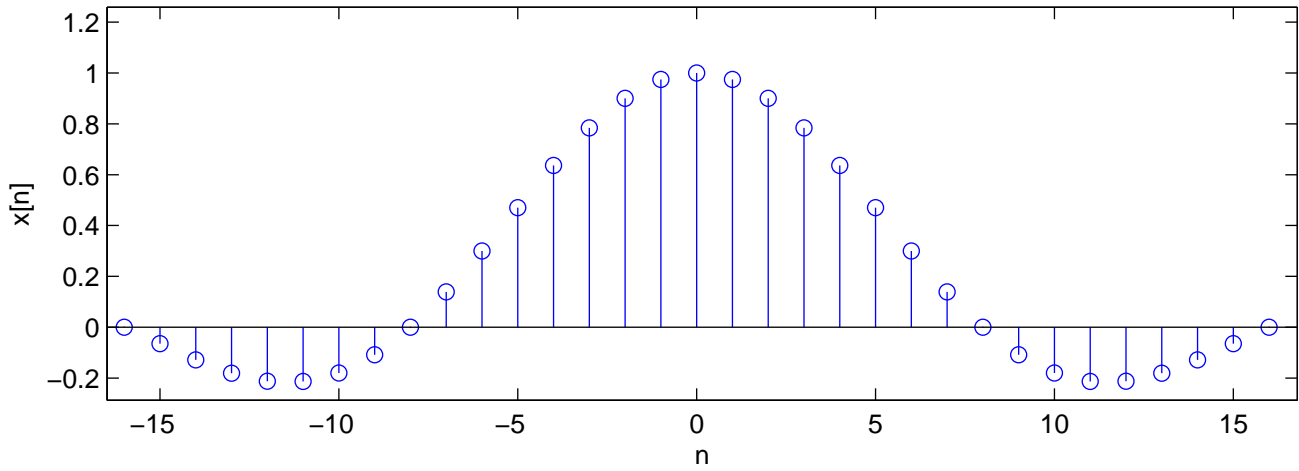


Part (d): $x[n]$, input to the half-delay system



$y[n]$, the output of the half-delay system

