

## <span id="page-0-0"></span>Deep Learning in Asset Pricing

### Luyang Chen  $\frac{1}{8}$  Markus Pelger  $\frac{1}{8}$  Jason Zhu  $\frac{1}{8}$

† Institute for Computational & Mathematical Engineering, Stanford University ‡Department of Management Science & Engineering, Stanford University §Advanced Financial Technologies Laboratory, Stanford

May 28, 2019



# <span id="page-1-0"></span>Hype: Machine Learning in Finance



- Portfolio Management
- Algorithmic Trading
- Fraud Detection
- $\bullet$  Etc  $\ldots$



# Motivation: Asset Pricing

### The Challenge of Asset Pricing

- One of the most important questions in finance is: Why are asset prices different for different assets?
- No-Arbitrage Pricing Theory: Stochastic discount factor (SDF) explains differences in risk and asset prices.
- Fundamental Question: What is the SDF?
- Challenges:
	- SDF should depend on all available economic information
	- Functional form of SDF is unknown and likely conplex
	- SDF needs to capture time-variation in economic conditions
	- Risk premium in stock returns has a low signal-to-noise ratio



# This paper

### Goals of this paper:

General non-linear asset pricing model and optimal portfolio design

 $\Rightarrow$  Deep-neural networks applied to all U.S. equity data and large sets of macroeconomic and firm-specific information.

### Why is it important?

- 1 Stochastic discount factor (SDF) generates tradeable portfolio with highest risk-adjusted return (Sharpe-ratio=expected excess return/standard deviation)
- **2** Arbitrage opportunities
	- Find underpriced assets and earn "alpha"
- **8** Risk management
	- Understand which information and how it drives the SDF
	- Manage risk exposure of financial assets



# Contribution of this paper

- This Paper: Estimate the SDF with deep neural networks
- Crucial innovation: Include no-arbitrage condition in the neural network algorithm and combine four neural networks in a novel way
- Key elements of estimator:
	- **1** Non-linearity: Feed-forward network captures non-linearities
	- **2** Time-variation: Recurrent (LSTM) network finds a small set of economic state processes
	- **3** Pricing all assets: Generative adversarial network identifies the states and portfolios with most unexplained pricing information
	- 4 Dimension reduction: Regularization through no-arbitrage condition
	- **5** Signal-to-noise ratio: No-arbitrage conditions improve the risk premium signal
- $\Rightarrow$  General model that includes all existing models as a special case



# Contribution of this paper

### Empirical Contributions

- Empirically outperforms all benchmark models.
- Optimal portfolio has out-of-sample annual Sharpe ratio of 2.6.
- Non-linearities and interaction between firm information matters.
- Most relevant firm characteristics are price trends, profitability, and capital structure variables.



# Literature (Partial List)

- Deep-learning for predicting asset prices
	- Feng, Polson and Xu (2019)
	- Gu, Kelly and Xiu (2018)
	- Feng, Polson and Xu (2018)
	- Messmer (2017)
	- $\Rightarrow$  Predicting future asset returns with feed forward network
		- Gu, Kelly and Xiu (2019)
		- Heaton, Polson and Witte (2017)
	- $\Rightarrow$  Fitting asset returns with an autoencoder
- Linear or kernel methods for asset pricing of large data sets
	- Lettau and Pelger (2018): Risk-premium PCA
	- Feng, Giglio and Xu (2017): Risk-premium lasso
	- Freyberger, Neuhierl and Weber (2017): Group lasso
	- Kelly, Pruitt and Su (2018): Instrumented PCA



