

ORIE 6326: Convex Optimization

Operators

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Beating the lower bound

problem: lower bound for subgradient method is **slow!**

Beating the lower bound

problem: lower bound for subgradient method is **slow!**

solution: find a more powerful oracle

Proximal operator

define the **proximal operator** of the function $f : \mathbf{R}^d \rightarrow \mathbf{R}$

$$\mathbf{prox}_f(x) = \underset{z}{\operatorname{argmin}}(f(z) + \frac{1}{2}\|z - x\|_2^2)$$

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- ▶ $\mathbf{prox}_f : \mathbf{R}^d \rightarrow \mathbf{R}^d$
- ▶ **generalized projection:** if $\mathbf{1}_C$ is the indicator of set C ,

$$\mathbf{prox}_{\mathbf{1}_C}(w) = \Pi_C(w)$$

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- ▶ **implicit gradient step:** if $z = \mathbf{prox}_f(x)$

$$\begin{aligned}\partial f(z) + z - x &= 0 \\ z &= x - \partial f(z)\end{aligned}$$

Maps from functions to functions

no consistent notation for map from functions to functions.

for a function $f : \mathbf{R}^d \rightarrow \mathbf{R}$,

- ▶ **prox** maps f to a new function $\mathbf{prox}_f : \mathbf{R}^d \rightarrow \mathbf{R}^d$
 - ▶ $\mathbf{prox}_f(x)$ evaluates this function at the point x
- ▶ ∇ maps f to a new function $\nabla f : \mathbf{R}^d \rightarrow \mathbf{R}^d$
 - ▶ $\nabla f(x)$ evaluates this function at the point x

Let's evaluate some proximal operators!

define the **proximal operator** of the function $f : \mathbf{R}^d \rightarrow \mathbf{R}$

$$\mathbf{prox}_f(x) = \underset{z}{\operatorname{argmin}} \left(f(z) + \frac{1}{2} \|z - x\|_2^2 \right)$$

► $f(x) = 0$

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- ▶ $f(X) = \|X\|_*$

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- ▶ $f(x) = \|x\|_1$ (soft-thresholding on each index)
- ▶ $f(X) = \|X\|_*$ (soft-thresholding on singular values)

Proxable functions

we say a function f is **proxable** if it's easy to evaluate $\mathbf{prox}_f(x)$

all examples from previous slide are proxable

Roadmap

suppose f is smooth, g is non-smooth. solve

$$\text{minimize } f(x) + g(x)$$

using proximal operators together with gradient steps?

- ▶ the proximal operator gives a **fast method** to step towards the minimum of g
- ▶ gradient method works well to step towards minimum of f
- ▶ put it together with gradients to make **fast optimization algorithms**

to do this elegantly, we will need more theory. . .

Outline

Relations

Fixed points

Averaged operators

Cocoercive and coercive operators

Operators and functions

Resolvents and prox

Functions

in much of what follows, we'll need to assume functions are

- ▶ closed: **epi**(f) is a closed set
- ▶ convex: f is convex
- ▶ proper: **dom** f is non-empty

which we abbreviate as CCP

Relations

$(x, \partial f(x))$ and $(x, \mathbf{prox}_f(x))$ define **relations** on \mathbf{R}^n

- ▶ a **relation** R on \mathbf{R}^n is a subset of $\mathbf{R}^n \times \mathbf{R}^n$
- ▶ **dom** $R = \{x : (x, y) \in R\}$
- ▶ let $R(x) = \{y : (x, y) \in R\}$
- ▶ if $R(x)$ is always empty or a singleton, we say R is a function
- ▶ any function $f : \mathbf{R} \rightarrow \mathbf{R}$ is a relation

Relations: examples

- ▶ empty relation: \emptyset
- ▶ full relation: $\mathbf{R}^n \times \mathbf{R}^n$
- ▶ identity: $\{(x, x) : x \in \mathbf{R}^n\}$
- ▶ zero: $\{(x, 0) : x \in \mathbf{R}^n\}$
- ▶ subdifferential: $\{(x, g) : x \in \mathbf{dom} f, g \in \partial f(x)\}$

