1))}{\sum_{i=1}^d P(|X_n(t_i)| > \frac{1}{2} \log(n+1))} \right) \\ &= P(X_n) \frac{\sum_j I(|x_n(t_j)| > \frac{1}{2} \log(n+1))}{\sum_{i=1}^d P(|X_n(t_i)| > \frac{1}{2} \log(n+1))}. \end{aligned}$$

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$$\frac{dQ}{dP}(X_n) = \frac{\sum_{j=1}^d I(|X_n(t_j)| > \log(n+1)/2)}{\sum_{i=1}^d P(|X_n(t_i)| > \log(n+1)/2)}.$$

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- We conclude

$$\begin{aligned} & \frac{dP\left(X_n \mid \|X_n\|_\infty > \frac{\log(n+1)}{2}\right)}{dQ} \\ &= \frac{I\left(\|X_n\|_\infty > \frac{\log(n+1)}{2}\right)}{P\left(\|X_n\|_\infty > \frac{\log(n+1)}{2}\right)} \frac{dP}{dQ} \leq \frac{\sum_{i=1}^d P\left(|X_n(t_i)| > \frac{\log(n+1)}{2}\right)}{P\left(\|X_n\|_\infty > \frac{\log(n+1)}{2}\right)}. \end{aligned}$$

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- By general acceptance / rejection theory we have:

$$\text{Probability of accepting} = \frac{P\left(\|X_n\|_\infty > \log(n+1)/2\right)}{\sum_{i=1}^d P\left(|X_n(t_i)| > \log(n+1)/2\right)}.$$

Summary

- We sampled $B = \text{Bernoulli}(h(n)) = I(\tau_1 < \infty)$ with $h(n)$:

$$\begin{aligned} h(n) &= \sum_{k=n_0}^{\infty} \sum_{i=1}^d P\left(|X_k(t_i)| > \frac{1}{2} \log(k+1)\right) \\ &\times P\left(\|X_k\|_{\infty} \leq \frac{1}{2} \log(1+k) \quad \forall n_0 \leq k < n\right) \\ &\times \frac{P\left(\|X_n\|_{\infty} > \frac{1}{2} \log(n+1)\right)}{\sum_{i=1}^d P\left(|X_n(t_i)| > \frac{1}{2} \log(n+1)\right)} < 1. \end{aligned}$$

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- Also sampled X_n given $\|X_n\|_{\infty} > \frac{1}{2} \log(n+1)$ by acceptance rejection:

$$\text{Probability of accepting} = \frac{P\left(\|X_n\|_{\infty} > \log(n+1)/2\right)}{\sum_{i=1}^d P\left(|X_n(t_i)| > \log(n+1)/2\right)}.$$

Exact Sampling Property

- **Also we actually obtain:**

$$\mathcal{L}aw_Q (X_1, \dots, X_K, K | B = 1) = \mathcal{L}aw_P (X_1, \dots, X_{\tau_1}, \tau_1 | \tau_1 < \infty).$$

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- Let's check this identity:

$$\begin{aligned} & Q(X_1 \in dx_1, \dots, X_n \in dx, K = n, B = 1) \\ &= Q(K = n) \sum_{k=n_0}^{\infty} \sum_{i=1}^d P\left(|X_k(t_i)| > \frac{1}{2} \log(k+1)\right) \\ & \quad \times P(X_{n_0} \in dx, \dots, X_{n-1} \in dx_{n-1} | \tau_1 > n-1) \\ & \quad \times P\left(X_n \in dx \mid \|X_n\|_{\infty} > \frac{\log(n+1)}{2}\right) \\ &= P(\tau_1 = n) P(X_1 \in dx_1, \dots, X_n \in dx \mid \tau_1 = n) \\ &= P(X_1 \in dx_1, \dots, X_n \in dx, \tau_1 = n, \tau_1 < \infty). \end{aligned}$$

How to Continue? What Drives the Complexity?

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- Total complexity turns out to be driven by n_0 such that

$$\sum_{k=n_0}^{\infty} \sum_{i=1}^d P\left(|X_k(t_i)| > \frac{1}{2} \log(k+1)\right) < 1$$
$$\implies n_0 = \exp\left(c\sqrt{\log(d)}\right) = O(d^\varepsilon) \text{ for any } \varepsilon > 0.$$

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- In this case it suffices to sample A_n jointly with

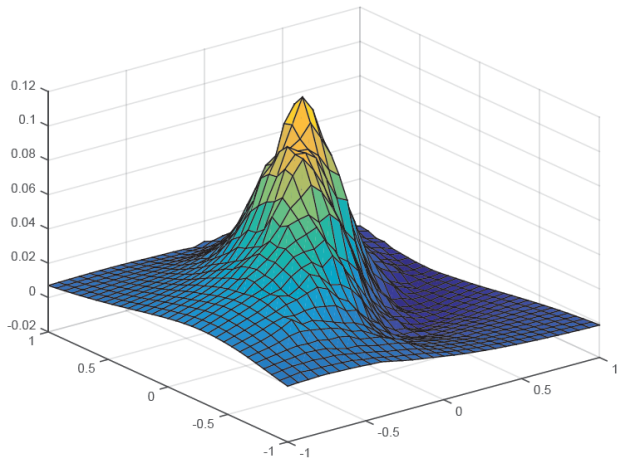
$$\max_{m \geq n} \{A_m - m/2\}$$

rare event simulation techniques can be applied (see B. & Wallwater (2014)).