# <span id="page-7-0"></span>No-Arbitrage Pricing Theory

• A stochastic discount factor<sup>1</sup> is a stochastic process  $\{M_t\}$ , such that for any asset *i* with payoff  $x_{i,t+1}$  at time  $t + 1$ , the price of that asset at time  $t$  is

$$
P_{i,t} = \mathbb{E}_t[M_{t+1}x_{i,t+1}].
$$

• Let  $R_{i,t+1}^e = R_{i,t+1} - R_f$ . Fundamental no-arbitrage condition:

$$
\mathbb{E}_t[M_{t+1}R_{i,t+1}^e]=0.
$$

• It implies infinitely many unconditional moments:

$$
\mathbb{E}[M_{t+1}R_{i,t+1}^e\hat{l}_{i,t}]=0
$$

for any  $\mathcal{F}_t$ -measurable variable  $\hat{l}_{i,t}.$ 

<sup>1</sup>Examples of SDF are included in the appendix [\[39\]](#page-38-0)-[\[40\]](#page-39-0).



# Model

• Without loss of generality, SDF is the projection on the return space<sup>2</sup>

$$
M_{t+1} = 1 - \sum_{i=1}^{N} w_{i,t} R_{i,t+1}^{e}.
$$

- $\Rightarrow$  The optimal portfolio  $\mathit{F}_{t+1} = \sum_{i=1}^{N} w_{i,t} \mathit{R}^e_{i,t+1}$  has the highest conditional Sharpe ratio.
	- The portfolio weights  $w_{i,t}$  are a general function of macro-economic information  $I_t$  and firm-specific characteristics  $I_{i,t}$ :

$$
w_{i,t}=w(I_t,I_{i,t}).
$$

- $\Rightarrow$  Need non-linear estimator with many explanatory variables!
- $\Rightarrow$  We use neural networks to estimate  $w_{i,t}.$

<sup>&</sup>lt;sup>2</sup>See e.g. [Back \[2010\]](#page-54-0). The SDF is an affine transformation of the tangency portfolio.



## Equivalent Factor Model Representation

• No-arbitrage condition is equivalent to

$$
\mathbb{E}_{t}[R_{i,t+1}^{e}] = \frac{\text{cov}_{t}(R_{i,t+1}^{e}, F_{t+1})}{\text{var}_{t}(F_{t+1})} \cdot \mathbb{E}_{t}[F_{t+1}] \n= \beta_{i,t} \mathbb{E}_{t}[F_{t+1}]
$$

with factor  $F_t = 1 - M_t$ .

 $\Rightarrow$  Without loss of generality we have a factor representation

$$
R_{t+1}^e = \beta_t F_{t+1} + \epsilon_{t+1}.
$$

## **Estimation**

- Estimate SDF portfolio weights  $w(\cdot)$  to minimize the no-arbitrage moment conditions.
- For a set of conditioning variables  $\hat{I}_{i,t} = \hat{g}(I_t, I_{i,t})$ , the corresponding loss function is

$$
L(w|\hat{g}, l_t, l_{i,t}) = \frac{1}{N} \sum_{i=1}^N \frac{T_i}{T} \left\| \frac{1}{T_i} \sum_{t \in T_i} M_{t+1} R_{i,t+1}^e \hat{g}(l_t, l_{i,t}) \right\|^2.
$$

- How can we choose the conditioning variables  $\hat{I}_{i,t}$  as general functions of the macroeconomic and firm-specific information?
- $\Rightarrow$  Generative Adversarial Network (GAN) $^3$  chooses  $\hat{g}!$



<sup>&</sup>lt;sup>3</sup>A brief introduction of GAN by [Goodfellow et al. \[2014\]](#page-54-1) is included in the appendix [\[41\]](#page-40-0).



# Generative Adversarial Network (GAN)

#### Formulate GMM as Zero-Sum Game

- Two networks play a zero-sum game:
	- **1 SDF Network** (w) creates the SDF  $M_{t+1}$ .
	- $\textbf{\textcolor{red}{\bullet}}$  Conditional Network  $(\hat{g})$  generates conditioning variables  $\hat{l}_{i,t}.$
- Alternatively update the two networks<sup>a</sup>:
	- $\bf D$  For a given set of conditioning variables  $\hat{I}_{i,t}$ , <code>SDF</code> network is updated to minimize the loss.
	- **2** For a given estimation of the SDF, **Conditional Network** finds  $\hat{l_{i,t}}$  with the largest loss (most mis-pricing).
- Intuition: find the economic states and assets with the most pricing information.