Operations on relations

if R and S are relations, define

- ▶ composition: $RS = \{(x, z) : (x, y) \in R, (y, z) \in S\}$
- ▶ addition: $R + S = \{(x, y + z) : (x, y) \in R, (x, z) \in S\}$
- ▶ inverses: $R^{-1} = \{(y, x) : (x, y) \in R\}$

use inequality on sets to mean the inequality holds for any element in the set, e.g.,

$$f(y) \geq f(x) + \partial f^T(y - x)$$

Example: fenchel conjugates and the subdifferential

if f is CPP, $(f^*)^* = f^{**} = f$, so

$$\begin{aligned}(u, v) \in (\partial f)^{-1} &\iff (v, u) \in \partial f \\ &\iff u \in \partial f(v) \\ &\iff 0 \in \partial f(v) - u \\ &\iff v \in \operatorname{argmin}_x (f(x) - u^T x) \\ &\iff v \in \operatorname{argmax}_x (u^T x - f(x)) \\ &\iff f(v) + f^*(u) = u^T v \\ &\iff u \in \operatorname{argmax}_y (y^T v - f^*(y)) \\ &\iff 0 \in v - \partial f^*(u) \\ &\iff (u, v) \in \partial f^*\end{aligned}$$

this shows $\partial f^* = \partial f^{-1}$

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- ▶ x is a **zero** of R if $0 \in R(x)$
- ▶ the **zero set** of R is $R^{-1}(0) = \{x : (x, 0) \in R\}$

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x is a zero of ∂f iff x solves minimize $f(x)$

Lipschitz operators

relation F has Lipschitz constant L if for all $(x, u) \in F$ and $(y, v) \in F$,

$$\|u - v\| \leq L\|x - y\|$$

fact: if F is Lipschitz, then F is a function.

proof:

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proof: if $(x, u) \in F$ and $(x, v) \in F$,

$$\|u - v\| \leq L\|x - x\| = 0$$

- ▶ the relation F is **nonexpansive** if $L \leq 1$
- ▶ the relation F is **contractive** if $L < 1$

Fixed points

x is a **fixed point** of F if $x = F(x)$

examples:

- ▶ $F(x) = x$: every point is a fixed point
- ▶ $F(x) = 0$: only 0 is a fixed point

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proof: if x and y are FPs, $\|x - y\| = \|F(x) - F(y)\| < \|x - y\|$
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proof: translation

Fixed point iteration

to find a fixed point of F , try the fixed point iteration

$$x^{(k+1)} = F(x^{(k)})$$

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Q: when does this converge?

Fixed point iteration: contractive

Banach fixed point theorem: if F is a contraction, the iteration

$$x^{(k+1)} = F(x^{(k)})$$

converges to the unique fixed point of F

properties: if L is the Lipschitz constant of F ,

- ▶ distance to fixed point decreases monotonically:

$$\|x^{(k+1)} - x^*\| = \|F(x^{(k)}) - F(x^*)\| \leq L\|x^{(k)} - x^*\|$$

(iteration is **Fejer-monotone**)

- ▶ linear convergence with rate L

Proof

if F is a contraction, $x^{(k+1)} = F(x^{(k)})$ converges to unique fixed point

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if F is a contraction, $x^{(k+1)} = F(x^{(k)})$ converges to unique fixed point

proof: if F has Lipschitz constant $L < 1$,

- ▶ sequence $x^{(k)}$ is Cauchy:

$$\begin{aligned}\|x^{(k+\ell)} - x^{(k)}\| &\leq \|x^{(k+\ell)} - x^{(k+\ell-1)}\| + \dots + \|x^{(k+1)} - x^{(k)}\| \\ &\leq (L^{\ell-1} + \dots + 1)\|x^{(k+1)} - x^{(k)}\| \\ &\leq \frac{1}{1-L}\|x^{(k+1)} - x^{(k)}\| \\ &\leq \frac{L^k}{1-L}\|x^{(1)} - x^{(0)}\|\end{aligned}$$

- ▶ so it converges to a point x^* , which must be the (unique) FP
- ▶ converges to x^* linearly with rate L

$$\|x^{(k)} - x^*\| = \|F(x^{(k-1)}) - F(x^*)\| \leq L\|x^{(k-1)} - x^*\| \leq L^k\|x^{(0)} - x^*\|$$

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Fixed point iteration: nonexpansive

if F is nonexpansive, the iteration

$$x^{(k+1)} = F(x^{(k)})$$

need not converge to a fixed point even if one exists.

proof:

Fixed point iteration: nonexpansive

if F is nonexpansive, the iteration

$$x^{(k+1)} = F(x^{(k)})$$

need not converge to a fixed point even if one exists.

proof:

- ▶ let F rotate its argument by θ degrees around the origin.
- ▶ then F is nonexpansive and has a fixed point at $x^* = 0$.
- ▶ but if $\|x^{(0)}\| = r$, then $\|F(x^{(k)})\| = r$ for all k .