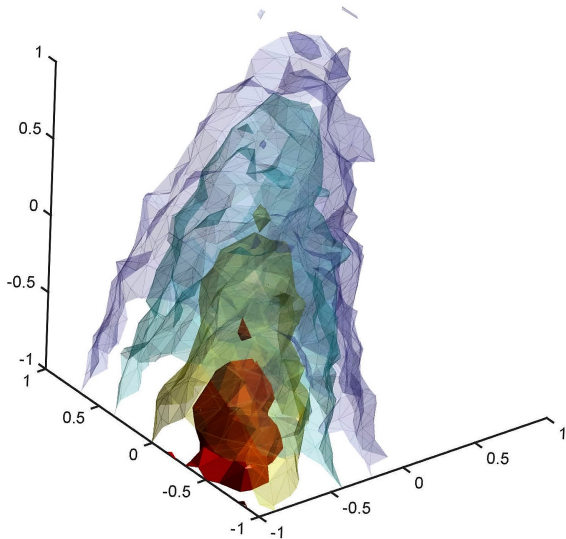
Want to design a finite variance estimator $W(y_1, \dots, y_d)$ so that

$$E(W(y_1, \dots, y_d)) = f_M(y_1, \dots, y_d).$$

An Illustration of the Density Pictures



Some Pictures: 3-d Density



Some Malliavin Calculus

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- So, formally

$$\begin{aligned}\Delta u(x) &= \int f(y) \Delta G(x-y) dy = f(x) \\ \Delta G(x-y) dy &= \delta(x-y) dy \\ f_M(x_1, \dots, x_d) &= E(\Delta G(x-M)).\end{aligned}$$

Applying Malliavin Thalmaier Formula

- For $d \geq 3$ we have that

$$\Delta G(x - y) = \sum_{i=1}^d \frac{\partial^2 G(x)}{\partial x_i^2} (x - y),$$

$$G_i(x) = \frac{\partial G(x)}{\partial x_i} = \kappa_d \frac{x_i}{\|x\|_2^d}, \quad G(x) = \kappa'_d \frac{1}{\|x\|_2^{d-2}}$$

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- Higher order derivatives of G implies higher variability...
- **Two ways to fix this: Integration by parts & Randomized Multilevel Monte Carlo.**

Improving Variance: Integration by Parts for Finite Maxima

- We claim

$$\frac{\partial G_i(x - M_n)}{\partial x_i} = -\frac{\partial G_i(x - M_n)}{\partial M_n(t_i)} = -\sum_{k=1}^n \frac{\partial G_i(x - M_n)}{\partial X_k(t_i)}.$$

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- Let's check second equality:

$$\begin{aligned} M_n(t_i) &= \max_{1 \leq k \leq n} \{X_k(t_i) - a_k\}. \\ \sum_{k=1}^n \frac{\partial M_n(t_i)}{\partial X_k(t_i)} &= \sum_{k=1}^n I(M_n(t_i) = X_k(t_i) - a_k) = 1. \\ \frac{\partial G_i(x - M_n)}{\partial X_k(t_i)} &= \frac{\partial G_i(x - M_n)}{\partial M_n(t_i)} \frac{\partial M_n(t_i)}{\partial X_k(t_i)} \\ \sum_{k=1}^n \frac{\partial G_i(x - M_n)}{\partial X_k(t_i)} &= \frac{\partial G_i(x - M_n)}{\partial M_n(t_i)}. \end{aligned}$$

Improving Variance: Integration by Parts for Finite Maxima

- Integration by parts yields (with $\Sigma = \text{cov}(X_k)$)

$$E \left(\frac{\partial G_i(x - M_n)}{\partial X_k(t_j)} \right) = -E \left(G_i(x - M_n) \cdot e_i^T \Sigma^{-1} X_k \right)$$

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- Therefore

$$\begin{aligned} E \left(\frac{\partial G_i(x - M_n)}{\partial x_i} \right) &= - \sum_{k=1}^n E \left(\frac{\partial G_i(x - M_n)}{\partial X_k(t_j)} \right) \\ &= E \left(G_i(x - M_n) \cdot e_i^T \Sigma^{-1} \sum_{k=1}^n X_k \right) \\ f_{M_n}(x_1, \dots, x_d) &= E \left(\sum_{k=1}^n \sum_{i=1}^d G_i(x - M_n) e_i^T \Sigma^{-1} X_k \right). \end{aligned}$$

Improving Variance: Infinite Horizon Maxima

- Let \mathcal{F}_N be the information generated by the exact sampling procedure so that

$$M_N = M,$$

then we have that for $m \geq 1$

$$E(X_{N+m} | \mathcal{F}_N) = 0,$$

because given $n > N$, we have that $X_n(t_i)$ has a symmetric distribution.

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- Thus

$$\begin{aligned} \lim_{n \rightarrow \infty} f_{M_n}(x_1, \dots, x_d) &= f_M(x_1, \dots, x_d) \\ &= E \left(\sum_{k=1}^N \sum_{i=1}^d G_i(x - M) e_i^T \Sigma^{-1} X_k \right). \end{aligned}$$

Continue Integrating by Parts

- The estimator

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- One can continue obtaining

quadratic weight \Rightarrow finite variance $d \leq 3$

Cubic weight \Rightarrow finite variance $d \leq 5$

...

Applying Multilevel Monte Carlo

- Out starting point is estimator

$$W(x) = \sum_{k=1}^N \sum_{i=1}^d G_i(x - M) e_i^T \Sigma^{-1} X_k.$$

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- Randomized Multilevel Monte Carlo, introducing the differences

$$\begin{aligned} \Delta_n &= G_i^{n+1}(x - M) - G_i^n(x - M); \\ G_i^n(x - M) &= \kappa_d \frac{x_i - M(t_i)}{\|x - M\|_2^d + \|x - M\|_2 / \log(n+1)}. \end{aligned}$$

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- First asymptotically optimal exact simulation algorithms for max-stable fields.
- Ideas based on record-breaking events & rare-event simulation.
- Malliavin calculus ideas for first efficient density estimators for max-stable fields.