<sup>a</sup>Model calibration details are included in the appendix [\[46\]](#page-45-0) and [\[47\]](#page-46-0).



# Neural Network Building Blocks

SDF Network and Conditional Network are independent, but share a similar structure.

- $\bullet$  Feedforward network<sup>4</sup> captures non-linearities.
- $\bullet$  Recurrent network with LSTM cells<sup>5</sup> transforms all macroeconomic time-series into a low dimensional vector of stationary state variables.
	- Time-series data is often non-stationary.
	- Business cycles can affect pricing.
	- Redundant information.

<sup>4</sup>The definition of feedforward network is included in the appendix [\[42\]](#page-41-0). <sup>5</sup>The definition of LSTM cells is included in the appendix [\[44\]](#page-43-0) and [\[45\]](#page-44-0).



## Model Architecture



#### Figure: Model Architecture



# <span id="page-14-0"></span>Simulation Results - Setup

Excess returns follow a no-arbitrage model with SDF factor F

$$
R_{i,t+1}^e = \beta_{i,t} F_{t+1} + \epsilon_{i,t+1}.
$$

- The SDF factor follows  $F_t \stackrel{i.i.d.}{\sim} \mathcal{N}(\mu_F, \sigma_F^2)$  with  $\sigma_F^2 = 0.1$  and  $SR_F = 1$ .
- The idiosyncratic component  $\epsilon_{i,t} \stackrel{i.i.d.}{\sim} \mathcal{N}(0, \sigma_e^2)$  with  $\sigma_e^2 = 1$ .
- $N = 500$  and  $T = 600$ . Training/validation/test split is 250,100,250.
- One characteristic and one macroeconomic state process:

$$
\beta_{i,t} = C_{i,t}^{(1)} \cdot b(h_t), \qquad h_t = \sin(\pi * t/24) + \epsilon_t^h.
$$

$$
b(h) = \begin{cases} 1 & \text{if } h > 0 \\ -1 & \text{otherwise.} \end{cases}
$$

We observe only the macroeconomic time-series  $Z_t = \mu_M t + h_t$ . All innovations are independent and normally distributed:  $\; C_{i,t}^{(1)} \stackrel{i.i.d.}{\sim} \mathcal{N}(0,1)$ and  $\epsilon_t^{h}\stackrel{i.i.d.}{\sim}\mathcal{N}(0,0.25)$ . <sup>6</sup>

 $6$ More simulation results are included in the appendix  $[48]$ - $[50]$ .



### Simulation Results - Observed Macroeconomic Variable







### Simulation Results - Fitted Macroeconomic State

#### True Hidden Macroeconomic State



#### Fitted Macroeconomic State by LSTM





## Simulation Results - Evaluation

#### Table: Performance of Different SDF Models





# <span id="page-18-0"></span>Empirical Results - Data

- 50 years of monthly observations: 01/1967 12/2016.
- Monthly stock returns for all U.S. securities from CRSP (around 31,000 stocks) Use only stocks with with all firm characteristics (around 10,000 stocks)
- 46 firm-specific characteristics for each stock and every month (usual suspects)  $\Rightarrow$   $I_{i,t}$ normalized to cross-sectional quantiles
- 178 macroeconomic variables (124 from FRED, 46 cross-sectional median time-series for characteristics, 8 from Goyal-Welch)  $\Rightarrow$   $I_t$
- T-bill rates from Kenneth-French website
- Training/validation/test split is 20y/5y/25y