Averaged operators

an operator F is **averaged** if

$$F = \theta G + (1 - \theta)I$$

for $\theta \in (0, 1)$, G nonexpansive

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proof:

$$\begin{aligned}x &= Fx = \theta Gx + (1 - \theta)x = \theta Gx + (1 - \theta)x \\ \theta x &= \theta Gx \\ x &= Gx\end{aligned}$$

\implies if G is nonexpansive, $F = \frac{1}{2}I + \frac{1}{2}G$ is averaged with same FPs

Fixed point iteration: averaged

if $F = \theta G + (1 - \theta)I$ is averaged ($\theta \in (0, 1)$, G nonexpansive), the iteration

$$x^{(k+1)} = F(x^{(k)})$$

converges to a fixed point if one exists.

(also called the damped, averaged, or Mann-Krasnosel'skii iteration.)

properties:

- ▶ distance to fixed point decreases monotonically (Fejer-monotone)
- ▶ sublinear convergence of fixed point residual

$$\|Gx^{(k)} - x^{(k)}\|^2 \leq \frac{1}{(k+1)\theta(1-\theta)} \|x^{(0)} - x^*\|^2$$

Proof

proof follows [Ryu and Boyd, 2015]

use $\|(1 - \theta)a + \theta b\|^2 = (1 - \theta)\|a\|^2 + \theta\|b\|^2 - \theta(1 - \theta)\|a - b\|^2$
(proof by expanding), and set

$$x^{(k+1)} - x^* = (1 - \theta)(x^{(k)} - x^*) + \theta(Gx^{(k)} - x^*) = (1 - \theta)a + \theta b$$

so $a - b = x^{(k)} - x^* - (Gx^{(k)} - x^*) = x^{(k)} - Gx^{(k)}$. then

$$\begin{aligned} & \|x^{(k+1)} - x^*\|^2 \\ &= (1 - \theta)\|x^{(k)} - x^*\|^2 + \theta\|Gx^{(k)} - x^*\|^2 - \theta(1 - \theta)\|x^{(k)} - Gx^{(k)}\|^2 \\ &\leq (1 - \theta)\|x^{(k)} - x^*\|^2 + \theta\|x^{(k)} - x^*\|^2 - \theta(1 - \theta)\|x^{(k)} - Gx^{(k)}\|^2 \\ &= \|x^{(k)} - x^*\|^2 - \theta(1 - \theta)\|x^{(k)} - Gx^{(k)}\|^2, \end{aligned}$$

(using the fact that G is nonexpansive for the first inequality)

this shows the iteration is Fejer monotone

Proof (II)

sum the last inequality over iterations k . it telescopes:

$$\|x^{(k+1)} - x^*\|^2 \leq \|x^{(0)} - x^*\|^2 - \theta(1 - \theta) \sum_{i=0}^k \|x^{(i)} - Gx^{(i)}\|^2$$

$$\sum_{i=0}^k \|x^{(i)} - Gx^{(i)}\|^2 \leq \frac{1}{\theta(1 - \theta)} \|x^{(0)} - x^*\|^2$$

$$\min_{i=0, \dots, k} \|x^{(i)} - Gx^{(i)}\|^2 \leq \frac{1}{(k+1)\theta(1 - \theta)} \|x^{(0)} - x^*\|^2$$

$$\|x^{(k)} - Gx^{(k)}\|^2 \leq \frac{1}{(k+1)\theta(1 - \theta)} \|x^{(0)} - x^*\|^2$$

where the last inequality uses the fact that G is nonexpansive.