## Empirical Results - Benchmark Models

**1 LS & EN - Linear factor models:** The optimal portfolio weights  $w_t = I_t \theta$  is linear in characteristics. We minimize loss function

$$
\frac{1}{2} \Big\| \frac{1}{\mathcal{T}} \tilde{\mathcal{R}}^{\mathcal{K}\top} 1 - \frac{1}{\mathcal{T}} \tilde{\mathcal{R}}^{\mathcal{K}\top} \tilde{\mathcal{R}}^{\mathcal{K}} \theta \Big\|_{2}^{2} + \lambda_1 \|\theta\|_1 + \frac{1}{2} \lambda_2 \|\theta\|_2^2.
$$

 $\tilde{R}^K_{t+1} = I_t^\top R^e_{t+1}$  are  $K$  portfolios weighted by characteristics  $I_t$ .

- **2** FFN Deep learning return forecasting [\(Gu et al. \[2018\]](#page-54-2)):
	- Predict conditional expected returns  $\mathbb{E}_t[R_{i,t+1}]$
	- Empirical loss function for prediction

$$
\frac{1}{NT}\sum_{i=1}^N\sum_{t=1}^T (R_{i,t+1} - g(l_t, l_{i,t}))^2
$$

• Use only simple feedforward network for forecasting



# Empirical Results - Evaluation

Objects of Interest:

- The SDF factor  $F_t$
- The risk loadings  $\beta_t$ <sup>7</sup>
- The unexplained residual  $\hat{e}_t = (I_N - \beta_{t-1}(\beta_{t-1}^\top \beta_{t-1})^{-1} \beta_{t-1}^\top) R_t^e$

Performance Measure:

- Sharpe ratio of SDF factor:  $SR = \frac{\hat{\mathbb{E}}[F_t]}{\sqrt{\hat{\mathbb{E}}[F_t]}}$
- $Var(F_t)$ • Explained variation:  $EV = 1 \left(\frac{1}{T}\sum_{t=1}^{T}\frac{1}{N_t}\sum_{i=1}^{N_t}(\hat{\epsilon}_{i,t+1})^2\right)$  $\left(\frac{1}{T}\sum_{t=1}^{T}\frac{1}{N_t}\sum_{i=1}^{N_t}(R_{i,t+1}^e)^2\right)$

• cross-sectional mean 
$$
R^2
$$
:  
\n
$$
\text{XS-}R^2 = 1 - \frac{\frac{1}{N} \sum_{i=1}^{N} \frac{T_i}{T} \left(\frac{1}{T_i} \sum_{t \in T_i} \hat{\epsilon}_{i,t+1}\right)^2}{\frac{1}{N} \sum_{i=1}^{N} \frac{T_i}{T} \left(\frac{1}{T_i} \sum_{t \in T_i} \hat{R}_{i,t+1}\right)^2}
$$

<sup>7</sup>We estimate loadings by fitting a feedforward network to predict  $R_tF_t$ .



## Empirical Results - Cross Section of Individual Stock Returns

#### Table: Performance of Different SDF Models





## Empirical Results - Cross Section of Individual Stock Returns

#### Table: SDF Factor Portfolio Performance<sup>8</sup>



<sup>8</sup>Turnover as a measure of transaction costs is included in the appendix [\[51\]](#page-50-0).



# Performance of Models with Different Macroeconomic Variables





## Empirical Results - SDF Factors and Market Factor



(a) Whole Time Horizon

(b) Test Period

Figure: Correlation between SDF Factors for Different Models

 $\Rightarrow$  GAN SDF factor has a small correlation with the market factor.



## Empirical Results - SDF Factor and Fama-French Factors

#### Table: GAN-SDF Factor and Fama-French 5 Factors



 $\Rightarrow$  Fama-French factors do not span SDF.



## Empirical Results - Size Effect

#### Table: Performance of Different SDF Models with Size Thresholds





## Empirical Results - Predictive Performance



Figure: Cumulative Excess Returns of Decile Sorted Portfolios by GAN

 $\Rightarrow$  Risk loadings predicts future stock returns.



### Empirical Results - Predictive Performance



Figure: Projected Excess Return of Decile Sorted Portfolios<br>May 28, 2019 Deep Learning in Asset Pricing

[Deep Learning in Asset Pricing](#page-0-0) 29 / 55



## Empirical Results - Predictive Performance

#### Table: Time Series Pricing Errors for β-Sorted Portfolios



 $\Rightarrow$  Standard factor models cannot explain cross-sectional returns.



## Empirical Results - Performance on Portfolios

Table: Explained Variation and Pricing Errors for Short-Term Reversal Sorted Portfolios<sup>9</sup>



<sup>9</sup>Results for Momentum sorted portfolios are included in the appendix [\[52\]](#page-51-0).



## Empirical Results - Performance on Portfolios

#### Table: Explained Variation and Pricing Errors for Size Sorted Portfolios<sup>10</sup>



<sup>10</sup>Results for Book-to-Market Ratio sorted portfolios are included in the appendix [\[53\]](#page-52-0).



## Empirical Results - Performance on Portfolios

#### Table: Explained Variation and Pricing Errors for Decile Sorted Portfolios





## Empirical Results - Characteristic Importance



Figure: Characteristic Importance<sup>11</sup> by  $GAN$ 

 $11$ Our sensitivity analysis is similar to [Sirignano et al. \[2016\]](#page-54-3). See the appendix [\[54\]](#page-53-0).



## Empirical Results - Macroeconomic Hidden States





## Empirical Results - SDF Weights



Figure: Weight as a Function of Size and Dividend Yield

 $\Rightarrow$  Size and dividend yield have close to linear effect!



## Empirical Results - SDF Weights





(a) Size and Dividend Yield

(b) Size, Dividend Yield and Short-Term Reversal

Figure: Weight as a Function of Multiple Variables

 $\Rightarrow$  Complex interaction between multiple variables!



# <span id="page-37-0"></span>Conclusion

- Linear models perform well because when considering characteristics in isolation, the models are approximately linear.
- Non-linearities matter for the interaction.
- Most relevant variables are price trends and liquidity.
- Macroeconomic data has a low dimensional factor structure.
- Pricing all individual stocks leads to better pricing models on portfolios.
- SDF structure stable over time.
- Mean-variance efficient portfolio implied by pricing kernel highly profitable in a risk-adjusted sense.



### Appendix - Deep Learning in Asset Pricing SDF Example - CAPM

<span id="page-38-0"></span>In CAPM, there is only one factor  $R^{\mathcal{M},e}=R^{\mathcal{M}}-R^f.$  Find the SDF  $M_{t+1}$ , which has the form of  $M_{t+1} = a + b R_{t+1}^{M,e}$ . With no-arbitrage condition  $\mathbb{E}_t[\mathcal{M}_{t+1} \mathcal{R}_{t+1}^e]=0$ , we have

$$
\frac{a}{b} = -\frac{\mathbb{E}_{t}[(R_{t+1}^{M,e})^{2}]}{\mathbb{E}_{t}[R_{t+1}^{M,e}]}
$$

Notice that the SDF is negatively correlated with the market factor.

[References](#page-54-4)



### Appendix - Deep Learning in Asset Pricing SDF Example - Geometric Brownian Motion

<span id="page-39-0"></span>Assume the stock price follows geometric Brownian Motion

$$
\frac{dS_t}{S_t} = \mu dt + \sigma dW_t
$$

Find the pricing kernel  $\pi_t$ , which has the form of

$$
\frac{d\pi_t}{\pi_t} = adt + bdW_t
$$

• For risk-free rate  $r$ .

$$
\mathbb{E}_t\Big[\frac{\pi_{t+dt}}{\pi_t}(1+rdt)\Big]=1\quad\Rightarrow\quad a=-r.
$$