How to design an algorithm

- ▶ look for an operator F
 - ▶ whose fixed points solve optimization problems
 - ▶ which is contractive or averaged
- ▶ iterate $x^{(k+1)} = F(x^{(k)})$
- ▶ get convergence
 - ▶ if F is contractive, get linear convergence
 - ▶ if F is averaged, get sublinear convergence

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Properties of operators

we'll need these properties of operators:

- ▶ Lipschitz
 - ▶ contractive
 - ▶ nonexpansive
 - ▶ averaged
- ▶ monotone
 - ▶ maximal
 - ▶ strongly monotone \implies coercive
- ▶ cocoercive

Properties of optimization operators

we'll show connection to optimization:

- ▶ gradient of convex function is monotone
- ▶ gradient of strongly convex function is strongly monotone
- ▶ gradient of smooth function is cocoercive
- ▶ prox of convex function is $\frac{1}{2}$ -averaged
- ▶ gradient step $I - \frac{2}{\beta} \nabla f$ of smooth function is nonexpansive (and so smaller stepsizes are averaged)
- ▶ prox of strongly convex function is contractive
- ▶ gradient step of SSC function is contractive

Monotone operators

- ▶ a relation F is **monotone** if, for all $(x, u) \in F$ and $(y, v) \in F$

$$(u - v)^T(x - y) \geq 0.$$

example: ∂f is monotone

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- ▶ a relation F is α -**strongly monotone** if, for all $(x, u) \in F$ and $(y, v) \in F$

$$(u - v)^T(x - y) \geq \alpha \|x - y\|^2.$$

(also called α -**coercive**)

example: ∂f is strongly monotone iff f is strongly convex

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- ▶ a relation F is **maximal monotone** if there is no monotone relation that properly contains it (as a subset of $\mathbf{R}^n \times \mathbf{R}^n$)

examples:

- ▶ if $F : \mathbf{R}^n \rightarrow \mathbf{R}^n$ is continuous and monotone, then F is maximal monotone
- ▶ if f is CCP then ∂f is maximal monotone

useful: makes sure FP iteration doesn't leave domain of F

Cocoercive operators

an operator F is $\frac{1}{\beta}$ -**cocoercive** if

$$(F(x) - F(y))^T(x - y) \geq \frac{1}{\beta} \|F(x) - F(y)\|^2.$$

example: we've already seen that ∇f is cocoercive if f is β -smooth

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- ▶ F is $\frac{1}{\beta}$ -cocoercive $\implies F$ is β -Lipschitz

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(proof by Cauchy-Schwarz)

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example: we've already seen that ∇f is cocoercive if f is β -smooth

- ▶ F is $\frac{1}{\beta}$ -cocoercive $\implies F$ is β -Lipschitz
(proof by Cauchy-Schwarz)
- ▶ F is α -coercive $\iff F^{-1}$ is α -cocoercive

Cocoercive operators

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(proof by Cauchy-Schwarz)
- ▶ F is α -coercive $\iff F^{-1}$ is α -cocoercive
(proof by interchanging x and $F(x)$)

Gradient step is nonexpansive (or averaged)

F is $\frac{1}{\beta}$ -**cocoercive** $\iff I - \frac{2}{\beta}F$ is nonexpansive
(and smaller step sizes are averaged)

proof:

Gradient step is nonexpansive (or averaged)

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proof:

$$\begin{aligned} & \|(I - \frac{2}{\beta}F)y - (I - \frac{2}{\beta}F)x\| \\ = & \|y - \frac{2}{\beta}Fy - x - \frac{2}{\beta}Fx\| \\ = & \|y - x\|^2 - \frac{4}{\beta}(Fy - Fx)^T(y - x) + \frac{4}{\beta^2}\|Fy - Fx\|^2 \\ = & \|y - x\|^2 - \frac{4}{\beta} \left((Fy - Fx)^T(y - x) - \frac{1}{\beta}\|Fy - Fx\|^2 \right) \\ \leq & \|y - x\|^2 \end{aligned}$$

inequality is definition of $\frac{1}{\beta}$ -cocoercivity

Outline

Relations

Fixed points

Averaged operators

Cocoercive and coercive operators

Operators and functions

Resolvents and prox

∂f as an operator

if f is convex, ∂f is maximal monotone

if f is β -smooth,

- ▶ $\partial f = \nabla f$ is $\frac{1}{\beta}$ -cocoercive
- ▶ $\partial f = \nabla f$ is β -Lipschitz
- ▶