• For stock return  $\mu dt + \sigma dW_t$ ,

$$
\mathbb{E}_t\Big[\frac{\pi_{t+dt}}{\pi_t}(1+\mu dt+\sigma dW_t)\Big]=1\quad\Rightarrow\quad b=(r-\mu)/\sigma
$$



<span id="page-40-0"></span>Appendix - Deep Learning in Asset Pricing Generative Adversarial Network by [Goodfellow et al. \[2014\]](#page-54-1)



Figure: GAN Structure by [Goodfellow et al. \[2014\]](#page-54-1)

- **1** The generator takes random numbers and returns an image.
- **2** This generated image is fed into the discriminator alongside a stream of images taken from the actual data set.
- **3** The discriminator takes in both real and fake images and returns probabilities, with 1 representing a prediction of authenticity and 0 representing fake.



#### <span id="page-41-0"></span>Appendix - Deep Learning in Asset Pricing Feedforward Network



Figure: Feedforward Network with 3 Hidden Layers

$$
x^{(l)} = \text{ReLU}(W^{(l-1)\top}x^{(l-1)} + w_0^{(l-1)})
$$

$$
y = W^{(L)\top}x^{(L)} + w_0^{(L)}
$$



### Appendix - Deep Learning in Asset Pricing Feedforward Network with Dropout



#### Figure: Feedforward Network with 3 Hidden Layers and Dropout



### <span id="page-43-0"></span>Appendix - Deep Learning in Asset Pricing Long-Short-Term-Memory Cell (LSTM)



Figure: Long-Short-Term-Memory Cell (LSTM)



### Appendix - Deep Learning in Asset Pricing LSTM Cell Structure

<span id="page-44-0"></span>At each step, a new memory cell  $\tilde{c}_t$  is created with current input  $x_t$ and previous hidden state  $h_{t-1}$ 

$$
\tilde{c}_t = \tanh(W_h^{(c)} h_{t-1} + W_x^{(c)} x_t + w_0^{(c)}).
$$

The input and forget gate control the memory cell, while the output gate controls the amount of information stored in the hidden state:

input<sub>t</sub> = 
$$
\sigma(W_h^{(i)} h_{t-1} + W_x^{(i)} x_t + w_0^{(i)})
$$
  
forget<sub>t</sub> =  $\sigma(W_h^{(f)} h_{t-1} + W_x^{(f)} x_t + w_0^{(f)})$   
out<sub>t</sub> =  $\sigma(W_h^{(o)} h_{t-1} + W_x^{(o)} x_t + w_0^{(o)})$ .

The final memory cell and hidden state are given by

$$
c_t = \text{forget}_t \circ c_{t-1} + \text{input}_t \circ \tilde{c}_t
$$
  

$$
h_t = \text{out}_t \circ \text{tanh}(c_t).
$$



#### <span id="page-45-0"></span>Appendix - Deep Learning in Asset Pricing Hyper-Parameter Search

#### Table: Selection of Hyperparameters for GAN



- 1 For each combination of hyperparameters (384 models) we fit the GAN model.
- 2 We select the five best combinations of hyperparameters on the validation data set.

3 For each of the five combinations we fit 9 models with the same hyperparameters but different initialization.

4 We select the ensemble model with the best performance on the validation data set.



#### Appendix - Deep Learning in Asset Pricing Other Implementation Details

- <span id="page-46-0"></span>• For training deep neural networks, the vanilla stochastic gradient descend method has proven to be not an efficient method. A better approach is to use optimization methods that introduce an adaptive learning rate (e.g. Adam).
- Regularization is crucial and prevents the model from over-fitting on the training sample. Although  $l_1/l_2$  regularization might also be used in training other neural networks, Dropout is preferable and generally results in better performances.
- We use ensemble averaging to create a group of models that provide a significantly more robust estimation. Let's denote  $\hat{w}^{(j)}$  to be the optimal portfolio weights given by the  $j<sup>th</sup>$  model. The ensemble model is a weighted average of the outputs from models with the same architecture but different starting values for the optimization and gives more robust estimates:  $\hat{\omega} = \frac{1}{9} \sum_{j=1}^{9} \hat{\omega}^{(j)}$ .



### Appendix - Deep Learning in Asset Pricing Simulation Setup

<span id="page-47-0"></span>• Excess returns follow a no-arbitrage model with SDF factor F

$$
R_{i,t+1}^e = \beta_{i,t} F_{t+1} + \epsilon_{i,t+1}.
$$

- The SDF factor follows  $F_t \stackrel{i.i.d.}{\sim} \mathcal{N}(\mu_F, \sigma_F^2)$  with  $\sigma_F^2 = 0.1$  and  $SR_F = 1$ .
- The risk loadings  $\beta$

$$
\beta_{i,t} = C_{i,t}^{(1)} \cdot C_{i,t}^{(2)} \qquad \text{with} \qquad C_{i,t}^{(1)}, C_{i,t}^{(2)} \stackrel{i.i.d.}{\sim} \mathcal{N}(0,1).
$$

- The idiosyncratic component  $\epsilon_{i,t} \stackrel{i.i.d.}{\sim} \mathcal{N}(0, \sigma_e^2)$  with  $\sigma_e^2 = 1$ .
- $N = 500$  and  $T = 600$ . Training/validation/test split is 250,100,250.



#### Appendix - Deep Learning in Asset Pricing Simulation Results

### Loadings  $\beta$  with 2 characteristics





### Appendix - Deep Learning in Asset Pricing Simulation Results

#### Table: Performance of Different SDF Models

<span id="page-49-0"></span>



### Appendix - Deep Learning in Asset Pricing **Turnover**

#### Table: Turnover by Models

<span id="page-50-0"></span>



#### Appendix - Deep Learning in Asset Pricing Performance on Portfolios

<span id="page-51-0"></span>Table: Explained Variation and Pricing Errors for Momentum Sorted Portfolios





#### Appendix - Deep Learning in Asset Pricing Performance on Portfolios

<span id="page-52-0"></span>Table: Explained Variation and Pricing Errors for Book-to-Market Ratio Sorted Portfolios





### Appendix - Deep Learning in Asset Pricing Economic Significance of Variables

<span id="page-53-0"></span>• we define the sensitivity of a particular variable as the average absolute derivative of the weight w with respect to this variable:

Sensitivity
$$
(x_j)
$$
 =  $\frac{1}{C} \sum_{i=1}^{N} \sum_{t=1}^{T} \left| \frac{\partial w(l_t, l_{t,i})}{\partial x_j} \right|$ ,

where C a normalization constant.

• A sensitivity of value z for a given variable means that the weight w will approximately change (in magnitude) by  $z\Delta$  for a small change of ∆ in this variable.



## <span id="page-54-4"></span>References I

<span id="page-54-0"></span>Kerry Back. Asset pricing and portfolio choice theory. Oxford University Press, 2010.

- Luyang Chen, Markus Pelger, and Jason Zhu. Deep learning in asset pricing. Available at SSRN 3350138, 2019.
- <span id="page-54-1"></span>Ian Goodfellow, Jean Pouget-Abadie, Mehdi Mirza, Bing Xu, David Warde-Farley, Sherjil Ozair, Aaron Courville, and Yoshua Bengio. Generative adversarial nets. In Advances in neural information processing systems, pages 2672–2680, 2014.
- <span id="page-54-2"></span>Shihao Gu, Bryan T Kelly, and Dacheng Xiu. Empirical asset pricing via machine learning. Working Paper 25398, National Bureau of Economic Research, 2018.
- <span id="page-54-3"></span>Justin Sirignano, Apaar Sadhwani, and Kay Giesecke. Deep learning for mortgage risk. Working paper, 2016.