if f is α -strongly convex

- ▶ ∂f is α -strongly monotone

Gradient method converges

if f is convex and β -smooth,

- ▶ $I - \frac{2}{\beta}\nabla f$ is nonexpansive,
- ▶ gradient mapping $I - t\nabla f$ is averaged for $t \in (0, \frac{2}{\beta})$
- ▶ so fixed point iteration

$$x^{(k+1)} = (I - \frac{2}{\beta}\nabla f)x^{(k)}$$

converges

- ▶ from convergence guarantee for damped iteration,

$$\begin{aligned} \frac{1}{(k+1)\theta(1-\theta)} \|x^{(0)} - x^*\|^2 &\geq \min_{i=0,\dots,k} \|(I - \frac{2}{\beta}\nabla f)x^{(i)} - x^{(i)}\|^2 \\ &\geq \min_{i=0,\dots,k} (\frac{2}{\beta})^2 \|\nabla f(x^{(i)})\|^2 \end{aligned}$$

Strong convexity and smoothness

f is α -strongly convex iff f^* is $\frac{1}{\alpha}$ -smooth

proof:

Strong convexity and smoothness

f is α -strongly convex iff f^* is $\frac{1}{\alpha}$ -smooth

proof: $\partial f^{-1} = \partial f^*$.

∂f α -coercive $\iff \partial f^*$ α -cocoercive $\iff f^*$ $\frac{1}{\alpha}$ -smooth.

moral: strong convexity and (strong) smoothness are dual

Gradient update is contractive for SSC functions

suppose f is α -strongly convex and β -smooth
the relation

$$I - t\nabla f = \{(x, x - t\nabla f(x)) : x \in \mathbf{dom} f\}$$

is contractive if $t \in (0, \frac{2\alpha}{\beta^2})$. best contraction factor if $t = \frac{\alpha}{\beta^2}$

proof:

$$\begin{aligned} & \|x - t\nabla f(x) - (y - t\nabla f(y))\|^2 \\ \leq & \|x - y\|^2 + t^2 \|\nabla f(x) - \nabla f(y)\|^2 - 2t(\nabla f(x) - \nabla f(y))^T(x - y) \\ \leq & \|x - y\|^2 + t^2\beta^2\|x - y\|^2 - 2t\alpha\|x - y\|^2 \\ \leq & (1 - 2t\alpha + t^2\beta^2)\|x - y\|^2 \end{aligned}$$

note: stronger proof (using co+cocoercive inequality from slide 28 of GD lecture) shows $I - t\nabla f$ is Lipschitz with parameter

$$L = \max\{|1 - t\alpha|, |1 - t\beta|\}. \text{ if } t = \frac{2}{\alpha + \beta}, L = \frac{\kappa - 1}{\kappa + 1}$$

Outline

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Resolvent operator

for relation F , define the **resolvent** of F

$$R_F = (I + F)^{-1}$$

consider resolvent of F

- ▶ $(I + F) = \{(x, x + y) : (x, y) \in F\}$
- ▶ $R_F = (I + F)^{-1} = \{(x + y, x) : (x, y) \in F\}$
- ▶ $R_F = \{(u, v) : (u - v) \in F(v)\}$

Prox is the resolvent of ∂f

► $\text{prox}_f = R_{\partial f} = (I + \partial f)^{-1}$

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proof: let $z \in \text{prox}_f(x)$,

$$z = \underset{z}{\operatorname{argmin}} f(z) + \frac{1}{2} \|z - x\|^2$$

$$0 \in \partial f(z) + z - x$$

$$(x - z) \in \partial f(z)$$

► $\text{prox}_f = \nabla h^*$ where $h(x) = f(x) + \frac{1}{2} \|x\|^2$

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► $\text{prox}_f = \nabla h^*$ where $h(x) = f(x) + \frac{1}{2} \|x\|^2$

proof: h is CCP and $\partial h = \partial f + I$, so

$$\nabla h^* = (\partial h)^{-1} = (I + \partial f)^{-1}$$

► prox_f is a function

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$$\nabla h^* = (\partial h)^{-1} = (I + \partial f)^{-1}$$

► prox_f is a function

proof: h is strongly convex, so h^* is smooth

Projection is resolvent of indicator function

let $f = I_C$, the indicator function of the convex set C

- ▶ ∂f is the **normal cone operator**

$$\partial f(x) = N_C(x) = \begin{cases} \emptyset & x \notin C \\ \{w : w^T(z - x) \leq 0, \quad \forall z \in C\} & x \in C \end{cases}$$

- ▶ $R_{\partial f} = \mathbf{prox}_f$ is

$$(I + \partial I_C)^{-1}(x) = \underset{u}{\operatorname{argmin}}(I_C(u) + \frac{1}{2}\|u - x\|^2) = \Pi_C(x)$$

Resolvent and Cayley operators

for relation F , recall the **resolvent** of F

$$R_F = (I + F)^{-1}$$

and define the **Cayley** operator (sometimes called reflection operator)

$$C_F = 2R_F - I = 2(I + F)^{-1} - I$$

properties:

- ▶ if F is monotone, then R_F and C_F are nonexpansive (and hence are functions)
- ▶ if F is maximal monotone, then R_F and C_F have full domain
- ▶ zeros of F are FPs of R_F and C_F

we'll prove the first and last properties; second is Minty's theorem

Fixed points of R and C are zeros of F

fact: fixed points of R and C are zeros of F

proof:

Fixed points of R and C are zeros of F

fact: fixed points of R and C are zeros of F

proof:

$$\begin{aligned}0 \in F(x) &\iff x \in (I + F)(x) \\ &\iff (I + F)^{-1}(x) \ni x \\ &\iff x = R(x)\end{aligned}$$

(using the fact that R is a function)

and if $x = R(x)$,

$$C(x) = 2R(x) - I(x) = 2x - x = x$$

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in particular, this means fixed points of $\mathbf{prox}_f(x)$ are zeros of ∂f

Resolvent is nonexpansive

fact: $R = R_{\lambda F}$ is nonexpansive

proof:

Resolvent is nonexpansive

fact: $R = R_{\lambda F}$ is nonexpansive

proof: if $(x, u) \in R$ and $(y, v) \in R$,

$$x \in u + F(u), \quad y \in v + F(v)$$

so for some $f_u \in F(u)$, $f_v \in F(v)$,

$$\begin{aligned}x - y &= u - v + f_u - f_v \\(u - v)^T(x - y) &= \|u - v\|^2 + (u - v)^T(f_u - f_v) \\(u - v)^T(x - y) &\geq \|u - v\|^2\end{aligned}$$

so R is 1-cocoercive. this implies R is nonexpansive, too:

$$\begin{aligned}\|u - v\| \|x - y\| &\geq \|u - v\|^2 \\ \|x - y\| &\geq \|u - v\|\end{aligned}$$

note: this also proves projections and prox are nonexpansive

Cayley operator is nonexpansive

fact: $C = C_F$ is nonexpansive

proof:

Cayley operator is nonexpansive

fact: $C = C_F$ is nonexpansive

proof:

$$\begin{aligned}\|C(x) - C(y)\|^2 &= \|2(u - v) - (x - y)\|^2 \\ &= 4\|u - v\|^2 - 4(x - y)^T(u - v) + \|x - y\|^2 \\ &\leq \|x - y\|^2\end{aligned}$$

using 1-cocoercivity of R (from above): $\|u - v\|^2 \leq (u - v)^T(x - y)$.

note:

- ▶ this also shows $R = \frac{1}{2}C + \frac{1}{2}I$ is $\frac{1}{2}$ -averaged
- ▶ more generally, $\theta C + (1 - \theta)I$ is θ -averaged for any $\theta \in (0, 1)$

More contractions!

- ▶ if F is α -strongly monotone
- ▶ then $(I + F)$ is $1 + \alpha$ -strongly monotone
- ▶ so $R_F = (I + F)^{-1}$ is $(1 + \alpha)$ -cocoercive
- ▶ and hence R_F is $\frac{1}{1+\alpha}$ -Lipschitz

More contractions!

- ▶ if F is α -strongly monotone
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moral: we now have two ways to manufacture contractions:

- ▶ as a gradient update of an SSC function
- ▶ as a proximal update of a strongly convex function